Protronic 100/500/550
Digitric 500

Controllers for process engineering controllers for industry

Configuration and parameterization

Manual

42/62-50012 EN

Rev. 06

Remarks

Preliminary Remarks

The documentation provided on delivery for Protronic 100 / 500 / Digitric 500 consists of the following parts:

Installation instructions Protronic 100 / 500 / 550 . . . . . 42/62-50011
or
Installation instructions Digitric 500 . . . . . 42/61-50011

Commissioning instructions: Configuration and parameter setting
Protronic 100 / 500 / 550 • Digitric 500 . . . . . 42/62-50012

Operating instructions Protronic 100 / 500 . . . . . 42/62-50013
or
Operating instructions Protronic 550 . . . . . 42/62-55013
or
Operationg instructions Digitric 500 . . . . . 42/61-50013

Also available on request:

Operating instructions IBIS_*R* • IBIS_*R*+ 42/62-50020

Operating instructions IBIS_*R*+ 42/62-50020
and
42/62-50030

Interfac description (MODBUS) 42/62-50040

The commissioning includes all information for the menu-guided configuration and parameter definition of the Protronic 100 / 500 / 550 and Digitric 500. The required inputs can either be made on the device itself or with the help of configuration and parameter definition software IBIS_*R*.

Configurations going above the capabilities of the menus can be undertaken with the help of the configuration and parameter definition software IBIS_*R*+. These configurations are not part of this commissioning manual.

Delivery condition

The devices supplied from the Hartmann & Braun warehouse without any further settings are delivered ex-factory with the following defined functions:
- Single-channel, continuous controller
- Input: 4...20 mA
- Output: 4...20 mA
- Language: German

The exact definition of the instrument is stated in the configuration tables in this Operation Manual and are underlined (= factory setting).

Other variations of this can also be ordered.

Switching on the instrument

On switching on the instrument and or in case of mains restoration, the device conducts an automatic test of the internal functions. The progress of the test is illustrated by changing displays. These can normally be ignored.

Firmware versions

Valid for all firmware versions through 1.190. library 3.5.0.

Z-19119

Contents

Comments

Comments on the displays in this operating manual

<Enter>	Keys of the instrument with their description.
<Ind>, <Loop> <Menu>, <Enter>	Keys are always enabled for operator interventions
[P-W]	Texts or text parts from the digital display.
P-W, A	Flashing texts or text parts from the digital display.
/8/	Comments on numerals in fig. 1.
M☼ ,A☼, C☼ Menu☼ Enter☼	LEDs next to keys with the same name light up
M● ,A●, C● Menu● Enter●	LEDs next to the keys with the same name do not light up.
Wex Hand	Forced set point source or operating mode.

Comments on the configuration and parameter definition tables

I	Instrument
AI	Analog input
AO	Analog output
BIO, BI/BO	Binary input/output
Lx	Loop No, number of control circuit
ZK	State corection
P	Programmer
P01	Parameter 1
B01	Block 01
Q01	Query 01

Parameter definition

L1-P01	Loop 1, Parameter 01 = Kp

Configuration

I-B01-Q01	Instrument, Block 1, Query 1 = Language
L2-B03-Q02	Loop 2, Block 3, Query 2 = Input signal connection

Comments on the configuration menu

The input values AIx, BIx as well as the outputs AO1 and BOx are global variables in the unit.

The binary inputs can control several functions at the same time, such as transferring between AI01 and AI02 and with simultaneous parameter transfer.

The binary outputs can output several items of information logically combined by OR.

Appropriate care is required for the configuration.

Numbering and identification of the inputs and outputs

Basic unit:

The analog inputs/outputs are designated as AI01 and AI02 or AO01.

The binary inputs/outputs are designated as BIO01 to BIO04. Depending on the configuration, they are used in the device as input BI0x or output BO0x.

Modules:

Protronic 100 has one slot.

Protronic 500/550 has up to 7 slots (counting from top to bottom).

Digitric 500 has up to 4 slots (counting from left to right).

Up to four analog or 6 binary inputs and outputs are processed in the modules. In the apparatus the digitalized inputs and outputs are identified as follows:

AIxy	Analog input no. y of the module at position x
AI32	Input 2 of the module on slot 3
BI76	Module 7, binary point 6, configured as input

Description of the Front Panel

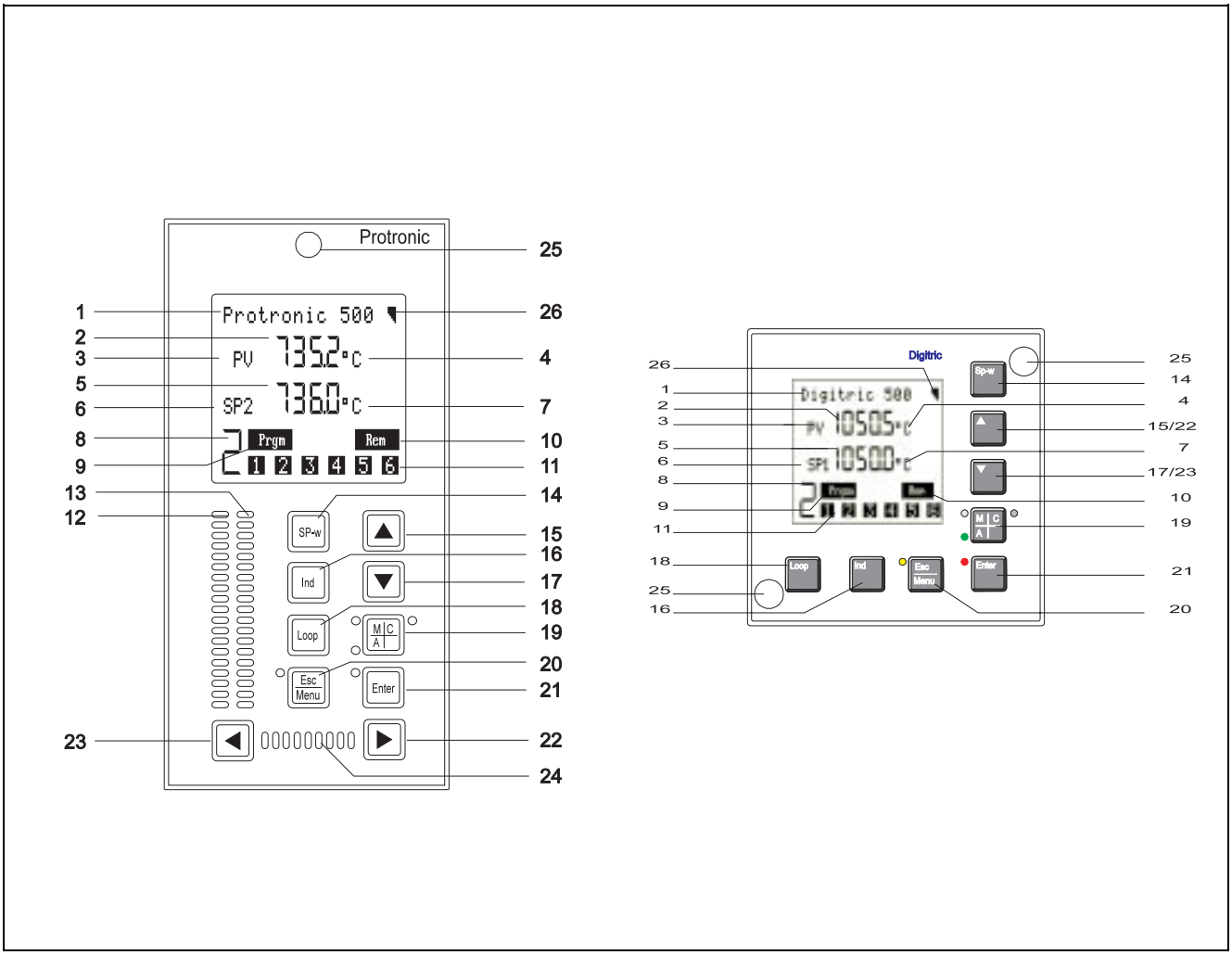


Fig. 1 Front panel Protronic 100 / 500 (right) • Digitric 500 (left)

Z-19037 Z-19062

1 Text line
2 Digital display of controlled variable PV
3 Designation of the controlled variable
4 Dimension of the controlled variable
5 Digital display: in automatic mode set point SP
in manual mode correction value OUT
6 Designation of the displayed value
7 Dimension of the displayed value
8 Number of the control system displayed, alternates in event of alarm with display “A”
9 Display for active programmer
10 Display of activated remote operation
11 Freely configurable binary messages (flags)
12 Analog display of controlled variable PV
13 Analog display of set point SP
14 Set point changeover (see Section on “Set points”)
15 Setting “raise” of the value displayed in 5, 6 and 7
16 Displaychangeover switch for displays 5, 6 and 7
17 Setting “lower” of the displayed value in 5, 6 and 7
18 Channel (loop) transfer
19 Operating modes changeover with manual-automatic-cascade with associated signal LEDs
20 Entry into parameter setting and configuration mode. Associated LED lights up immediately the operating level exitted. At the same time, the menu symbol 26 in the text line is visible.
21 Acknowledgment of alarms, parameter setting and configuration data
22 In manual mode “raise”
23 In manual mode “lower”
24 Controller output
25 Closing screw
26 Menu symbol displays the momentary menu level

The numbers of the individual operating and display elements are used identically in all parts of the equipment documentation.

Menu system

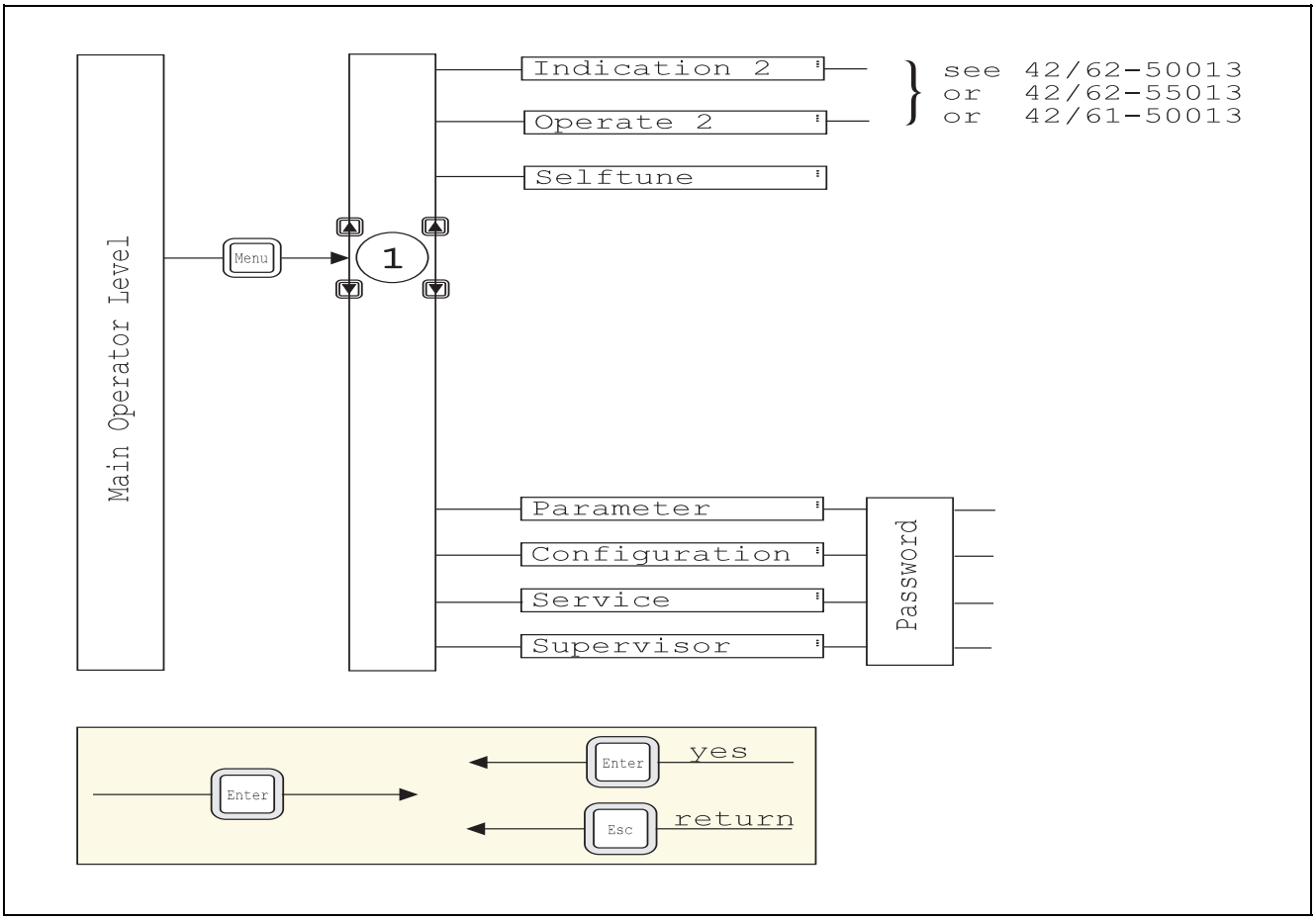


Fig. 2 Menu system
Z-19093

Self-tuning

The self-tuning function is enabled in the configuration menu. Once enabled, it can be used without a password.

Depending on the operating status of the self-tuning feature, the menu of the second level is opened.

Parameter

Setting of the values for the configurable functions. During the parameter setting, the controller is online, i.e. all functions are in operation.

Confi(guration)

Definition of the controller function, e.g. type of controller output, the number of channels etc. During configuration, the controller is offline, i.e. all analog and binary outputs are blocked (frozen).

Service

This menu contains i.a. the functions lead balancing, display illumination adjustment, calibration, diagnosis ...

Supervisor

This menu contains among others the menu item “Factory setting”, which enables the controller to be reset to its basic setting (single-channel, continuous controller; inputs 1 and 2: 4...20 mA; output: 4...20 mA). The basic settings are underlined in the configuration tables.

⚠ Attention

All previously set functions are lost in case of a reset!

Alarm treatment

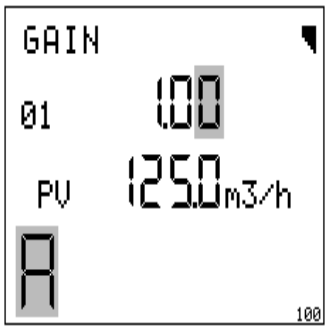


Fig. 3 Gain selected for setting. Alarm message in channel display
Z-19100

In case of alarm, alarm value infringement or error in the processing cycle during parametering or configuration work, the channel display changes over from /8/ to “A”.

For acknowledgment, switch back to the operator control level (I-B10).

Password protection

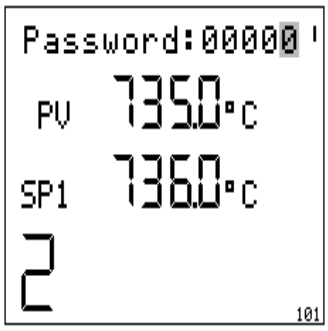


Fig. 4 Password input. 1. field on the right
Z-19101

If a password protection has been configured (I-B20), access to the protected area is gained by changing the default input “00000”.

The password is a five-digit figure.

1. Shift the flashing (= changeable) field:
   <Ind>

2. Change the figure:
   <▲>, <▼>

3. Confirm the password:
   <Enter>

With a correct password, access is gained to the desired level. Without having to restate the password, it is now possible to change to any level of the menu system (Query: I-B20-Q01).

If the password is wrong, the display will change back to the main operation level.

If a hardware inhibition has been configured (I-B02-Q01) and the binary output set, any attempt to access a protected level will produce the message “OL inhibited”.

The message is displayed for 3 s, after which there is an automatic return to the operator control level.

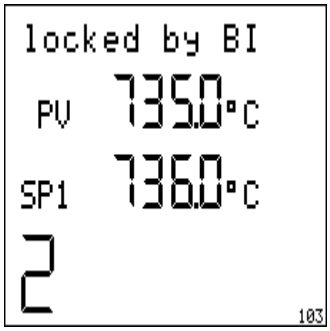


Fig. 5 Blockade of the parameter setting and configuration level by a binary input
Z-19103

Abort the password input

1. Abort the password input:
   <Esc>

Lost password

A lost password can be reset by provisionally changing a plug-in jumper in the device. This is on condition that the control loop has been switched off. Please find detailed information in the Section entitled “Service”.

Parameter setting

During the parameter setting mode, the controller is online, i.e. all functions are in operation.

Since the automatic mode can be damaged by parameter modifications, the controller should be switched to “Manual” during configuration.

Parameter setting menu

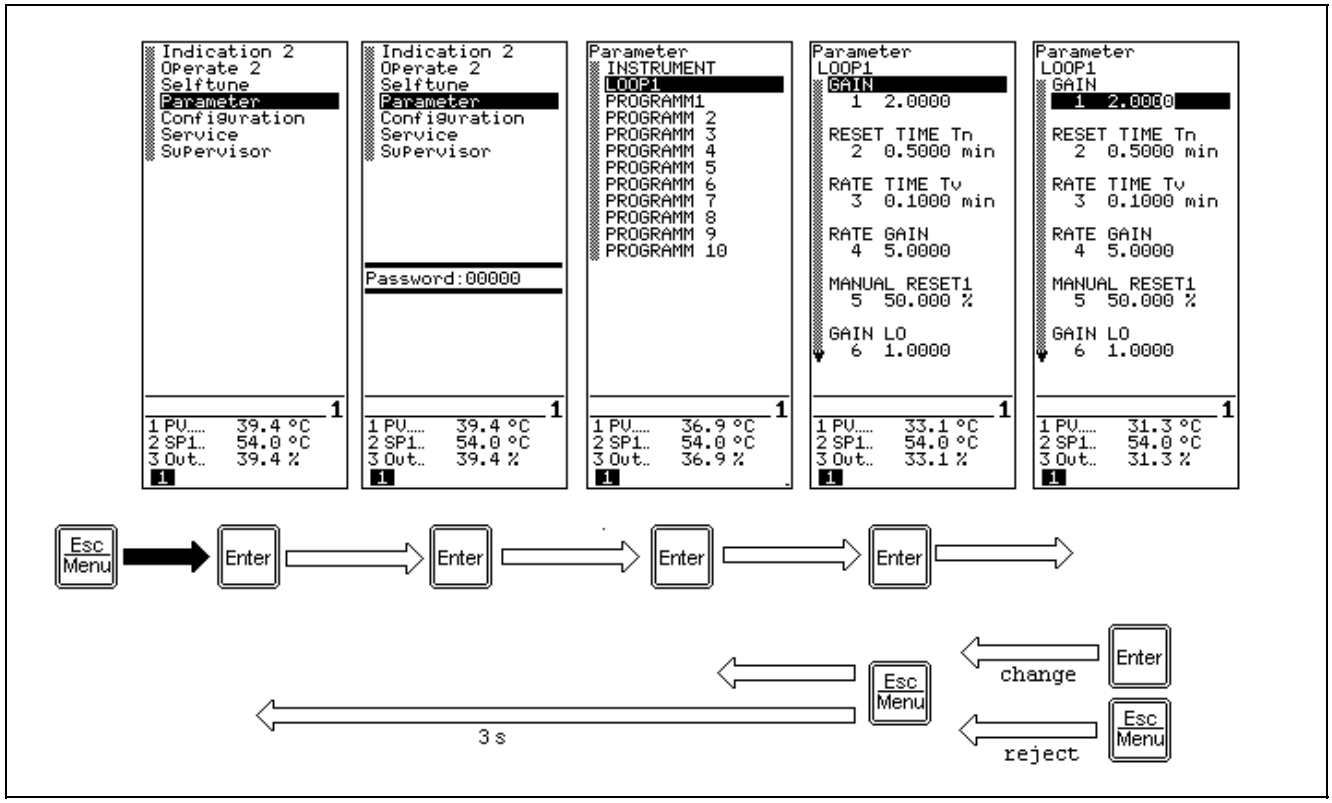


Fig. 6 Parameter setting menu (**Protronic 100: only Loops 1 and 2**)
Z-19036

Parameter selection and modification

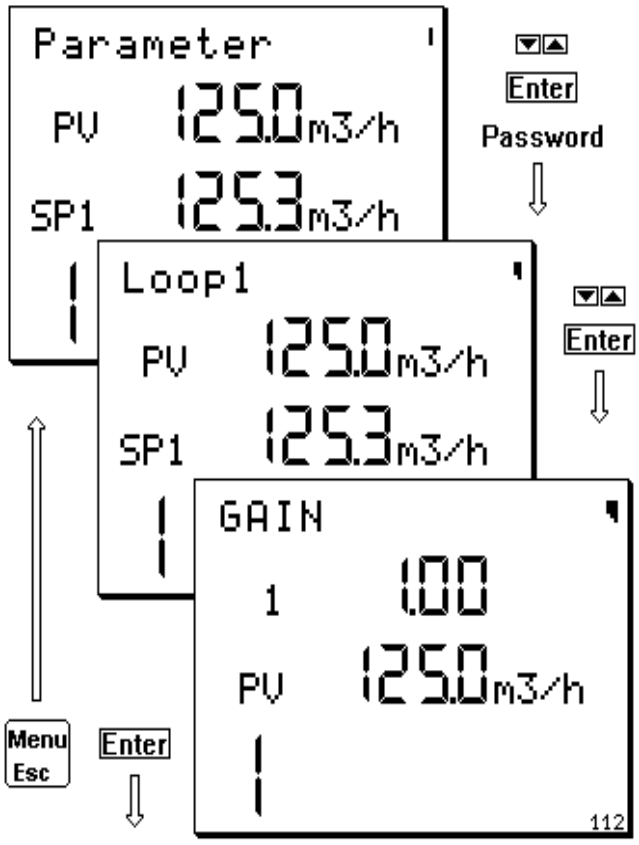


Fig. 7 Parameter selection
Z-19112

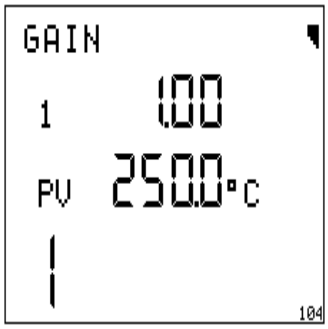


Fig. 8 Gain selected for modification
Z-19104

(Menu●)

1. Enter the parameter menu:
   <Menu>
2. If required, input password (proceed according to steps 4. to 8.):

(Menu✲)

3. Select parameter:
   <▲>, <▼>
4. Parameter released for modification:
   <Enter>

(Enter✲)

The parameter flashes at one position.

5. Modify at the flashing position:
   <Ind>
6. Shift the decimal point:
   Press and hold <Ind>
7. Change value:
   <▲>, <▼>
8. Take over modified parameters (including decimal point change):
   <Enter>

   or

   Reject modification:
   <Esc>

Enter●.

Parameter classification

The parameter stting Tables in this manual (as of page 62) have the following headings:

Device	All parameters valid for the entire device.
Loop 1 to 4	Parameters relating to control loops.
Program 1-10	Program 1 to 10 for the programmer (see Section on “Programmer”).

Parameter setting of device

The parameter setting for the device consists of the four linearization tables. The dimension (EU) depends on the configured application. It is not input into the tables.

The tables can be parameterized only when the tables are integrated into the configuration (e.g. AI-Bx-Q02).

Parameter setting of loops 1 to 4

(**Protronic 100: only loops 1 and 2**)

PID Parameters (Lx-P01 to Lx-P19)

With a normal PID controller only the following parameters are possible:

01 Gain
02 Integral action time
03 Derivative time
04 Derivative gain
05 Operating point (if no integral action component) is accessible.

If a parameter control has been configured (Lx-B02-F7...Q22), the necessary parameters from range P06 to P21 become active and can be seen in the display. The currently active values are always displayed in the menu items “Display”, “Parameter” even with active parameter control in P01 to P05.

PID2 Parameters (Lx-P25 - Lx-P37)

The parameters apply to a second controller output (**heat-off-cool** or **split range**). A parameter control of the first controller output is also effective for the second output. If the function is not intended to be effective for the second output, the start and end values must be equal (Gain 2 start = Gain 2 end).

Self-tuning Lx-P125 - Lx-P128

With the parameters P125 to P128, limitations are imposed on the self-tuning which are intended to ensure that no illegal operating situations arise.

Dead time (Parameters Lx-P39 to Lx-P53)

The time constants for the Smith Predictor (dead time algorithms) are set with these parameters. They are only accessible if this function has been configured.

Control output (Parameters Lx-P55 to Lx-P72)

The parameters P55 to P62 con only be seen if the corresponding output function has been configured (Lx-B01-Q02).

Limitations on the positioning signal (P67 to P70) are always available. Factory settings make them inoperative.

The safety correction values P71, P72 are configuration-dependent (Lx-B07-Q03, Q05, Q06 and Lx-B10-Q03, Q05).

Set points (Parameter Lx-P75 to Lx-P84)

The parameters P75 to P80 define the limits for the set points and their rate of change. Factory settings of parameters P77 to P80 make them inoperative.

Parameters P81 to P84 only become visible when the set points are configured as parameters (Lx-B05-Q02 ...).

Alarm values (Parameter Lx-P91 to Lx-P96)

If an alarm value has been configured for monitoring the rate of change, the parameter P96 will determine the time limit during which the values set with P71 to P75 may not be overshot.

P96 has only 3 possible values:

1 = 0:00:01 h = 1 second
2 = 0:01:00 h = 1 minute
3 = 1:00:00 h = 1 hour

Example:

The alarm value 1 should switch on at a change rate of more than 15 °C/min:

AL1	Lx-B08-Q01 = 11	(AL1: function dx/dt)
	Lx-P96 = 2	min
	Lx-P91 = 15	15 (°C, if x in °C)

Input ratio (Parameter Lx-P101 to Lx-P104)

These parameters are displayed during the description of the input circuits.

Input ratio (Parameters Lx-P115 to Lx-P117)

These parameters are only effective in the ratio input circuits. They define the limits of the ratio set point and the magnitude of the bias.

Disturbance variable feedforward (parameters Lx-P120, Lx-P121)

These parameters determine the transfer function of a differential disturbance variable feedforward.

TAG name (parameter Lx-P199)

Fig. 9 Parameter 199 ´TAG name´ selected for setting
Z-19105

The parameter 199, the TAG name is set in the text line.

<▲>, <▼> permit the setting of A...Z, a...z, +, ., /, %, _,), (, °, 9...0, spacing, -

<Enter> terminates the entry and accepts the text input.

<Ind> relocates the entry position.

Exit the parameter definition level

<Menu> jumps to a higher level.

If this key is pressed and held for more than 5 s, the menu system will be exitted.

Self-tune mode

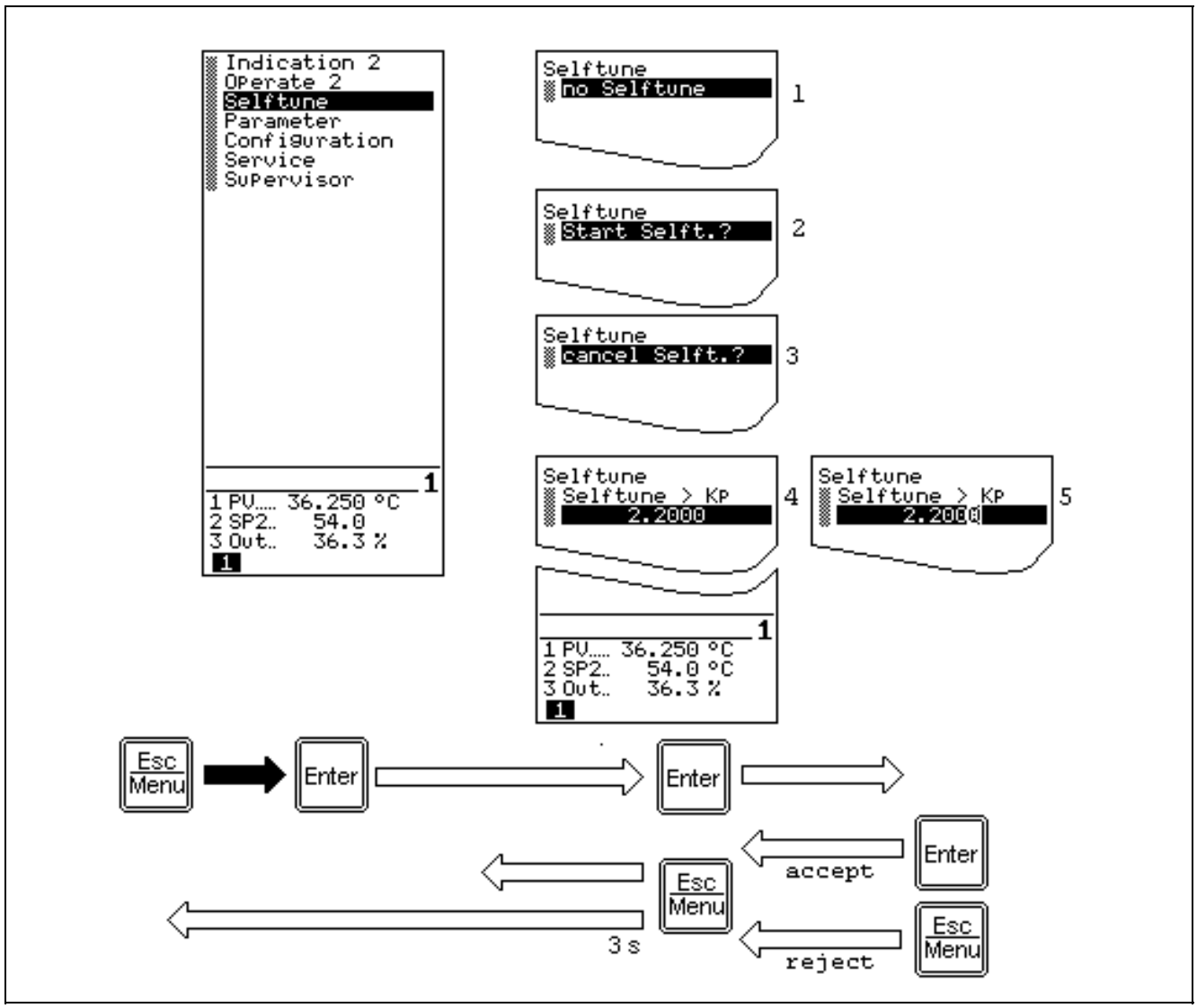


Fig. 10 Self-tuning. Accessible menu points:
Z-19109
1 self-tuning inhibited
2 before the start
3 during self-tuning
4 after calculating the parameter
5 calculated G can be manually altered

Remarks

The self-tuning of several loops in an apparatus must be done after after the other. The self-tuning mode can become active in only one loop at a time.

The self-tuning mode should be only started if the control variable has been constant for some time. This is generally only possible manually prior to the parameter definition.

In order to define a controller with the function heat-off-cool, the temperature of the path must be so high at the start of self-tuning, that cooling can become effective.

Procedure

In order to activate the controlled system, a control jump is applied to the controlled system at the start of the self-tune mode. This is then withdrawn after achieving an adjustable pulse duration.

From this control pulse, the controller identifies the type of controlled system and the first parameters. A further jump takes place for balanced controlled systems to enable more exact calculation of the parameters.

Parameter

In the parameter menu 4 parameters are reserved for self-tuning. If required, these can be matched to the conditions of the controlled system:

Control jump Lx-P125

The selection must be so big that an evaluatable change in the controlled system can take place. Without that, the controlled system would reach a critical limit. Factory setting: +5.0 %.

Max. duration of jump Lx-P126

Duration of the first actuating pulse. The interval ought to reach at least 1/10 of the expected path compensation time Tg. Factory setting: 0.25 min (15 s).

If the length of the 1st test pulse is selected at a length permitting a complete step response to be fully accepted (in both directions), no further step takes place on systems with balancing.

Max. Pos. control deviation Lx-P127
Max. Neg. control deviation Lx-P128

The first control pulse is withdrawn from the start value, if the there is a risk that the control variable could exceed the set range.

Factory setting: 99999 EU

If a second control pulse is given on the controlled system, the controller reduces this second pulse in such manner that no overranging takes place.

Start of self-tuning

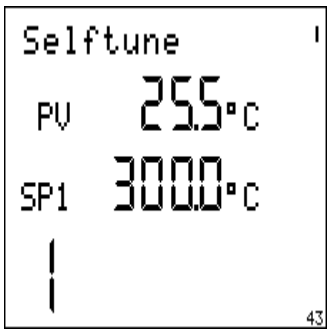


Fig. 11 Self-tuning
Z-19043

1. Call up the self-tune mode:
   <Menu> <▾> <▾>

Fig. 12 Inhibited for self-tuning
Z-19143

The self-tune mode can only be started, if enabled in the configuration menu (Lx-B01-Q05 > 0). If the self-tune mode is inhibited, the message “inhibited f. SP”. will appear on call-up.

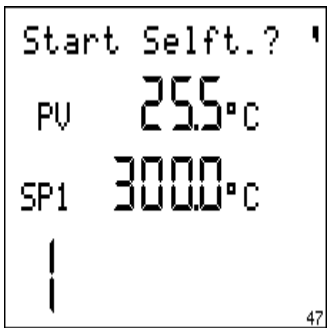


Fig. 13 Start self-tuning?
Z-19047

3. Upon opening the menu point “Self-tune”, self-tuning will start:
<Enter>

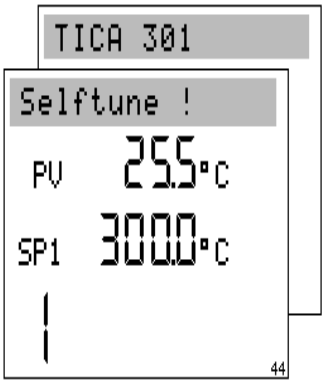


Fig. 14
Z-19044

The display springs back to the main operator control level. A loop changeover is now possible. The display in the text line of the loop with active self-tuning changes between the TAG names and “Selftune!”.

⚠ Attention

During the determination of the parameters, the loop is in the manual mode. In this situation, the controller output and the set point may not be changed manually. Manual adjustments are enabled for emergency interventions.

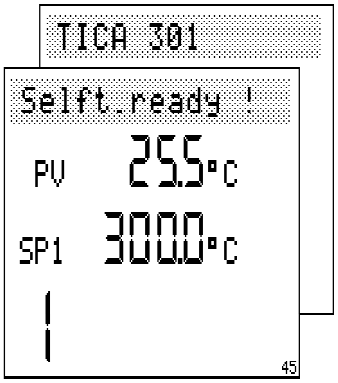


Fig. 15
Z-19045

On completing the self-tuning exercise, the display changes. After re-entering the self-tune mode (fig. 11 and subsequently 16), the calculated values are offered for acceptance.

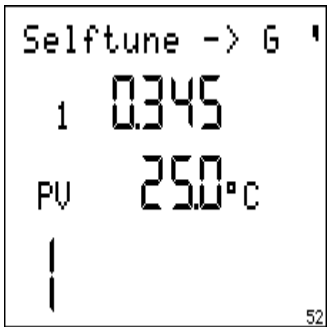


Fig. 16
Z-19052

4. Changeover between the displays G, *Tn* and *Tv*:
<▲>, <▼>

5. Change the displayed value:
<Enter>
<▲>, <▼>

or

5. Exit the self-tune mode:
<Esc>

Acceptance of parameters

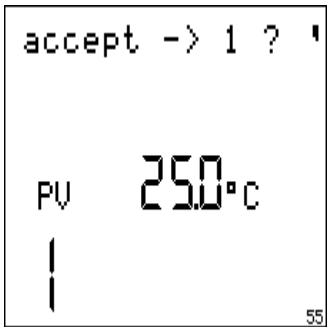


Fig. 17 Accept >1?
Z-19055

After displaying and modifying, if necessary, the determined values, these can be accepted.

1. Accept the values:
   <Enter>

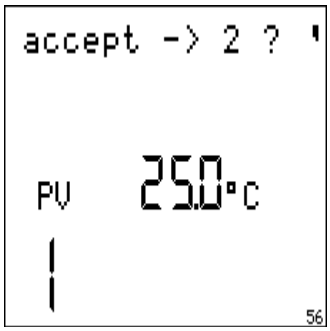


Fig. 18 Accept >2?
Z-19056

For controllers with two control functions heat-off-cool or split range, it must be decided, if the obtained parameter set for heat (accept > 1) or cool (accept > 2) should be used.

Rejection of parameters

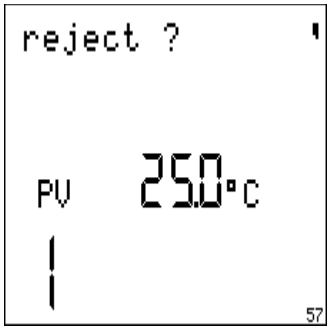


Fig. 19 Reject?
Z-19057

1. Reject parameter:
   <Enter>

The previously set values remain valid.

Abort the self-tuning mode

Fig. 20 Abort parameter definition?
Z-19046

Whilst self-tuning is in process, it can be aborted by reaccessing the operation level 2 and opening the menu item self-tuning.

1. Abort the self-tuning exercise:
   <Enter>

or

1. Do not abort the self-tuning exercise:
   <Menu>

The display springs back to the second operation level 2.

Configuration

Selection of the configuration menu

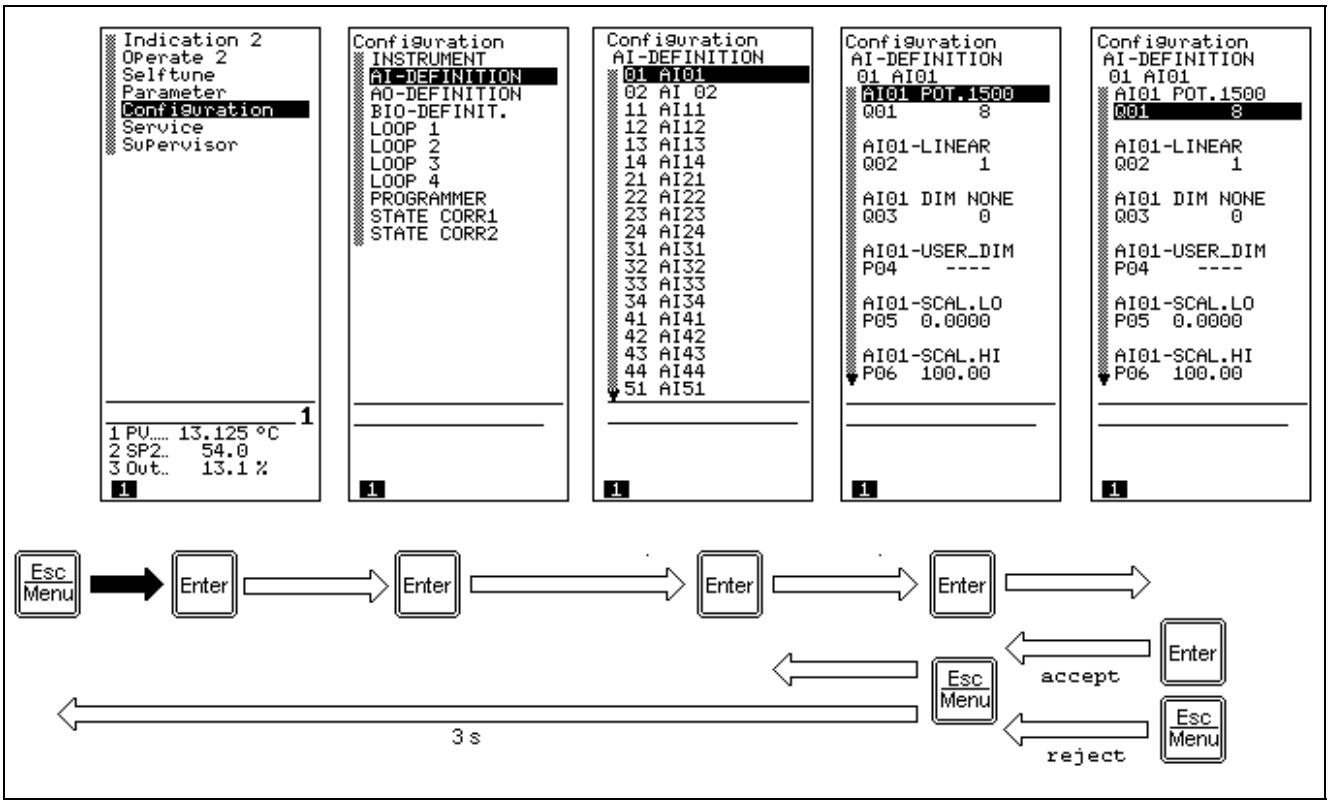


Fig. 21 Configuration menu
Z-19061

Classification of the configuration tables

The configuration tables (as of page 74) provided in this instruction manual are classified as follows:

Unit	all functions which apply to the entire instrument
AI-Definition	define analog inputs with the functions sensor, linearization, filtering, scaling
AO-Definition	define signal ranges of the analog outputs
BIO-Definition	define the binary inputs/outputs as inputs or outputs
Loop 1 to 4	configure control tasks with the functions control output, input signal connection, PID structure
State corr-x	select and parameter-set state correction
Programmer	activate programs

Configuration sequence

The following sequence is suggested for the configuration of a new unit:

1. Unit
2. Analog inputs
3. State correction, if provided
4. Analog outputs
5. Binary input/outputs
6. Controller function

Changing the configuration

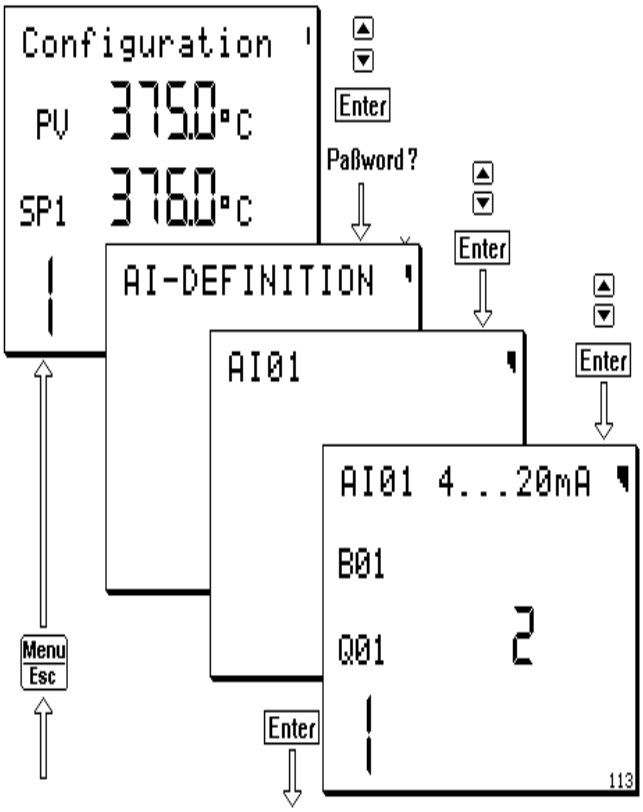


Fig. 22 Select AI → B01 → Q01
Z-19113

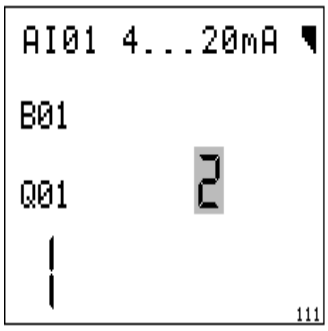


Fig. 23 Change configuration
Z-19111

During configuration, queries (Fx) or parameters (Px) can be provided for adjustment.

⚠ Attention

If a free configuration is loaded, this is displayed on calling up the configuration menu through "Confi(free)" (instead of "Confi").

Only a few menu items can be called up. These are identified in the configuration tables provided as of page 74.

1. The selected query / the selected parameters for adjustment are enabled:
   <Enter>

Enter☼

The response enabled for change flashes.

Queries are responded to with one- or two-digit figures. Parameters require the input of one- to 5-digit values (see Chapter on "Parameter setting").

2. Change the flashing position:
   <▲>, <▼>
3. Shift the flashing position:
   <Ind>
4. Shift the decimal point:
   hold <Ind>

The text corresponding to the currently visible numeral is displayed in the text line.

5. Accept the selected response with:
   <Enter>

Enter●

The response ceases to flash.

Exit the configuration menu

<Menu> jumps up one level higher.

If you keep this key pressed for more than 5 s, the menu is exitted.

When the plausibility check is switched on (see Section on “Supervisor”), the unit checks the configuration for completeness and plausibility on exitting the configuration menu.

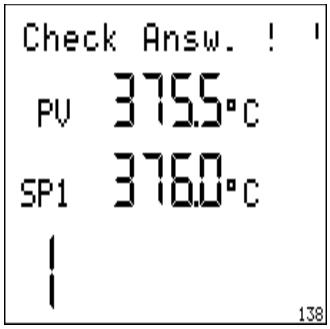


Fig. 24 Check response!
Z-19138

After that, the set functions are conditioned for processing.

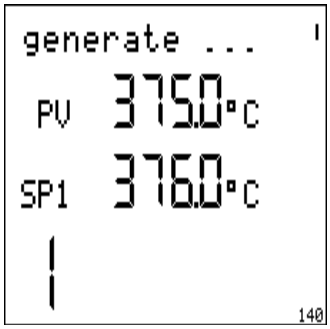


Fig. 25 Generate ...
Z-19140

After successfully taking over the configuration, the unit returns to the configuration menu.

1. Exit the configuration menu:
   <Esc>

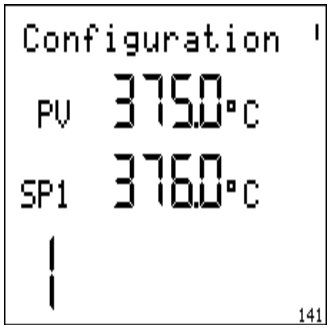


Fig. 26 Configuration
Z-19141

Configuration Examples

The following configuration examples are detailed illustrations of some of the most important configurations.

The configuration tables (as of page 74) illustrate complete configuration possibilities.

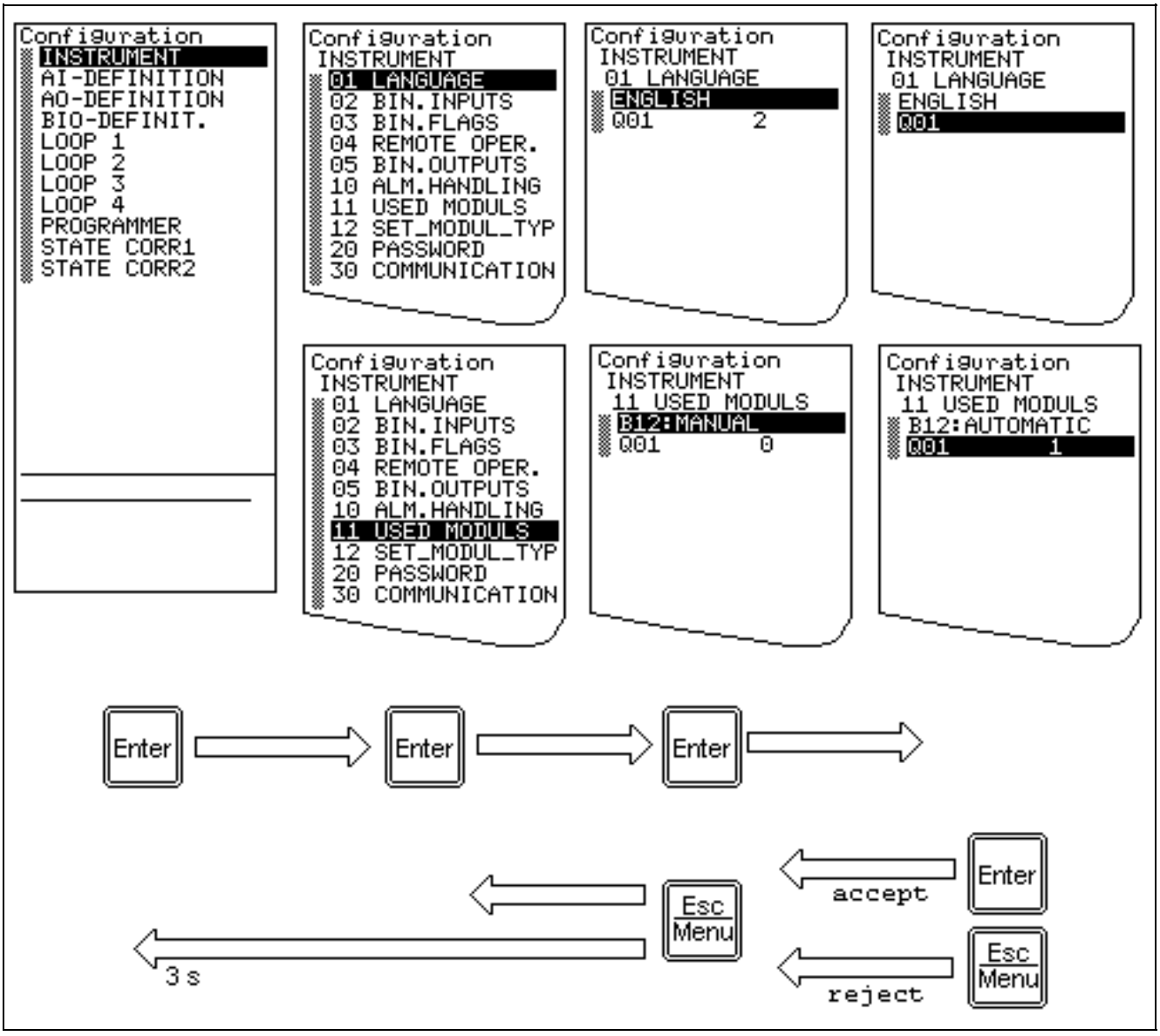


Fig. 27 Configuration menu “Instrument”
Z-19074

Instrument

Hardware

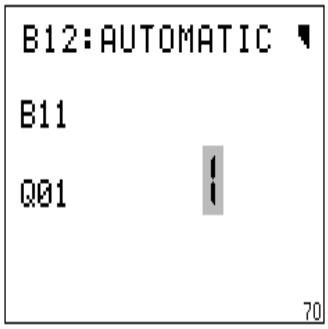


Fig. 28
Z-19070

To be given special attention is Point I-B11-Q01 “Hardware definition”. The configurable input/output functionen are determined by the existing modules. These are recorded in I-B12-Q01 to Q07 (Digitric 500: Q04). If the hardware identification is switched on (I-B11-Q01=1), the existing modules will be automatically recognized and recorded in I-B12-Q01 to Q07 (Digitric 500: Q04). I-B11-Q01 is automatically reset to 0.

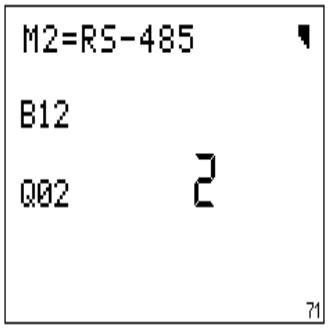


Fig. 29 Display Protronic 500: B2=RS-485 (shown here)
Z-19071 Display Digitric 500: B4=RS-485

By manually changing the inputs in I-B12, it is possible also to include modules in the configuration which are not (yet) available. It is not possible to commission a unit with incomplete hardware. An error message “Module slot x” is generated.

Password

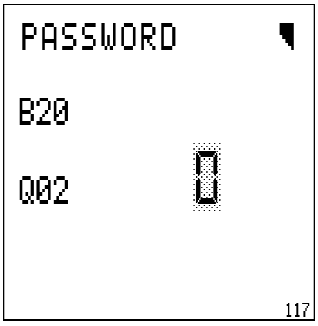


Fig. 30 Password definition
Z-19117

The password is a five-digit figure.

I-B20-Q01 = 0	The existing password is switched off.
I-B20-Q01 = 1	The password protection is activated. On exitting the menu system, the password protection becomes immediately active.
I-B20-Q01 = 2	Password protection remains switched off for a further 30 s after exitting the menu system. During this period it is possible to restate the parameter setting or configuration level without having to restate the password.
I-B20-Q02	The stated password is released for modification. It is changed in the same way as parameters.

AI Definition

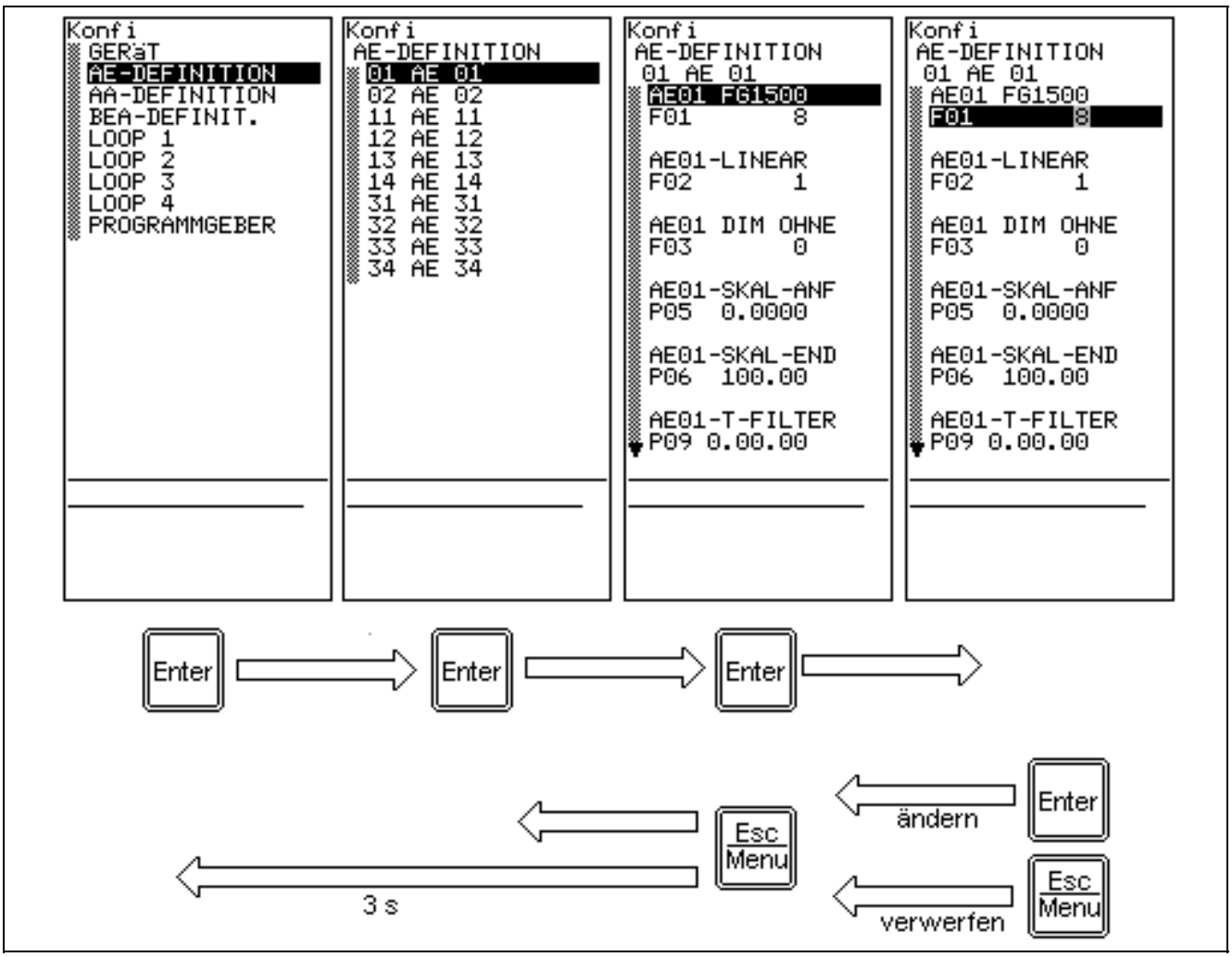


Fig. 31 Analog input menu
Z-19049

General

All analog inputs must be scaled for further use in the device. The values so defined are used as floating decimal point values for all further calculations in the device.

The display of an analog input as control variable PV can be adjusted independent of range and the number of additional decimal points.

Example:

Thermocouple type K
Measuring range of the sensor: −200...+1400 °C
Control range: 300.0...500.0 °C

AI01 is the universal input of the basic unit. The primary detector is connected according to type and according to the relevant connection diagram. In the device, the inut type must be input in the AI-B01-Q01.

AI02 is the current input of the basic unit.

AIxy are the analog inputs of the modules. x defines the card slot, y the number of the input on the module.

Sensor fault

Monitoring is implemented at all inputs and for all types of sensors.

1. Reaction of controller:

AI-Bxy-Q10 = 1

The missing measured value is replaced by a default value if there is a sensor fault/line break. This can be inside or outside the mormal measuring reange, so that an appropriate controller response is forced.

AI-Bxy-Q10 = 2

The controller receives an unchanged measured value simulated. The controller output does **not** respond to sensor fault.

2. Signalling:

Alarm signalling independent of the controller response can be effected if AI-Bxy-Q12 > 0 and AI-Bxy-Q13 > 0.

Dimension

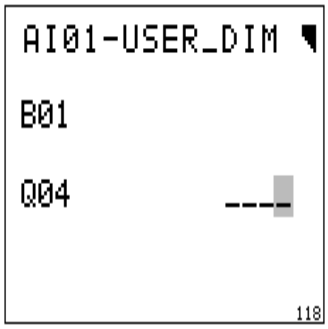


Fig. 32 Creating a user-dedicated dimension
Z-19118

Each input is scaled in itself and can be provided with a dimension.

In the case of inputs for temperature sensors, "°C" is automatically provided as dimension. It is possible to change over to "°F" with automatic conversion.

AI-Bxy-Q03 offers a number of dimensions. If the dimension required is not available, then a four-digit dimension can be generated in AI-Bxy-Q04 = 1 using AI-Bxy-Q04.

Filtering

Fig. 33 Filter time constant 0.00.20 h = 20 s
Z-19120

To suppress deleterious fluctations in measured values, all measured signals can be attenuated by a first order delay filter 1. The time constant is set with AI-Bxy-Q09 (maximum 0.02.00 h = 2 min).

---

mA Inputs

AI-Bxy-Q01 = 1.2	Signal range 0 or 4 to 20 mA.
AI-Bxy-Q03	Measured value is displayed linearly in the seclected scaling.
AI-Bxy-P05	Display at measured value 0 or 4 mA.
AI-Bxy-P06	Display at measured value 20 mA.
AI-Bxy-Q02 = 2.3	The measured value is square rooted. Below PV0, the resultant measured value is forced to 0, or replaced by a measured value with a linear characteristic.
AI-Bxy-P08	is used for setting PV0.
AI-Bxy-Q02 = 4...14	If the measured value originates from a non-linearising temperature transmitter, the sensor characteristic can be predefined.

The range of the transmitter is set by AI-Bxy-P05 and P06.

Example:

Transmitter
300 to 700 °C, type K = 0... 20 mA, mV-proportional:

AI-Bxy-Q01 = 1
AI-Bxy-Q02 = 6
AI-Pxy-Q05 = 300.0
AI-Pxy-Q06 = 700.0
AI-Bxy-Q03 = 3 (automatic)

Thermocouple input

AIxy-Q01 = 3	Thermocouple.
AIxy-Q02 = 4...13	Celection of thermocouple type.
AIxy-Q03 = 3	Changeable to °F AI-Bxy-Q03 = 4.
AIxy-Q07 = 0...4	Depending on reference junction compensation.

Resistance thermometer input

AI-Bxy-Q01 = 4, 5, 6	Depending on mode of connections used.
AI-B01-Q02	Distinguishes between 2 ranges: = 13 -200,0...+200.0 °C = 15 -200,0...+800.0 °C
AI-B02-Q02	doesn‘t permit Pt100 measurement.

Lead balancing must be performed with two-wire circuit (see Section ”Service”).

Teletransmitter input

Balancing for start and end is normally required with teletransmitter measurement. The balancing is described in the section on “Service”. The scaling and linearization correspond to the mA inputs.

Universal input AI01 for teletransmitter measurement:

AI01-Q01 = 7 or 8 (Digitric 500: AI02-Q01 = 7 or 8)

Current input AI02 and other current inputs:

AI02-Q01 = 1 (0...20 mA)

Characteristics

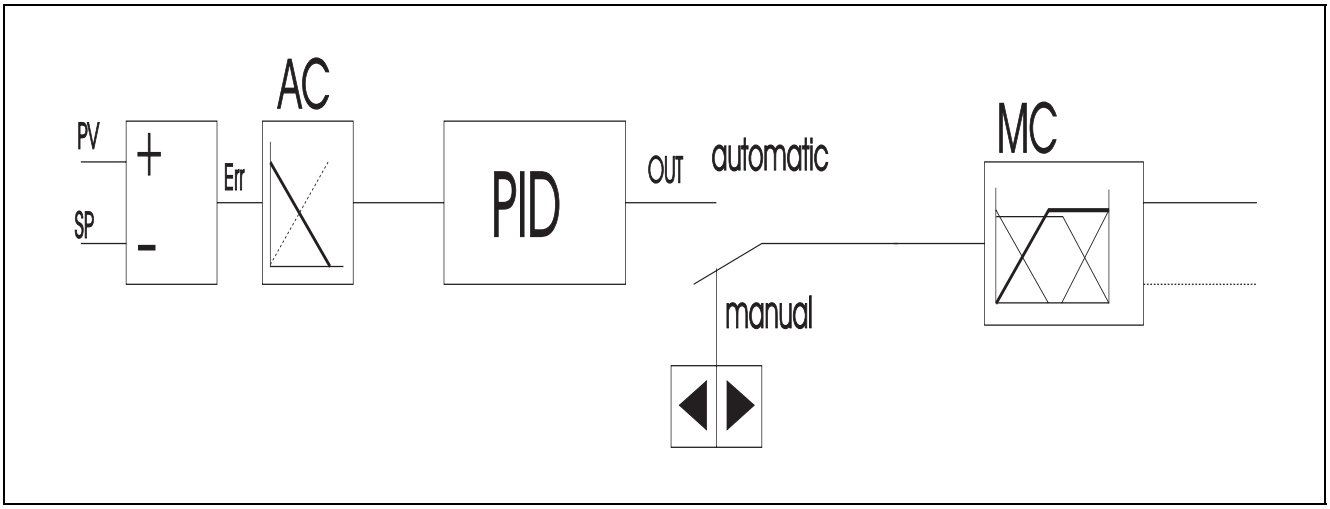


Fig. 34
Z-19079

There are two characteristics for controllers, whose setting must be conducted as follows:

Manual characteristic (MC) Lx-B01-Q03

The manual characteristic determines how the controller output behaves when the manual keys <◂> and <▸> are actuated (in step controllers this function is defined by the wiring).

The requirements for this are dictated by the safety precautions taken for the regulating unit.

Example:

The valve opens with spring force and closes proportionally to the regulating current, which means it is opened in current-free condition

or

the valve coloses with spring force and opens proportionally to the regulating current, which means it is closed in current-free condition.

By selecting the appropriate characteristic, the key <▸> can be used to open a valve of any type. An open valve is always displayed with y = 100 %.

The block MC further contains an optional classification of the output signal of the PID function on two output signals with equal or different characteristic (split range).

Automatic characteristic (AC) Lx-B02-Q01

The automatic characteristic determines, how the controller reacts to a change in the controller variable. Should the output rise or fall in case of increasing controlled variable? Should there be more cooling or less heating in case of increasing temperature?

When setting the automatic characteristic, please pay attention to the manually set characteristic.

Set points

Up to 7 set point sources are provided in the controllers:
- up to 4 manual set points which can be set via the serial interface,
- 1 external set point, linked with an analog input,
- 1 Computer set point and
- 1 Programmer (only once in the unit).

Which set points are available is defined by configuration.

Set point 1

Lx-B05-Q01 = 0	Set point 1 is switched off in applications with only external set point.
Lx-B05-Q01 = 1	Set point can be changed with the keys and via the interface.
Lx-B05-Q01 = 2	if another set point is active, set point 1 follows the the active set point. This makes bumpless resetting to set point 1 possible.

Lx-B05-Q02 = 0	The current set point is not stored in unit. It cannot be transferred to another unit with the configuration.
Lx-B05-Q02 = 1	At the parameter level, Lx-P81 is set and stored as set point 1. This value can be transferred to other units. Process-related set point changes at the operator control level are not stored.

Set point 2 to 4 = Ratio set point 1 to 3

It is possible to configure individually, if these set points
- can be activated,
- can be adjusted from the front panel or
- can be adjusted and stored as parameters Lx-P82 to Lx-P84 or
- can be effective as absolute or differential value to set point 1 (adjusting the differential is only possible at the parameter setting level).

Computer set point

The computer set point can only be changed via the interface.

Set point ramp

A set point ramp is always activated, although it is practically inoperative because of its factory setting 99999 EU/s.

The ramp function becomes active by setting Lx-P77 and Lx-P79 to lower values.

Set point display during the transition from old set point to target set point:

Lx-B05-Q09 = 1	Target value to which the set point will change.
Lx-B05-Q09 = 2	The current set point determined by the ramp.

Programmer

One programmer is available for each unit. This programmer can store up to ten programs, each with 15 sections.

Activating programs

The individual programs are activated in the configuration menu (P-B01-Q01 bis Q10):

0 The program has not been activated and connot be selected on the front panel.

1 At the start of the program, the program starts at the programmed start set point Px-P01.

2 If the current measured value is within the first section, then the program starts with this value. The section is shortened accordingly. If the value lies outside of the section, then the program is started with the start set point.

Parameter setting of programs

How the program behaves at start of the program (start at set point or at the control variable) is determined in the configuration (P-B01-Q01 to Q10).

The parameters of programs 1 to 10 are set separately.

Parameters Px-P01 to Px-P31

The programmer parameters Px01 to Px31 define the behaviour of the set point as a function of time. The parameter Px-P01 is the start value. The value of parameter Px-P02 is attained after the time Px-P17 is reached. The time is set to “0” for a step-shaped curve.

⚠ Attention

Sections which have the end values −9999 are sprung over by the program.

Parameters P-P32 to P-P46

The binary channels are synchronised chronologically with the sections of the set point program. Up to four binary flags can be set in each section. In the parameters, the required numeral to be input is calculated as follows:
Flag 1 set: P0x = 1
Flag 2 set: P0x = 2
Flag 3 set: P0x = 4
Flag 4 set: P0x = 8

Example:
In section 2 flags 1, 3 and 4 are to be set:
P-P33 = 13.

Parameters P-P47 to P-P49

With the parameters Px-P47 to Px-P49 it is possible to define and configure a loop between Px-P47 and Px-P48, which the programmer so often repeats upon reaching the end of section Px-P48, until the value Px-P49 is obtained. It is after that that the remaining sections are processed.

Parameters P-P50 to P-P64

Using the parameters P-P50 to P-P64, it is possible to define whether the program is to be stopped in individual sections, if the measured value cannot follow the prescribed set point curve.

Ramps are stopped with them, stop times start running when the measured value is within the tolerance range. The factory settings 99999 make this function inoperative.

Parameter setting for one program

Section	Value	Time	Tolerance	Binary track
Start value	Px-P1			
1	Px-P2	Px-P17	Px-P50	Px-P32
2	Px-P3	Px-P18	Px-P51	Px-P33
3	Px-P4	Px-P19	Px-P52	Px-P34
4	Px-P5	Px-P20	Px-P53	Px-P35
5	Px-P6	Px-P21	Px-P54	Px-P36
6	Px-P7	Px-P22	Px-P55	Px-P37
7	Px-P8	Px-P23	Px-P56	Px-P38
8	Px-P9	Px-P24	Px-P57	Px-P39
9	Px-P10	Px-P25	Px-P58	Px-P40
10	Px-P11	Px-P26	Px-P59	Px-P41
11	Px-P12	Px-P27	Px-P60	Px-P42
12	Px-P13	Px-P28	Px-P61	Px-P43
13	Px-P14	Px-P29	Px-P62	Px-P44
14	Px-P15	Px-P30	Px-P63	Px-P45
15	Px-P16	Px-P31	Px-P64	Px-P46

Tab. 1

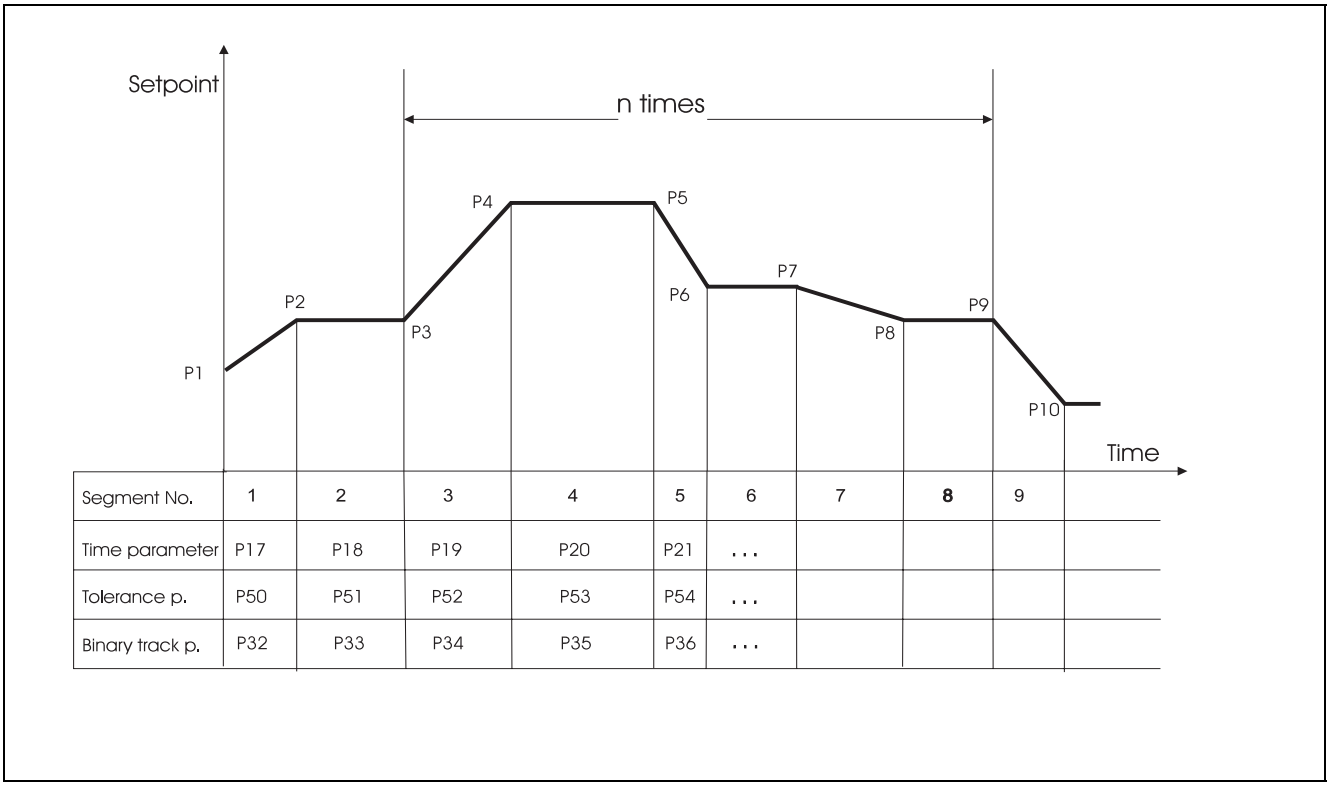


Fig. 35 Programmer with loop Section 3 to Section 8
Z-19102

Fixed value control

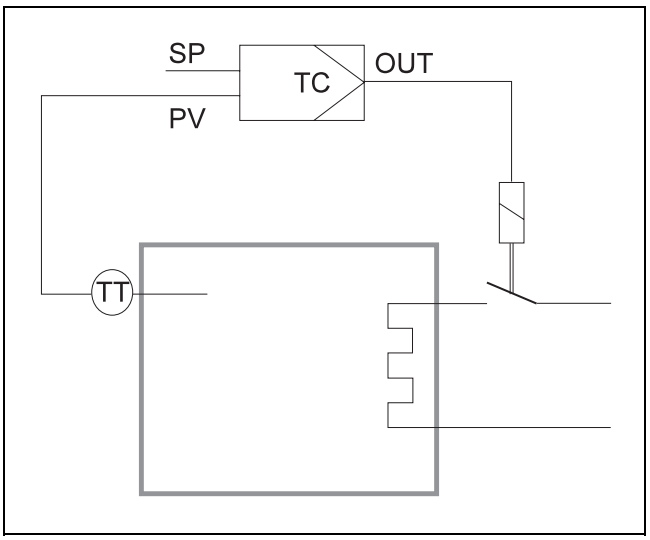


Fig. 36 Fixed value control
Z-19066

The fixed value input circuit is possible in:
- single- and multi-channel controllers and
- in slave controllers of cascades.

Task

The controlled variable PV is controlled to a set point SP produced in the controller or outside it. A state correction can be switched on in quantity control of steam or gas (see Section on “State correction”)

Configuration

Input signal connection

Lx-B03-Q01 = 1	Input circuit fixed value.
Lx-B03-Q02	Does not apply.
Lx-B03-Q03	Normally 2, Err in EU.
Lx-B03-Q04	Dimension for PV/SP display.
Lx-B03-P05	User-defined dimension.
Lx-B03-Q06	Decimal point position in the digital display.
Lx-B03-P07	Numerical value for digital display for start of measuring range.
Lx-B03-P08	Numerical value display for end of measuring range.
Lx-B03-P16	Required starting value for analog display.
Lx-B03-P17	Required end value for analog display.

The difference between Lx-B03-P08 and Lx-B03-P07 is the reference value for G. For a P controller with Kp = 1, if the input is changed by P08 − P07, the output will be changed by 100 %.

Example 1

Thermo couple type K measuring range −200...+1400 °C: The measurement produces between −200 °C and +1400 °C correct values.

Control range

900.0 to 1100.0 °C with one decimal place after the point:

Lx-B03-Q04 = 3	Display in °C.
Lx-B03-Q06 = 1	Decimal point position 0000.0.

Note
If the number of decimal point positions of the measured value and decimal places is more than the number of displayable positions, the number of decimal places will automatically be reduced.

Lx-B03-P07 = 900	Lower-range value.
Lx-B03-P08 = 1100	Upper-range value.

The placing of a decimal point is not necessary.

Analog display

Lx-B03-P16 = 900	Start of measuring range.
Lx-B03-P17 = 1100	End of measuring range.

Every other setting within the range −200 to +1400 is possible and permissible, if it appears meaningful for the system.

It is not necessary to set a decimal point position.

Set point limits

The set point limit should be set to meaningful values within the control range.

Lx-B03-P75	SPmin = 900 (°C)
Lx-B03-P76	SPmax = 1050 (°C)

Example 2
(**not Protronic 100**)

Fixed value control with state correction.

The inputs required for calculating the flow must be configured in the required units (mbar, bar, °C). The resultant signal is calculated for example in m^3/h.

Measuring range

0...20000 m^3/h after state correction.

Control range

is equal to measuring range.

Lx-B03-Q04 = 7 Display in m^3/h.
Lx-B03-Q06 = 0 No decimal point position.

Note
For displays up to 20000 no decimal position is possible after the decimal point.

Lx-B03-P07 = 0 Measuring range start.
Lx-B03-P08 = 20000 Measuring range end.

Analog display

Lx-B03-P16 = 0 Measuring range start.
Lx-B03-P17 = 20000 Measuring range end.

Set point limits

The set point limits are to be set to meaningful values within the control range.

Lx-B03-P75 SPmin = 5000 (m^3/h)
Lx-B03-P76 SPmax = 18000 (m^3/h)

Routing of analog inputs

The following normally applies to single-channel controllers without modules:
L1-B04-Q01 = 1: 1. input = control variable PV.

In the case of multi-channel controllers, the configuration is according to the arrangement of the available inputs.

The second analog input can perform different tasks:

1. Position feed back signal for step controllers
   L1-B01-Q04 = 2

2. External set point
   L1-B05-Q06 = 2

3. 2nd adjustable measured value source
   L1-B04-Q02 = 2 together with
   L1-B04-Q06 = 1 to 76 (Digitric 500: 46), depending on the binary input available

   Note
   The two measured values must have the same dimension but not the same measuring range.

   Application examples:
   - Level control on two different tanks.
   - Temperature control
     with thermocouple measurement up to 1200 °C
     and with
     pyrometer between 1000 and 2500 °C.

4. Parameter control
   G L1-B02-Q07 = 13 or/and
   Tn L1-B02-Q10 = 13 or/and
   Tv L1-B02-Q13 = 13 or/and
   OUT0 L1-B02-Q16 = 13 or/and
   TT L1-B02-Q19 = 13 or/and
   T1 L1-B02-Q22 = 13
   KS L1-B02-Q25 = 13

5. Disturbance variable feedforward
   L1-B02-Q25 = 2 together with
   L1-B02-Q26 = 1 to 4

6. Y tracking (at times, controller output is forced to the value of input 2, not for step controllers)
   L1-B10-Q10 = 2 together with
   L1-B09-Q11 = 1 to 76 (Digitric 500: 46) (BIxy)

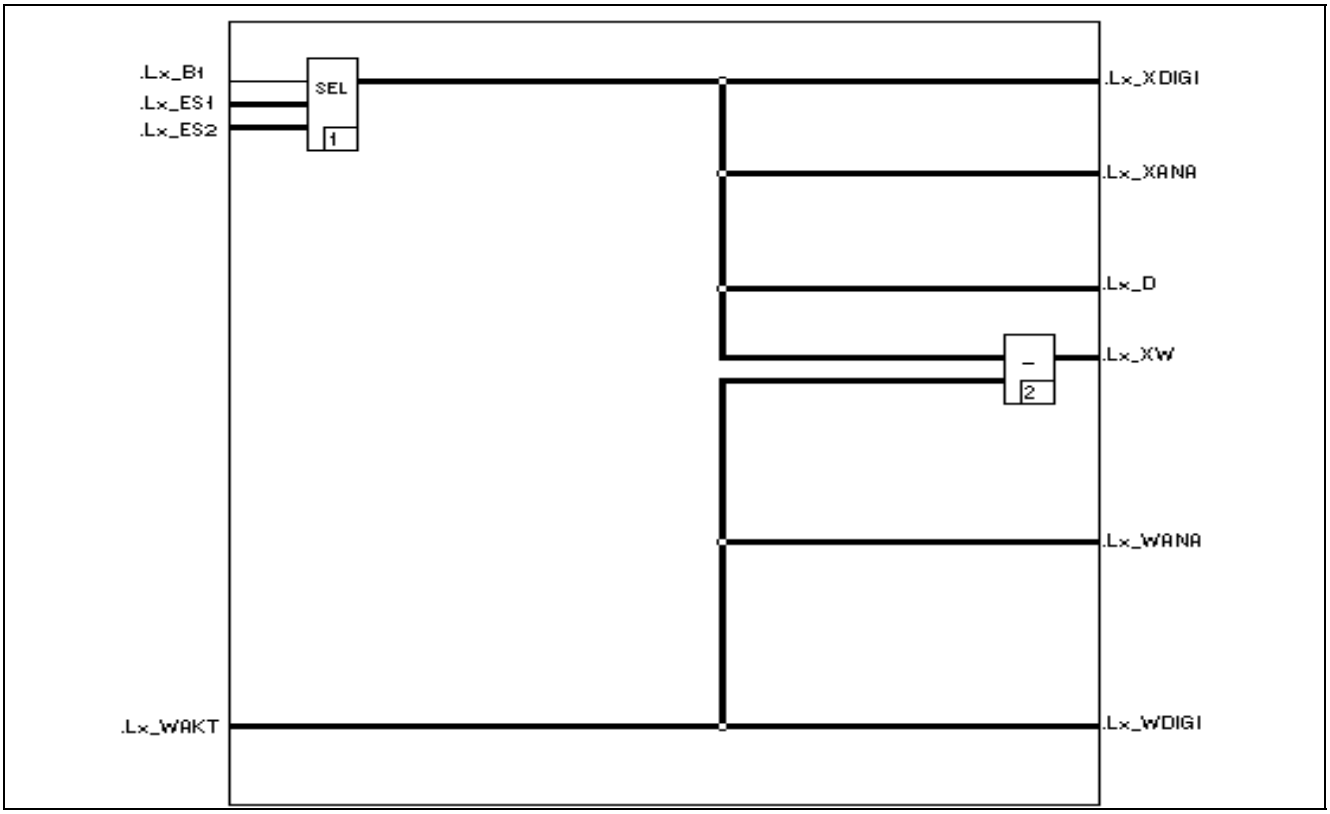


Fig. 37 Input circuit fixed value

Z-19069

.Lx_B1	Changeover ES1 ⟷ ES2 with switch SEL	.Lx_XANA	Analog display of PV
.Lx_ES1	Input 1, routes via Lx-B04-Q01	.Lx_WANA	Analog display of SP
.Lx_ES2	Input 2, routes via Lx-B04-Q02	.Lx_D	to D component
.Lx_WAKT	Current set point	.Lx_XW	Control deviation
.Lx_XDIGI	Digital display of PV		
.Lx_WDIGI	Digital display of SP		

Multi-component control

The multi-component input circuit is possible in:
- single- and multi-component controllers
- in slave controllers of cascades.

It normally requires additional analog inputs.

Applications

1. Feed water control of drum water tanks. Instead of this circuit, a cascade circuit can be used (see section on “Cascades”) (**not Protronic 100**).
2. Additional interconnection of measuring signals or set points. Example: Control of the total of two quantity signals.

For both quantity measurements, an additional state correction can be coupled for gas or steam (see section on “State correction”).

Configuration on 1.
(**not Protronic 100**)

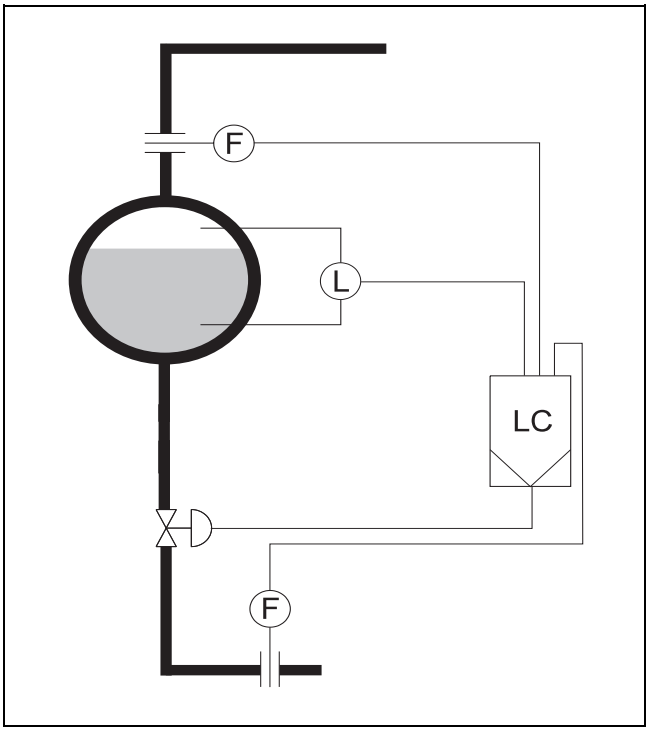


Fig. 38 Drum water level
Z-19122

Multi-component input circuit

Lx-B03-Q01 = 2

The difference between feed water and quantity of steam can be injected linearly or differentially, depending on the task definition.

Linear feed:

Err = PV + K2 × (ES2 + K3 × ES3) - SP

Lx-B03-Q02 = 2	Displayed water level is falsified by the difference between feed water and quantity of steam.
Lx-B03-Q02 = 3	Unfalsified water level display.

Differential feed:

Err = PV - SP

A D component: K2 × (ES.2 + K3 × ES.3) requires PID control:
Lx-B02-Q02 = 4

Lx-B03-Q03 = 1	Preferably display of the control deviation in %.
Lx-B03-Q04 - Q08	Corresponds to the configuration of ES1.
Lx-B03-P16	Corresponds to the configuration of ES1.
Lx-B03-P17	Corresponds to the configuration of ES1.
Lx-P101 to P103	Must be adapted in the commissioning.

Routing the inputs Lx-B04 as a function of the available analog inputs.

Configuration of 2.

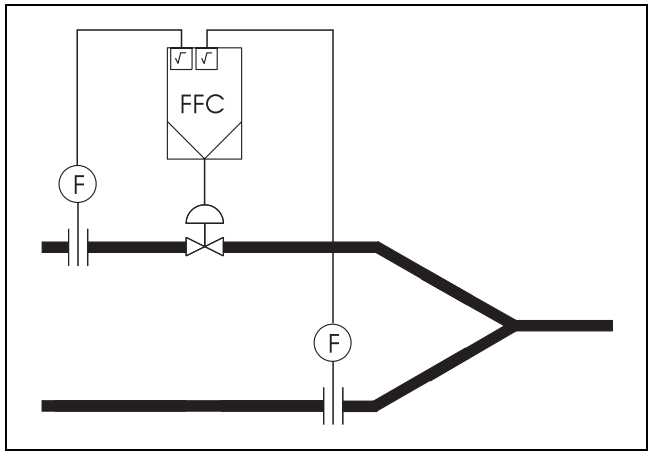


Fig. 39 Total flow
Z-19068

If only two values are to be added in a single-channel controller, it is also possible under certain circumstances to operate with the basic unit.

Multi-component input circuit:

Lx-B03-Q01 = 2	Err = ES1 × K1 + K2 (ES2 + K3 × ES3) − SP
Lx-B03-Q02 = 2	
Lx-P101 = 1	
Lx-P102 = 1	
Lx-P103 = 0	With only two inputs.
Lx-B03-Q03 to P08	According to the configuration of the inputs.
Lx-B03-P16	Start value of the analog display.
Lx-B03-P17	End value of the analog display.

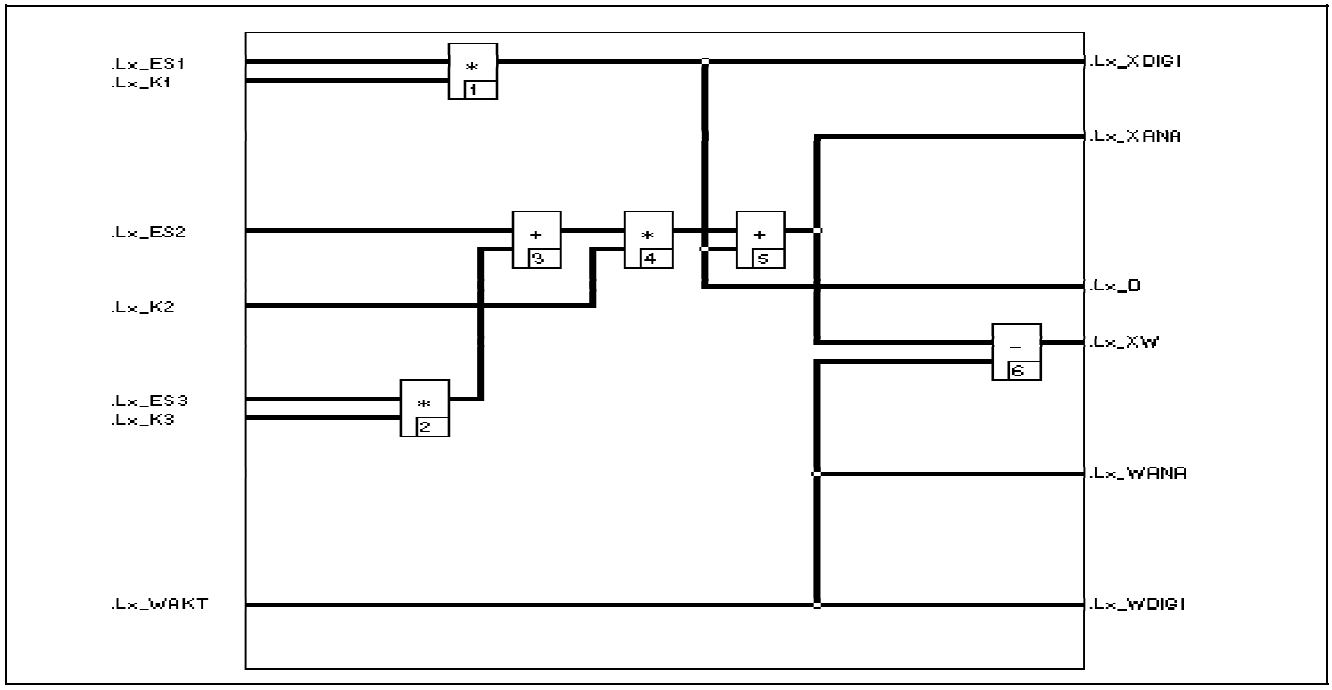


Fig. 40 Input circuit: Multi-components
Z-19095

.Lx_ESx	Inputs of the input circuit Multi-components routed via Lx-B04-Q0x with the analog inputs AIxy	.Lx_XDIGI	Digital display for PV
		.Lx_WDIGI	Digital display for SP
		.Lx_XANA	Analog display for PV
.Lx_Kx	Evaluation factors K1 to K3 = Lx-P101 to Lx-P103	.Lx_WANA	Analog display for SP
		.Lx_D	to D component
.Lx_WAKT	Current set point	.Lx_XW	Control deviation

Ratio control

The input circuit ration is possible in:
- single-channel controllers,
- controllers with several independent channels and
- master and slave controllers of cascades.

Ratio and set points

An external (current signal) set point, the programmer and a computer are available as set point sources SP1 to SP3 in ratio control.

All ratio input circuits as well as fixed value input/ratio input circuits can be used. There is also the set point SP1 for this application.

The ratio set point SP1 - as long as not used - can be tracked in such a way that bumpless changeover to the ratio → fixed value can take place.

Configuration:

Lx-B05-Q01 = 3 The set point 1 is tracked to the current ratio.

The ratio-set point Vw1 can be configured in such a way that with fixed-value control or when using another ratio set point, it is tracked to this so that bumpless resetting to the ratio set point 1 SP1 is possible.

Configuration:

Lx-B05-Q03 = 6 The set point 2 = SP1 is tracked to the current ratio.

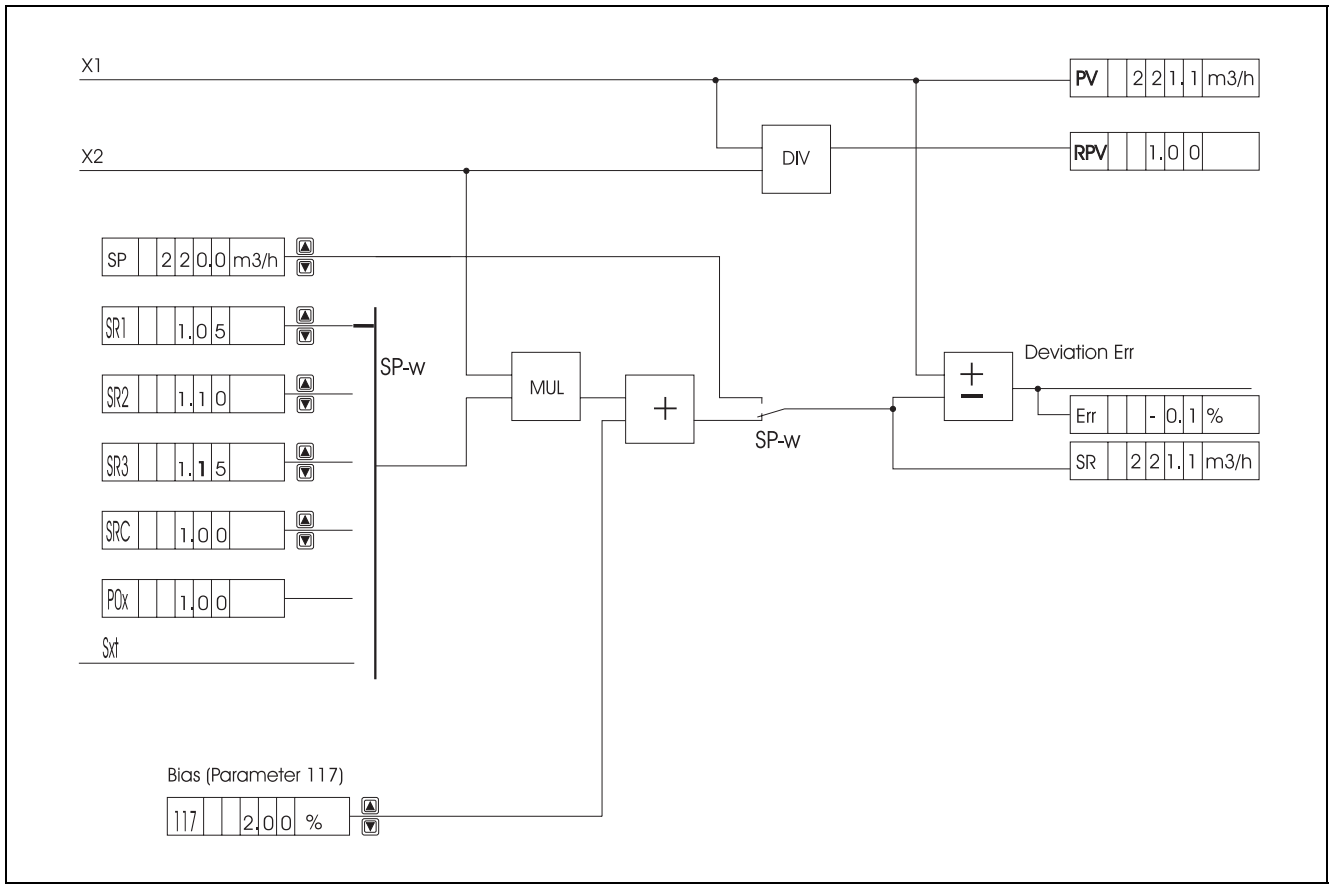


Fig. 41 Functional diagram of the input signal connection “Ratio” without signal conditioning for PV1 and PV2 and without scaling and limiting parameters.
Z-19125

Ratio control I: λ control

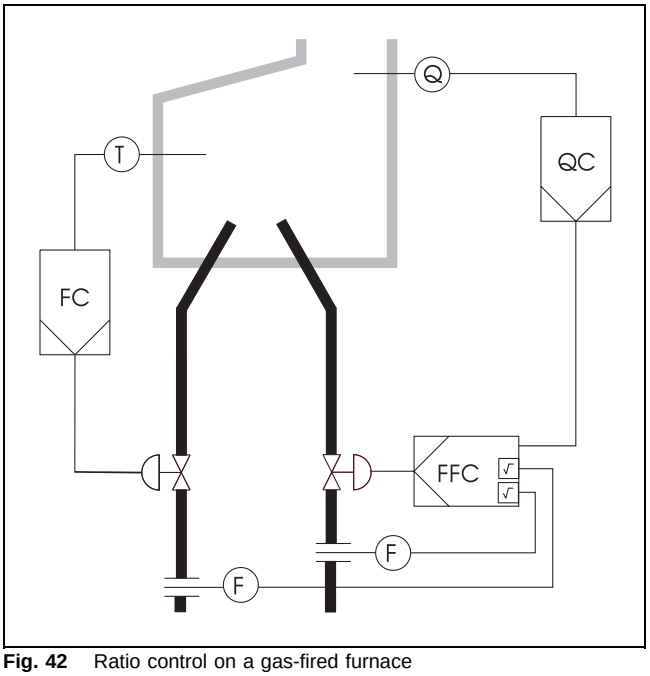


Fig. 42 Ratio control on a gas-fired furnace
Z-19067

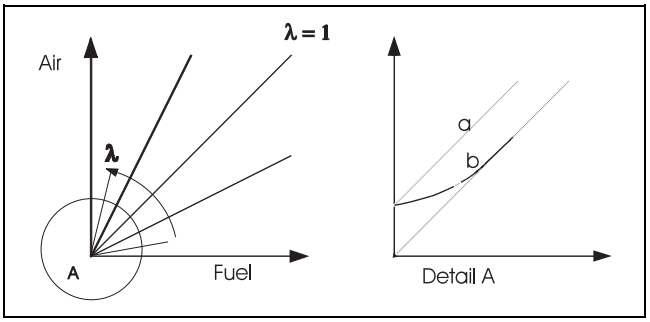


Fig. 43 Superfluous air, a = linear, b = non-linear
Z-19073

The atmosphere of an oil- or gas-fired furnace is to be controlled, λ being regarded as the set point. Optimum combustion is defined as λ = 1.

Excess air is to be guaranteed in the lower load range (A).

λ is defined as the air/fuel ratio. The air signal must therefore always be linked to ES1, irrespective of the controlling air or fuel.

Examples of configuration

The following modules must be configured for the loop x:

Lx-B03-Q01 = 4, 5	Ratio or fixed value/ratio changeable.
Lx-B03-Q02	disabled.
Lx-B03-Q03 = 0	Err in %, produces qualitative information.

Configuration air (PV1)

Lx-B03-Q04 = e.g. m3/h.	
Lx-B03-Q06 = 1	1 decimal point position.
Lx-B03-P07 = 0	Digital display transmitter range start value = 0.
Lx-B03-P08 =	Digital display transmitter range end.

The difference of Lx-B03-P08 and P07 is the reference value for G. An P controller with Kp = 1 produces an output of about 100 %, if the input is changed at this difference.

Configuration, display for ratio

Lx-B03-Q09 = 1	Displayed in the digital display. Displayed in the digital display are *Vx* (RPV) and the selected R set point *Vw*.
Lx-B03-Q09 = 2	Displayed in the digital display are PV (air) and SP = *Vw* × fuel: *Vw* can be selected with <Ind>.
Lx-B03-Q10 = 0	Dimension for R.
Lx-B03-Q12 = 2	With two digits to the right of the decimal point
Lx-B03-P14 =	Stochiometric air/gas for λ = 1. Example: for λ = 1:, air : fuel = 4.15 : 1 Lx-B03-P14 = 4.15

Analog display

Lx-B03-Q15 = 2	Normally analog display for *Vx* and *Vw*.
Lx-B03-P16	Define the display range for the
Lx-B03-P17	analog displays. Example: Display range 0.75 to 1.25 Lx-B03-P16 = 0.75

Lx-B03-P17 = 1.25

In the case of fixed value/ratio, the pair of values Lx-B03-P07/P08 is used as analog display for fixed value.

Excess air

The excess air is attained by setting a “Bias”.

Linear:
A linear bias is set with the parameter Lx-P117. It always has the dimension of the air signal.

Non-linear:
The bias is derived from the fuel quantity.

Configuration:

Lx-B04-Q04 = 94	The value of ES4 is obtained from Table 4.
Lx-B04-Q02	is equal to Lx-B04-Q05. The input of Table 4 is the same as the input ES2 (fuel).

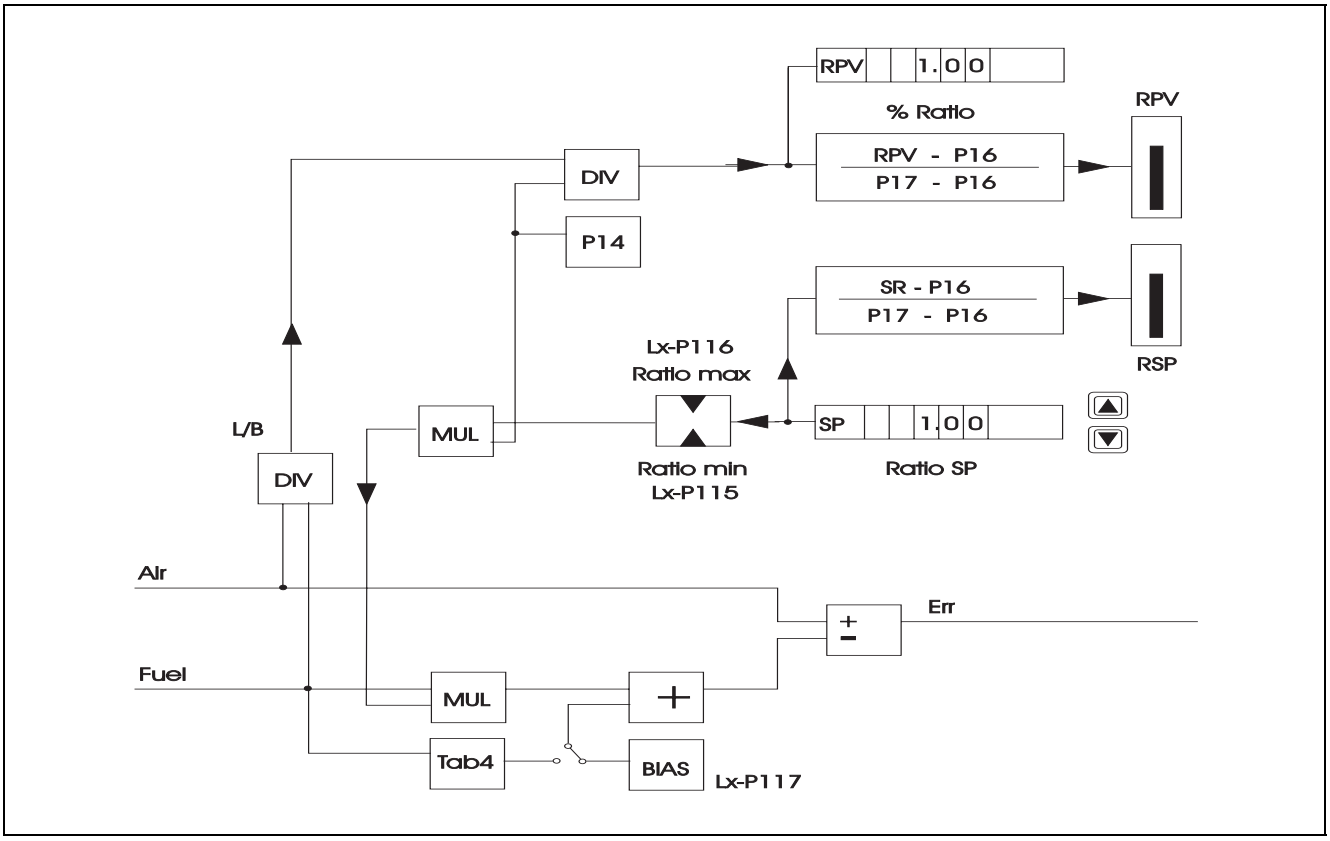


Fig. 44 Structure of the input circuit ratio, displays and creation of the control deviation. Display of RPV and RSP. without combining the input signals
Z-19123

Ratio control II: Mixture control

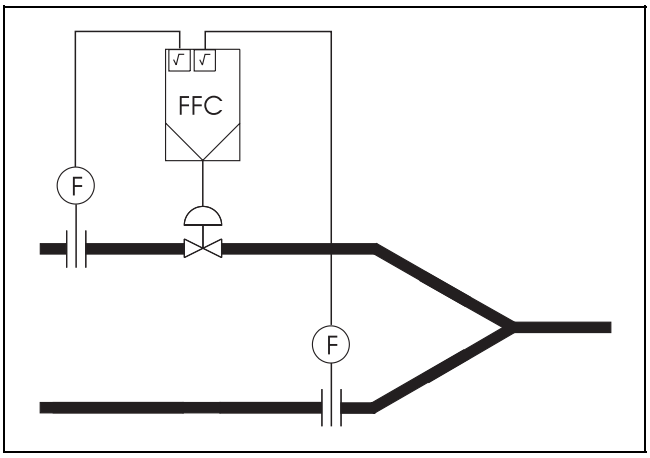


Fig. 45 Mixture control
Z-19068

In mixture control, two different setting procedures for the nominal ratio are required in process engineering.

Mixing ratio of the two components to one another:

Ratio 1 R = quantity 1 / quantity 2
Example: Neutralisation control

Proportion of a component in the end product:

Ratio 2 R = quantity 1 / (quantity 1 + quantity 2)
Example: Fat percentage in milk products

The routing of the inputs is defined by the definition of R. The signal in the counter must always be combined with ES1, irrespective of whether quantity 1 or quantity 2 is controlling.

The configuration below is required, as well as the routing of the inputs as a function of the input modules and their arrangement:

Configuration ratio 1

Mixture control R = quantity 1 / quantity 2

Theoretically, R can accept any value between 0 and infinity as the actual value.

Lx-B03-Q01 = 4 or 5 ratio or fixed value/ratio

Depending on user requirement, the analog display can be defined as follows:

Lx-B03-Q15 = 2	Mixture ratio is actual value and set point.
Lx-B03-Q03 = 0	Control deviation in % as qualitative statement.

or

Lx-B03-Q15 = 1	Quantity 1 and quantity 2 × R set point.
Lx-B03-Q03 = 1	Control deviation display in EU as quantity 1, e.g. in m^3/h.

Configuration quantity 1:

Lx-B03-Q04	Dimension e.g. m^3/h.
Lx-B03-Q06	Decimal point depending on use.
Lx-B03-P07	Lower-range value (normally 0).
Lx-B03-P08	Upper-range value.

Configuration ratio:

Lx-B03-Q09	Digital display RPV and RSP or PV (quantity 1) and RSP × quantity 2.
Lx-B03.Q10	Dimension for R e.g without or %.
Lx-B03-Q12	Digits right to the decimal point for R display.
Lx-B03-P14	Quantity 1 (20 mA) / quantity 2 (20 mA) Numerical value of the quotient of the scaled input signals with equal measured values in mA e.g. upper-range value.
Lx-B03-Q15	Analog display RPV and RSP or PV and RSP × quantity 2.
Lx-B03-P16	Analog display of required lower-range value.
Lx-B03-P17	Required upper-range value.
Lx-B03-Q18	Output of the display defined by Lx-B03-Q15 to P17 on analog output.

Configuration ratio 2

Mixture control component in the end product
V = quantity 1 / (quantity 1 + quantity 2)

As actual value and set point, R can only assume the value range 0 to 1. Scaling is therefore normally performed in 0 to 100 % or part ranges thereof.

Configuration is effected as with ratio 1, with the following differences:

Lx-B03-Q09	normally %
Lx-B03-P14 = $\frac{quantitity1(20\ mA)}{quantitity1(20\ mA) + quantitity2(20\ mA)}$	The numerical value of the quotients of the scaled input signals with equal easured values in mA e.g. upper-range value.

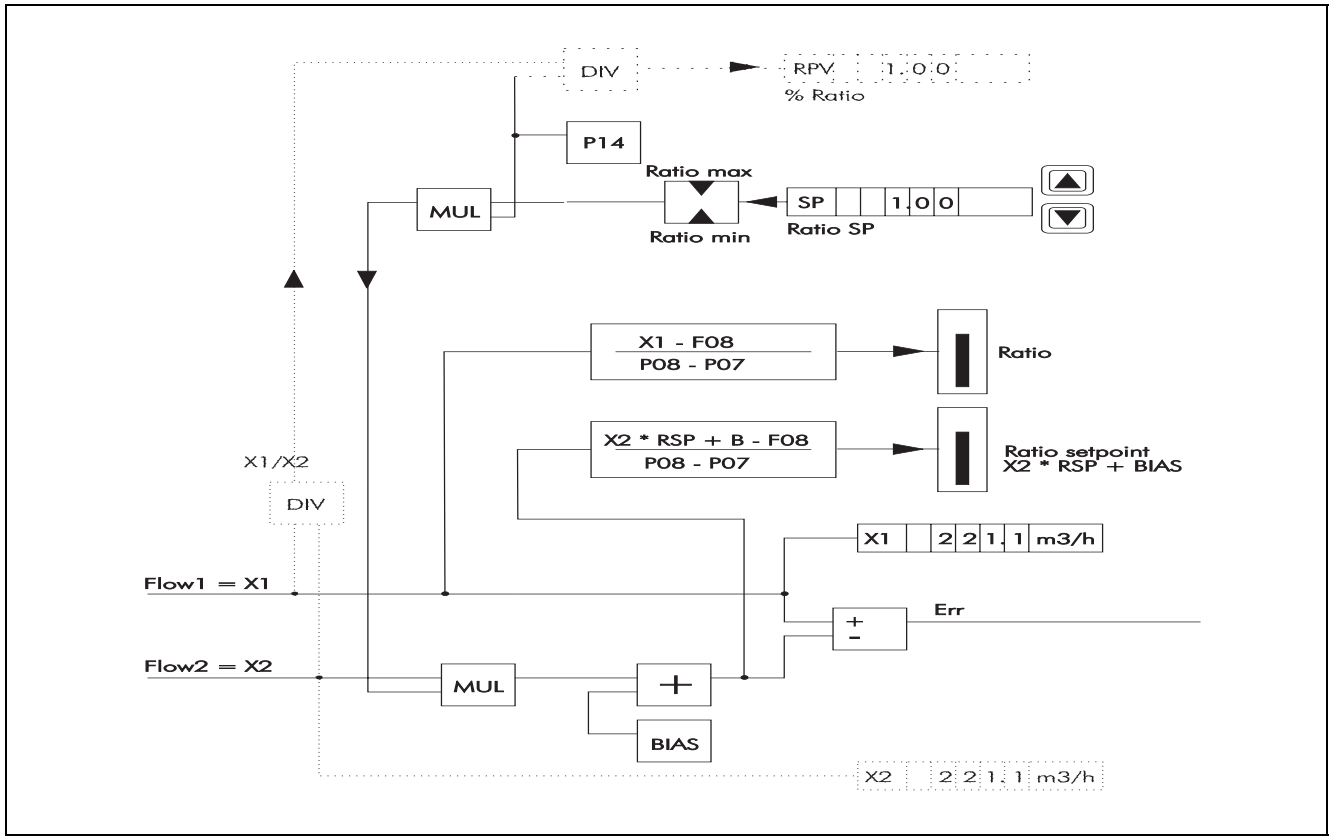


Fig. 46 Structure of the input circuit ratio. Displays and development of the control deviation. Display the quantity 1 and R × quantity 2. Without
Z-19124 combination of the input signals.

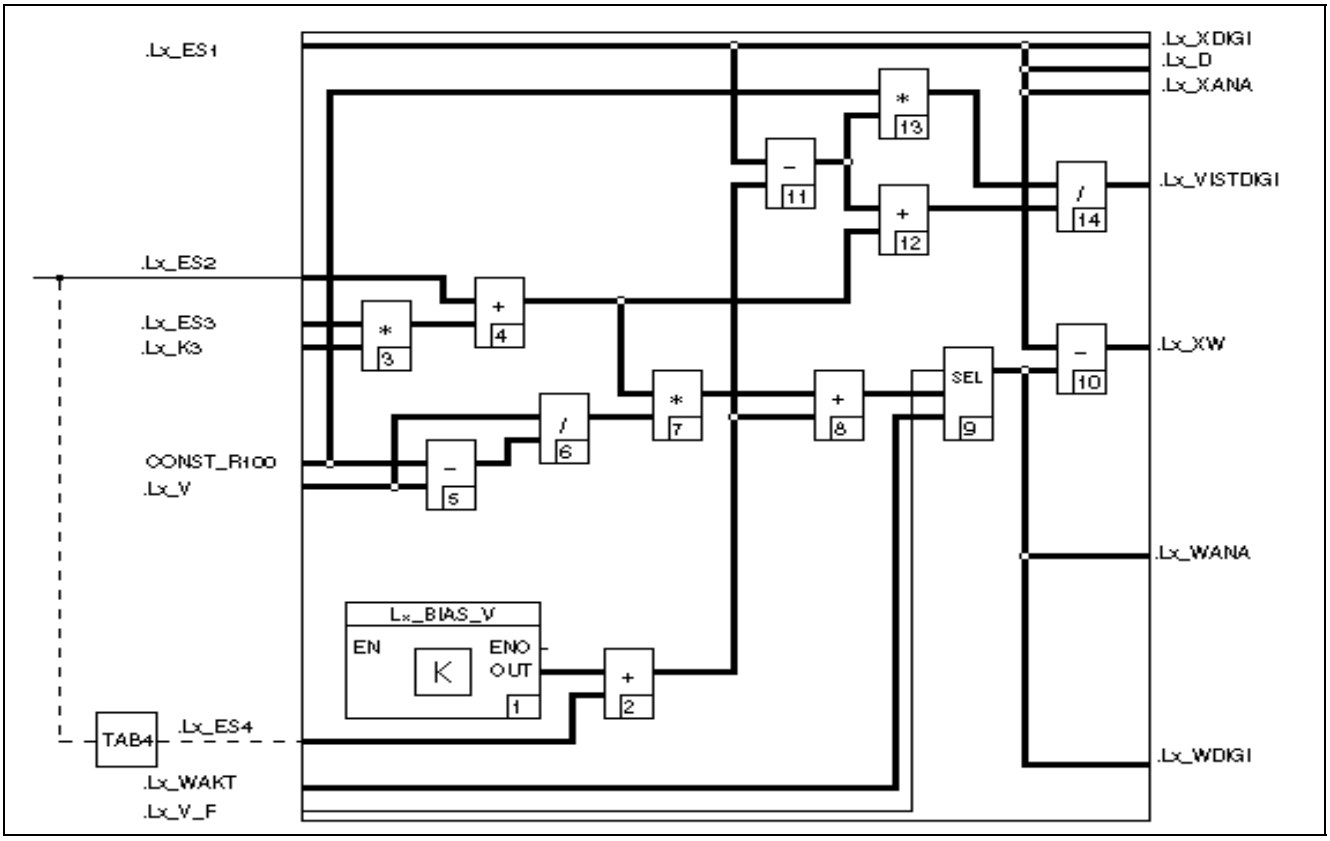


Fig. 47 Input circuit fixed value/ratio 2

Z-19126

.Lx-ESx	Inputs of the input circuit ratio route via Lx-B04 to the analog inputs	.Lx-XDIGI	Digital display for PV
.Lx-V	R set point	.Lx-WDIGI	Digital display for SP
CONST_R100	100	.Lx-VISTDIGI	Digital display for RPV
.Lx-AKT	Current fixed value set point	.Lx-XANA	Analog display for PV
		.Lx-WANA	Analog display for SP
		.Lx_V_F	Changeover fixed value/ratio

Multiplication

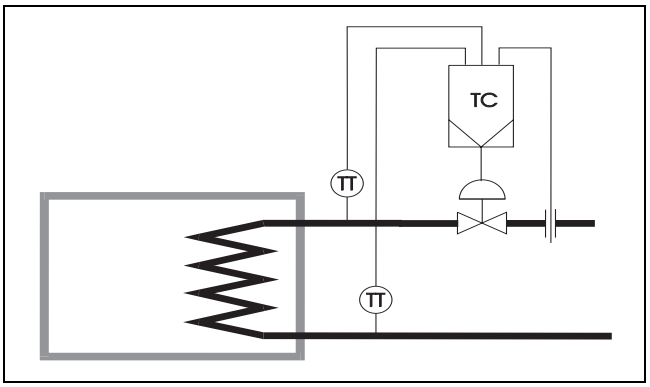


Fig. 48 Heat quantity control with Protronic 500
Z-19127

The input signal connection multiplication enables the control of a product of two input variables. Instead of one input variable, the evaluated sum can also consist of two variables.

Err = E1 × (E2 + K3 × E3) - SP

One user application example is the heat quantity control. This involves the measurement of the inflowing (or outflowing) quantity of a heat transfer system on an energy consuming unit e.g. water and the temperature difference between feed forward and feedback.

For an exact measurement, the quantity is corrected according to pressure and temperature (for water, it is usually a temperature correction). Depending on the arrangement of the flow rate measurement - inflow or outflow - the associated inflow or outflow temperature must be corrected.

Configuration

The three inputs should be scaled with their dimensions.

Input signal connection:
Lx-B03-Q01 = 3 Multiplication.

Routing of state correction:
ZK1-B02-Q01 = Flow rate signal depending on the input used.
ZK1-B02-Q02 = 0 No pressure correction.
ZK1-B02-Q03 = Inlet temperature depending on the input used.
ZK1-B02-Q04 = 0 No density correction.

Routing of the input connection signal:
Lx-B03-Q01 = 91 Corrected quantity signal from state correction 1.
Lx-B03-Q02 = Inlet temperature depending on the input used.
Lx-B03-Q03 = Outlet temperature depending on the input used.

Parameter:
Lx-P102 = −1 Makes the required subtraction from the addition.

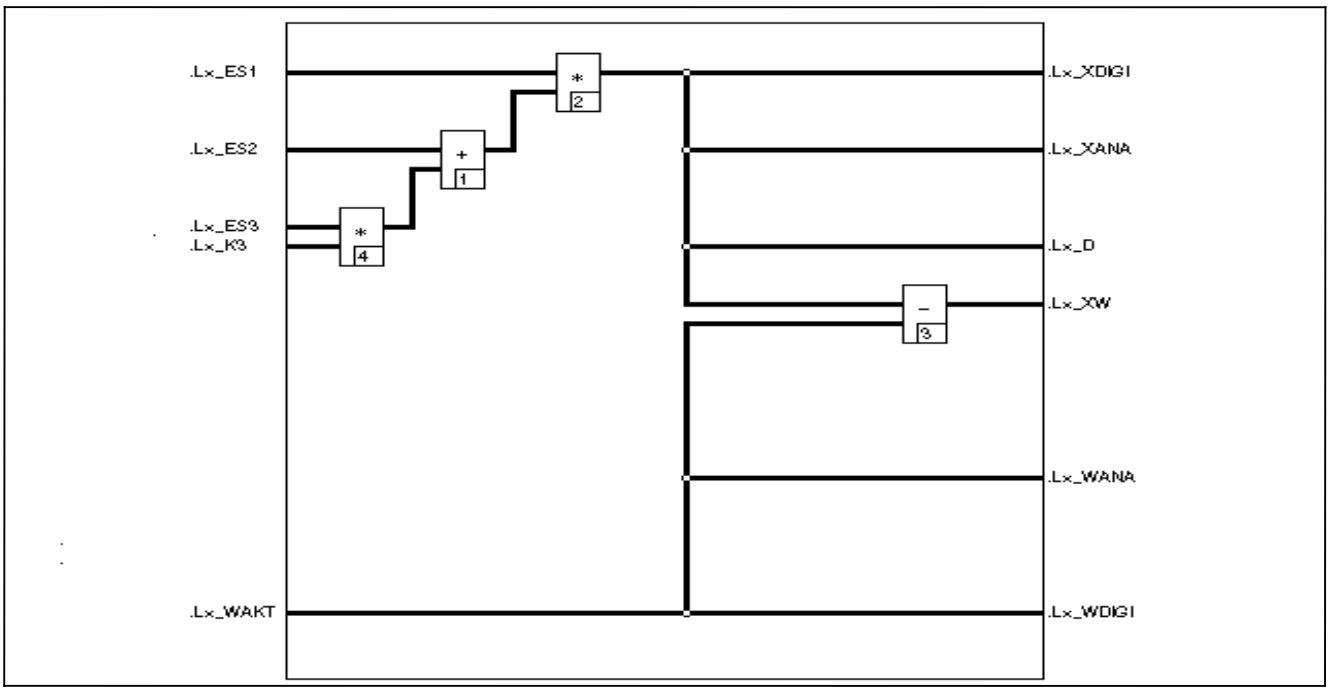


Fig. 49 Input circuit Multiplication
Z-19096

.Lx-ESx	Inputs of the input circuit ratio route via Lx-B04 to the analog inputs	.Lx_WDIGI	Digital display for SP
.Lx-K3	Evaluation factor for ES3	.Lx_XANA	Analog display for PV
.Lx_WAKT	Current set point	.Lx_WANA	Analog display for SP
.Lx_XDIGI	Digital display for PV	.Lx_D	to D component
		.Lx_XW	Control deviation

Parameter variation

Parameter control permits selective adaptation to reproducibly changing conditions in the process.

Parameter changeover

One or several parameters can be changed over, depending on an alarm value or a binary input. This is necessary when transferring between two different measured signals as controlled variable, for example.

The changeover is not necessary when transferring between transmitters with different measuring ranges for the same physical variable. The measured value doesn't change at the changeover because of the scaling of the inputs.

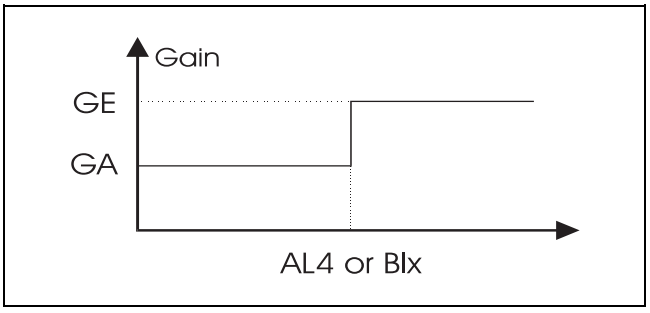


Fig. 50 Gain changeover
Z-19086

Configuration and parameter setting:
Lx-B02-Q07 = 11 or 12 Changeover through AL4 or BIx.
Lx-P07 = GS
Lx-P08 = GE

Special case P-PI changeover:

For instance, here is to TnA = 0. As long as TnA is effective, the I component remains switched off.

Parameter control

Linear

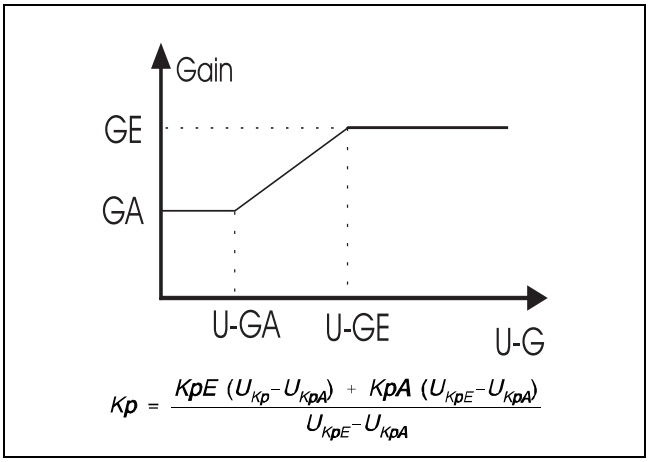


Bild 51 Linear parameter control, U is the controlling variable
Z-19085

The active parameter between a start value and an end value is changed linearly as a function of freely selectable analog variables (set point, measured value, ouput variable etc.).

Configuration and parameter setting:
Lx-B02-Q07 = 1 to 5 or 13 Gain control through selected variable e.g. set point (Lx-B02-Q07 = 2).
Lx-P06 = GS
Lx-P07 = GE
Lx-P08 = U-GA
Lx-P09 = U-GE

Non-linear

The system gain with pH control changes considerably with the pH value. The gain is at its maximum at about pH 7 and decreases very rapidly for pH0 and pH14. Inverse gain is required in the controllers.

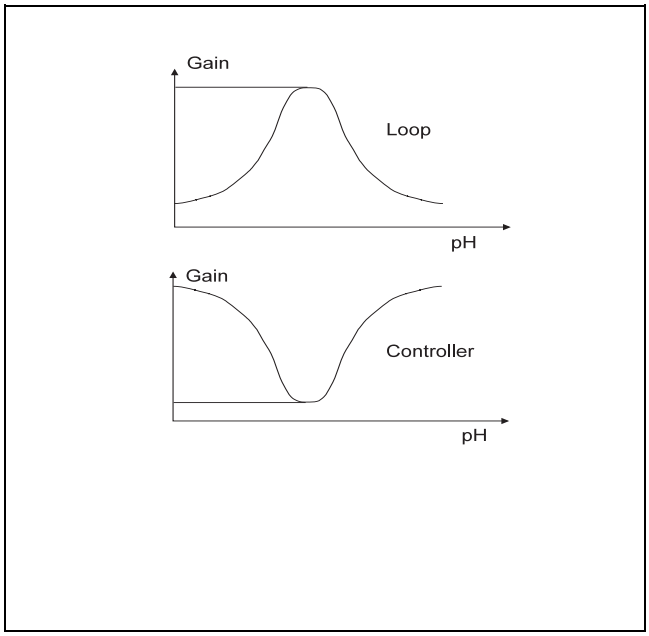


Fig. 52 Non-linear parameter control through the measured value pH
Z-19099

Configuration:
Lx-B02-Q07 = 7 Parameter control by the control variable PV via Table 1.

Table 1 is defined with the controller circuit gain G (by using the titration curve).

State correction

(**not Protronic 100**)

For the measurement of gases or steam, the measuring unit is designed for certain pressure and temperature values. If the actual values differ from the projected values, the result will be drastic measurment errors. To correct these errors, compensation adjustment possibilities are provided for the correction of both ideal and real gases.

The state correction calculates the standard quantities (0 °C and 1.013 bar) from the current measured values.

The state correction is possible with all input signal connections.

Within the unit, a maximum of two corrections are available simultaneously.

The state correction normally requires additional analog inputs. The state correction can only be processed after it has been integrated into the configuration (e.g. with Lx-B04-Q01 = 91 (flow control with state correction).

Routing the inputs and outputs

The routing of the inputs of the state correction unit depends on the module location of the analog inputs. **The inputs must each be scaled**. It is irrelevant whether a temperature reading is fed directly or via transmitter.

Abbreviations and terms

Index “r” for “computing values” (values for defining orifice)

Qv	Operating volume flow in m^3/h
Qn	Volume flow in standard condition in m3/h
Qm	Mass flow in standard condition t/h
P	in absolute bar or overpressure (depending on the transmitter)
Pr	in absolute pressure
T	Temperature in °C
Pn	Standard pressure 1.0135 bar
Tn	Standard temperature 273,15 K = 0 °C
RHO	Density in kg/m^3
RHO-MIN	Correction range for RHO
RHO-MAX	Correction range for RHO
Patm	atmospheric pressure in absolute bar
Pr	in absolute bar
Zn	Real gas factor for Pn and Tn (compressibility figure)
Pmin/Pmax	Correction range for P (according to transmitter)
Tmin/Tmax	Correction range for T
P20...28	Real gas factors (factory setting 1.00) (compressibility figure)

	Tmin	Tmitte	Tmax
Pabsmin	P20	P23	P26
Pabsmitte	P21	P24	P27
Pabsmax	P22	P25	P28

Tab. 2

HAB	Nozzle spacing in mm is equal water level in mm
Tvgl	Temperature of the reference column in °C

Configuration of gases and steam

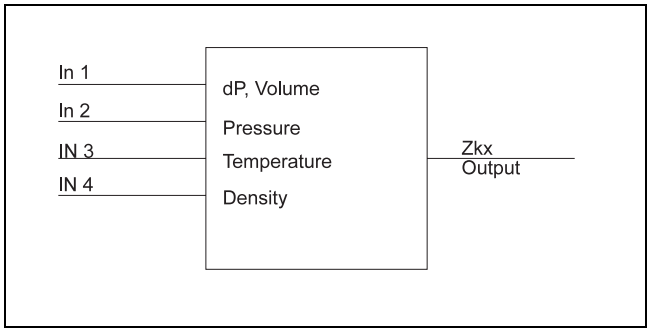


Fig. 53 State correction gas, steam
Z-19144 The parameter and configuration data are illustrated in Tables 3 to 5.

Configuration of water mass flow

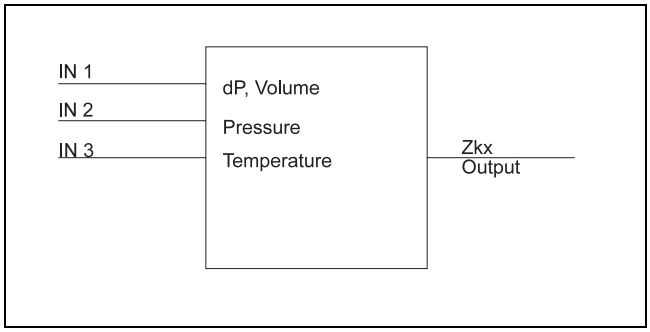


Fig. 54 State correction gas, steam, drum water level
Z-19145 The parameter and configuration data are illustrated in Tables 6 and 7 or 8 and 9.

Configuration of drum water level

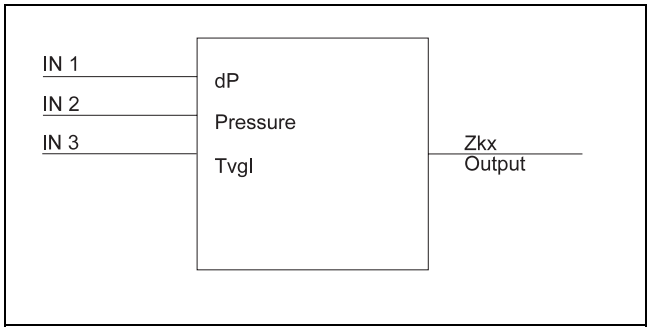


Fig. 55 Water level
Z-19146 The parameter and configuration data are illustrated in Tables 8 and 9.

Gas and steam

Table 3	Query/ Para-meter ZKx-B01-	Gas, Differential measurement		Gas, volumem easurme nt	Steam, mass flow, differential pressure		Saturated steam mass flow, differential pressure pressure correction		Saturated steam mass flow, differential pressure temperature correction		Dim.
		linear	square-rooted		linear	square-rooted	linear	square-rooted	linear	square-rooted	
	Q01	1	1	2	3	3	4	4	5	5	–
Square rooting	Q29	0	1		0	1	0	1	0	1	–
Standard flow Qn,r or	P02	Value	Value	Value							Nm^3/h
Mass flow Qm,r	P02	Value	Value	Value	Value	Value	Value	Value	Value	Value	kg/h
Differential pressure ΔP,r	P03	Value			Value		Value		Value		mbar
Atmospheric pressure Patm,rabs	P04	Value	Value	Value	Value	Value	Value	Value			bar abs
Pressure P,r abs	P05	Value	Value	Value	Value	Value	Value	Value			bar abs
Temperature T,r	P06	Value	Value	Value	Value	Value			Value	Value	°C
Real gas factor Z(Pr,Tr),r	P07	Value	Value	Value							–
Standard density ϱn,r	P08	Value	Value	Value							kg/m^3

Tab. 3 Specification values of the measuring unit (computation values)
Linear no square rooting in transmitter or in analog input
Square-rooted Square rooting in transmitter or in analog input
Grey underground no input required, inputs are ignored

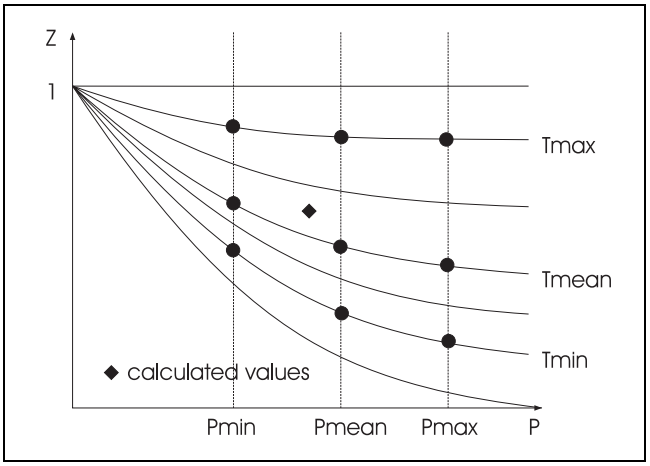


Fig. 56 Principal trend of the characteristic for Z = f(P,T)
Z-19147

Table 4	Tmin	Tmitte	Tmax
Pabs,min	Value (P20)	Value (P23)	Value (P26)
Pabs,middle	Value (P21)	Value (P24)	Value (P27)
Pabs,max	Value (P22)	Value (P25)	Value (P28)

Tab. 4 Real gas factors (factory setting 1.00 for ideal gases). The real gas factors must be additionally determined during the calculation of the orifice and made provided for the commissioning.

Table 3	Query/ Parameter ZKx-B01-	Gas, differential pressure measurement		Gas, volume measurement	Steam, mass flow, differential pressure		Saturated steam mass flow, differential pressure correction		Saturated steam Mass flow, Differential pressure temperature corection		Dim.
		linear	sq. rooted		linear	sq. rooted	linear	sq. rooted	linear	sq. rooted	
	Q01	1	1	2	3	3	4	4	5	5	–
Pressure transmitter											
Overpressure	Q18	1	1	1	1	1	1	1	1	1	–
Absolute pressure	Q18	2	2	2	2	2	2	2	2	2	–
Correction thresholds:											
Pressure min.	P10	Value	Value	Value	Value	Value	Value	Value			bar
Drcuk max.	P11	Value	Value	Value	Value	Value	Value	Value			bar
Temperature min.	P12	Value	Value	Value	Value	Value			Value	Value	°C
Temperature max.	P13	Value	Value	Value	Value	Value			Value	Value	°C
Density min.	P14	Value	Value	Value							kg/m³
Density max.	P15	Value	Value	Value							kg/m³

Tab. 5 Measured values and correction range

The threshold limits for the pressure correction should be input as in the case of the pressure transmitter:

- **Overpressure transmitter requires pressure thresholds in overpressure**
- **Absolute pressure transmitter requires pressure thresholds in absolute pressure**

If one or several measured signals are not available, the correction thresholds should be input identically with the computation values. In the case of a missing pressure measurement, Q18 must be additionally input and stated, if the thresholds stand for absolute pressure or for overpressure.

Water mass flow

Table 6	Query/ Parameter ZKx-B01-	Water, differential pressure measurement		Water, volume measurement	Dimension
		linear	square-rooted		
	Q01	6	6	7	–
Square rooting	Q29	0	1		–
Mass flow Qm,r	P02	Value	Value	Value	kg/h
Differential pressure dP,r	P03	Value			mbar
Atmospheric pressure Patm,r	P04	Value	Value	Value	bar abs
Pressure P,r abs	P05	Value	Value	Value	bar abs
Temperature T,r	P06	Value	Value	Value	°C
Real gas factor Z(Pr,Tr),r	P07	Value	Value	Value	kg/m³
Standard density Rho,r	P08	Value	Value	Value	kg/m³
Pressure transmitter					
Overpressure	Q18	1	1	1	
Absolute pressure	Q19	2	2	2	
Correction thresholds					
Pressure min.	P10	Value	Value	Value	bar
Pressure max.	P11	Value	Value	Value	bar
Temperature min.	P12	Value	Value	Value	°C
Temperature max.	P13	Value	Value	Value	°C
Density min.	P14	Value	Value	Value	kg/m³
Density max.	P15	Value	Value	Value	kg/m³

Tab. 6 Specification values of the measuring unit (computation values)

The thresholds for the pressure correction are to be input in the same way as for the pressure transmitter:

- **Overpressure transmitter requires pressure thresholds in overpressure**
- **Absolute pressure transmitter requires pressure thresholds in absolute pressure**

If one or more measuring signals are missing, then the correction limits must be input as calculated values. If the pressure measuring is missing, then in Q18 must be input if the limits are given in absolute pressure or overpressure.

Drum water level

Table 8	Question	Level measurement	Dimension
	Q01 =	8	-
Pipe socket distance HAB	P16 =	Value	mm
Tcomp[1]	P17 =	Value	°C
Tmin	P12 =	Value	°C
Tmax	P13 =	Value	°C

Tab. 7 Evaluation values of the measuring unit (computation values)
1 as of version 3.4.1

In case of missing temperature measurement, Tmin = Tmax should be adjusted to the temperature of the reference column (as of version 3.4.1).

Table 9	Question	Level measurement	Dimension
Differential pressure End value dP	Q09 =	value	mbar
Pressure correction Min limit Pmin	Q10 =	value	bar
Pressure correction Max limit Pmax	Q11 =	value	bar
Output range start	Q30 =	value	mm
Output range end	Q31 =	value	mm

Tab. 8 Measured values and correction range

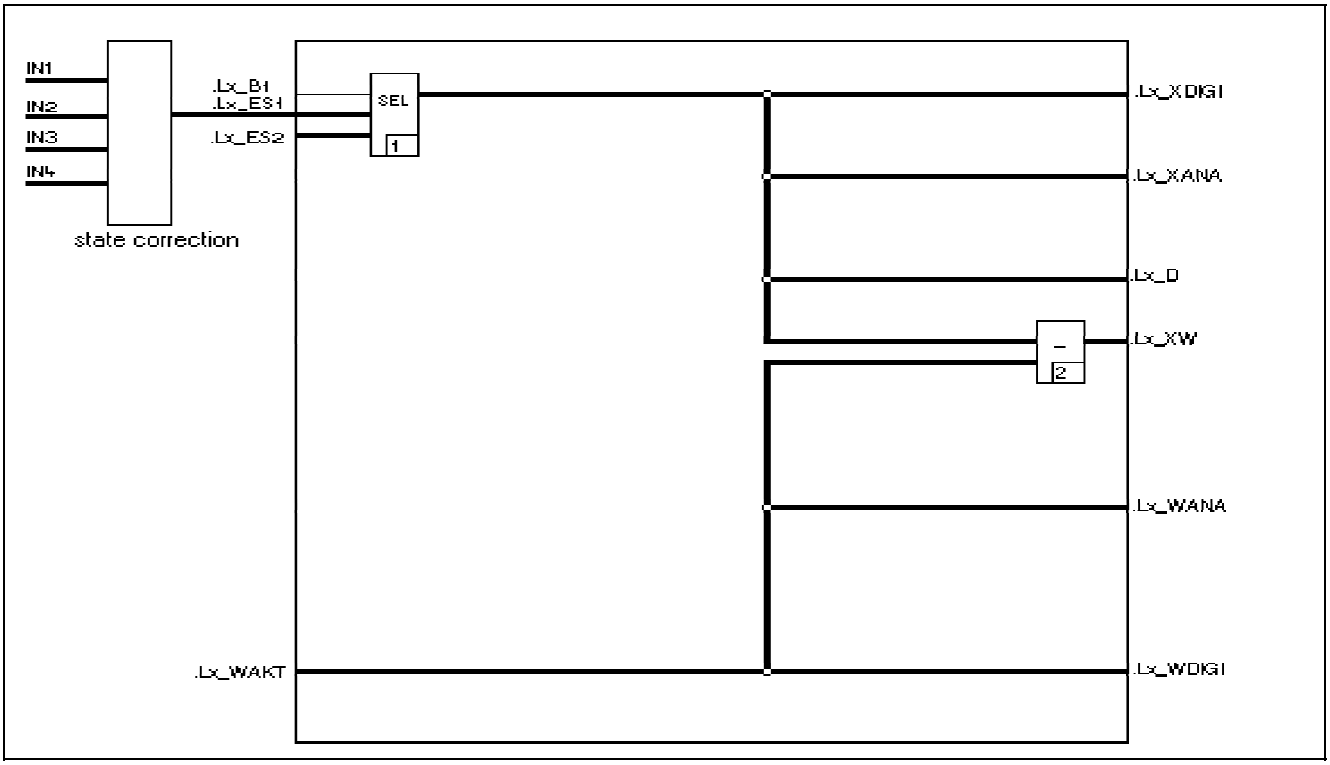


Fig. 57 Input circuit fixed value with additional state correction

Z-19072

.EZKx	Input routing of the state correction ZKx-B02-Fx	.Lx_XDIGI	Digital display for PV
.Lx-B1	Changeover ES1 ⟷ ES2 with switch SEL	.Lx_WDIGI	Digital display for SP
.Lx-ESx	Routed inputs of the input circuit fixed value routed via state correction	.Lx_XANA	Analog display for PV
.Lx_WAKT	Current set point	.Lx_WANA	Analog display for SP
		.Lx_D	to D component
		.Lx_XW	Control deviation

Definition of an analog output from the state correction

In the configuration shown in fig. 57, the state correction provides the computation result of the input circuit directly as a measured value.

If an additional analog current/voltage output with the state correction result is required, this can be defined with the following parameters:

ZKx-B01-P30 Start of range = measured value for 0 % = 0/4 mA or 0/2 V
ZKx-B01-P30 End of range = measured value for 100 % = 20 mA or 10 V

The values for P30 and P31 can lie within or without the expected calculation results.

The statement of ZKx-B01-Q32 and ZKx-B01-P33 is optional. They are of no significance to the unit, but they provide easy control during retrospective checks of the configuration.

A free analog output of the correction results is defined with ZKx-B03-Q01.

Controller outputs

In the controllers, the following controller outputs can be configured:

Two-position controller
- with transistor output or
- with relay output

(strong-weak-off-control e.g. Δ-OUT-off = two-position controller with precontact).

Three-position controller (heat-off-cool)
- with transistor output or
- with relay output,

Optionally 1 output, also continuous (parameters Lx-P25 to P27 are active).

Step controller and positioner
- with transistor step controller output or
- with relay output.

Continuous controller
optionally also with split range output (the parameters Lx-P25 to P27 are active).

The controller outputs of master and override controllers cannot be configured. They are automatically adjusted to the continuous output signal.

In the following examples, the binary outputs BO01 and BO02 are used as examples. It is also possible to use other BOxy.

Two-position controller

Single-channel with transistor output in the basic unit

Binary definition:

BIO-B01-Q01 = 3	BIO01 is output with quiescent current action = BO01.
L1-B01-Q02 = 3	Two-position controller.
L1-B10-Q04 = 1	Controller output OUT1 to BO01.

Two-position controller for stron-weak-off

Binary definition:

BIO-B01-Q01 = 3	BIO01 is output with quiescent current action = BO01.
BIO-B02 = 3	BIO02 is output with. quiescent current action = BO02.
L1-B01-Q02 = 3	Two-position controller with precontact.
L1-B08-Q03 = 4	Alarm value 3 as precontact max.
L1-P93 = −3 bis −5 %	Adjust to exact value for commissioning.
L1-B10-Q04 = 1	Controller output to BO01.
L1-B11-Q03 = 2	Alarm value 3 on BO02. switches from “strong” to “weak”.

Single-channel controller with relay output and multi-channel Controller

For multi-channel controllers and controllers with relay output, the existing outputs should be configured accordingly.

Three-position controller

(Heat-off-cool)

Single-channel with transistor output in the basic unit

BIO-B01-Q01 = 3	BIO01 is output with quiescent current action = BO01.
BIO-B02-Q01 = 3	BIO02 is output with quiescent current action = BO02.
L1-B01-Q02 = 5	Three-position controller.
L1-B10-Q04 = 1	1. Controller output (heating) OUT1 at BO01.
L1-B10-Q05 = 2	2. Controller output (cooling) OUT2 at BO02.

Three-position (heat-off-cool) with continuous controller output for heat

Binary definition

BIO-B01-Q01 = 3	BIO01 is output with quiescent-current action = BO01.
L1-B01-Q01 = 6	
L1-B10-Q05 = 1	Switching controller output (cooling) OUT2 at BO01.
L1-B10-Q01 = 1	continuous output (heating) OUT1 at AO01.

single-channel controllers with relay output and multi-channel controllers

With multi-channel controllers and with controllers having relay output, the available outputs must be configured accordingly.

Step controller

If using the basic unit without modules, the second signal input can either be used for the feedback signal or for another function.

L1-B01-Q04 = 2	Position feedback signal to AI02.
AO-B01-Q01 = 5	Analog output supplies 20 mA for feeding a position feedback signal via AI02.
AI-B02-Q01 = 1	AI02 = 0...20 mA.

Balancing of 0 and 100 % see Section on “Service”.

Outputs:

BIO-B01-Q01 = 3	Binary BIO01 is output with quiescent current action = BO01.
BIO-B02-Q01 = 3	Binary BIO02 is output with quiescent current action = BO02.
L1-B10-Q04 = 1	Controller output “more” OUT1 to BO01.
L1-B10-Q05 = 2	Controller output “less” OUT2 to BO02.

Positioner

A positioner is a step controller which drives an electrical control actuator to a - mostly externally preset - position. A positioner requires a position feedback signal as measured value.

L1-B01-Q01 = 11	Positioner.
L1-B03-Q01 = 1	Input circuit fixed value.
L1-B04-Q01 = 1	Position feedback signal to AI01.
L1-B05-Q06 = 2	External set point to AI02.

Controller output as for step controller

Single channel controllers with relay output and multi-channel controllers

In the cases of multi-channel controllers and controllers with relay output, configuration must be performed according to the available outputs.

Continuous controller

In the basic unit, only a continuous controller with one controller ouput is possible. For a second analog controller output, a continuous output module is required.

One controller output (corresponds to factory setting):
L1-B01-Q02 = 1

AO-B01-Q01 = 1 or 2	Depending on the signal range.
L1-B10-Q01 = 1	1. Controller output OUT1 to AO01.

Two controller outputs (split range) (**not Protronic 100**):
Output module e.g. to slot 3
L1-B01-Q01 = 7

L1-B10-Q02 = 31	2. Controller output to 1. output of the output module to slot 3.
AO-B31=Q01 = 1 or 2	Depending on the signal range.

Cascades

Cascade with one slave controller

This configuration is possible in the basic unit if no particular demands are made on inputs and outputs.

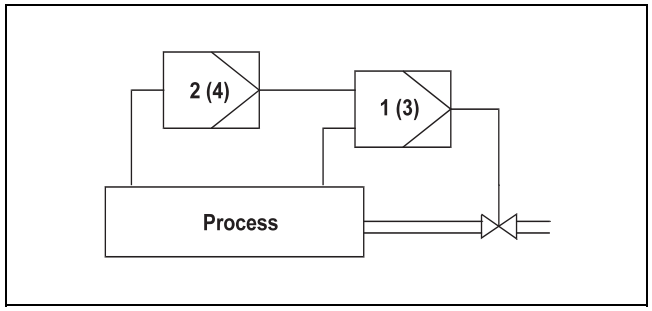


Fig. 58
Z-19076

Configuration

Master controller is loop 2 or loop 4 (**Protronic 100**: Loop 2)
L2-B01-Q01 = 2 or
L4-B01-Q01 = 2

Slave controller to loop 2 is loop 1
L1-B01-Q01 = 3

Slave controller to loop 4 is loop 3 (**not Protronic 100**)
L3-B01-Q01 = 3

Die input signal connections of the controllers can be selected as single-channel controllers.

The controller output of the controllers 1 (3) can be freely configured.

Cascade with two slave controllers
(**not Protronic 100**)

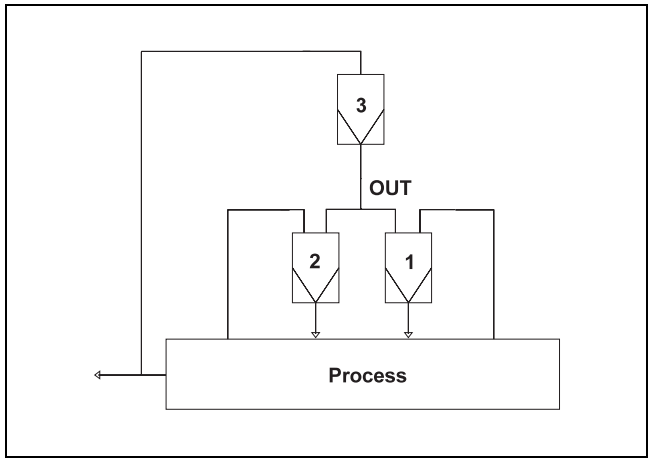


Fig. 59
Z-19077

Configuration

Master controller is loop 3:
L3-B01-Q01 = 2

Slave controllers are loop 1 and loop 2:
L1-B01-Q01 = 3
L2-B01-Q01 = 3

The input signal connections of the controllers can be selected as for single-channel controllers.

The controller output of the controllers 1 (2) can be configured freely.

Cascade control with two slave controllers and ratio station
(**not Protronic 100**)

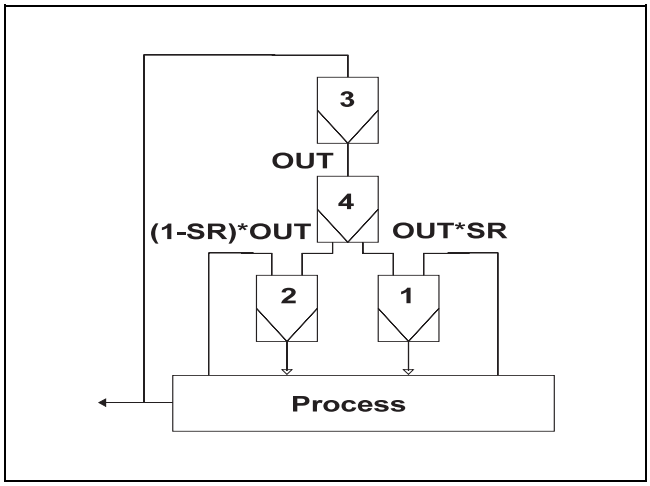


Fig. 60
Z-19078

Configuration

Master controller is loop 3:
L3-B01-Q01 = 2

Slave controllers are loop 1 and loop 2:
L1-B01-Q01 = 3
L2-B01-Q01 = 3

Ratio station is loop 4:
L4-B01-Q01 = 12

The input signal connections of the controller can be selected as for single-channel controllers.

The controller output of the controllers 1 (2) can be freely configured.

Combustion control: Load control
(not Protronic 100)

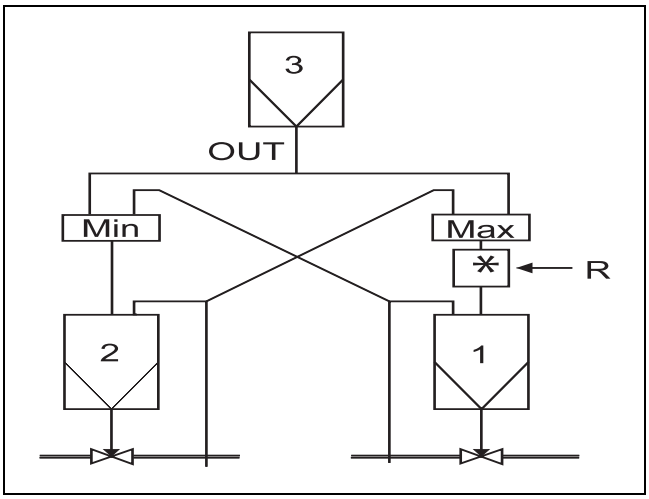


Fig. 61 (**not Protronic 100**)
Z-19087

Combustion control is preferably applied in steam generation and in furnace construction. It also depends on ensuring optimum combustion - even with load changes - in both applications.

During steam generation, care is taken to ensure that air scarcity never causes poor combustion and thereby poor exhaust quality. If a higher volume of steam is required, the air quantity is first increased before increasing the fuel. A provisionally bigger air surplus is, in most cases, more acceptable for quicker control than when the efficiency of the system is unsatisfactory during this time.

Comment
The air set point with ration = 1 is shown in the diagrams below. The control of the set point is steeper or flatter with other ratios.

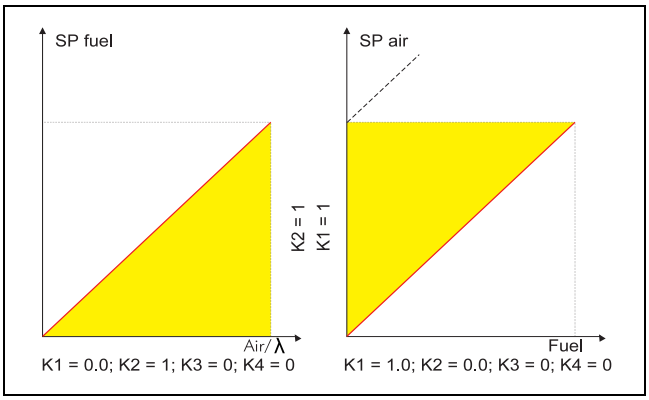


Fig. 62 Combustion control on steam boilers, grey fields stand for permissible set points
Z-19089

Furnaces for the thermal treatment of iron and steel:

In furnaces in which the material to be heated to incandescence is exposed to the furnace atmosphere, it is important to keep the oxygen within specific limits in order to be able to control any oxidation or reduction of the material. This is achieved by limiting the permissible set point change when the load changes.

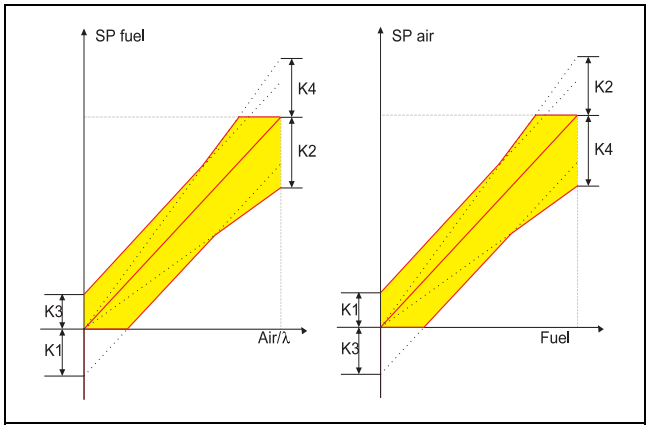


Fig. 63 Combustion control in furnace construction: grey areas indicate permissible set points
Z-19088

Configuration

The following classification is required for the configuration of the control loops:

Master controller loop 3	L3-B01-Q01 = 2
Air controller	L1-B01-Q01 = 3
(only loop 1)	L1-B03-Q01 = 12
Fuel controller	L2-B01-Q01 = 3
(only loop 2)	L2-B03-Q01 = 13

Parameter definition

The different requirements of the load control input circuit are satisfied by diffeent parameter settings. The parameters define the limit in the grey-background fields within which the set point can move.

Parameters: Lx-P101 to 104

Steam generation (all values positive)

	Air controller		Fuel controller	
K1:	L1-P101 =	1.0	L2-P101 =	0.0
K2:	L1-P102 =	0.0	L2-P102 =	1.0
K3:	L1-P103 =	0.0	L2-P103 =	0.0
K4:	L1-P104 =	0.0	L2-P104 =	0.0

Furnace construction:

K1 to K4 as required

Drum water level control in cascade
(**not Protronic 100**)

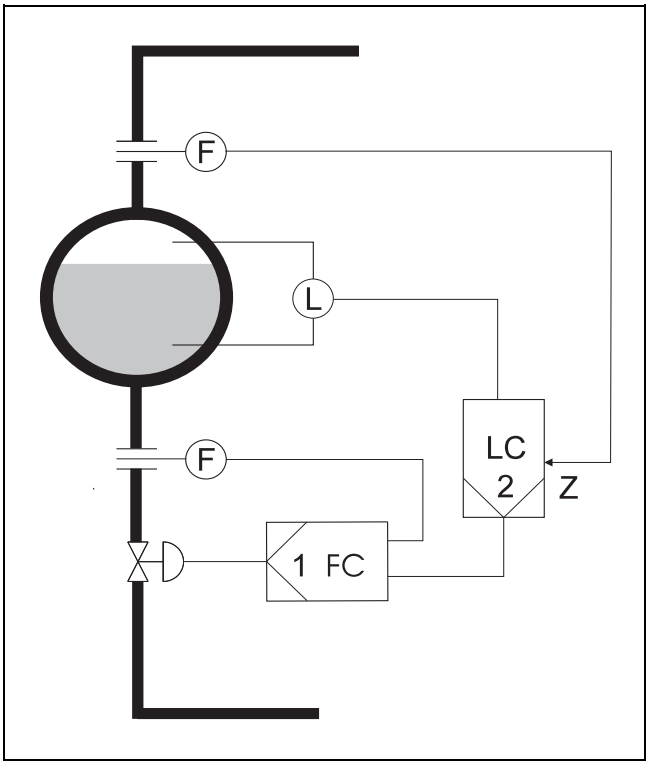


Fig. 64 Steam quantity fed as disturbance variable on output of controller 1 (**not Protronic 100**)
Z-19121

The loop shown in Fig. 64 is easier to put into operation than the classical multi-component control (fig. 38).

A level correction can be swiched onto the level loop. When dealing with heavily fluctuating pressures on the steam side, a steam correction is recommended.

Configuration

Master controller = loop 2
L2-B01-Q01 = 2

Slave controller = loop 1
L1-B01 = 3

Input signal connection for loop 1 in the most uncomplicated case
L2-B03-Q01 = 1 Fixed value.
or
L2-B03-Q01 = 91 State correction 1.
ZK1-B01-Q01 = 8 Drum water level.

Feedforward control (Z)
L2-B02-Q25 = 1..74 (Digitric 500: 44) depending on the existence of analog input.
L2-B02-Q26 = 1 Linear feedforward of Z.
or
L2-B02-Q26 = 92 State correction 2.
ZK2-B01-Q01 = 3 Steam correction.

Input signal connection for loop 2
L1-B03-Q01 = 1 Fixed value.

Override control

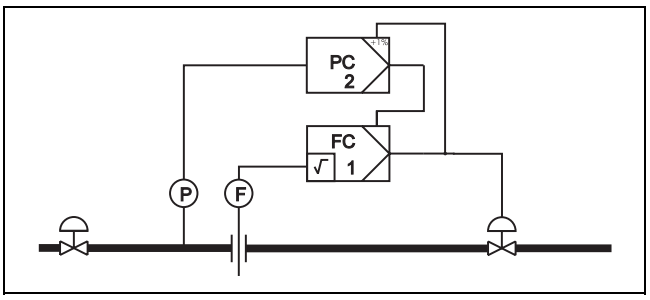


Fig. 65 Override control with one master controller and one override controller
Z-19097

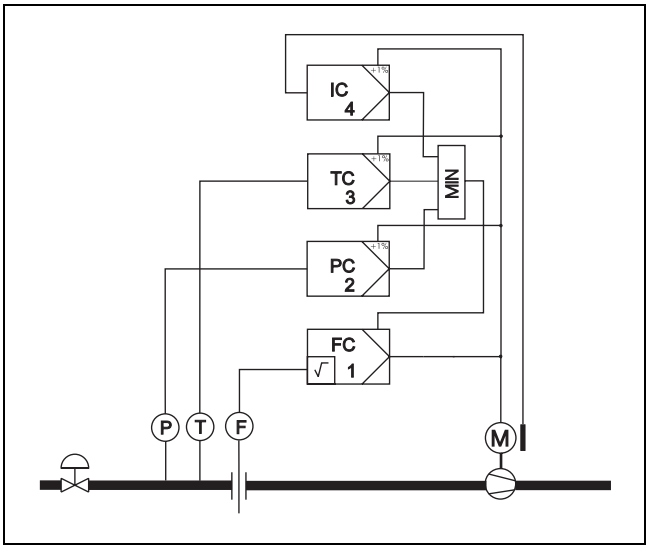


Fig. 66 Override control with one master controller and up to three override controllers (**not Protronic 100**)
Z-19098

Application

In normal operation, the master controller (1) in the illustrated applications is in the intervention mode. The override controllers ensure that even during irregular operation the other variables - pressure, temperature, power consumption - do not shoot over the set thresholds.

Configuration

Master controller:

L1-B01-Q01 = 4 or 5	Master controller with min. or max. selector.

Override controller:

L2-B01-Q01 = 6 or 7	Override controller with min. or max. selector.
L3-B01-Q01 = 0, 6, 7	Override controller with min. or max. selector (**not Protronic 100**)
L4-B01-Q01 = 0, 6, 7	Override controller with min. or max. selector (**not Protronic 100**)

The min. or max. selection must be uniform for all controllers involved.

If varying adjustments are required, these can be achieved only via the “Free configuration” feature with IBIS_R+.

Dead time, Smith predictor

A controller with Smith Predictor is used for the control of control systems with dead time, or of control sysems with large values of delay time Tu in comparison with the system time constants.

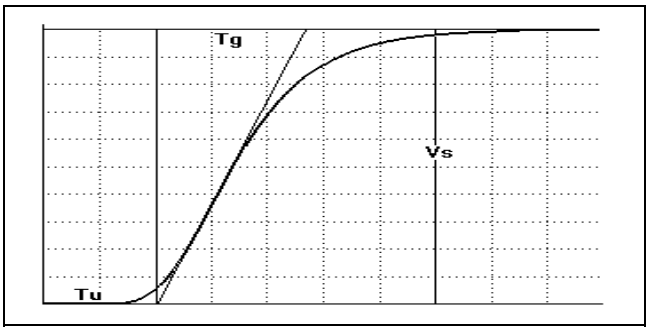


Fig. 67 Controlled system with Tu/Tg ≈ 1
Z-19053

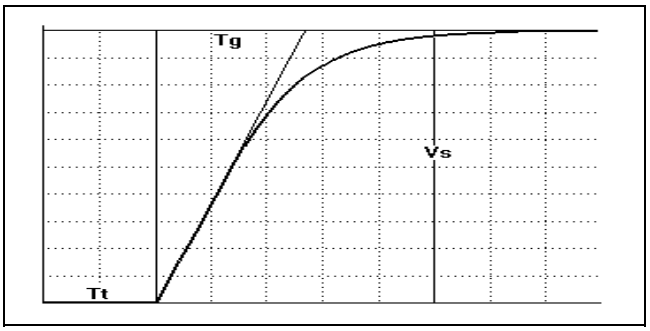


Fig. 68 Controlled system with dead time
Z-19050

Configuration

The Smith Predictor is possible in combination with all control actions and input signal connections.

Lx-B02-Q02 = 5 PI controller with Smith Predictor (PI suffices in most cases)

Parameter definition

The following must be adjusted as parameters for the Smith Predictor:

1. Lx_P39 T_t on the value of the controlled system dead time.
   Lx_P40 T1 on the value of Tg.
3. Lx_P41 Ks on the value of Vs.

For the first commissioning, Tn ≈ Tg and Kp ≈ 1/Vs should be adjusted.

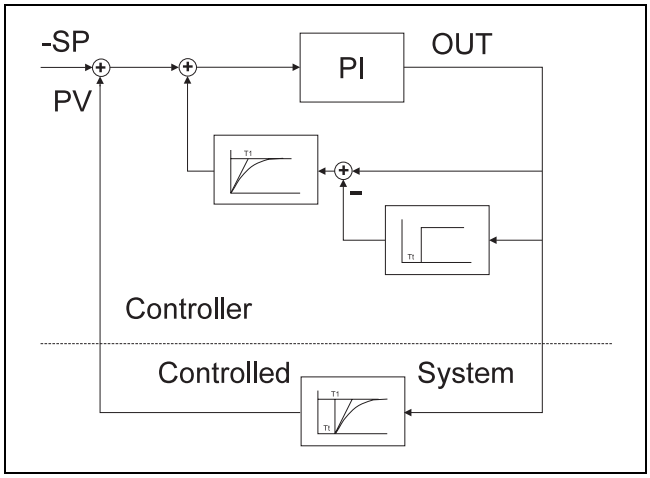


Fig. 69 Controller should be adjusted with Smith predictor to the controlled system with dead time
Z-19108

Service

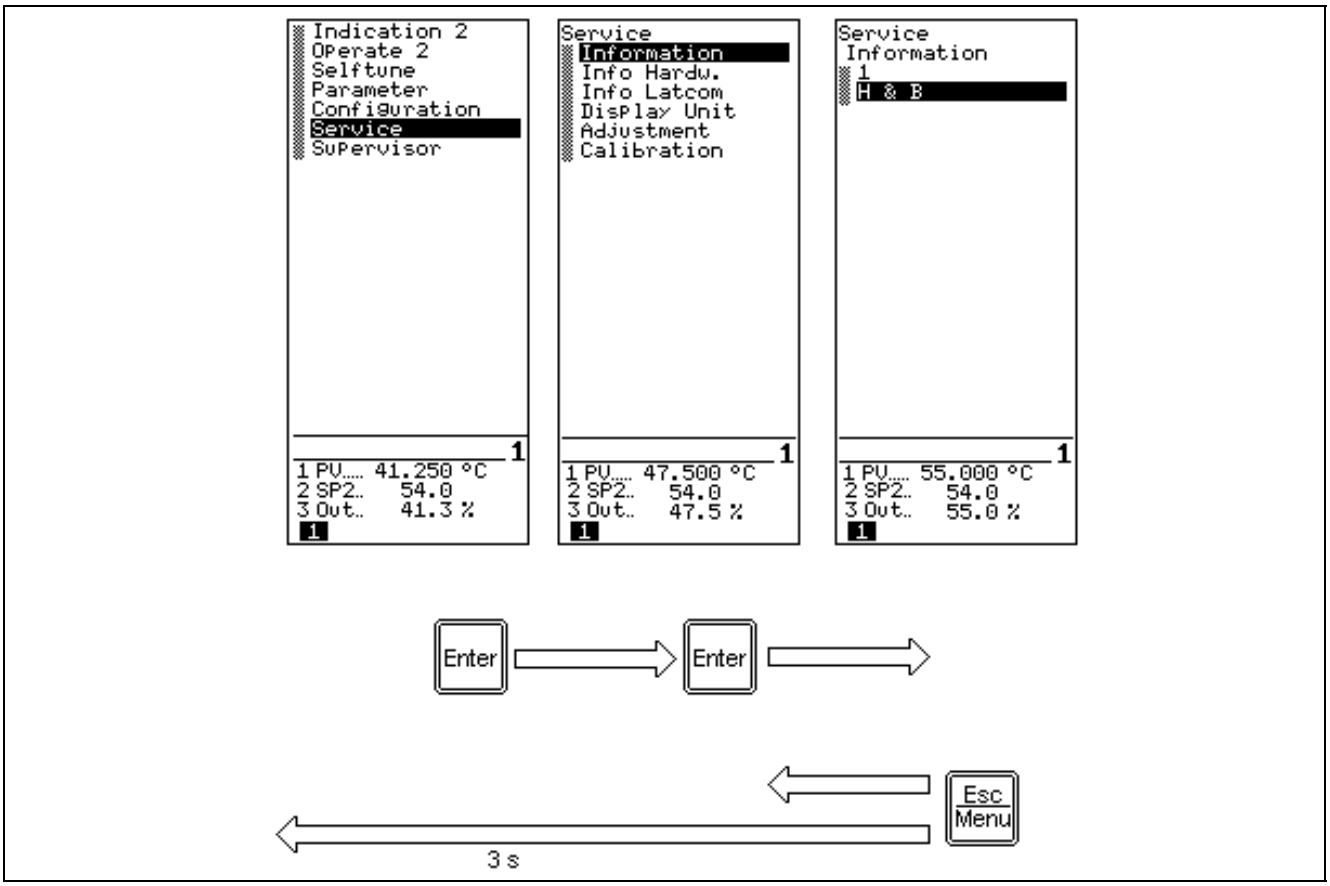


Fig. 70 Service menu (**Protronic 100**: only module 1)
Z-19115

General information (Info.allg.)

This menu shows information input by manufacturer during production (or retrospective repair) and which cannot be modified by customer:

Item	Description	in unit
1	Manufacturer	H & B
2	unit type	Protronic 500
3	Motherboard index	CPU: ...
4	Serial number	F: ...
5	Date of manufacture	F-Dat: ...
6	Configuration No.	Konfi-Nr.: ...
7	Repair date	Rep.-Dat: ...
8	free text	...

Information Hardware

Fig. 71
Z-19116

This menu shows the slotted modules.

These modules are not automatically available in the configuration.

They are input with I-B11-Q01 = 1.

Info Latcom

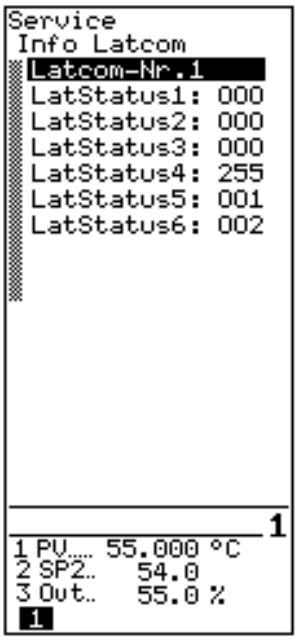
This menu item shows if a lateral communication was configured, and if yes, which status it has.

If no lateral communication was configured, the following display will appear upon calling up the menu item:

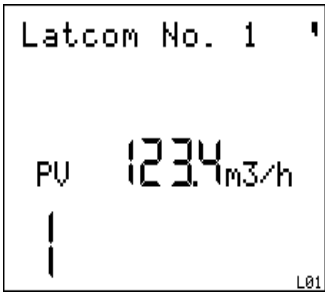
Fig. 72
Z-19059

or

Protronic 550



Protronic 100 / 500, Digitric 500



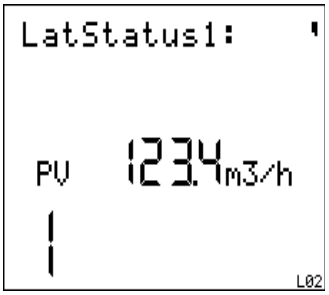


Fig.s 73, 74, 75
Z-19060, z-19054, Z-19058

If the lateral communication is configured, the following display will appear on calling up the menu item:

Left (Protronic 550):

1. Lines: Status of the controller with the subscriber 1.
and with <▲>, <▼>
status of subscribers.

Right (other controllers):

Call up of the status of the lateral communication on the controller and subscriber No. 1 on the lateral bus and
with <Enter> and <▲>, <▼>
status of subscribers.

Possible status information

0 Lateral communication information required for processing FBD or AL are also received correctly and correspond to the structural description which existed in the connection file during plausibility check.

1 Lateral communication information is received correctly, but do **not** correspond to the structural description which existed in the connection file during plausibility. This data is however not required for processing the FBD or AL.

2 Lateral communication information is received correctly, but do **not** correspond to the structural description which existed in the connection file during plausibility. This data is however required for processing the FBD or AL.

3 Your own data were not transmitted for 5 seconds. This is normally the case when a lateral communication subscriber has not yet been connected to a second subscriber via RS-485.

4 The data of a unit participating in the lateral communication have not been received for 5 seconds, even though these are required. This happens when the respective subscriber suffers a breakdown.

5 Despite participation in the lateral communication, thee is no description of the data to be transmitted.

6 The transmission data buffer is faulty.

7 Subscriber can neither receive nor transmit lateral communication data.

8 No RS-485 module was found. This information applies to the particular unit in question, but is output for all third-party devices.

9 The reporting subscriber has suffered a breakdown.

255 The subscriber has not been configured for the lateral communication.

Display

Brightness LED
(**not Protronic 550**)

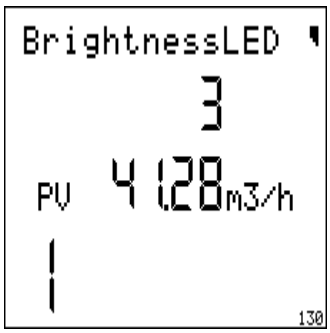


Fig. 76
Z-19130

1. Modify brightness (in four steps, step 1 is the least bright):
<▲>, <▼>

2. Acknowledge modification:
<Enter>

Contrast LCD

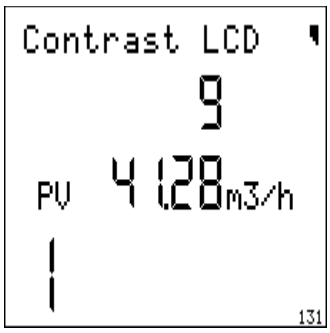


Fig. 77
Z-19131

1. Modify contrast (in nine steps, step 1 is the least contrast):
<▲>, <▼>

2. Acknowledge modification:
<Enter>

By modifying the contrast, colour tolerances of several controllers mounted beside each other can be compensated for.

Background illumination LCD
(**not Protronic 550**)

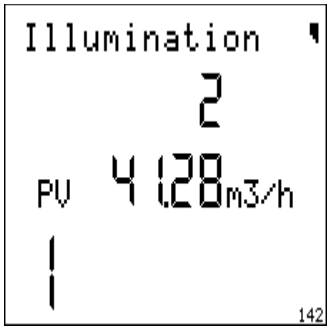


Fig. 78
Z-19142

1. Modify brightness (in two steps, step 1 is least bright):
<▲>, <▼>

2. Acknowledge modification:
<Enter>

Balancing

The balancing for the measurement with Pt100 resistance thermometers in 2-wire technique and the balancing of teletransmitters are undertaken in this menu.

Balancing Pt100

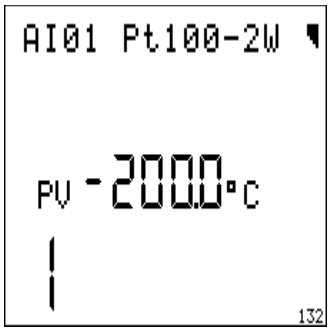


Fig. 79 Balancing for AI01 is selected
Z-19132

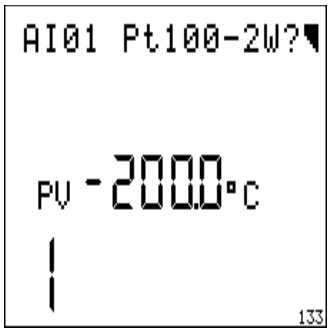


Fig. 80 Should balancing be started?
Z-19133

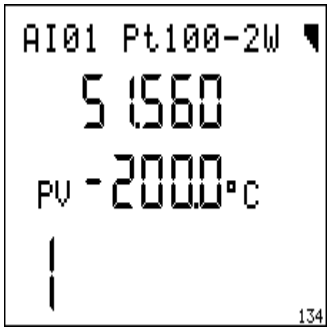


Fig. 81
Z-19134

⚠ Attention

Do not conduct balancing with input open!

Select the balancing point separately for the respective inputs in the basic unit and for the modules.

The submenu point AIxy Pt100-2L can only be selected if the Pt100 2-wire measurement for the respective input was configured.

Balancing steps

0. On the sensor, short-circuit the line between sensor and controller.

In the lower line, the controller displays the set reference value.

1. Call up the balancing mode on controller:
   <Enter>

In the first line “?” is supplemented.

Enter☼

2. Start balancing:
   <Enter>

For three seconds after completing balancing, “AIxy adjusted” is written in the text lines, a balancing variable is written and stored in the upper line of the display.

Enter●

Balancing is now successfully completed.

3. Exit the balancing menu:
   <Esc>

4. **Undo the short-circuiting on sensor!**

Teletransmitter balancing

The menu items for teletransmitter balancing can be selected when the respective input for “Teletransmitter” or for “0/4... 20 mA” is configured. The balancing procedure is the same in both cases. Balancing is always required, when the teletransmitter or a measured signal (e.g. position feedback signal) cannot be fully utilized as a valid measured value.

Application

Position feedback signal with potentiometer via teletransmitter input (AI01 or Pt100 module for 3/4-wire circuitry) or current input 0...20 mA AI02.

Zero point balancing

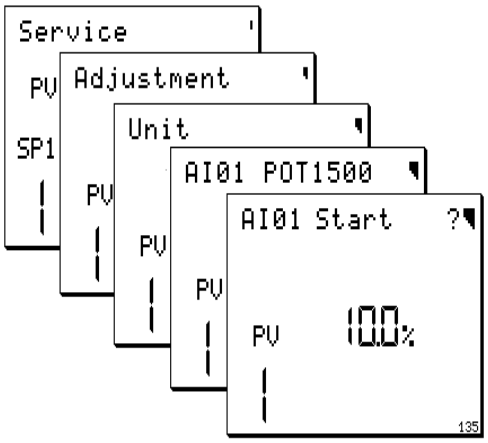


Fig. 82
Z-19135

1. Call up the balancing routine by pressing <Enter> several times in the menu “Service”.

The signal “AI01 start” prompts you to return the teletransmitter to its start position mechanically.

2. Bring the teletransmitter to its start position mechanically.
3. Acknowledge “AI01 start” with <Enter>.

Balancing is effected, the message cursor springs to “AI01 end”:

Span balancing

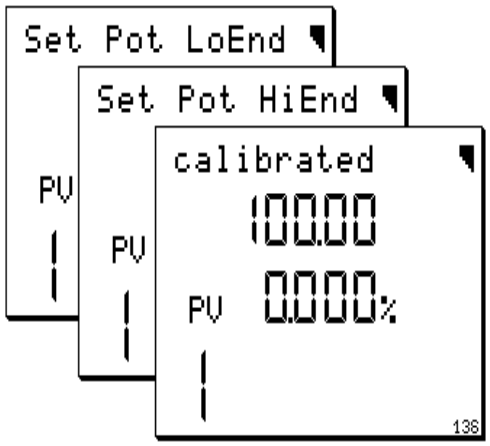


Fig. 83
Z-19136

4. Bring the teletransmitter mechanically to its final position.
5. Acknowledge “AI01 end” with <Enter>.

The balancing routine returns to the next higher operator control level via the message ”AI01 adjusted”.

Return to the main operator control level with <Esc>.

The position feedback signal is balanced in the same way, using a 0/4...20 mA current or a potentiometer fed with constant current. The signal “AIxy Pot150x” is then replaced by “AIxy20mA p. Pot”.

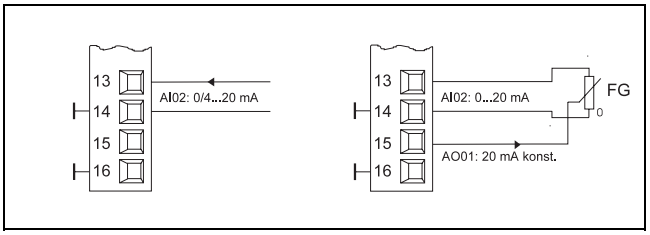


Fig. 84
Z-19128, Z-19129

Fig. 84

left	right
AI-B02-Q01 = 1 or 2	AI-B02-Q01 = 1
AI-B02-Q01 = 1	AI-B02-Q02 = 1
AI-B02-Q03 = 2	AI-B02-Q03 = 2
AI-B02-P05 = 0	AI-B02-P05 = 0
AI-B02-P06 = 100	AI-B02-P06 = 100
	AO-B01-Q01 = 5

Calibration

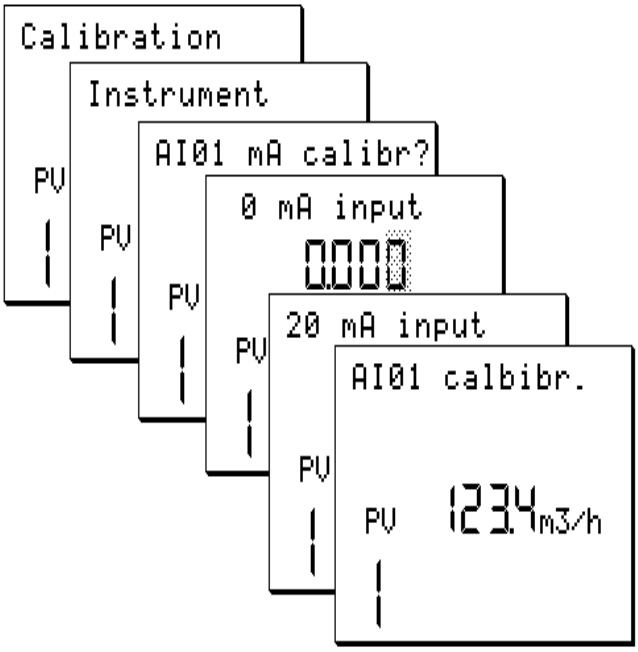


Fig. 85
Z-19075

Both inputs of the basic unit can be calbirated with the calibration routine. To accomplish this, external transmitters with the required accuracy are necessary.

Upon calling up the calibration routine, this provides the calibration of the inputs AI01 and AI02 of the basic unit in the configured type of measurement.

During calibration, the following values are made available with the stated adjustment ranges.

For calibration, the exact measured values must be stated in the ranges provided on the terminals. Adjust the values in the display to the required data with the keys <▾> and <▴> acknowldege with <Enter>.

mA Input

Display: **AI0x mA calib.?**

AI		Display	Range
01	mA	0.000	−1.00 ... +5.00
		20.000	15.00 ... 22.00
02	mA	0.000	−1.00 ... +5.00
		20.000	15.00 ... 22.00

Tab. 9 mA input

Adjust the values in the display to the required data with the keys <▾> and <▴> acknowldege with <Enter>. The calibration must be conducted for both items. 0 mA is provided in default by short-circuiting terminals 10 and 11.

mV Measurement

Display: **AI01 mV calib.?**

AI		Display	Range
01	mV	−10.000	−10.00 ... −5.00
		80.000	60.00 ... 85.00

Tab. 10 mV measurement

Adjust the values in the display to the required data with the keys <▾> and <▴> acknowldege with <Enter>. The calibration must be conducted for both items.

Pt100 measurement

Display: **AI01 Pt calib.?**

Calibration is effected in 4-wire technique, independent of the configuration. The resistance teletransmitter is connected with two lines each to terminals 8, 9 and 11, 12.

AI		Display	Range
01	Ω	0.000	0
	Ω	60.000	50.0 ... 85.0
	Ω	150.000	130.0 ... 200.0
	Ω	200.000	180.0 ... 220.0
	Ω	400.000	360.0 ... 450.0

Tab. 11 Pt100 measurement

Adjust the values in the display to the required data with the keys <▾> and <▴> acknowldege with <Enter>. The calibration must be conducted for all four items.

Teletransmitter measurement

Display: **AI01 Fg calib.?**

The total resistance of the teletransmitter is calibrated in 4-wire techniquae. The teleransmitter is connected with two lines each to terminals 8, 9 (start) and 11, 12 (end).

AI		Display	Range
01	Ω	800.0	700.0 ... 1100.0
	Ω	1000.0	1000.0 ... 1200.0
	Ω	2000.0	2000.0 ... 2500.0

Tab. 12 mA Input

Adjust the values in the display to the required data with the keys <▾> and <▴> acknowldege with <Enter>. The calbiration is to be conducted for the point closest to the resistance value of the teletransmitter.

Supervisor

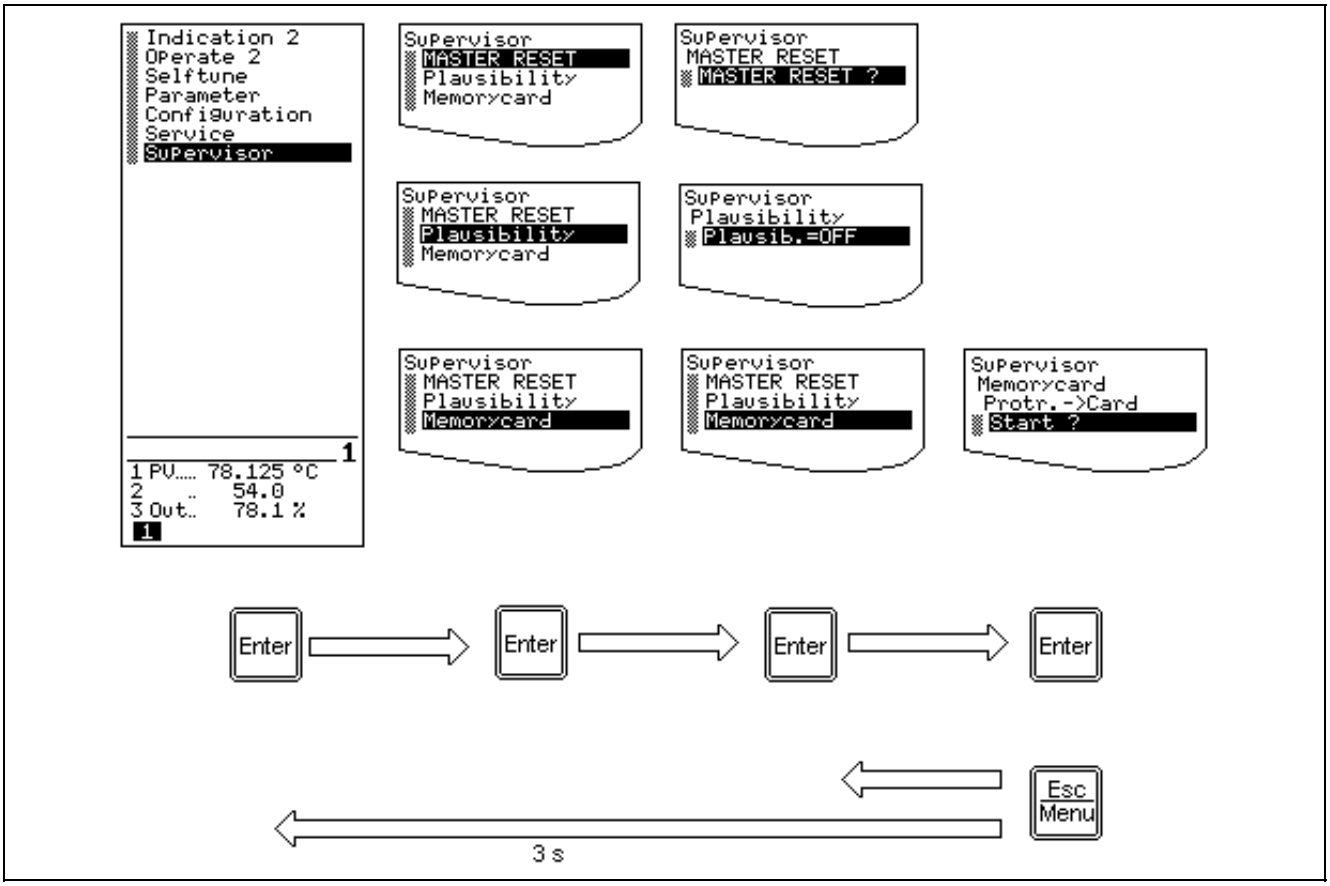


Fig. 86
Z-19110

Plausibility check

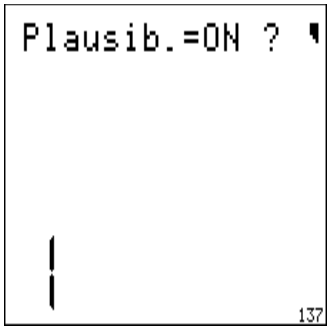


Fig. 87 Switch on plausibility check?
Z-19137

The plausibility check is used to verify, if the various configuration inputs are correct and complete.

After selecting the plausibility check, a query appears to inquire if the plausibility check should be switched on or off, depending on the current plausibility function.

1. For changeover between the queries:
   <▲>, <▼>

Enter☼

2. Acknowledge query:
   <Enter>

The question mark is deleted.

Enter●

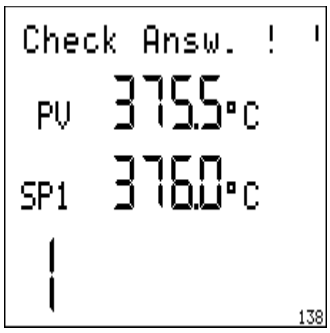


Fig. 88 Message when exitting the configuration
Z-19138

If the plausibility check mode is set, the following message appears when exitting the configuration:

Factory setting

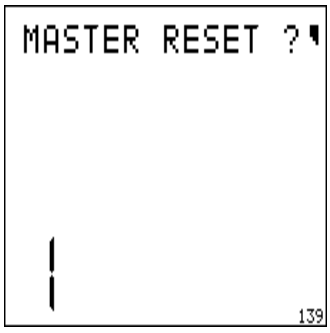


Fig. 89 Reset configuration and factory setting?
Z-19139

The menu item called factory setting permits all configurations to be reset to the factory settings at a go.

⚠ Attention

A reset to the factory setting results in the loss of all previously effected configurations! Only the language setting remains unchanged.

1. Call up the factory setting menu.

After call-up of the menu item, the query apprears, if the factory setting should be restored (fig. 89).

Enter☼

Either

2. Acknowledge query:
   <Enter>

"?" is changed to "!". With a few messages which disclose the progress of the factory settings, there is an automatic switch-back to the main operator control level.

Enter●

or

2. Abort:
   <Esc>

Memory card

(**only Protronic 500 / 550**)

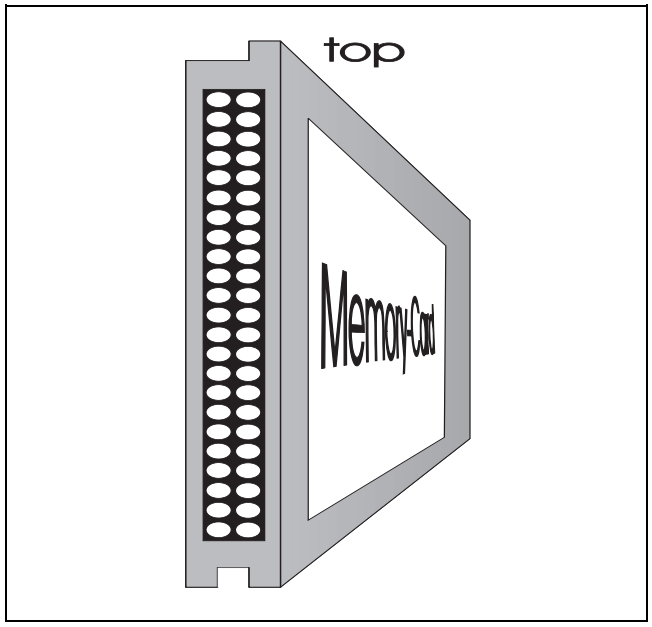


Fig. 90 Memory card
Z-19092

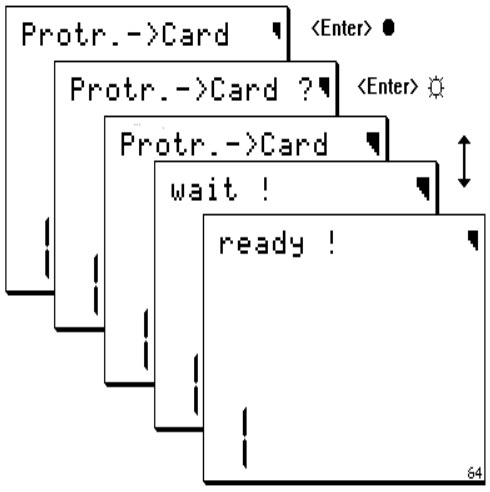


Fig. 91
Z-19064

In the memory card menu the configuration of a controller can be stored on a memory card or the configuration of a controller can be loaded from a memory card.

1. Remove the front module.
2. Plug memory card into the vertical slot as shown in fig. 90, irrespective of the arrangement of the label (wrong polarity not possible due to mechanical polarity protection).
3. Call up the memory card.

Either

4. Call up “Protr→Card”.

After call-up of the menu item with <Enter>, the menu line is supplemented with a “?”.

5. Acknowledge query:
   <Enter>

The progress of the saving mode is illustrated with “... wait” and “completed”. If a fault occurs, the message “Fault” will appear instead of “completed”.

or

4. Call up “Card→Protr”:

After call-up of the menu item with <Enter>, the menu line is supplemented by a “?”.

5. Acknowldege query:
   <Enter>

The progress of the loading is illustrated with “... wait” and “completed”. If a fault occurs, the message “Fault” will appear instead of “completed”.

Delete password (as of FW 1.163)

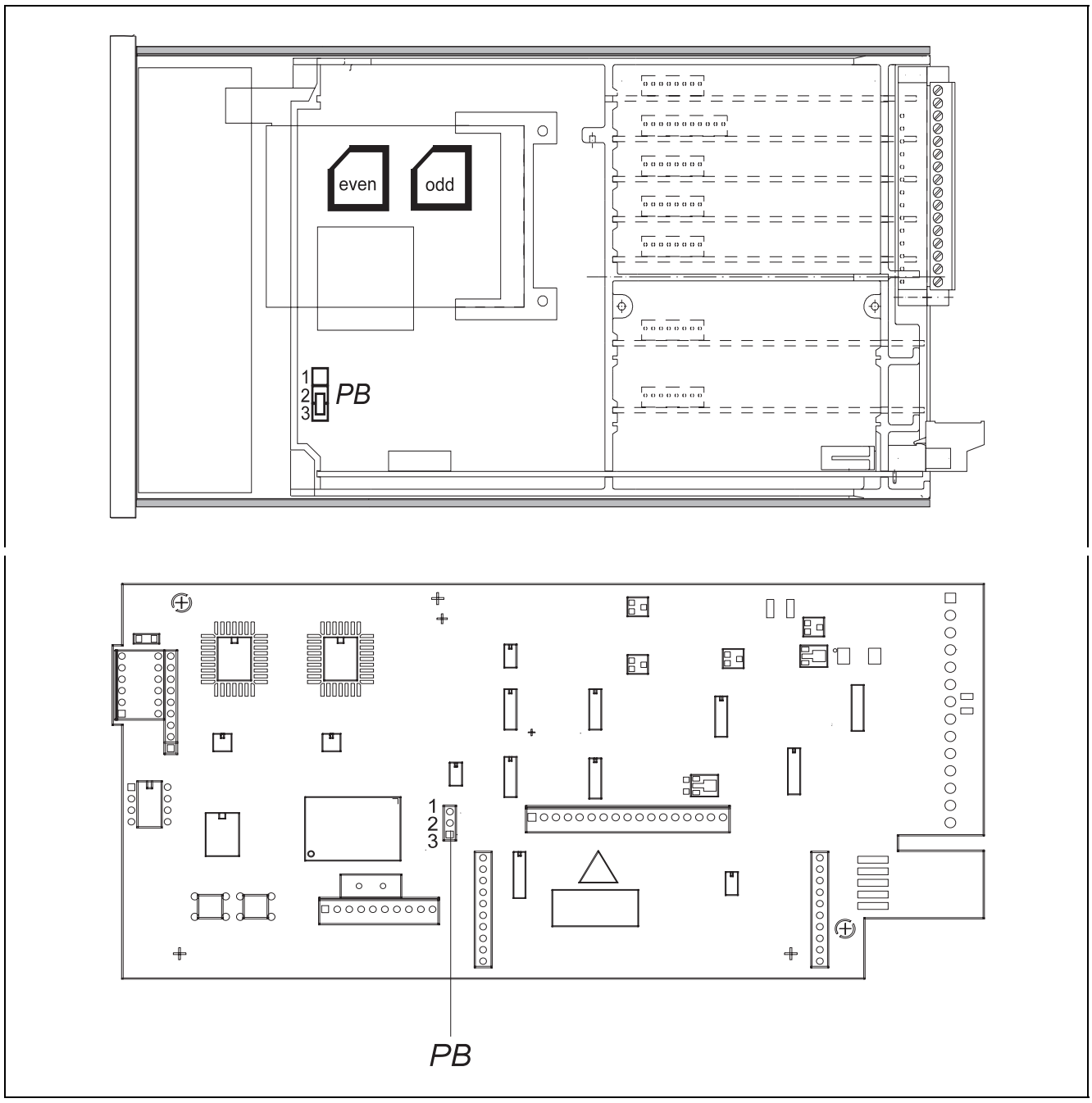


Fig. 92 aboveMotherboard Protronic 100 / 500
Z-19090 below Motherboard Digitric 500
Z-19091 *PB* Password bridge

1. Switch off power supply.
2. Dismantle unit and open.
   (Protronic 100/ 500: Operation Manual 42/62-50011).
   (Digitric 500: Operation Manual 42/61-50011).

If the plug-in jumpers *PB* connect posts 1 and 2, the adjusted password will be active. If the plug-in jumper is changed to posts 2 and 3, the adjusted password will no longer be required.

3. Change the plugging of bridge *PB*.
4. Close unit and install.
5. Connect power supply.

The levels protected with password are freely accessible.

6. Read password and eventually modify.
7. Replug the plug-in jumper according to steps 1-5.

Parameter Definition Tables

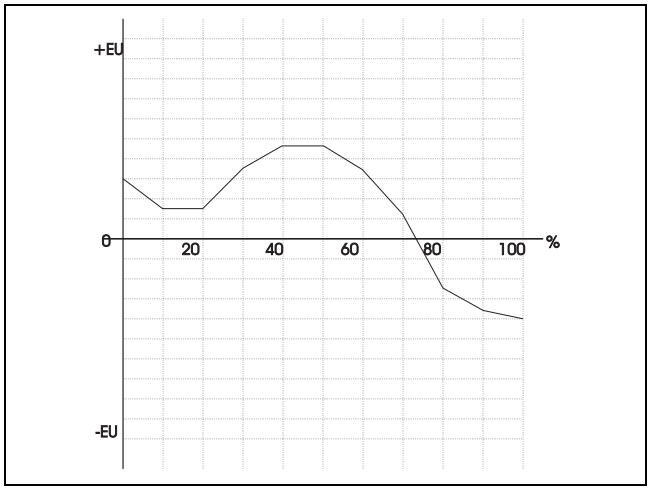


Fig. 93 Examples of parameter definition table

Instrument			Range		Unit	Resolu-tion	Factory setting	System setting	Rem. p.66
Param. No.	Parameter text	Parameter	Min.	Max.					
	Table 1								
10	TAB-1.0	Checkpt. 0 at 0%	-9999	99999	EU	1 Digit	0.0		1
11	TAB-1.1	Checkpt. val. 1 at 10%					0.1		
12	TAB-1.2	Checkpt. val. 2 at 20%					0.2		
13	TAB-1.3	Checkpt. val. 3 at 30%					0.3		
14	TAB-1.4	Checkpt. val. 4 at 40%					0.4		
15	TAB-1.5	Checkpt. val. 5 at 50%					0.5		
16	TAB-1.6	Checkpt. val. 6 at 60%					0.6		
17	TAB-1.7	Checkpt. val. 7 at 70%					0.7		
18	TAB-1.8	Checkpt. val. 8 at 80%					0.8		
19	TAB-1.9	Checkpt. val. 9 at 90%					0.9		
20	TAB-1.10	Checkpt.val.10 at 100%					1.0		
	Table 2								
30	TAB-2.0	Checkpt. val. 0 at 0%	-9999	99999	EU	1	0.0		1
31	TAB-2.1	Checkpt. val. 1 at 10%					0.1		
32	TAB-2.2	Checkpt. val. 2 at 20%					0.2		
33	TAB-2.3	Checkpt. val. 3 at 30%					0.3		
34	TAB-2.4	Checkpt. val. 4 at 40%					0.4		
35	TAB-2.5	Checkpt. val. 5 at 50%					0.5		
36	TAB-2.6	Checkpt. val. 6 at 60%					0.6		
37	TAB-2.7	Checkpt. val. 7 at 70%					0.7		
38	TAB-2.8	Checkpt. val. 8 at 80%					0.8		
39	TAB-2.9	Checkpt. val. 9 at 90%					0.9		
40	TAB-2.10	Checkpt.val.10 at 100%					1.0		

Instrument			Range		Unit	Resolu-tion	Factory setting	System setting	Rem. p.66
Param. No.	Parameter text	Parameter	Min.	Max.					
50	TAB-3.0	As tables 1 and 2							1
	|								
60	TAB-3.10								
70	TAB-4.0	As tables 1 and 2							1
	|								
80	TAB-4.10								

1 For all parameters, which can be illustrated in EUs the possible start and final values are 5-digit figures with arbitrary decimal point position. The numerical volume ranges from −9999 to 99999. The statement “Resolution = 1” means that the parameters can be adjusted by one digit at the last numerical position irrespective of the decimal position selected.

Loop 1 - 4 **Protronic 100**: Loops 1 and 2			Range			Resolu-tion	Factory setting	System setting	Rem. p.71
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit				
	PID Parameter (single-loop, slave controller, master controller)								
1	GAIN G	Controller gain G (active)	0.001	1000	without	0.0001	1		1
2	RESET-TIME	Reset time Tn (active)	0 min	600 min	min	0,0001 min	0.5 min		1, 8
3	RATE TIME	Rate time Tv (active)	0 min	600 min	min	0,0001 min	0.1 min		1, 8
4	RATE GAIN	Rate gain Vv	1	10	without	0.0001	5		
5	MANUAL RESET 1	Manual reset OUT0 (active)	-100	+100	%	0.1	50		1
	Parameter control $G = \frac{GE(U1-U10) + GA(U1E-U1)}{U1E-U10}$ U1 controls G		U1 < U10: G = GA U1 > U1E: G = GE						
6	GAIN LO	G for parameter control	0.001	1000	without	0.0001	1		7
7	GAIN HI	G for parameter control	0.001	1000	without	0.0001	1		7
8	U-GAIN-LO	Value of U1 for GA	Defined as variable U1 through Lx-B02-F07						2
9	U-GAIN-HI	Valaue of U1 for GE							
	Tn control as G control								
10	Tn_LO	Tn for parameter control	0 min	600 min	min	0,0001 min	0.5 min		7, 8
11	Tn_HI	Tn for parameter control	0 min	600 min	min	0,0001 min	0.5 min		7, 8
12	U_Tn_LO	Value of U2 for TnA	Defined as variable U2 through Lx-B02-F10						
13	U_Tn_HI	Value of U2 for TnE							
	Tv control as G control								
14	Tv-LO	Tv for parameter control	0 min	600 min	min	0,0001 min	0.1 min		7, 8
15	Tv HI	Tv for parameter control	0 min	600 min	min	0,0001 min	0.1 min		7, 8
16	U-Tv_LO	Value of U3 for TvA	Defined as variable U3 through Lx-B02-F13						
17	U-Tv_HI	Value of U3 for TvE							
	OUT0 control as G control								
18	MR_LO	OUT0 for parameter control	-100	+100	%	0.1	50		7
19	MR_HI	OUT0 for parameter control	-100	+100	%	0.1	50		7
20	U-MR-LO	Value of U4 for OUT0 start	Defined as variable U4 through Lx-B02-F16						
21	U-MR-HI	Value for U4 for OUT0 end							

Loop 1 - 4 **Protronic 100**: Loops 1 and 2			Range			Resolu-tion	Factory setting	System setting	Rem. p.71
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit				
	Parameter for split range (only displayed in case of configured split range or three-step control)								
25	GAIN 2	Controller gain G (active)	0.001	1000	without	0.01 min	1		1, 7
26	RESET-TIME 2	Reset time Tn (active)	0 min	600 min	min	0,0001 min	0.5 min		1, 7, 8
27	RATE TIME 2	Rate time Tv (active)	0 min	600 min	min	0,0001 min	0.1 min		1, 8
28	RATE GAIN 2	Rate gain Vv2	1	10	without	0.0001	5		
29	MANUAL RESET 2	Manual reset OUT0 (active)	-100	+100	%	0.1	50		1
	Parameter control split range								
	G2 control variable as G1								
30	GAIN2_LO	G for parameter control	0.001	1000	without	0.01	1		7
31	GAIN2_HI	G for parameter control	0.001	1000	without	0.01	1		7
	Tn2 control variable as Tn1								
32	Tn2-LO	Tn for parameter control	0 min	600 min	min	0,0001 min	0.5 min		7, 8
33	Tn2_HI	Tn for parameter control	0 min	600 min	min	0,0001 min	0.1 min		7, 8
	Tv2 control variable as Tv1								
34	Tv2_LO	Tv for parameter control	0 min	600 min	min	0,0001 min	0.1 min		7, 8
35	TV2_HI	Tv for parameter control	0 min	600 min	min	0,0001 min	0.1 min		7, 8
	OUT02 control variable as Y01								
36	MR2_LO	OUT0 for parameter control	-100	+100	%	1	50		7
37	MR2_HI	OUT0 for parameter control	-100	+100	%	1	50		7
	Smith Predictor								
39	DEAD-TIME Tt	acive dead time Smith Predictor	0.01 min	60 min	min	0,0001 min	0.01 min		
40	MODEL TIME T1	Time constant for Smith Predictor (active)	0.01 min	600 min	min	0,0001 min	0.01 min		
41	MODEL GAIN Gs	Gain of Smith Predictor	0.0001	100	without	0.0001	1		
	Parameter control Smith Predictor								
	Td control as G control								
42	Td_LO	Dead time for parameter control	0 min	60 min	min	0,0001 min	0.01 min		7
43	Td_HI	Dead time for parameter control	0 min	60 min	min	0,0001 min	0.01 min		7
44	U-Td_LO	Value for U5 for Td_LO	Defined as variable U5 through Lx-B02-F19						
45	U-Td_HI	Value for U5 for Td_HI							

Loop 1 - 4 **Protronic 100**: Loops 1 and 2			Range						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolu-tion	Factory setting	System setting	Rem. p.71
	T1 control as G control								
46	T1_LO	T1 for parameter control	0.0 min	600 min	min	0.01 min	0.01 min		7
47	T1_HI	T1 for parameter control	0.0 min	600 min	min	0.01 min	0.01 min		7
48	U-T1_LO	Value for U6 for T1_LO	Defined as variable U6 through Lx-B02-F22						
49	U-T1_HI	Value for U6 for T1_HI							
50	Gs_LO	Gs for parameter control	0.001	100	without	0.0001	1		
51	Gs_HI	Gs for parameter control	0.001	100	without	0.0001	1		
52	U-Gs_LO	Value for U7 for Gs_LO	control variable U7 is defined through x-B02-F25						
53	U-Gs_HI	Value for U7 for Gs_HI							
	Controller output								
55	DEAD ZONE	Dead zone	0	25	%	0.1	1		
56	PULS DURAT.	Minimum ON period Step controller	0	5 s	s	0.05	0.05		
57	N PER min_1	Transfers per minute Z1	0.05	60	1/min	0.05	6	6	
58	N PER min_2	Transfers per minute Z2	0.05	60	1/min	0.05	6	6	
67	OUT-MIN	Control variable min.	-5	100	%	0.1	0		
68	OUT-MAX	Control variable max.	0	105	%	0.1	100		
69	RAMP OUT +	Output variable ramp rising	0.1	9999	%/s	0.001	9999		
70	RAMP OUT −	Output variable ramp falling	0.1	9999	%/s	0.001	9999		
71	OUT S1	Safety control outp. 1	−5	105	%	0.1	0		
72	OUT S2	Safety control outp. 2	−5	105	%	0.1	0		

Loop 1 - 4 **Protronic 100**: Loops 1 and 2			Range						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolu-tion	Factory setting	System setting	Rem. p.71
	Set points and alarms								
75	Sp_MIN	Set point min.	−9999	99999	EU	1	−9999		4
76	SP_MAX	Set point max.	−9999	99999	EU	1	99999		4
77	RAMP SP +	Set point ramp rising	0.0001	99999	EU/s	0.0001	99999		
78	TOL.RAMP SP+	Permissible difference between set point and actual value (Ramp stop)	0	99999	EU	1	99999		4
79	RAMP SP -	Set point ramp falling	0.0001	99999	EU/s	0.0001	99999		
80	TOL.RAMP SP-	as 63	0	99999	EU	1	99999		4
81	SP1	Set point 1	−9999	99999	EU	1	0		4
82	SP2	Set point 2 or delta for set point 1	−9999	99999	EU	1	0		4
83	SP3	Set point 3 or delta for set point 1	−9999	99999	EU	1	0		4
84	SP4	Set point 4 or delta for set point 1	−9999	99999	EU	1	0		4
	Alarm values								
91	ALARM 1	Alarm value 1	−9999	99999	EU	1	−9999		4
92	ALARM 2	Alarm value 2	−9999	99999	EU	1	99999		4
93	ALARM 3	Alarm value 3	−9999	99999	EU	1	99999		4
94	ALARM 4	Alarm value 4	−9999	99999	EU	1	99999		4
95	HYSTERESIS	Hysteresis	0	99999	EU	1	1		
96	TIME-UNIT	Time unit for dx/dt alarm value	1	3	without	1 = s 2 = min 3 = h	1		5
	Weighting factors of the input circuits								
101	K1	Weighting factor in input signal connection	−9999	+99999		0.0001	1.00		
102	K2	Weighting factor in input signal connection	−9999	+99999		0.0001	1.00		
103	K3	Weighting factor in input signal connection	−9999	+99999		0.0001	1.00		
104	K4	Weighting factor in input signal connection	−9999	+99999		0.0001	1.00		
	Ratio 1: Err = PV - [R × PV1 + Bias] **Ratio 2: Err = PV -[(R / (1 - R)) × PV1 + Bias]**								
115	RATIO MIN	Ratio min.	0	99999	EU	0.0001	0.00		
116	RATIO MAX.	Ratio max.	0	99999	EU	0.0001	2.00		
117	BIAS	Bias ratio control	−9999	99999	EU	0.0001	0		

Loop 1 - 4 **Protronic 100**: Loops 1 and 2			Range						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolution	Factory setting	System setting	Rem. p.71
	Disturbance value feedforward								
120	FF:TIME-CONST	Time constant d/dt	0.00.01 h	1.00.00	h.mm.ss	0	0.00.15 h		
121	FF:DIFF-GAIN	Differential gain	0	10	without	0.1	1		
	Selftune								
125	dY-AMOUNT	1. positioning step	-100.0	+100.0	%	0.1	5.0		
126	MAX.OUT. DUR.	Max. step duration	0.00.09 h	20.00 h	h.mm.ss	1 s	15 s		
127	MAX.POS. ERR	Max. permissible positive control deviation	0.0001	99999	EU	0.0001	99999		
128	MAX.NEG. ERR	Max. permissible negative control deviation	0.0001	99999	EU	0.0001	99999		
199	Keys ▲ and ▼ act on text line	TAG name A...Z, a...z, +,. , /, %, _,), (, °, 9...0, spacing, -, 12 character	Default entry '------------'						3, 9

1 Active parameter. Can be set if no parameter control has been configured. This value will only be displayed if a parameter control has been configured.

2 The units for U1 to U8 depend on the variables to be controlled. If PV or SP is controlling, then U1 to U8 are in EU (e.g. °C); if OUT is controlling, the unit is %.

3 Using the keys <▼> and <▲> in conjunction with <Ind>, the text is input by scrolling the letters and the numerals.

4 The value is set in EU. 1 EU corresponds to the first significant digit left of the desired decimal point position.

5 Selection possibilities, min, h. If alarm values for monitoring the rate of change have been configured, the value is set with the alarm value parameter and the time constant set with parameter 96.

Example: Set alarm value for 15 °C per minute:
Parameter 96 = “min”, alarm value = 15 °C.
AL1: Lx-B08-F01 = 11
Lx-P91 = 15
Lx-P96 = 2

6 The minimum switch-on time and the minimum switch-off time are calculated as follows:

$t_{on,min} = t_{off,min} = 60\ s / 4 \times N$, N = 6 / min
$t_{on,min} = t_{off,min} = 2.5\ s$

7 Without function if controlled via table.

8 0 min switches I- or D part off.

9 9-digit for the versions prior to 1.174

Programmer

The tables for programs 1 to 10 can only be edited after the programmer has been activated as set point source in a loop (Lx-B05-F08 = 1) and the respective program (P-B01-Fx > 0) has been activated.

Program 1			Ranges						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolution	Factory setting	System setting	Rem. p.70
01	VALUE 1.0	Start value, value 0	−9999	99999	EU	1	−9999		
02	VALUE 1.1	Value 1					−9999		
00	VALUE 1.2	Value 2					−9999		
04	VALUE 1.3	Value 3					−9999		
		|					−9999		
15	VALUE 1.14	Value 14					−9999		
16	VALUE 1.15	Value 15					−9999		
17	TIME 1.1	Time for segment 1	0.00.00 h	99.59. h	h.mm.ss	v	0.10.00 h		1
18	TIME 1.2	Time for segment 2					0.10.00 h		
		|					0.10.00 h		
30	TIME 1.14	Time for segment 14					0.10.00 h		
31	TIME 1.15	Time for segment 15					0.10.00 h		
	Binary track								
32	SEGMENT1 BIN.	Section 1 (0 = off, 1 = bin. marker 1, 2 = bin. marker 2, ...	0	15 (1+2+ +4+8)	without	1	2		
33	SEGMENT2 BIN	Segment 2					2		
		|					2		
45	SEGMENT14 BIN	Segment 14					2		
46	SEGMENT15 BIN	Segment 15					2		
	Loop								
47	PGR.LOOP_BEG	from segment	1	14	without	1	1		
48	PGR.LOOP_END	up to segment	2	15	without	1	15		
49	# OF LOOPS	Number of loop executions	1	9999	without	1	1		

Program 1			Ranges						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolution	Factory setting	System setting	Rem. p.70
50	TOL.SEG1	If the measured value deviates from the setpoint by more than the set tolerance, the program sequence in ramps is stopped. The holding time only begins once the set point has reached the holding time and the measured value is within the tolerance on the set point.	0	99999	EU	1	99999	3	
51	TOL.SEG2								
52	TOL.SEG3								
63	TOL.SEG14								
64	TOL.SEG15								

Program 2			Ranges						
Param.-No.	Parameter text	Parameter	Min.	Max.	Unit	Resolution	Factory setting	Sytem setting	Rem. p.70
01	VALUE 2.0	Start value, value 0	−9999	99999	EU	1	−9999		
02	VALUE 2.1	Value 1					−9999		
to									
64									

to

Program 10			Ranges						
Param.-Nr.	Parameter-text	Parameter	Min.	Max.	Unit	Resolution	Factory setting	System setting	Rem. p.70
01	VALUE 10.1	Start value, value 0	−9999	99999	EU	1	−9999		
02	VALUE 10.2	Value 1					−9999		
to									
64									

1 The resolution varies according to the momentary time value. In the lower range (display “0.00.00”) the resolution amounts to one second, in the upper range (display “00.00”) the resolution amounts to 1 minute.

Configuration tables

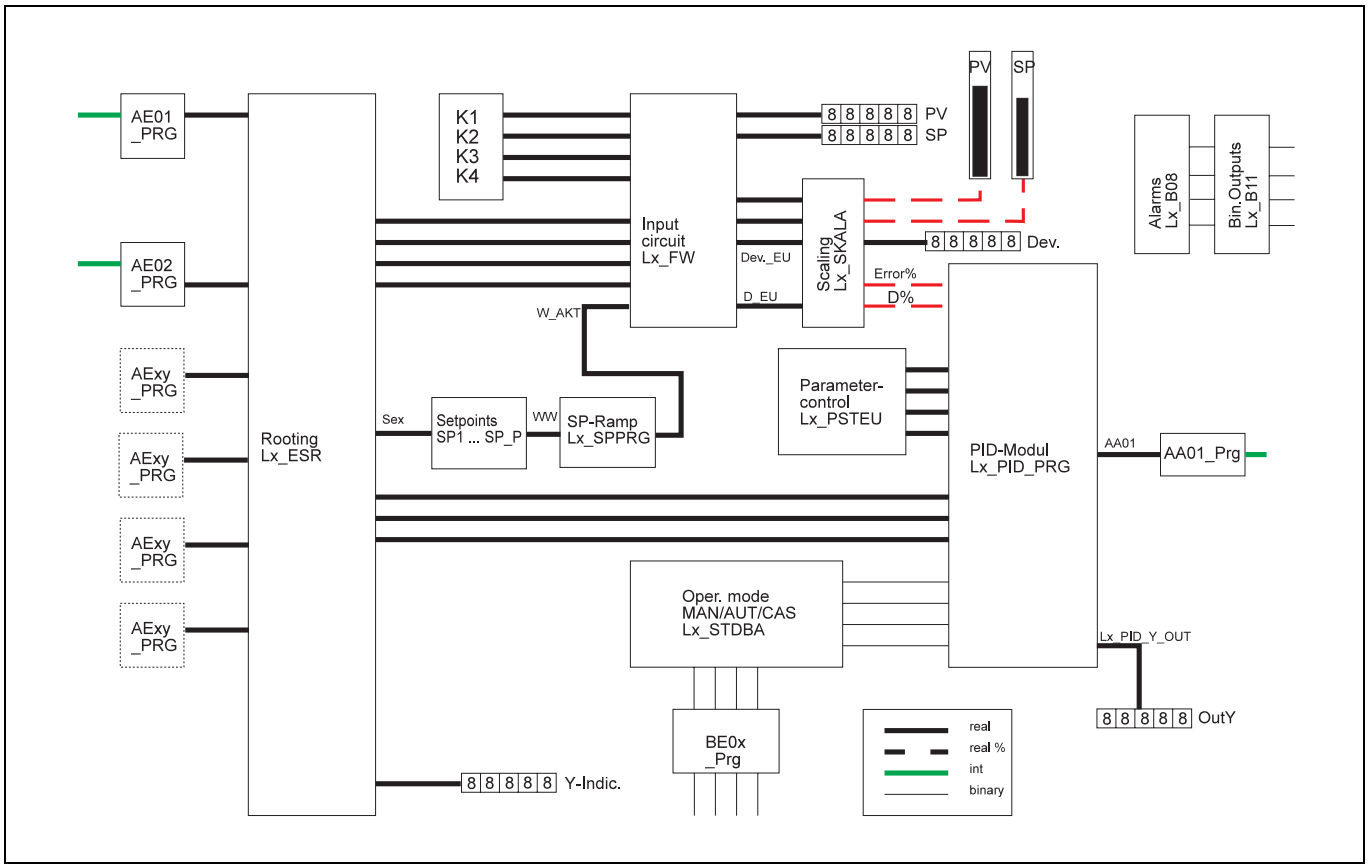


Fig. 94 Configuration - Factory setting

Important information

1. If a free Configuration is loaded, only a part of the following described configuration modules and queries are accessible.

   These are characterized by “fC” (see 2.)

2. Meanings in der “Response” column
   D = Digitric 100,
   1 = Protronic 100,
   5 = Protronic 500/550,
   • = available,
   − = not available,
   fC = free Configuration and
   + = changeable via key despite free Configuration.

3. The factory setting is underlined.

4. Instead of the values quoted for Protronic 500/550:
   − AI74,
   − AO73,
   − BI76 and BO76,
   the following values are for Protronic 100:
   − AI02,
   − AO01,
   − BI02 and BO02, and
   the following values are for Digitric 500:
   − AI44,
   − AO43,
   − BI46 and BO46.

5. Any other differences between the controllers are marked at the appropriate position.

Instrument							Function	Rem. p.78
Module	Query Param.	Response						
01						***LANGUAGE***		
	Q01	D	1	5	fC			
		•	•	•	+	1 DEUTSCH	German texts	
		•	•	•		2 ENGLISH	English texts	
		•	•	•		3 FRENCH	French texts	
		•	•	•		4 ...	...	
02						***BINARY INPUTS***		
	Q01	D	1	5	fC		Inhibition of parameter def. and confi. levels	
		•	•	•	+	0 LOCK PAR OFF	no inhibition	
		•	•	•		1 LOCK PAR.BI01	with BI01	
		•	•	•		|	|	
		•	•	•		4 LOCK PAR.BI04	with BI04	
		•	–	•		|	|	
		•	–	•		46 LOCK PAR.BI46	with BI46	
		–	–	•		|	|	
		–	–	•		76 LOCK PAR.BI76	with BI76	
	Q02	D	1	5	fC		Inhibition of all operator interventions	
		•	•	•	+	0 LOCK OP.BIOFF	no hardware inhibition	
		•	•	•		1 LOCK OP.BI01	BI01	
		•	•	•		|	|	
		•	•	•		4 LOCK OP.BI04	BI04	
		•	–	•		|	|	
		•	–	•		46 LOCK OP.BI46	BI46	
		–	–	•		|	|	
		–	–	•		76 LOCK OP.BI76	BI76	
	Q03	D	1	5	fC		Alarm acknowledgement with bin.inp.	
		•	•	•	+	0 NO ALM.QUIT	No alarm acknowledgement with bin.inp.	
		•	•	•		1 QUIT ALM.BI01	BI01	
		•	•	•		|	|	
		•	•	•		4 QUIT ALM.BI01	BI04	
		•	–	•		|	|	
		•	–	•		46 QUIT ALM.BI46	BI46	
		–	–	•		|	|	
		–	–	•		76 QUIT ALM.BI76	BI76	
03						***BINARY FLAGS***		
	Q01	D	1	5	fC		Flag1 coupled with binary-input / output	
		•	•	•		0 FLAG1_BX._OFF	not coupled	
		•	•	•		1 FLAG1_Bx01	Bx01	
		•	•	•		|	|	
		•	•	•		4 FLAG1_Bx04	Bx04	
		•	–	•		|	|	
		•	–	•		46 FLAG1_Bx46	Bx46	
		–	–	•		|	|	
		–	–	•		76 FLAG1_Bx76	Bx76 x = I or O	
	Q02- Q06	like Flag 1					like Flag 1	
04						***REMOTE OPERATION*** via port or binary inputs		
	Q01	D	1	5	fC		Local/Remote	
		•	•	•	+	1 LOCAL OPER.	Local operation on unit only	
		•	•	•		2 LOC/REM	Local operation on unit or via port Changeover in operation 2	
		•	•	•		3 REMOTE	Local operation via port only	
		•	•	•		4 LOCAL & REMOTE	Local operation equally on unit or via port	

Instrument							Function	Rem. p.78
Module	Query Param.	Response						
05							***BINARY OUTPUTS***	
	Q01	D	1	5	fC		Self-test	
		•	•	•		0 SELFTEST=NO_BO	No output	
		•	•	•		1 SELFTEST BO01	BO01	2
		•	•	•		|	|	
		•	•	•		4 SELFTEST BO04	BO04	
		•	–	•		|	|	
		•	–	•		46 SELFTEST BO46	BO46	
		–	–	•		|	|	
		–	–	•		76 SELFTEST BO76	BO76	
	Q02	D	1	5	fC		Error in telegram communication	
		•	•	•		0 COM_ERR=NO_BO	No output	
		•	•	•		1 COM_ERR=BO01	BO01	2
		•	•	•		|	|	
		•	•	•		4 COM_ERR=BO04	BO04	
		•	–	•		|	|	
		•	–	•		46 COM_ERR=BO46	BO46	
		–	–	•		|	|	
		–	–	•		76 COM_ERR=BO76	BO76	
10							***ALARM TREATMENT***	
	Q01	D	1	5	fC		Alarm ind Alarm texts are not displayed on front panel	
		•	•	•	+	0 ALM_IND_OFF	Alarm text are displayed	
		•	•	•		1 ALM_IND_ON		
	Q02	D	1	5	fC		Alarm acknowledgement	
		•	•	•	+	0 QUIT_OFF	No acknowledgement envisaged	
		•	•	•		1 QUIT_SINGLE	Only the alarm displayed is acknowledged	
		•	•	•		2 QUIT_ALL	All alarms are always acknowledged	
11							***MODULE ASSIGNMENT***	
	Q01	D	1	5	fC			1
		•	•	•		0 B12:MANUAL	Modules must be input manually in G-B12	
		•	•	•		1 B12:AUTOMATIC	Unit recognizes the existing modules	
12							***MODULE PRESETTING***	
	Q01	D	1	5	fC		Slot 1	
		•	–	•	+	0 M1=UNUSED	free	
		•	–	•		10 M1=AI4-mV	4 x thermocouple/ mV	
		•	–	•		15 M1=AI2-mAmA i	2 x mA with electrical isolation	
		•	–	•		16 M1=AI2-mAmV i	1 x mA + 1 x thermocouple with isolation	
		•	–	•		17 M1=AI2-mVmA i	1 x thermocouple + 1 x mA with isolation	
		•	–	•		18 M1=AI2-mVmV i	2 x thermocouple with isolation	
		•	–	•		20 M1=AI4 mA p	4 x mA with potential isolation	
		•	–	•		24 M1=AI4-f/t	Frequency or time measurement	
		•	–	•		25 M1=AI4_mA_MUS	4 × mA with transmitter supply	
		•	–	•		30 M1=AI4-Pt-2W	4 x Pt100 2-wire circuit	
		•	–	•		35 M1=AI2-Pt-3/4	2 x Pt100 3/4-wire circuit	
		•	–	•		40 M1=AO3-V	Output 3 x V	
		•	–	•		50 M1=AO3-mA	Output 3 x 20 mA	
		•	–	•		60 M1=BIO6-BIN.	6-fold binary input/output	
		•	–	–		70 M1=BO4-RELAIS	Output 4 x relays	
		•	–	–		2 M1=RS485	Serial interface	
		•	–	•		4 M1=PROFIBUS	PROFIBUS module	

Instrument						Function	Rem. p.78
Module	Query Param.	Response					
12	Q02	D	1	5	fC	Slot 2	
		•	–	•	+	0 M2=UNUSED	free
		•	–	•		10 M2=AI4-mV	4 x thermocouple/ mV
		•	–	•		15 M2=AI2-mAmA i	2 x mA with electrical isolation
		•	–	•		16 M2=AI2-mAmV i	1 x mA + 1 x thermocouple with isolation
		•	–	•		17 M2=AI2-mVmA i	1 x thermocouple + 1 x mA with isolation
		•	–	•		18 M2=AI2-mVmV i	2 x thermocouple with isolation
		•	–	•		20 M2=AI4 mA p	4 x mA with potential isolation
		•	–	•		24 M2=AI4-f/t	Frequency or time measurement
		•	–	•		25 M2=AI4_mA_MUS	4 x mA with transmitter supply
		•	–	•		30 M2=AI4-Pt-2W	4 x Pt100 2-wire circuit
		•	–	•		35 M2=AI2-Pt-3/4	2 x Pt100 3/4-wire circuit
		•	–	•		40 M2=AO3-V	Output 3 x V
		•	–	•		50 M2=AO3-mA	Output 3 x 20 mA
		•	–	•		60 M2=BIO6-BIN.	6-fold binary input/output
		–	•	•		2 M2=RS-485	Serial port
		•	•	•		4 M2=PROFIBUS	PROFIBUS module
	Q03	D	1	5	fC	Slot 3	
		•	–	•	+	0 M3=UNUSED	free
		•	–	•		10 M3=AI4-mV	4 x thermocouple/ mV
		•	–	•		15 M3=AI2-mAmA i	2 x mA with electrical isolation
		•	–	•		16 M3=AI2-mAmV i	1 x mA + 1 x thermocouple with isolation
		•	–	•		17 M3=AI2-mVmA i	1 x thermocouple + 1 x mA with isolation
		•	–	•		18 M3=AI2-mVmV i	2 x thermocouple with isolation
		•	–	•		20 M3=AI4 mA p	4 x mA with potential isolation
		•	–	•		24 M3=AI4-f/t	Frequncy or time measurement
		•	–	•		25 M3=AI4_mA_MUS	4 x mA with transmitter supply
		•	–	•		30 M3=AI4-Pt-2W	4 x Pt100 2-wire circuit
		•	–	•		35 M3=AI2-Pt-3/4	2 x Pt100 3/4-wire circuit
		•	–	•		40 M3=AO3-V	Output 3 x V
		•	–	•		50 M3=AO3-mA	Output 3 × 20 mA
		•	–	•		60 M3=BIO6-BIN.	6-fold binary input/output
		•	–	•		4 M3=PROFIBUS	PROFIBUS module
	Q04	D	1	5	fC	Slot 4	
		•	–	•	+	0 M4=UNUSED	free
		•	–	•		10 M4=AI4-mV	4 x thermocouple/ mV
		•	–	•		15 M4=AI2-mAmA i	2 x mA with electrical isolation
		•	–	•		16 M4=AI2-mAmV i	1 x mA + 1 x thermocouple with isolation
		•	–	•		17 M4=AI2-mVmA i	1 x thermocouple + 1 x mA with isolation
		•	–	•		18 M4=AI2-mVmV i	2 x thermocouple with isolation
		•	–	•		20 M4=AI4 mA p	4 x mA with potential isolation
		•	–	•		24 M4=AI4-f/t	Frequncy or time measurement
		•	–	•		25 M4=AI4_mA_MUS	4 × mA with transmitter supply
		•	–	•		30 M4=AI4-Pt-2W	4 x Pt100 2-wire circuit
		•	–	•		35 M4=AI2-Pt-3/4	2 x Pt100 3/4-wire circuit
		•	–	•		40 M4=AO3-V	Output 3 x V
		•	–	•		50 M4=AO3-mA	Output 3 x 20 mA
		•	–	•		60 M4=BIO6-BIN.	6-fold binary input/output
		•	–	–		2 M4=RS-485	Serial port
		•	–	•		4 M4=PROFIBUS	PROFIBUS module
	Q05	for Protronic 500/550 like slot 3				like slot 3	2

Instrument							Function	Rem. p.78
Module	Query Param.	Response						
12	Q06	D	1	5	fC		Slot 6	2
		–	–	•	+	0 M6=UNUSED	free	
		–	–	•		10 M6=AI4-mV	4 x thermocouple/ mV	
		–	–	•		15 M6=AI2-mAmA i	2 x mA with electrical isolation	
		–	–	•		16 M6=AI2-mAmV i	1 x mA + 1 x thermocouple with isolation	
		–	–	•		17 M6=AI2-mVmA i	1 x thermocouple + 1 x mA with isolation	
		–	–	•		18 M6=AI2-mVmV i	2 x thermocouple with isolation	
		–	–	•		20 M6=AI4 mA p	4 x mA with potential isolation	
		–	–	•		24 M6=AI4-f/t	Frequncy or time measurement	
		–	–	•		25 M6=AI4_mA_MUS	4 × mA with transmitter supply	
		–	–	•		30 M6=AI4-Pt-2W	4 x Pt100 2-wire circuit	
		–	–	•		35 M6=AI2-Pt-3/4	2 x Pt100 3/4-wire circuit	
		–	–	•		40 M6=AO3-V	Output 3 x V	
		–	–	•		50 M6=AO3-mA	Output 3 × 20 mA	
		–	–	•		60 M6=BIO6-BIN.	6-fold binary input/output	
		–	–	•		70 M6=BO4-RELAIS	Output 4 x relay	
		–	–	•		4 M6=PROFIBUS	PROFIBUS module	
	Q07	like slot 6					like slot 6	2
20							***PASSWORD***	
	Q01	D	1	5	fC			
		•	•	•	+	0 PASSWORD_OFF	Password protection is switched off, not activated, but available	
		•	•	•		1 PASSWORD_ON	Password protection is activated	
		•	•	•		2 PASSWORD_TIME	Password protection is activated, but stays off for about 30 s after returning to the operating level.	
	P02	D	1	5	fC		Password definition	
		•	•	•	+	PASSWORD _ _ _ _ _		
30							***COMMUNICATION***	
	P01	D	1	5	fC			
		•	•	•	+	ADDRESS 1...127	Unit address on bus 00 = Global address 1 = Factory setting	
	Q02	D	1	5	fC		Baud rate	
		•	•	•	+	1 300 BAUD	300	
		•	•	•		2 600 BAUD	600	
		•	•	•		3 1200 BAUD	1200	
		•	•	•		4 2400 BAUD	2400	
		•	•	•		5 4800 BAUD	4800	
		•	•	•		6 9600 BAUD	9600	
		•	•	•		7 19200 BAUD	19200	
		•	•	•		8 38400 BAUD	38400	
		•	•	•		9 57600 BAUD	57600 ┐	
		•	•	•		10 115200 BAUD	115200 ├ only for lateral communication	
		•	•	•		11 187500 BAUD	187500 ┘ Protronic 500 / 550, Digitric 500	
	Q03	D	1	5	fC		Protocol	
		•	•	•	+	2 MODBUS_RTU	Modbus RTU	
	Q04	D	1	5	fC		Parity	
		•	•	•	+	0 NONE	no parity test	
		•	•	•		2 EVEN	even	
	Q05	D	1	5	fC		Time out, time monitoring of miss. telegr. on bus	
		•	•	•	+	0 NO TIMEOUT	without monitoring	
		•	•	•		1 SECOND	1 s	
						|	|	
		•	•	•		25 SECONDS	25 s	
	Q06	D	1	5	fC			
		•	•	•		DP-SLAVE-ADDR 1...125	PROFIBUS device address 1 = Factory setting	

Instrument							Function	Rem. p.78
Module	Query Param.	Response						
	Q07	D • • • • • •	1 • • • • • •	5 • • • • • •	fC	<u>0 CFG_I_NONE</u> 1 CFG_I_1WORD 2 CFG_I_2WORDS 3 CFG_I_4WORDS 4 CFG_I_8WORDS 5 CFG_I_16WORDS	Default DP configuration Input data	
	Q08	D • • • • • •	1 • • • • • •	5 • • • • • •	fC	<u>0 CFG_O_NONE</u> 1 CFG_O_1WORD 2 CFG_O_2WORDS 3 CFG_O_4WORDS 4 CFG_O_8WORDS 5 CFG_O_16WORDS	Default DP configuration Output data	

1 Only modules can be configured, which have already been input into the unit.

For the automatic recognition of the existing modules, the query Q01 in module 11 must be answered with 1. Upon acknowledging with the key <Enter>, the slotted modules are recognized and entered into Module 12. The query Q01 is reset to 0.

If modules are to be configured, which are not (yet) available, these must be manually input into the module B12 .

2 Not required for Digitric 500.

AI Definition				Function	Rem. p.81
Module	Query Param.				
01 to ...				***Protronic 100: AI01 ... AI02*** ***Protronic 500/550: AI01 ... AI74*** ***Digitric 500: AI01 ... AI44***	
	Q01	fC +		Signal range Universal used for unused not AI01 and AI02	
			0 AIxy UNUSED	<u>(Factory setting AI11 to AI74)</u>	
			1 AI01 0...20 mA	0...20 mA	
			<u>2 AI01 4...20 mA</u>	<u>4...20 mA</u>	
			3 AI01 TC	Thermocouple	
			4 AI01 RTD-2W	Pt 100 in 2-wire circuit	
			5 AI01 RTD-3W	Pt 100 in 3-wire circuit	
			6 AI01 RTD-4W	Pt 100 in 4-wire circuit	1
			7 AI01 POT.150	Teletransmitter nominal range ca. 150 Ohm	1
			8 AI01 POT.1500	Teletransmitter nominal range ca. 1500 Ohm	
			9 AI01 PERIOD20	Time measurement	6
			10 AIx1 FREQ 10k	Frequency measurement up to 10 kHz	6
			11 AIx1 FREQ 20k	Frequency measurement up to 20 kHz	6,7
			12 AIx1 PULSE	Pulse counter	
			13 AIx1 INCREMNT	Increm. transm. and direct. of rotat. (2 inputs)	
			14 AIx1 INCREM.0	Increm. transm. with zero transm. (3 inputs)	

AI Definition				Function	Rem. p.81
Module	Query Param.				
01	Q02	fC	1 AI01-LINEAR	Linearization linear	
			2 AI01-SQR1	Square rooting (switch-off < PV0)	
			3 AI01-SQR2	Square rooting (linear under PV0)	
			4 AI01-TYPE L	Type L (-200...1000 °C)	
			5 AI01-TYPE J	Type J (-200...1200 °C)	
			6 AI01-TYPE K	Type K (-200...1400 °C)	
			7 AI01-TYPE U	Type U (-200... 600 °C)	
			8 AI01-TYPE R	Type R (0...1700 °C)	
			9 AI01-TYPE S	Type S (0...1800 °C)	
			10 AI01-TYPE T	Type T (-200... 400 °C)	
			11 AI01-TYPE B	Type B (0...1800 °C)	
			12 AI01-TYPE D	Type D (0...2300 °C)	
			13 AI01-TYPE E	Type E (-200...1000 °C)	
			14 AI01-RTD-200	Pt 100 -200 ... 200 °C	
			15 AI01-RTD-450	Pt 100 0 ... 450 °C	2
			16 AI01-RTD-800	Pt 100 -200 ... 800 °C	
			17 AI01-TAB1	Table 1	
			18 AI01-TAB2	Table 2	
			19 AI01-TAB3	Table 3	
			20 AI01-TAB4	Table 4	
	Q03	fC +	0 AI01 DIM NONE	Dimension for AI01 none	
			1 AI01 DIM USER	4-digit user-defined	
			2 AI01 DIM %		
			3 AI01 DIM °C	°C	
			4 AI01 DIM °F	°F automatic range switch-over	
			5 AI01 DIM mbar		
			6 AI01 DIM bar		
			7 AI01 DIM m3/h		
			8 AI01 DIM kg/h		
			9 AI01 DIM t/h		
			10 AI01 DIM l/h		
			11 AI01 DIM hl/h		
			12 AI01 DIM pH		
			13 AI01 DIM mm		
			14 AI01 DIM m		
			15 AI01 DIM m/h		
			16 AI01 DIM mV		
			17 AI01 DIM V		
			18 AI01 DIM mA		
			19 AI01 DIM A		
	P04	fC +	AI01-USER-DIM - - - -	Edit dimension in the display, if Q03 = 1	
to ..	P05	fC +	AI01-SCAL.LO Value	Start of scaling (for sensor automatically in °C) Range: -9999 to 99999 Resolution : 1 Factory setting 0 % of measuring range (0.00000)	4
	P06	fC +	AI01-SCAL.HI Value	End of scaling (for sensor automatically in °C) Range: -9999 to 99999 Resolution : 1 Factory setting 100 % of measuring range (100.00)	4

AI Definition				Function	Rem. p.81
Module	Query Param.				
	Q07	fC	0 AI01 NONE 1 AI01 TREF INT 2 AI01 TREF 0 C 3 AI01 TREF 20C 4 AI01 TREF 50C 5 AI01 TREF 60C	Reference junction compensation no reference junction internal external 0 °C external 20 °C external 50 °C external 60 °C	5
	P08	fC	AI01-SQR Value	Square rooting value of PV0 Range -9999 to +99999, Resolution 0.01 Factory setting 0.0	
	P09	fC	AI01-FILTERT. Value	T-Filter time constant Range 0 to 120 s Resolution 1 s Factory setting 0 s (0.00.00 h)	
	Q10	fC	1 AI01-FAIL.VAL 2 AI01-OLD VAL.	Default value strategy for sensor fault Default value Hold last measured value	
	P11	fC	AI01-FAIL.VAL Value	Default value Range 0 to 102 % Resolution 0.0001 Factory setting 102 %	
	Q12	fC	0 AI01-ERR=N.BO 1 AI01-ERR=BO01 | 76 AI01-ERR=BO76	Error message via BOx No message BO01 | BO76	
	Q13	fC	0 AI01=N.FLG 1 AI01ERR=FLG01 2 AI01ERR=FLG02 3 AI01ERR=FLG03 4 AI01ERR=FLG04 5 AI01ERR=FLG05 6 AI01ERR=FLG06	Error message via Flag No message via Flag 1 via Flag 2 via Flag 3 via Flag 4 via Flag 5 via Flag 6	
	Q15	fC	1 NAMUR + 2 NAMUR − 3 NAMUR +/− 4 24 V POS 5 24 V NEG 6 24 V +/− 7 TTL POS 8 TTL NEG 9 TTL +/−	Pick-up acc. to NAMUR DIN 19 232 positive edge Pick-up acc. to NAMUR DIN 19 232 negative edge Pick-up acc. to NAMUR DIN 19 232 both edges binary signal 0/24 V positive edge binary signal 0/24 V negative edge binary signal 0/24 V both edges TTL signal 0/5 V positive edge TTL signal 0/5 V negative edge TTL signal 0/5 V both edges	6

1 Only for AI01 and module 2_Pt100_3/4L.

2 For modules for Pt 100.

3 Text in unit AIxy-Bxy-Fn
Module number is identical with input number
x = Module on slot, y = input y on module x

4 Scaling is according to the transmitter data. The scaling for the control variable can deviate from this. See Lx-B03-P07, P08.

5 Reference junction only for thermocouple.

6 Only modules.

7 If only one input per module is used.

8 Two pulse inputs required for measuring.

9 Three pulse inputs required for measuring.

AO Definition			function	Rem. p.81
Module	Query Param.			
01 to ...		***Protronic 100: AO01*** ***Protronic 500/550: AO01 ... AO73*** ***Digitric 500: AO01 ... AO43*** (Analog outputs)		
	Q01	fC +	Signal range output AOxy	
		0 UNUSED	unused (not for AO01)	
		1 AO01 DEAD ZERO	0...20 mA	1
		2 AO01 LIFE ZERO	4...20 mA	1
		4 AO01 10 mA	10 mA constant current for current module	
		5 AO01 20 mA	20 mA constant current for current module	
	Q02	fC	Output of impedance monitoring, Output via	
		0 AO01 LD=N.BO	No output	
		1 AO01 LD.=BO01	BO01	
		|	|	
		76 AO01 LD.=BO76	BO76	
	Q03	fC	Error message via Flag	
		0 AO01 LD=N.FLG	No messge	
		1 AO01 LD=FLG01	via Flag 1	
		2 AO01 LD=FLG02	via Flag 2	
		3 AO01 LD=FLG03	via Flag 3	
		4 AO01 LD=FLG04	via Flag 4	
		5 AO01 LD=FLG05	via Flag 5	
		6 AO01 LD=FLG06	via Flag 6	

1 For output module AO3_V:
0...20 mA stands for 0...10 V
4...20 mA stands for 2...10 V

BIO-Definition			Function	Rem. p.81
Module	Query Param.			
01 to ...		***Protronic 100: BIO01 ... BIO 04*** ***Protronic 500/550: BIO01 ... BIO74*** ***Digitric 500: BIO01 ... BIO46***		
	Q01	fC +		1
		0 UNUSED	Unused for modules	2
		1 BI01 DIRECT	Binary 1 = input contact = "1"	
		2 BI01 INVERS	Binary 1 = input contact = "0"	
		3 BO01 ENGISED	Binary 1 = output - operating current	
		4 BO01 DENGISED	Binary 1 = output - quiescent current	

1 In Digitric 500, BO03 and BO04 are designed as relay outputs and cannot be configured as inputs.
Q01 = 0 not for BIO01 to BIO04

2 With free configuration, only the following functions can be exchanged subsequently in the list configuration: function 1 for 3 and/or function 2 for 4.

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
01							***CONTROLLER FUNCTION***	
	Q01	D	1	5	fC			
		•	•	•	+	1 SINGLE LOOP	Single-channel controller	
		•	•	•		3 SLAVE CONTR.	Slave controller in cascade	
		•	•	•		4 OVERR.M.MIN	Min. override adjustment Master controller	
		•	•	•		5 OVERR.M.MAX	Max. override adjustment Master controller	
		•	•	•		8 MANUALSTATION	Single-channel manual station	
		•	•	•		9 SETPT.STATION	Single-channel set point station	
		•	•	•		10 RATIO STATION	Single-channel ratio station	
		•	•	•		11 POSITIONER	Single-channel positioner	
	Q02	D	1	5	fC		Controller output	
		•	•	•		1 CONTINUOUS	K = continuous	
		•	•	•		2 STEP CONTR.	S = step	
		•	•	•		3 ON/OFF CONTR.	Z = two-position	
		•	•	•		5 H-OFF-C (S+S)	D = three position heat-o-cool (relay)	
		•	•	•		6 H-OFF-C (C+S)	D = three-position Heat (cont.)-o-cool (relay)	
		•	–	•		7 SPLIT.R.(C+C)	KK = split range with 2 continuous outputs	
	Q03	D	1	5	fC		Manual characteristic Position display =	
		•	•	•		1 M:CHAR-DIR	Z=K: off / on	
		•	•	•		2 M:CHAR-INV	off / on	
		•	•	•		3 M:INV-DIR	D: out2on / out2off / out1off / out1on	
		•	•	•		4 M:DIR-DIR	=: out2off / out2on / out1off / out1on	
		•	•	•		5 M:INV-INV	KK: out2on / out2off / out1on / out1off	
		•	•	•		6 M:DIR-INV	out2off / out2on / out1on / out1off	
							S: independent of wiring	
							off = permanenty off or 0/4 mA; on = permanently on or 20 mA	
	Q04	D	1	5	fC		y-feedback signal and display	
		•	•	•	+	0 NO PS.FBACK	No y-feedback signal	
		•	•	•		1 POS.FBCK=AI01	AI01	
		•	•	•		2 POS.FBCK=AI02	AI02	
		•	–	•		|	|	
		•	–	•		44 POS.FBCK=AI44	AI44	
		–	–	•		|	|	
		–	–	•		74 POS.FBCK=AI74	AI74	
	Q05	D	1	5	fC		Self-tuning	
					+	0 SELFTUNE OFF	Off	
						1 SELFTUNE1 ON	On	
02							***CONTROLLER PARAMETER***	
	Q01	D	1	5	fC		Aut. characteristic	
		•	•	•		1 A:CHAR.-DIR.	automatic direct action characteristic	
		•	•	•		2 A:CHAR.-INV.	Automatic indirect action characteristic	
	Q02	D	1	5	fC		PI-behaviour	
		•	•	•	+	1 P CONTROL	P (I for step controller)	
		•	•	•		2 PI CONTROL	PI	
		•	•	•		3 PD CONTROL	PD (not with step controller)	
		•	•	•		4 PID CONTROL	PID	
		•	•	•		5 PI+DEADTIME	Smith Predictor with PI	
		•	•	•		6 PID+DEADTIME	Smith Predictor with PID	
	Q03	D	1	5	fC		D compartment connected with	
		•	•	•		1 DIFF. PV	controlled variable	
		•	•	•		2 DIFF. ERROR	Controller deviation	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
02	Q05	D • • •	1 • • •	5 • • •	fC	<u>1 DIFF.BIPOLAR</u> 2 DIFF.POSITIV 3 DIFF.NEGATIV	Differentiation <u>bipolar</u> only positive changes only negative changes	
	Q07	D • • • • • • • • • • • •	1 • • • • • • • • • • • •	5 • • • • • • • • • • • •	fC	<u>0 G CONST</u> 1 G LIN PV 2 G LIN SP 3 G LIN OUT 4 G LIN ERR 5 G LIN |ERR| 7 G TAB1 PV 8 G TAB1 SP 9 G TAB1 OUT 10 G TAB1 ERR 11 G TRANS.ALM4 12 G TRANS=BIx 13 G CONTR.AIx	G control <u>off</u> linear from PV linear from SP linear from Out linear from Err linear from |Err| via Table 1 of PV ┐ via Table 1 of SP | for loop 2-4 via Table 1 of Out ├ Table 2-4 via Table 1 of Err ┘ G changeover with AL4 Parameter 02/03 G changeover with BIx see query 8 G of AIx see query 9	1 2 2
	Q08	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 G TRANS=OFF</u> 1 G TRANS=BI01 | 4 G TRANS=BI04 | 46 G TRANS=BI64 | 76 G TRANS=BI76	G Changeover <u>No G-Changeover</u> Changeover with BI01 Parameter 02/03 | Changeover with BI04 Parameter 02/03 | Changeover with BI46 Parameter 02/03 | Changeover with BI76 Parameter 02/03	
	Q09	D • • • • • – –	1 • • • – – – –	5 • • • • • • •	fC	<u>0 G V. AIx=OFF</u> 1 G V. AI01 2 G V. AI02 | 44 G V. AI44 | 74 G V. AI74	G-Steuer.AIx <u>No G control by AIx</u> controlled by AI01 controlled by AI02 | controlled by AI44 | controlled by AI74	
	Q10-Q12						Tn Control like G	
	Q13-Q15						Tv Control like G	
	Q16-Q18						Y0 Control like G	
	Q19-Q21						Tt Control Smith Predictor like G	
	Q22-Q24						T1 Control Smith Predictor like G	
	Q25-Q27						Ks Control Smith Predictor like G	
	Q28	D • • • • • – – • •	1 • • • – – – – – –	5 • • • • • • • • •	fC	<u>0 FF:ADD=OFF</u> 1 FF:ADD=AI01 2 FF:ADD=AI02 | 44 FF:ADD=AI44 | 74 FF:ADD=AI74 91 FF:ADD=ZK1 92 FF:ADD=ZK2	Disturbance Variable Out + Z <u>No disturbance variable feedforward to Out</u> AI01 adds to Out AI02 adds to Out | AI44 adds to Out | AI74 adds to Out Output state correction 1 adds to Out Output state correction 2 adds to Out	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
	Q29	D	1	5	fC		Disturbance variable adds to Out	
		•	•	•		1 FF:LINEAR	linear	
		•	•	•		2 FF:DIF.BIPOL	different. bipolar	
		•	•	•		3 FF:DIF.UNIPOL+	different. unipolar positive changes	
		•	•	•		4 FF:DIF.UNIPOL-	different. unipolar negative changes	
03							*INPUT CIRCUIT*	
	Q01	D	1	5	fC		Input circuit	
		•	•	•		0 NO INPUT CIRC	Without input signal connection (stations)	1
		•	•	•		1 ONE PV	Fixed value Err = IC1 - SP	
		•	•	•		2 3 COMPONENT	Multicomponents Err = IC1 × K1 - SP + K2 × (IC2 + K3 × IC3)	
		•	•	•		3 MULTIPLICATE	Multiplication Err = IC1 × (IC2 + K3 × IC3) - SP	
		•	•	•		4 RATIO1	ratio1 Err = IC1 - (R × (IC2 + K3 × IC3) + Bias + IC4)	
		•	•	•		5 FIX/RATIO1	Fixed value/ratio1 switchable (1 <-> 4)	
		•	•	•		6 RATIO2	ratio2 Err = IC1 - [(R / (1 - R)) × (IC2 + K3 × IC3) + Bias + IC4]	14
		•	•	•		7 FIX/RATIO2	Fixed value/ratio2 switchable (1 <-> 6)	
		•	•	•		8 EXTR.PV.MAX	Extreme value PV: Err = Max(IC1,..IC3) - SP	
		•	•	•		9 EXTR.PV.MIN	Extreme value PV: Err = Min(IC1,..IC3) - SP	
		•	•	•		10 EXTR.SP.MAX	Extreme value SP: Err = IC1 - Max(SP1,IC2,IC3)	
		•	•	•		11 EXTR.SP.MIN	Extreme value SP: Err = IC1 - Min(SP1,IC2,IC3)	
		•	–	•		12 LOAD AIR	Air control for air (only loop 1)	
		•	–	•		13 LOAD FUEL	Air control for fuel (only loop 2)	
	Q02	D	1	5	fC		Multicomponents - Structure ΣPV = K2 × (IC2 + K3 × IC3)	
							Err= | D | PVan,PVdi | SPan	
		•	•	•		1 3 COMPONENT_01	PV - SP, | ΣPVh | PV | SP	
		•	•	•		2 3 COMPONENT_02	PV+ΣPVh-SP | PV | PV+ΣPVh | SP	
		•	•	•		3 3 COMPONENT_03	PV+ΣPVh-SP | ΣPVh | PV | SP	
		•	•	•		4 3 COMPONENT_04	PV+ΣPVh-SP | ΣPVh | PV+ΣPVh | SP	
		•	•	•		5 3 COMPONENT_05	PV+ΣPVh-SP | PV+ΣPVh | PV+ΣPVh | SP	14
		•	•	•		6 3 COMPONENT_06	PV+ΣPVh-SP | ΣPVh | PV | SP	
		•	•	•		7 3 COMPONENT_07	PV+ΣPVh-SP | PV+ΣPVh | PV | SP	
		•	•	•		8 3 COMPONENT_08	PV-(SP+ΣPVh) | PV | PV | SP	
		•	•	•		9 3 COMPONENT_09	PV-(SP+ΣPVh) | PV | PV | SP+ΣPVh	
							D D component connected with PVan,PVdi Analog and digital display for PV SPan Analog display for SP	
	Q03	D	1	5	fC		Display of the control deviation	
		•	•	•		1 IND.ERR:%	in percent (100 % = measuring range of IC1)	
		•	•	•		2 IND.ERR:EU	in EU like IC1	
	Q04	D	1	5	fC		Dimension for control variable and setpoint (not ratio and multiplication)	
		•	•	•	+	0 P,S NO DIM.	Without dimension	
		•	•	•		1 P,S USER DIM.	4-digit dimension freely definable	
		•	•	•		2 P,S DIM.%	%	
		•	•	•		3 P,S DIM.°C	°C	
		•	•	•		4 P,S DIM.°F	°F with automatic range changeover	
						|		
						etc.	see AI Definition Q03	
	P05	D	1	5	fC		Edit the user dimension	
		•	•	•	+	L1 USER DIM.	(if Q04 = 1)	
						- - - -	see AI Definition Q03	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
03	Q06	D • • • • • •	1 • • • • • •	5 • • • • • •	fC +	0 P,S 10000. 1 P,S 1000.0 2 P,S 100.00 3 P,S 10.000 4 P,S 1.0000 5 P,S FLOAT.PT.	Decimal places for PV, SP 0 decimal places 1 decimal place 2 decimal places 3 decimal places 4 decimal places Display of floating decimal point	
	P07	D •	1 •	5 •	fC	DIG.IND.LO. Value	Scaling for PV, SP Start Factory setting SP = 0,0 Range -9999 to 99999	3
	P08	D •	1 •	5 •	fC	DIG.IND.HI Value	Scaling for PV, R(SP) End Factory setting SP = 100,0 Range -9999 to 99999	3
	Q09	D • •	1 • •	5 • •	fC +	1 RATIO IS/SP 2 ES1, RATIO × ES2	Digital display for ratio Ract and Rset IC1 and R × IC2	
	Q10	D • • •	1 • • •	5 • • •	fC +	0 NO DIM. 1 USER DIM. 2 DIM.= %	Dimension R ratio for ratio and multiplication without dimension (e.g. ratio) 4-digit dimension freely definable % (Factory setting for ratio 2)	
	P11	D •	1 •	5 •	fC +	R USER DIM. - - - -	Edit the user dimension ratio (if Q04 = 1) see AI Definition Q04	
	Q12	D • • • • • •	1 • • • • • •	5 • • • • • •	fC	0 R 10000. 1 R 1000.0 2 R 100.00 3 R 10.000 4 R 1.0000 5 R FLOAT.PT.	Decimal places of R-points for R-display 0 Decimal places 1 Decimal places 2 Decimal places 3 Decimal places 4 Decimal places Display of floating decimal point	
	P14	D •	1 •	5 •	fC	SCAL.RATIO Value	Scaling for ratio Factory setting R = 100.0 Range -9999 to 99999	
	Q15	D • •	1 • •	5 • •	fC	1 ANALOG PV,SP 2 ANALOG RATIO	Analog display for ratio PV1 and R × PV2 Ract and Rset	8
	P16	D •	1 •	5 •	fC	ANALOG.0 Value	Analog.0% s. B03-Q15 Value of analog display for 0 % Factory setting 0.0 Range -9999 to 99999	9
	P17	D •	1 •	5 •	fC	ANALOG.100 Value	Analog.100% see B03-Q15 Value of analog display for 100 % Factory setting 100.0 Range -9999 to 99999	9
	Q18	D • • • • – –	1 • • – – – –	5 • • • • • •	fC	0 PV,R=NO AO 1 PV,R=AO01 | 43 PV,R=AO43 | 73 PV,R=AO73	PV retransmission Current control variable or Ract to Not routed to output Analog output AO01 | Analog output AO43 | Analog output AO73	

Loop 1						Function	Rem. S.96
Module	Query Param.	Response					
04						***ROUTING_ES-AI*** Routing of the analog inputs and the input circuit)	
	Q01	D	1	5	fC	Routing_IC1 IC1 of input circuit connected with:	
		•	•	•		0 ES1=0%	fixed value 0 %
		•	•	•		1 ES1=AI01	AI01 for loop
		•	•	•		2 ES1=AI02	AI02
		•	–	•		|	|
		•	–	•		44 ES1=AI44	AI44
		–	–	•		|	|
		–	–	•		74 ES1=AI74	AI74
		•	–	•		91 ES1=FC_1	Output of the state correction 1
		•	–	•		92 ES1=FC_2	Output of the state correction 2
		•	•	•		94 ES1=TAB4	Output of Table 4
		•	•	•		100 ES1=100%	Fixed value 100 %
	Q02	D	1	5	fC	Routing_IC2 IC2 of the input circuit connected with:	
						like Q01	as IC1
	Q03	D	1	5	fC	Routing_IC3 IC3 of the input circuit connected with:	
						like Q01	like IC1
	Q04	D	1	5	fC	Rangier_IC4 IC4 of the input circuit connected with:	
						like Q01	like IC1
	Q05	D	1	5	fC	TAB4.AI Table 4 connected with	
		•	•	•		0 TAB4 NO.AI	Not individually used
		•	•	•		1 TAB4.AI01	AI01
		•	•	•		2 TAB4.AI02	AI02
		•	–	•		|	|
		•	–	•		44 TAB4.AI44	AI44
		–	–	•		|	|
		–	–	•		74 TAB4.AI74	AI74
	Q06	D	1	5	fC	Routing_B1 Routing of binary signal with BIx	
		•	•	•		0 B1 NO BI	B1 unused
		•	•	•		1 B1=BI01	BI01
		•	•	•		|	|
		•	•	•		4 B1=BI04	BI04
		•	–	•		|	|
		•	–	•		46 B1=BI46	BI46
		–	–	•		|	|
		–	–	•		76 B1=BI76	BI76
05						***SETPOINTS***	
	Q01	D	1	5	fC	Setpoint 1 of controller 1	
		•	•	•		0 SP1.INT=OFF	off
		•	•	•		1 SP1.INT=ON	can only be changed per keys or interface
		•	•	•		2 SP1.INT=TRACK	follows current set point
	Q02	D	1	5	fC	Type SP1 SP1 as parameter (then becomes part of the configuration and can be taken over by other unit per Confi)	
		•	•	•		0 SP1=NO PARAM.	no
		•	•	•		1 SP1=PARAM.	yes is not tracked

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
05	Q03	D • • • • •	1 • • • • •	5 • • • • •	fC	<u>0 SP2.INT=OFF</u> 1 SP2.INT=ON 2 SP2.INT=PARA.FLX 3 SP2=DELTA.PAR 4 SP2=RATIO.TRK	Set point 2 = ratio set point 1 SR1 <u>off</u> Only changeable per key or interface Only operatable at paralevel Delta only operatable at paralevel SR1 follows actual ratio	
	Q04	D • • • •	1 • • • •	5 • • • •	fC	<u>0 SP3.INT=OFF</u> 1 SP3.INT=ON 2 SP3.INT=PARA.FLX 3 SP3=DELTA.PAR	Set point 3 = ratio set point 2 SR2 <u>off</u> Only changeable per key or interface Only operatable at paralevel Delta only operatable at paralevel	
	Q05	D • • • •	1 • • • •	5 • • • •	fC	<u>0 SP4.INT=OFF</u> 1 SP4.INT=ON 2 SP4.INT=PARA.FLX 3 SP4=DELTA.PAR	Set point 4 = ratio set point 3 SR3 <u>off</u> only changeable per keys or interface Only operatable at paralevel Delta only operatable at paralevel	
	Q06	D • • • • • – –	1 • • • – – – –	5 • • • • • • •	fC	<u>0 SP.EXT=OFF</u> 1 SP.EXT=AI01 2 SP.EXT=AI02 | 44 SP.EXT=AI44 | 74 SP.EXT=AI74	External set point <u>off</u> AI01 AI02 | AI44 | AI74	
	Q07	D • •	1 • •	5 • •	fC	<u>0 SP.COMP=OFF</u> 1 SP.COMP=ON	Computer set point <u>off</u> on	
	Q08	D • •	1 • •	5 • •	fC	<u>0 SP.PRGRM=OFF</u> 1 SP.PRGRM=ON	Program transmitter set point <u>off</u> on	4
	Q09	D • •	1 • •	5 • •	fC +	 <u>1 SP:IND/TARGT</u> 2 SP.IND.RAMP	SP Display Display of set point falsified temporarily by ramp <u>Display of the targeted set point</u> Display of the falsified value. The targeted set point is displayed during set point adjustment, 3 s after the last actuating key of the current set point.	
	Q10	D • • • • – –	1 • • – – – –	5 • • • • • •	fC	<u>0 SP.ACT.NO AO</u> 1 SP.ACT=AO01 | 43 SP.ACT=AO43 | 73 SP.ACT=AO73	Current set point to AOx <u>Set point not on output</u> Analog output AO01 | Analog output AO43 | Analog output AO73	
	Q11	D • • •	1 • • •	5 • • •	fC	 <u>0 SP.TRANS=OFF</u> 1 SP1-SP2 BIx 2 SP1-SP4 BIy	SP Changeover Set point changeover <u>off</u> BIx | BIy | Setpoint 0 | 0 | 1 1 | 0 | 2 0 | 1 | 3 1 | 1 | 4 Definition BIx, BIy see B09-Q13, Q14	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
06						***TREND INDICATION***		
	Q01	D	1	5	fC +		Time for trend display in graphic display of Protronic 550	13
		–	–	•		1 TREND 75 sec	Time difference between current time and 1. point on left display edge	
		–	–	•		2 TREND 3 min		
		–	–	•		3 TREND 5 min		
		–	–	•		4 TREND 10 min		
		–	–	•		5 TREND 20 min		
		–	–	•		6 TREND 30 min		
		–	–	•		7 TREND 1 h		
		–	–	•		8 TREND 2 hrs		
		–	–	•		9 TREND 3 hrs		
		–	–	•		0 TREND 5 hrs		
07						***CONTROLLER MODES***		
	Q01	D	1	5	fC		Type of operation	
		•	•	•		1 MODE=MAN/AUTO	Manual/Automatic	
		•	•	•		2 MODE=MAN	only manual	
		•	•	•		3 MODE=AUT	only automatic	
		•	•	•		4 MODE=AUTO_MIN	only automatic, manual adjustment has effect on min. threshold for Out	10
		•	•	•		5 MODE=AUTO_MAX	only automatic, manual adjustment has effect on max. threshold for Out	10
		•	•	•		6 MAN/AUT/CASC	manual/automatic/cascade	
		•	•	•		7 MAN/AUT/DDC	manual/automatic/computer(DDC)	
		•	•	•		8 MAN/DDC	manual/computer(DDC)	
	Q02	D	1	5	fC		SP-Tracking (SP is set to PV)	
		•	•	•		0 TRACK SP OFF	SP1 tracking for Man OFF	
		•	•	•		1 TRACK SP/ACT	SP1 tracking for Man On has effect on SP1 and RAMP	
		•	•	•		2 TRACK SP	SP1 tracking for Man On has effect only on RAMP	
	Q03	D	1	5	fC		DDC function	
		•	•	•		0 DDC=OFF	No DDC	
							In case of computer failure:	
		•	•	•		1 DDC=MAN,HOLD	Manual + last correction value	
		•	•	•		2 DDC=MAN OUT=0	Man. + safety correct. value 0 %	
		•	•	•		3 DDC=MAN OUTS1	Manual + saftey correct. value 1	
		•	•	•		4 DDC=MAN OUTS2	Manual + safety correct. value 2	
		•	•	•		5 DDC=AUTO	begins automatically with last correction value	
		•	•	•		6 DDC=CASC	cascade	
	Q04	D	1	5	fC		SP Back-up	
							Set point in case of computer failure (HOST)	
		•	•	•		0 SP-ACTUAL	Adjusted set point	
		•	•	•		1 SP-COMP.	Computer set point	
		•	•	•		2 PV-ACTUAL	last control variable (PV-tracking)	
	Q05	D	1	5	fC		OM Operation	
							Operation mode after mains resumption	
		•	•	•		1 POWER=OLDMODE	Previous operation mode	
		•	•	•		2 POWER=MAN,HLD	Manual last correction value	
		•	•	•		3 POWER=MAN,0%	Manual safety correct. value 0 %	
		•	•	•		4 POWER=MAN,S1	Manual safety correct. value 1	
		•	•	•		5 POWER=MAN,S2	Manual safety correct. value 2	
	Q06	D	1	5	fC		Operation mode during fault at input (fault on PV)	
		•	•	•		1 ?AI=OLD MODE	No change	
		•	•	•		2 ?AI=MAN,HOLD	Manual, last correction value	
		•	•	•		3 ?AI=MAN,0%	Man., safety correct. value 0 %	
		•	•	•		4 ?AI=MAN,S1	Manual, safety correct. value 1	
		•	•	•		5 ?AI=MAN,S2	Manual, safety corect. value 2	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
08							***ALARMS***	
	Q01	D	1	5	fC		Alarm value 1	
		•	•	•		0 ALARM1=OFF	Alarm value without function	
		•	•	•		1 ALARM1 SP.MIN	Alarm value to PV - Min	
		•	•	•		2 ALARM1 SP.MAX	Alarm value to PV - Max	
		•	•	•		3 ALM1 ERR-MIN	Alarm value to Err - Min	
		•	•	•		4 ALM1 ERR-MAX	Alarm value to Err - Max	
		•	•	•		6 ALM1 |ERR|-MX	Alarm value to |Err| - Max	
		•	•	•		7 AL1 ER-SP%MIN	Alarm value to Err - Min in % of SP	
		•	•	•		8 AL1 ER-SP%MAX	Alarm value to Err - Max in % of SP	
		•	•	•		10 AL1 |ERR|S%,MAX	Alarm value to |Err| - Max in % of SP	
		•	•	•		11 AL1 DX/DT-MAX	Alarm value dx/dt Max	
		•	•	•		12 AL1 RATIO MIN	Alarm value R = Min. for input Ratio	
		•	•	•		13 AL1 RATIO MAX	Alarm value R = Max. for input Ratio	
		•	•	•		14 AL1 OUT-MIN	Alarm value to Out - Min	
		•	•	•		15 AL1 OUT-MAX	Alarm value to Out - Max	
	Q02	D	1	5	fC		Alarm value 2 like alarm value 1	
		•	•	•		2 ALARM2 SP.MAX	default alarm value to PV - Max	
	Q03	D	1	5	fC		Alarm value 3 like alarm value 1	
		•	•	•		3 ALM3 ERR-MIN	Alarm value to Err - Min	
	Q04	D	1	5	fC		Alarm value 4 like alarm value 1	
		•	•	•		4 ALM4 ERR-MAX	Alarm value to Err - Max	
	Q05	D	1	5	fC		Type Alarm 1 adjustable to | displayed in	
		•	•	•		1 ALM1 OP/OP	Operation level | Operation level	
		•	•	•		2 ALM1 PAR/OP	Para-Level | Operation level	
		•	•	•		3 ALM1 PAR/PAR	Para-Level | Para-Level	
	Q06	D	1	5	fC		Type Alarm 2 adjustable to | displayed in	
		•	•	•		1 ALM2 OP/OP	Operation level | Operation level	
		•	•	•		2 ALM2 PAR/OP	Para-Level | Operation level	
		•	•	•		3 ALM2 PAR/PAR	Para-Level | Para-Level	
	Q07	D	1	5	fC		Type Alarm 3 adjustable to | displayed in	
		•	•	•		1 ALM3 OP/OP	Operation level | Operation level	
		•	•	•		2 ALM3 PAR/OP	Para-Level | Operation level	
		•	•	•		3 ALM3 PAR/PAR	Para-Level | Para-Level	
	Q08	D	1	5	fC		Type Alarm 4 adjustable to | displayed in	
		•	•	•		1 ALM4 OP/OP	Operation level | Operation level	
		•	•	•		2 ALM4 PAR/OP	Para-Level | Operation level	
		•	•	•		3 ALM4 PAR/PAR	Para-Level | Para-Level	
09							***BINARY INPUTS***	
	Q01	D	1	5	fC		Changeover to Manual with last Out-value	
		•	•	•		0 MAN.BI OFF	No function	
		•	•	•		1 MAN.BI01	BI01	
		•	•	•		|	|	
		•	•	•		4 MAN.BI04	BI04	
		•	–	•		|	|	
		•	–	•		46 MAN.BI46	BI46	
		–	–	•		|	|	
		–	–	•		76 MAN.BI76	BI76	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
09	Q02	D • •	1 • •	5 • •	fC	<u>1 MAN STATIC</u> 2 MAN DYNAMIC	Dyn.<-->Stat. function depends on duration of bin. input (0 = PREVIOUS MODE, 1 = MAN) Changing 0 to 1 switches MAN-AUT-MAN	7
	Q03	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 CASC.BI AUS</u> 1 CASC.BI01 | 4 CASC.BI04 | 46 CASC.BI46 | 76 CASC.BI76	Cascade BIx Changeover Autom <--> Cascade <u>like query 1</u>	
	Q04	D • •	1 • •	5 • •	fC	<u>1 CASC STATIC</u> 2 CASC DYNAMIC	Dynamic <-> Static function depends on duration of binary input Changing 0 to 1 switches	
	Q05	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 MAN Y=0% BI OFF</u> 1 MAN Y=0% BI01 | 4 MAN Y=0%.BI04 | 46 MAN Y=0%.BI46 | 76 MAN Y=0%.BI76	Changeover to manual mode with Out = 0 % <u>like query 1</u>	7,11
	Q06	D • •	1 • •	5 • •	fC	<u>1 MAN 0%.STATIC</u> 2 MAN 0%.DYNAM	Dynamic <-> Static function depends on duration of the binary input Changing 0 to 1 switches	7,11
	Q07	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 MAN YS1 BI OFF</u> 1 MAN YS1.BI01 | 4 MAN YS1.BI04 | 46 MAN YS1.BI46 | 76 MAN YS1.BI76	Changeover to manual mode with safety output value 1 <u>like query 1</u>	11
	Q08	D • •	1 • •	5 • •	fC	<u>1 MAN YS1 STATIC</u> 2 MAN YS1 DYNAM	Dynamic <-> Static function depends on duration of the binary input Changing 0 tof 1 switches	7,11
	Q09	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 MAN YS2 BI OFF</u> 1 MAN YS2.BI01 | 4 MAN YS2.BI04 | 46 MAN YS2.BI46 | 76 MAN YS2.BI76	Changeover to manual mode with safety output value 1 <u>like query 1</u>	11
	Q10	D • •	1 • •	5 • •	fC	<u>1 MAN YS2 STATIC</u> 2 MAN YS2 02	Dynamic <-> Static function depends on <u>like query 2</u>	7,11
	Q11	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	<u>0 TRCKOUT BI OFF</u> 1 TRCKOUT.BI01 | 4 TRCKOUT.BI04 | 46 TRCKOUT.BI46 | 76 TRCKOUT.BI76	Switch on output tracking (Out = AIxy) like query 1 see Lx-B10-Q10	11

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
09	Q12	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 SRAMP BI OFF 1 SRAMP=0.BI01 | 4 SRAMP=0.BI04 | 46 SRAMP=0.BI46 | 76 SRAMP=0.BI76	Ramp stop static SP ramp stopped. like query 1	
	Q13	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 SP1-4 BIx OFF 1 SP1-4 BIx=BI01 | 4 SP1-4 BIx=BI04 | 46 SP1-4 BIx=BI46 | 76 SP1-4 BIx=BI76	SP changeover: Definition of BIx (B05-Q11) No setpoint changeover with BIx with BI01 | BI04 | BI46 | with BI76	
	Q14	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 SP1-4 BIy OFF 1 SP1-4 BIy=BI01 | 4 SP1-4 BIy=BI04 | 46 SP1-4 BIy=BI46 | 76 SP1-4 BIy=BI76	SP changeover: Definition of BIy (B05-Q11) No setpoint changeover with BIy with BI01 | BI04 | BI46 | with BI76	
	Q15	D • • • • • – –	1 • • • – – – –	5 • • • • • • •	fC	0 SPI-EXT BI OFF 1 SPI-EXT.BI01 | 4 SPI-EXT.BI04 | 46 SPI-EXT.BI46 | 76 SPI-EXT.BI76	SPint <-> SPext static changeover like query 1	
	Q16	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 CHAR BI OFF 1 CHAR BI.BI01 | 4 CHAR BI.BI04 | 46 CHAR BI.BI46 | 76 CHAR BI.BI76	DIR <-> INV static Changeover of characteristic like query 1	
	Q17	D • • • • • – –	1 • • • – – – –	5 • • • • • • •	fC	0 LOCK SP BI OFF 1 LOCK SP.BI01 | 4 LOCK SP.BI04 | 46 LOCK SP.BI46 | 76 LOCK SP.BI76	Locking SP change static Inhibition of the SP adjustment capability with like query 1	
	Q18	D • • • •	1 • • • •	5 • • • •	fC	0 REMOTE BI=OFF 1 REMOTE SP 2 REMOTE OUT 3 A=SP,M=OUT	Enabling of teleadjustment (static) Inhibition of teleadjustment only setpoint (in all operation states) only correction value (in manual) setpoint in automatic, Out in manual	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
09	Q19	D	1	5	fC	0 MORE BI OFF	Teleadjustment (more) 100%/60s- adjustment	
		•	•	•		1 MORE.BI01	with BI01	
		•	•	•		|	|	
		•	•	•		4 MORE.BI04	with BI04	
		•	–	•		|	|	
		•	–	•		46 MORE.BI46	with BI46	
		–	–	•		|	|	
		–	–	•		76 MORE.BI76	with BI76	
	Q20	D	1	5	fC	1 LESS BI OFF	Teleadjustment (less) 100%/60s-adjustment	
		•	•	•		|	with BI01	
		•	•	•		4 LESS.BI04	|	
		•	–	•		|	with BI04	
		•	–	•		46 LESS.BI46	|	
		–	–	•		|	with BI46	
		–	–	•		76 LESS.BI76	|	
							with BI76	
	Q21	D	1	5	fC	0 CR BI OFF	Computation ready	
		•	•	•		1 CR BI01	not used	
		•	•	•		|	via binary input BI01	
		•	•	•		4 CR BI04	|	
		•	–	•		|	via binary input BI04	
		•	–	•		46 CR BI46	|	
		–	–	•		|	via binary input BI46	
		–	–	•		76 CR BI76	|	
							via binary input BI76	
10							***ROUTE OUT*** (Routing of the controller outputs)	
	Q01	D	1	5	fC	0 OUT1 NO AO	Routing Out1 to AOx first continuous controller output to for switching controllers	
		•	•	•		1 OUT1.CON=AO01	Analog output AO01	
		•	•	•		|	|	
		•	–	•		43 OUT1.CON=AO43	Analog output AO43	
		•	–	•		|	|	
		–	–	•		73 OUT1.CON=AO73	Analog output AO73	
		–	–	•				
	Q02	D	1	5	fC	0 OUT2 NO AO	Routing Out2 to AOx second continuous controller output (split range) Unsed	
		•	•	•		1 OUT2.CON=AO01	Analog output AO01	
		•	•	•		|	|	
		•	–	•		43 OUT2.CON=AO43	Analog output AO43	
		•	–	•		|	|	
		–	–	•		73 OUT2.CON=AO73	Analog output AO73	
		–	–	•				
	Q03	D	1	5	fC	0 OUTA NO AO	Routing Out to AOx Diagram of position display Out for switching controllers and split range No output	
		•	•	•		1 OUTA.CON=AO01	Analog output AO01	
		•	•	•		|	|	
		•	–	•		43 OUTA.CON=AO43	Analog output AO43	
		•	–	•		|	|	
		–	–	•		73 OUTA.CON=AO73	Analog output AO73	
		–	–	•				
	Q04	D	1	5	fC	0 OUT1=NO BO	Routing Out1 to BOx First switch contact (for step controller 'more') for continuous controller	
		•	•	•		1 OUT1=BO01	to binary output BO01	
		•	•	•		|	|	
		•	•	•		4 OUT1=BO04	to binary output BO04	
		•	–	•		|	|	
		•	–	•		46 OUT1=BO46	to binary output BO46	
		–	–	•		|	|	
		–	–	•		76 OUT1=BO76	to binary output BO76	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
10	Q05	D	1	5	fC	0 OUT2=NO BO 1 OUT2=BO01 | 4 OUT2=BO04 | 46 OUT2=BO46 | 76 OUT2=BO76	Routing of Out2 to BOx second switch contact (for step controller 'less') for continuous controller to binary output BO01 | to binary output BO04 | to binary output BO46 | to binary output BO76	
	Q06	D	1	5	fC	0 OUT.LIMIT=OFF 1 OUT.LIMIT.AUT 2 OUT.LIMIT=ON	Output limits always inactive (for step controller) active only in automatic operation active in manual and automatic operation	6
	Q08	D	1	5	fC	0 OUT-MAX=PAR 1 OUT-MAX=AI01 2 OUT-MAX=AI02 | 44 OUT-MAX=AI44 | 74 OUT-MAX=AI74	Out-Max int./extern. defined Internal parameter routed through AI01 routed through AI02 | routed through AI44 | routed through AI74	
	Q09	D	1	5	fC	0 OUT-MIN=PARAM. 1 OUT-MIN=AI01 2 OUT-MIN=AI02 | 44 OUT-MIN=AI44 | 74 OUT-MIN=AI74	Out-Min int/extern. defined Internal parameter routed through AI01 routed through AI02 | routed through AI44 | routed through AI74	
	Q10	D	1	5	fC	0 OUT-TRCK=AUS 1 OUT-TRCK=AI01 2 OUT-TRCK=AI02 | 44 OUT-TRCK=AI44 | 74 OUT-TRCK=AI74	Out Track (see B09-Q11) No Out tracking Out = AI01 if BIx Out = AI02 if BIx | Out = AI44 if BIx | Out = AI74 if BIx	
11							***BINARY OUTPUTS***	
	Q01	D	1	5	fC	0 ALARM1.NO BO 1 ALARM1.BO01 | 4 ALARM1.BO04 | 46 ALARM1.BO46 | 76 ALARM1.BO76	Alarm value 1 to output No output BO01 | BO04 | BO46 | BO76	
	Q02	D	1	5	fC	0 ALARM2.NO BO 1 ALARM2.BO01 | 4 ALARM2.BO04 | 46 ALARM2.BO46 | 76 ALARM2.BO76	Alarm value 2 to output like alarm value 1	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
11	Q03	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 ALARM3.NO BO 1 ALARM3.BO01 | 4 ALARM3.BO04 | 46 ALARM3.BO46 | 76 ALARM3.BO76	Alarm value 3 to output like alarm value 1	
	Q04	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 ALARM4.NO BO 1 ALARM4.BO01 | 4 ALARM4.BO04 | 46 ALARM4.BO46 | 76 ALARM4.BO76	Alarm value 4 to output like alarm value 1	
	Q05	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 MAN NO BO 1 MAN NO.BO01 | 4 MAN NO.BO04 | 46 MAN NO.BO46 | 76 MAN NO.BO76	Feedback signal manual to output like alarm value 1	
	Q06	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 AUTO NO BO 1 AUTO NO.BO01 | 4 AUTO NO.BO04 | 46 AUTO NO.BO46 | 76 AUTO NICHT.BO76	Feedback signal automatic to output like alarm value 1	
	Q07	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 CASC.NO BO 1 CASC.NO.BO01 | 4 CASC.NO.BO04 | 46 CASC.NO.BO46 | 76 CASC.NO.BO76	Feedback signal cascade to output like alarm value 1	
	Q08	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 WEXT NO BO 1 WEXT NO.BO01 | 4 WEXT NO.BO04 | 46 WEXT NO.BO46 | 76 WEXT NO.BO76	Feedback signal - external set point like alarm value 1	
	Q09	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 PRG.END NO BO 1 PRG.END NO BO01 | 4 PRG.END NO BO04 | 46 PRG.END NO BO46 | 76 PRG.END NO BO76	Program end signal to output like alarm value 1	

Loop 1							Function	Rem. S.96
Module	Query Param.	Response						
11	Q10	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 PRG.BIN1 NO BO 1 PRG.BIN1 NO BO01 | 4 PRG.BIN1 NO BO04 | 46 PRG.BIN1 NOBO46 | 76 PRG.BIN1 NOBO76	Binary track 1 of the programmer to binary output like alarm value 1	
	Q11	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 PRG.BIN2 NO BO 1 PRG.BIN2 NO BO01 | 4 PRG.BIN2 NO BO04 | 46 PRG.BIN2 NOBO46 | 76 PRG.BIN2 NOBO76	Binary track 2 of the programmer to binary output like alarm value 1	
	Q12	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 PRG.BIN3 NO BO 1 PRG.BIN3 NO BO01 | 4 PRG.BIN3 NO BO04 | 46 PRG.BIN3 NOBO46 | 76 PRG.BIN3 NOBO76	Binary track 3 of the programmer to binary output like alarm value 1	
	Q13	D • • • • • • – –	1 • • • • – – – –	5 • • • • • • • •	fC	0 PRG.BIN4 NO BO 1 PRG.BIN4 NO BO01 | 4 PRG.BIN4 NO BO04 | 46 PRG.BIN4 NOBO46 | 76 PRG.BIN4 NOBO76	Binary track 4 of the programmer to binary output like alarm value 1	
12		***BINARY FLAGS*** (Function of binary flags in display)						
	Q01	D • • • •	1 • • • •	5 • • • •	fC	0 ALARM1.NO FLG 1 ALARM1.FLG1 | 6 ALARM1.FLG6	Alarm value1 Alarm value1 not connected to Flag1 Display with Flag 1 | Display with Flag 6	
	Q02	D • • • •	1 • • • •	5 • • • •	fC	0 ALARM2.NO FLG 1 ALARM2.FLG1 | 6 ALARM2.FLG6	Alarm value 2 like query 1	
	Q03	D • • • •	1 • • • •	5 • • • •	fC	0 ALARM3.NO FLG 1 ALARM3.FLG1 | 6 ALARM3.FLG6	Alarm value 3 like query 1	
	Q04	D • • • •	1 • • • •	5 • • • •	fC	0 ALARM4.NO FLG 1 ALARM4.FLG1 | 6 ALARM4.FLG6	Alarm value 4 like query 1	

1 In split range mode the G control has effect on both controller outputs. If the parameter variation is not desired in a controller output, the values for G start and G end should be set equally.

2 Not for three-position controllers and split range.

3 The difference between Lx-B03-P07 and P08 is the reference value for G. The values must lie within the measuring range limits of the analog input. They can match, they can however also deviate. See examples in Section on ´Fixed value control´.

4 Only available in the loop in which the programmer was first switched. Configure additionally: PG01-P0x.

5 Display in the front require activation of the alarm management for unit: G-B10-Q01 = 1.

6 For step controllers.

7 OLDMODE = previous operation mode

8 Not for Digitric 500.

9 For Digitric 500 for scaling the analog output, when Q18 <> 0.

10 Not for Digitric 500.

11 Invalid for step controllers.

12 Changeable but changes eventually lead to faulty displays.

13 Only Protronic 550.

14 IC3 and IC4 not with Protronic 100.

Loop 2, 4 (Protronic 100: only loop 2)							**function**	**Rem. S.96**
Module	**Query Param.**	**Response**						
01						***CONTROLLER FUNCTION***		
	Q01	**D**	**1**	**5**	**fC**		**Controller function**	
		•	•	•		**0 NO CONTROLLER**	**Unused**	
		•	–	•		**1 SINGLE LOOP**	**Single-channel controller**	
		•	•	•		**2 MASTER CONTR.**	**Master controller in cascade**	
		•	–	•		**3 SLAVE CONTR.**	**Slave controller in cascade (for 2 slave controllers)**	
		•	•	•		**6 OVERR.SL.MIN**	**Min. override controller adjustment**	
		•	•	•		**7 OVERR.SL.MAX**	**Max. override controller adjustment**	
		•	–	•		**8 MANUALSTATION**	**Single-channel manual station**	
		•	–	•		**9 SETPT.STATION**	**Single-channel set point station**	
		•	–	•		**10 RATIO STATION**	**Single-channel ratio station**	
		•	–	•		**11 POSITIONER**	**Single-channel positioner**	**1**
		•	–	•		**12 RAT.STAT.CASC**	**Ratio station in cascade (only loop 4)**	
	Q02	**D**	**1**	**5**	**fC**		**Controller output (not required for Q1 = 2,6,7)**	
		•	•	•		**1 CONTINUOUS**	**K = continuous**	
		•	•	•		**2 STEP CONTR.**	**S = step**	
		•	•	•		**3 ON/OFF CONTR.**	**Z = two-position**	
		•	•	•		**5 H-OFF-C (S+S)**	**D = three-position heat-o-cool (relay)**	
		•	•	•		**6 H-OFF-C (C+S)**	**D = three-position heat (cont.)-o-cool (relay)**	
		•	–	•		**7 SPLIT.R.(C+C)**	**KK = split range with 2 continuous outputs**	
	Q03	**D**	**1**	**5**	**fC**		**Manual characteristic (not required for Q1 = 2, 6, 7, 12)**	
		•	•	•		**1 M-CHAR-DIR**		
		•	•	•		**2 M-CHAR-INV**		
		•	–	•		**3 M:INV-DIR**		
		•	–	•		**4 M:DIR-DIR**		
		•	–	•		**5 M:INV-INV**		
		•	–	•		**6 M:DIR-INV**		

Position display =

	0 %	50 %	100 %
Z=K	off		on
	on		off

D = KK	Out2on	Out2off	Out1off	Out1on
	Out2off	Out2on	Out1off	Out1on
	Out2on	Out2off	Out1on	Out1off
	Out2off	Out2on	Out1on	Out1off
S	depending on the wiring			

off = permanently off or 0/4 mA;
on = permanently on or 20 mA

B01-Q04+Q05 and module 02 to 12 as Loop 1

1 Cascade with two slave controllers and ratio station (see page 50).

Loop 3 (not Protronic 100)						Function	Rem.
Module	Query Param.	Response					
01						***CONTROLLER FUNCTION***	
	Q01	D	1	5	fC	Control function	
		•	–	•		0 NO CONTROLLER	Unused
		•	–	•		1 SINGLE LOOP	Single-channel controller
		•	–	•		2 MASTER CONTR.	Master controller in cascade for 2 slaves.
		•	–	•		3 SLAVE CONTR.	Slave controller in cascade
		•	–	•		6 OVERR.SL.MIN	Override min. override controller adjustment
		•	–	•		7 OVERR.SL.MAX	Override max. override controller adjustment
		•	–	•		8 MANUALSTATION	Single-channel manual station
		•	–	•		9 SETPT.STATION	Single-channel set point station
		•	–	•		10 RATIO STATION	Single-channel ratio station
		•	–	•		11 POSITIONER	Single-channel positioner
	Q02	D	1	5	fC		Controller output (not required for Q1 = 6, 7)
		•	–	•		1 CONTINUOUS	K = continuous
		•	–	•		2 STEP CONTR.	S = step
		•	–	•		3 ON/OFF CONTR.	Z = two-position
		•	–	•		5 H-OFF-C (S+S)	D = three position heat-o-cool (relay)
		•	–	•		6 H-OFF-C (C+S)	D = three-position heat (cont.)-o-cool (relay)
		•	–	•		7 SPLIT.R.(C+C)	KK = split range with 2 continuous outputs
	Q03	D	1	5	fC		Manual characteristic (unnecessary for Q1 = 6, 7)
		•	–	•		1 M-CHAR-DIR	
		•	–	•		2 M-CHAR-INV	
		•	–	•		3 M:INV-DIR	
		•	–	•		4 M:DIR-DIR	
		•	–	•		5 M:INV-INV	
		•	–	•		6 M:DIR-INV	

Position display =

	0 %	50 %	100 %
Z	off		on
	on		off

D	Out2on	Out2off	Out1off	Out1on
=	Out2off	Out2on	Out1off	Out1on
KK	Out2on	Out2off	Out1on	Out1off
	Out2off	Out2on	Out1on	Out1off
S	depending on wiring			

off = permanently off or 0/4 mA;
on = permanently on or 20 mA

B01-Q04+Q05 and module 02 to 12 as Loop 1

Note
The state correction can only be edited, after it has been integrated into the configuration in a loop.

State correction 1/2 (not Protronic 100)			Function								Rem. p.100
Module	Query Param.	Response									
01		***TASK***									
	Q01	D 1 5 fC	State correction								
		• • •	0 UNUSED	Unused							
		• — •	1 GAS ORIF	Gas flow (m3/h) - differential pressure method							
		• — •	2 GAS VOLUM	Gas flow (m3/h) - volume measurement							
		• — •	3 STEAM,ORI	Steam mass flow - differential pressure							
		• — •	4 SATSTEAM,P	Saturated steam pressure correction							
		• — •	5 SATSTEAM,T	Saturated steam temperature correction							
		• — •	6 WATER ORI	Water mass flow - differential pressure							
		• — •	7 WATER VOL	Water mass flow - volume measurement							
		• — •	8 BOIL.LEV.	Tank water level							
		D 1 5 fC	Q01 = >	Required parameters for							
				1	2	3	4	5	6	7	8	
	P02	Qn-CALCUL Value		Qn,r Qm,r	-	Qm,r	Qm,r	Qm,r	Qm,r	-	-	
	P03	dP-CALCUL Value		dP,r	-	dP,r	dP,r	dP,r	dP,r	-	-	
	P04	P-atm-CALCUL Value		Patm,r	Patm,r	Patm,r	Patm,r	-	Patm,r	Patm,r		
	P05	P-CALCUL Value		Pü,r	-	Pü,r	Pü,r	-	Pü,r	Pü,r	-	
	P06	T-CALCUL Value		T,r	-	T,r	-	T,r	T,r	-	-	
	P07	Z-CALCUL (P,r;T,r) Value		Z,r	-	-	-	-	-	-	-	
	P08	RHO-CALCUL Value		RHOnr	RHOnr	-	-	-	-	-	-	
	P10	P-MIN Value		Pmin	Pmin	Pmin	Pmin	-	Pmin	Pmin	Pmin	
	P11	P-MAX Value		Pmax	Pmax	Pmax	Pmax	-	Pmax	Pmax	Pmax	
	P12	T-MIN Value		Tmin	Tmin	Tmin	-	Tmin	Tmin	Tmin	-	
	P13	T-MAX Value		Tmax	Tmax	Tmax	-	Tmax	Tmax	Tmax	-	
	P14	RHO-MIN Value		Rho min	Rho min	-	-	-	-	-	-	
	P15	RHO-MAX Value		Rho max	Rho max	-	-	-	-	-	-	
	P16	DISTANCE Value		-	-	-	-	-	-	-	HAB	
	P17	T-REFERENC Value			-	-	-	-	-	-	Tvgl	1
	Q18	0 OVERPRESSURE 1 ABS. PRESSURE		x x	x x	x x	x x	- -	x x	x x	x x	
	P20	COMP.COEF Z1 Value		Z(1)	Z(1)	-	-	-	-	-	-	
	...	to		...	...	-	-	-	-	-	-	
				1	2	3	4	5	6	7	8	
	P28	COMP.COEF Z9 Value		Z(9)	Z(9)	-	-	-	-	-	-	

State correction 1/2 (not Protronic 100)			Function	Rem. p.100
Module	Query Param.	Response		
	Q29	0 LINEAR 1 SQR	| | - | | | | - | - | No square rooting in the transmitter or in AIxy Square rooting in transmitter or in AIxy	
	P30	RANGE LO Value	0 | 0 | 0 | 0 | 0 | 0 | 0 | Value lower range value of the corrected signal corresponds to 0/4 mA for analog output	0 = pre-set
	P31	Value RANGE HI	upper range value of the corrected signal corresponds to 20 mA for analog output	
	Q32	0 NO DIM. 1 DIM USER DIM. 7 DIM = m³/h 8 DIM = kg/h 9 DIM = t/h | n	Dimension for AI01 No dimension 4-digit, freely definable Q33 m³/h kg/h t/h | see AI-Bxy-Q03	
	P33	DIMENSION - - - -	Editing of the user dimension if query 32 = 1	
02		***ROUTING AI*** (Routing of the analog inputs to the state correction)		
	Q01	D 1 5 fC • – • 1 IFC_Q=AI01 • – • 2 IFC_Q=AI02 • – • | • – • 44 IFC_Q=AI44 – – • | – – • 74 IFC_Q=AI74	Flow measured value, differential pressure when B01-Q01 = 8 AI01 AI02 | AI44 | AI74	
	Q02	D 1 5 fC • – • 0 IFC_P_CALC • – • 1 IFC_P=AI01 • – • 2 IFC_P=AI02 • – • | • – • 44 IFC_P=AI44 – – • | – – • 74 IFC_P=AI74	Pressure measured value (P) in bar Not used P = Pr AI01 AI02 | AI44 | AI74	
	Q03	D 1 5 fC • – • 0 IFC_T_CALC • – • 1 IFC_T=AI01 • – • 2 IFC_T=AI02 • – • | • – • 44 IFC_T=AI44 – – • | – – • 74 IFC_T=AI74	Temperature measured value (T) in °C not used T = Tr AI01 AI02 | AI44 | AI74	
	Q04	D 1 5 fC • – • 0 IFC_DENS=CALC • – • 1 IFC_D=AI01 • – • 2 IFC_D=AI02 • – • | • – • 44 IFC_D=AI44 – – • | – – • 74 IFC_D=AI74	Density measured value in kg/m³ not used Rho = Rhonr AI01 AI02 | AI44 | AI74	
03		***ROUTING AO*** (Routing of the result of the state correction on analog output)		
	Q01	D 1 5 fC • – • 0 FC1=NO_AO • – • 1 FC1=AO01 • – • | • – • 43 FC1=AO43 – – • | – – • 73 FC1=AO73	State correction on analog output No output AO01 | AO43 | AO73	

1 Up to version 3.4.0. Afterwards replaced by T-MIN = T-MAX = Tvgl or direct measured values. Routing ZKx-B02-Q03. Then T-MIN unequal to T-MAX.

Abbreviations and terms

Index “r” for “calculated values” (values for defining orifice)

Qv	Operating volume flow in m^3/h
Qn	Volume flow in standard condition in m3/h
Qm	Mass flow in standard condition t/h
P	in absolute bar or overpressure (depending on the transmitter)
Pr	in absolute pressure
T	Temperature in °C
Pn	Standard pressure 1.0135 bar
Tn	Standard temperature 273,15 K = 0 °C
RHO	Density in kg/m^3
RHO-MIN	Correction range for RHO
RHO-MAX	Correction range for RHO
Patm	atmospheric pressure in absolute bar
Pr	in absolute bar
Zn	Real gas factor for Pn and Tn (compressibility figure)
Pmin/Pmax	Correction range for P (according to transmitter)
Tmin/Tmax	Correction range for T
P20...28	Real gas factors (factory setting 1.00) (compressibility figure)

	Tmin	Tmitte	Tmax
Pabsmin	P20	P23	P26
Pabsmitte	P21	P24	P27
Pabsmax	P22	P25	P28

HAB	Nozzle spacing in mm produces water level in mm.
Tvgl	Temperature of the reference column in °C (up to version 3.4.0. After that replaced by T-MIN = T-MAX = Tvgl or direct measured value. Routing ZKx-B02-Q03. Then T-MIN unequal to T-MAX).

Notice
The programs can only be edited, when the programmer has been activated as set point source in a loop (Lx-B05-Q08 = 1).

Programmer							Function	Rem.
Module	Query Param.	Response						
01							***PROGRAMMER***	
	1	D • • •	1 • • •	5 • • •	fC	0 PROGR1=OFF 1 PG1-START SP0 2 PG1-START PV	Program 1 Not activated, without function Start at programmed value Start at instantaneous value	
	|						Program 2 to 9	
	10	D • • •	1 • • •	5 • • •	fC	0 PROGR10=OFF 1 PG10-START SP0 2 PG10-START PV	Program 10 Not activated, without function Start at programmed value Start at instantaneous value	

Fault messages

Unit fault messages

When reading or writing in the non-volatile flash memory (all controllers) or in the memory card (only Protronic 500/550), faults can occur. These are reported in the upper text line of the display as

!Fault ....

Instead of the four dots, the fault number of the particular fault will be stated (4-digit). Table 10 gives information on the cause and eventual remedy of the faults involved. The input “xy” in a fault number refers to Table 11 on page 99, which provides more exact details on the faults.

It can happen that a fault cannot be remedied, despite the information provided for remedy. In such case, the manufacturer should be informed, supplying the following details:

- unit version,
- firmware version,
- IBIS_*R*/IBIS_*R*+ version,
- action already undertaken,
- configuration,
- project and
- fault number.

Fault messages

Fault number	Fault description	Remarks on fault remedy
32	faults have occured during download of a configuration	reset unit to factory setting and restart the downloading of the configuration after approximately 2 minutes
3100	insufficient flash memory available for storing a configuration	reset unit to factory setting and restart the downloading of the configuration after approximately 2 minutes or reduced configuration and restart the download exercise
3200 3201	internal computing process is incorrect	inform the manufacturer
40xy	a fault has occured during the storage of back documentation information	after approximately 2 minutes of configuration without reverse documentation information, restart the download
41xy	a fault has occured during the storage of the project head	inform the manufacturer
42xy	a fault has occured during the storage of the list configuration	inform the manufacturer
43xy 44xy	a fault has occured during the storage of the project version data	inform the manufacturer
45xy	a fault has occured during the storage of the hardware configuration	inform the manufacturer
46xy	a fault has occured during the storage of the self-tuned variables.	inform the manufacturer
47xy		
48xy	a fault has occured during the storage of changes made on the online parameters	inform the manufacturer
49xy		
60xy	the reverse documentation cannot be read	reset unit to factory setting and restart the downloading of the configuration again, if the error persists, let the Flash-memory be exchanged by the manufacturer

Fault number	Fault description	Remarks on fault remedy
61xy	the project head cannot be read	as 60xy
62xy	the list configuration cannot be read	as 60xy
63xy	the project version data cannot be read	as 60xy
64xy		
65xy	the hardware configuration cannot be read	as 60xy
66xy	the self-tuned variables cannot be read	inform the manufacturer
67xy	the free configuration cannot be read	as 60xy
68xy	the changes in the online parameters cannot be read	as 65xy
69xy		
80xy	general hardware fault	let manufacturer conduct maintenance
81xy	flash memory cannot be initialized completely	as 65xy
82xy	due to grave fault in the flash memory, this has been completely deleted	as 60xy
83xy 84xy 85xy 86xy 87xy		

Tab. 13 Instrument error messages

1 During download of a configuration, it can take up to 2 minutes until the data is stored in the failproof flash memory. In case of power failure during this time, not all configuration parts will be found upon starting.

Fault legend

xy	**Fault description** (refers to flash memory in unit)
0	CRC error when reading a block
1	no free block is found during writing
2	an invalid block number is output during a function call-up
3	a much bigger address offset is stated during a function call-up
4	the flash memory is faulty
5	the flash memory is not available
6	(memory) block not found
7	the stated files were not found
8	(memory) block cannot be deleted
9	power failure
10	power failure during initialization
20	(memory) block content cannot be deleted
21 - 24, 29	incorrectible errors have been made during writing
26	type of memory card invalid
27, 35	no memory card found
28	write protection for memory card active
30	no free storage space available
31 - 34, 36, 39	internal fault
37	read file on memory card is faulty
38	required utility is not available

Tab. 14 Fault legend

Fault messages in the controller self-tune mode

The fault is output in the form

S.Par.Err.X

Here is **X** the fault numbers 1 to 5:

Fault number	Faulty behaviour	Recommendation
1	**general errors**	
	the conditions for a fault-free processing of the self-tune mode are not provided, however, it cannot be clearly determined, if there is any faulty behaviour	restart the self-tuning exercise
2	***rauschband***	
	the *rauschband* determined by the unit itself at the beginning of self-tuning has turned out to be too small in the course of the self-tuning exercise, this is then the case when interferences greatly increase during self-tuning	restart the self-tuning exercise
3	**change of control variable**	
	to be able to analyse the controlled system behaviour, there is too little movement in the controlled system	the definable output variable change should be increased
4	**time overflow**	
	in the controlled system, no movement was determined for a period of 10 hours	the measured value wiring and configuration should be checked for errors, if there are no errors, then the controlled system cannot be identified, due to a too great dead time
5	**no relaxation**	
	within a time window, no relaxation of the controlled system can be perceived, a stationary condition of the controlled system is however necessary for identification	exit the self-tune mode and switch the control loop to “Manual”, wait until the controlled systems no longer show any “visible” movements, restart the self-tuning exercise
6	only for Selftune2	

Tab. 15 Error messages of the controller self-tune mode

Error messages of the input/output level

On switching on the supply voltage, the unit checks the calibration data for the inputs and outputs. If during this, errors are discovered, these are output in clear text.

Error text	Error description	Remarks for error remedy
E_AI01CONF 3	at least one calibration of AI01 has infringed upon the lower alarm threshold only the values required according to configuration AI01-Q01 are checked here	configured mA- or thermocouple input, the signal transmitters can be recalibrated by way of the front panel, in case of Pt100 input, the calibration must be made by the manufacturer
E_AI01CONF 4	at least one calibration value of AI01 has infringed upon the upper alarm threshold only the values required according to configuration AI01-Q01 are checked here	as E_AI01CONF 3
E_AI02CONF 3	at least one calibration value of AI02 has infringed upon the lower alarm threshold	since AI02 can only be configured as mA input, it can be recalibrated via the front panel with the appropriate signal transmitters
E_AI02CONF 4	at least one calibration value of AI02 has infringed upon the upper alarm thershold	as E_AI02CONF 3
E_BIOCONF 3	at least one calibration value from BIO01 to BIO04 has infringed upon the lower alarm threshold	the calibration must be done by the manufacturer
E_BIOCONF 4	at least one calibration value from BIO01 to BIO04 has infringed upon the upper alarm threshold	as E_BIOCONF 3

Tab. 16 Error messages of the input/output level

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General menu overview

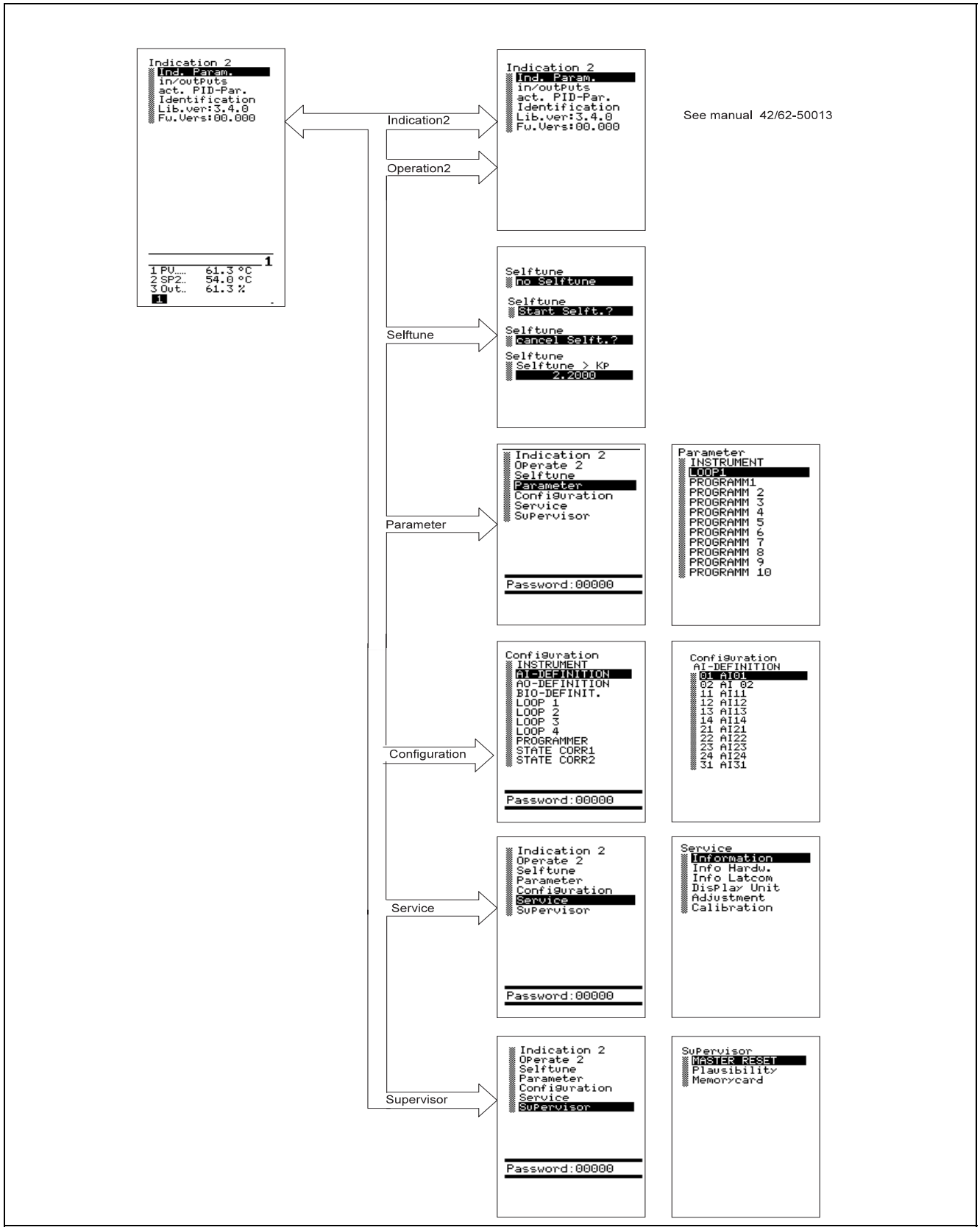

Fig. 95 General menu overview

Subject to technical changes.

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