## 2600T Series Safety Pressure Transmitters

Models 268D/V/P







## **ABB**

## The Company

ABB is an established world force in the design and manufacture of instrumentation for industrial process control, flow measurement, gas and liquid analysis and environmental applications.

As a part of ABB, a world leader in process automation technology, we offer customers application expertise, service and support worldwide.

We are committed to teamwork, high quality manufacturing, advanced technology and unrivalled service and support.

The quality, accuracy and performance of the Company's products result from over 100 years experience, combined with a continuous program of innovative design and development to incorporate the latest technology.

The NAMAS Calibration Laboratory No. 0255(B) is just one of the ten flow calibration plants operated by the Company , and is indicative of ABB dedication to quality and accuracy.

#### EN ISO 9001: 1994



Cert. No. Q5907

ISO 9001: 2000



Cert. No. 9/90A



Cert. No. 0255

#### **Use of Instructions**



#### Warning.

An instruction that draws attention to the risk of injury or death.



#### Caution.

An instruction that draws attention to the risk of damage to the product, process or surroundings.



#### Note.

Clarification of an instruction or additional information.



#### Information.

Further reference for more detailed information or technical details.

Although **Warning** hazards are related to personal injury, and **Caution** hazards are associated with equipment or property damage, it must be understood that operation of damaged equipment could, under certain operational conditions, result in degraded process system performance leading to personal injury or death. Therefore, comply fully with all **Warning** and **Caution** notices.

Information in this manual is intended only to assist our customers in the defent operation of our equipment. Use of this negation and other purpose is specifically prohibited and its contents are not to be reproduced in full or part without prior approal of Technical Communications Department, ABB.

#### **Health and Safety**

To ensure that our products are safe and without risk to health, the following points must be noted:

- 1. The relevant sections of these instructions must be read carefully before proceeding.
- 2. Warning labels on containers and packages must be observed.
- 3. Installation, operation, maintenance and servicing must only be carried out by suitably trained personnel and in accordance ith the information given. Any deviation from these instructions, will transfer the complete liability to the user.
- 4. Normal safety precautions must be taken to avoid the possibility of an accident occurring when operating in conditions of hig pressure and/or temperature.
- 5. Chemicals must be stored away from heat, protected from temperature extremes and powders kept dry. Normal safe handling procedures must be used.
- 6. When disposing of chemicals ensure that no two chemicals are mixed.

Safety advice concerning the use of the equipment described in this manual or any relevant hazard data sheets (where applica) be abtained from the Company address on the back cover, together with servicing and spares information.

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## **INTRODUCTION**

The **2600T** series is a modular range of field mounted, microprocessor based electronic transmitters, using a unique inductive sensing element. Accurate and reliable measurement of differential pressure, gauge and absolute pressure, flow and liquid level is provided, in the even most difficult and hazardous industrial environments.

Now a Safety pressure Transmitter is included in the 2600T Series, with its analog output signal plus HART digital communication.

The HART digital protocol allows remote re-ranging, calibration and diagnostics, without any interference with the standard 4-20 mA analog output signal.

This operating instructions manual describes the Safety version of the 2600T Series transmitters and specify all information necessary to safely connect the Safety 2600T pressure transmitter in a Safety Instrumented System. It details also how the signals from the input field device should be interpreted.

Refer to the shortened contents of this manual, here in this page for addressing the section of your interest, and also to the supplementary documentation for additional remarks.

## SUPPLEMENTARY DOCUMENTATION

Reference information on remote seals and configuration of the transmitter can be found in the following documents:

SS/S26 Remote Seal Specification

SS/268xx Data Sheets

IM / 691HT Hand-Held Communicator

Online HELP SMART VISION Configuration Program

IEC 61508 Functional Safety of e/e/pe Safety-related systems

ISA S84.01 Application of Safety Instrumented Systems for the Process Industries

NE43 Standardization of the signal level for the breakdown information of digital transmitters

Other help ful or general information can be found in the ABB web site, at www.abb.com

### **TRANSPORT**

After final calibration, the instrument is packed in a carton (Type 2 to ANSI/ASME N45.2.2-1978), intended to provide protection from physical damage.

## **STORAGE**

The instrument does not require any special treatment if stored as despatched and within the specified ambient conditions level (Type 2 to ANSI/ASME N45.2.2-1978). There is no limit to the storage period, although the terms of guarantee remain as agreed with the Company and as given in the order acknowledgement.

## **HANDLING**

The instrument does not require any special precautions during handling although normal good practice should be observed.

## PRODUCT IDENTIFICATION

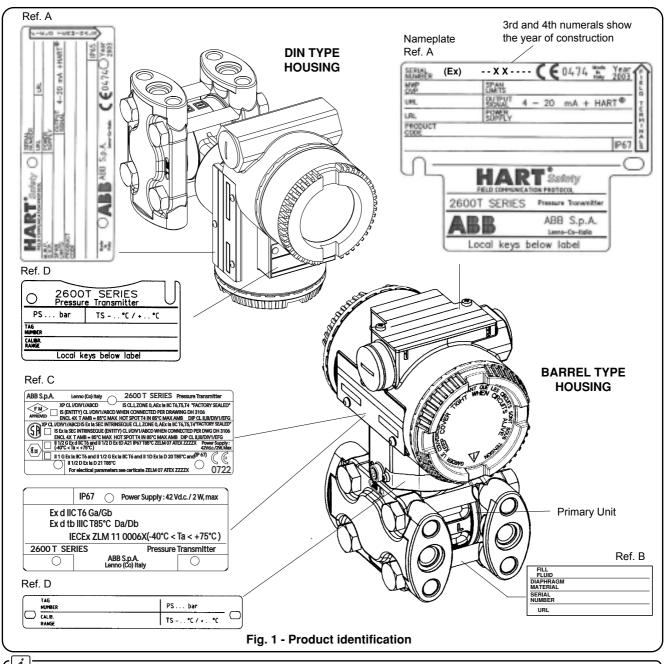
The instrument is identified by the data plates shown in Figure 1.

The Nameplate (ref.A) provides information concerning the code number, maximum process working pressure, range and span limits, power supply and output signal. See code/specification sheet for detailed information. This plate also shows the transmitter serial number.

#### Please refer to this number when making enquiries.

A dedicated label (ref. B) is welded as standard to the primary unit, carrying specific details of the transducer (diaphragms material, fill fluid, range limit and identification number). A Safety Marking plate ( ref. C) is fitted when the transmitter is required to comply with hazardous area regulations, e.g. flameproof or intrinsic safety protection. Additionally Tag plate (ref. D) provides the customer tag number and calibrated range, maximum process working pressure (PS) and temperature (TS).

The instrument may be used as a safety accessory (category IV) as defined by the Pressure Equipment Directive 97/23/EC. In this case, near the CE mark, there is the number of the notified body (0474) that verified the compliance.



## SAFETY PHILOSOPHY

The Safety 2600T Pressure Transmitters are field devices designed according to the requirements of the standard IEC61508 for the Safety Related Systems. Standard currently used focus on individual parts of all the safe instrumentation used to implement a safety function. The IEC61508 defines requirements related to all the system that normally comprises initiating devices, logic solver and final elements. It also introduces the concept of Safety lifecycle defining the sequence of activities involved in the implementation of the safety instrumented system from conception through decommissioning. For a single component it is not correct to define a SIL level. The term SIL (Safety Integrity Level) refers to the complete safety loop therefore the single device shall be designed in order to be suitable to achieve the desired SIL level in the entire Safety Loop.

#### **Application**

The Safety 2600T Pressure Transmitters are intended to be applied for safety relevant application in the process industry. They are suitable to be used in SIL2 applications. Special attention has to be given to the separation of safety and non-safety relevant use.

#### **Physical Environment**

The transmitter is designed for use in industrial field environments and must be operated within the specified environmental limits as indicated in the Transmitter Data Sheet.

#### Role an Responsibilities

All the people, departments and organisations involved in the life-cycle phases which are responsible for carrying out and reviewing the applicable overall, E/E/PES (Electrical/Electronic/Programmable Electronic System) or software safety lifecycle phases of a Safety Instrumented System shall be identified. All those specified as responsible for management of functional safety activities shall be informed of the responsibilities assigned to them. All persons involved in any overall, E/E/PES or software safety lifecycle activity, including management activities, should have the appropriate training, technical knowledge, experience and qualifications relevant to the specific duties they have to perform.

# MANAGEMENT OF FUNCTIONAL SAFETY

For each application the installer of the owner of a safety system must prepare a Safety Planning which must be updated throughout the Safety Life-cycle of the Safety Instrumented System. The requirements for the management of functional safety shall run in parallel with the overall safety lifecycle phases.

#### Safety Planning

The Safety Planning shall consider:

- policies and strategies for achieving safety;
- safety life-cycle activities to be applied, including names of responsible persons and departments;
- procedures relevant to the various life-cycle phases;
- · audits and procedures for follow up.

## **INFORMATION REQUIREMENTS**

The information shall comprehensively describe the system installation and its use in order that all phases of the overall safety lifecycles, the management of functional safety, verification and the functional safety assessment can be effectively performed.

#### **Overall Safety Life-cycle Information**

The overall safety lifecycle shall be used as the basis for claiming conformance to the standard IEC61508. The lifecycle phases consider all the activities related to the Safety Instrumented System (SIS) from the initial concept through design, implementation, operation and maintenance to decommissioning.

## **LIFE-CYCLE ACTIVITIES**

#### **Application Scope**

#### **Definition of the Application Target**

The process equipment shall be described in order to define clearly the application target with its hazard potential.

#### **Applicable LAWS and Standards**

All applicable general Laws and Standards related to the allowed operations of the equipment, as EU-Directives shall be collected. The plant owner shall produce a Regulatory Requirements List document.

#### **Definition of the Application Scope**

The scope for the safety-related application shall be fully described in order to produce the following documentation:

- Safety Integrity Level classification;
- Functional safety requirements of the equipment under control

Necessary steps for the definition of the above listed documents are:

- Detailed investigation about which potential hazards of the process equipment have been reduced by design or an independent layer of protection.
- Checking of the necessary functional requirements required by the applicable laws and Standards.
- Determination of the Safety Integrity Level with a specific risk reduction method.
- Specification of each functional risk reduction by its physical risk, properties to be measured, its safe action to be performed

## <u>Functional Safety Requirements of the Target Equipment</u>

#### **Safety Functions**

The documents:

- Safety Requirement Specification;
- Piping and Instrument Diagram;

Shall be produced in order to fully define the safety functions of the Safety Instrumented System. Necessary steps for the definition of the above listed documents are:

- Definition of the required Safety Functions.
- List of all the process conditions under which the safe action is required.
- Investigation of the effect of common cause failures.
- Specification of the actions required for the process measurement failures which are not covered by the Safety Functions.
- Identification if the required safe actions are dependent on operating states or are effective under all operating states.
- Transformation of the verbal functional requirements into a graphical form.

#### **Process Interface**

The documents:

- Functional Requirement Specification;
- Piping and Instrument Diagram;
- Functional Diagram

Shall be produced in order to fully describe the process interface and connections. Necessary steps for the definition of the above listed documents are:

- Definition of the Process Interface requirements.
- Identification of the instrumentation for every physical risk property (input) and define their fail safe signal.
- Definition of the required amount of instruments and certifications according the SIL requirements
- Identification of the type of actuator and definition of their fail safe position for the required safe action
- Definition of the required redundancy and certification
- Completion of the functional diagram with instrumentation details
- Definition of the necessity of a regulatory body approval;

#### **System Safety Requirement Assignment**

#### I/O System Response Time

The total system response time is determined by the following elements:

- Sensor detection time,
- Logic solver time;
- Actuator response time;

The total system response time must be less than the process safety time. To ensure a safe operation of the system, the scan rate of each section of the logic solver multiplied by the number of channels must be less than the safety time less actuator and sensor response time.

#### I/O System Selection

The I/O system selection is mainly dictated by the required logic solver time. Appropriate selection procedures and analysis shall be used.

#### **System Structure**

System configuration drawings shall be available to describe the equipment and interfaces required for a complete operational system. The system must be fully operational before start-up.

#### **Safety Requirement Allocation**

Each safety function, with its associated safety integrity requirement, shall be allocated to the designated safety-related systems taking into account the risk reductions achieved by the other technology safety-related systems and external risk reduction facilities, so the necessary risk reduction for that safety function is achieved. The allocation indicated shall be done in such a way that all safety functions are allocated and the safety integrity requirements are met for each safety function.

#### **Programming Environment**

Computer system which provides the necessary software to program, compile, and load an application shall be separated.

#### **Safety Routines**

Safety additional requirements may be defined in order to ensure the correct functionality of sequences in the Safety Instrumented System.

#### **Safety Templates**

Safety Templates must be followed for particular applications. (e.g. SIL 2 and burner management applications have certified "Templates" that adhere to all the rules spelled out by the applicable regulations).

#### Separation of Safety Functions

Each safety function shall be separated in a different programming section.

#### .... LIFE-CYCLE ACTIVITIES

#### **Application Software Development**

#### **Programming Environment**

The application software of the Safety 2600T has been developed in ANSI C language. Emulation and system testing have been performed with the support of Mitsubishi ICE development system.

#### **Program Structure for Safety Applications**

The complete software has been separated in a safety relevant and a non-safety relevant sections. The safety relevant area is **Operation** constituted by a set of modules and functions which are rigorously separated and checked in their correct execution.

#### **Safety Logic Programming**

A specific document has been developed to define the basic rules for C-Programming in safety related system applications in compliance with what defined by the IEC 61508-3. The software development of the Safety 2600T has been carried out following the restrictions and recommendation contained in the above mentioned documents.

#### **Program Compilation**

Special accuracy have been used in the software development in order to avoid any error and warnings.

#### **Application Software Testing**

A Safety 2600T transmitter functional test report document has been issued after the operational and the safety related program have gone through their initial check. It verifies that the program will perform as desired and specified.

#### **Application Software Safety Validation**

The Safety 2600T Application Software testing has been carried out and audited by TUV. A Test Report document approved by TUV states that the system reacted in each test as expected and that the safety related program fulfil the Safety Requirement Specification

#### Installation

#### **Environmental Requirements**

The Safety 2600T pressure transmitter has been designed to operate in a wide range of environmental conditions typical of industrial field and in hazardous environments. The environmental conditions under which the measuring equipment is designed to operate within its specified accuracy limits and without impairment of its operating characteristics are specified in the "Specification Sheet" document.

#### Mechanical installation and System completion

All the necessary operations to correctly installing the device in order to assure operator and plant safety are described in the section "installation" of the present manual.

#### **System Wiring**

The procedures to safely make the electrical connections of the device are described in the section "electrical connections" of the present manual. For installation in hazardous areas, compliance with safety information on the safety marking plate shall be ensured.

#### Commissioning

#### **Field Instrument Functionality**

All the necessary activities to assure that the process sensor

or final element are operating together and perform the required function are described in the "Electrical connections" and "Calibration" sections of the present document.

#### **Overall System Functionality**

The activities to validate the required safety functionality of the system together with the target equipment according to the Safety Requirement Specification are Pre-Startup Acceptance test section of the present document.

#### **System Operating Discipline**

A Plant policy guideline document containing the specific plant policy guideline for the daily safe operation has to be produced and periodically reviewed by representatives of the Process Control Service.

#### Maintenance

Maintenance is defined as the routine activities which are carried out to detect unrevealed faults.

#### **Preventive and Routine Maintenance**

Preventive and routine maintenance activities are defined in the maintenance section of the present manual.

#### **Function-unit Replacement**

In case of hardware failure corrective actions may be carried out. In case of transmitter replacement all the operations described in "Electrical Connection", "Calibration" and "Pre-Startup Acceptance tests" shall be conducted.

All maintenance activities shall be documented in the system documentation. Possible safety critical failures shall be reported using the Incident Report process.

#### **Function-unit Repair**

The transmitter is constituted of two main units (transducer and electronics). It can be repaired following the information contained in the Dismantling and Reassembly section of the present manual.

Central repair shall maintain a record of detected failures, calculate actual failure rates and compare with the expected failure rate. Extensive failure rates shall be communicated to the supplier.

#### **Modification Request**

Request of modification due to possible safety critical failures and performance deviations shall be reported to the factory. Modifications shall follow the company modification procedures.

### **Management of Change**

All process changes or SIL category change shall follow the procedures defined in the safety life-cycle of the system and shall be reviewed and validated by the external competent body for a new functional safety assessment.

#### Management of change Process Components and Roles

Each process component needs to be defined in details according to the requirements and the relevant documentation. Each process component change shall follow the activities defined in the overall safety life cycle.

#### Management of change Documentation and Training Requirements

The Management of Change process shall follow documentation and training requirements defined in the system implementation.

## **FAULTS OUTSIDE THE FUNCTIONAL SAFETY**

The redundant algorithms and the electronics are designed to detect all the internal hardware faults therefore the transmitter diagnostic is not able to detect faults related to the process and to the installation configuration. In the following table:

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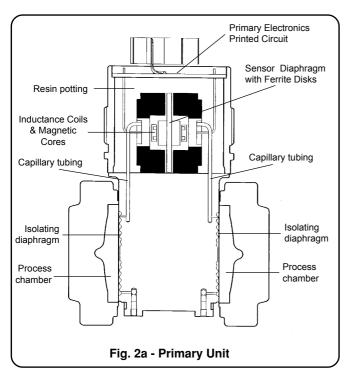
| The reduction of the process are designed to the process are designed to the process and the process are designed to the process are designed to

failure	failure effect	Comments
Assembled material at the pipes of the transmitter, blockage of pipe.	Δp-level measurement is wrong	Piping should be periodically inspected and cleaned.
Application outside specified temperature range. Excess of temperature	wrong measurement	The transmitter should operate inside the specified temperature ranges.
Assembled gas at the transmitter, if the transmitter is mounted above the process line	insensitive, wrong measurement	Transmitter should be installed properly as specified in this manual.
Overload pressure, high peak pressure pulses in process lines	wrong measurement after compression stress	The transmitter should operate inside the specified temperature ranges.
Penetration of hydrogen, diaphragm crack in applications with hydrogen process medium.	insensitive measurement, breakdown	Hydrogen service allowed with the application of a special grace on diaphragms or by using gold plated diaphragms.
Thin walled diaphragm, leaky diaphragm in applications with abrasive medium.	wrong measurement, breakdown	Transmitter manual specifies the preventive periodic maintenance.
Thin walled diaphragm, leaky diaphragm in applications with corrosive medium.	wrong measurement, breakdown	Appropriate materials should be selected for corrosive applications.
Higher diaphragm stiffness, crack in application with contamination of metal ions	insensitive measurement	Appropriate materials should be selected for particular applications.
Mechanical damage through cleaning, damage of the coating, corrosion.	faulty or insensitive measurement, breakdown	Transmitter manual specifies correct maintenance procedures.

#### Other considerations

The alarm levels of the transmitter (down-scale or up-scale) can be selected by the user. For some faults (e.g. crystal breakdown), the output will latch at 22 mA even if the down scale alarm level is selected.

## PRINCIPLE OF OPERATION



The instrument consists of two functional units:

- Primary Unit
- Secondary Unit

The Primary Unit includes the process interface, the sensor and the Primary electronics; the Secondary Unit includes the electronics, the terminal block and the housing. The two units are mechanically coupled by a threaded joint. Electronics are based on custom integrated components (Application Specific Integrated Circuit - ASIC).

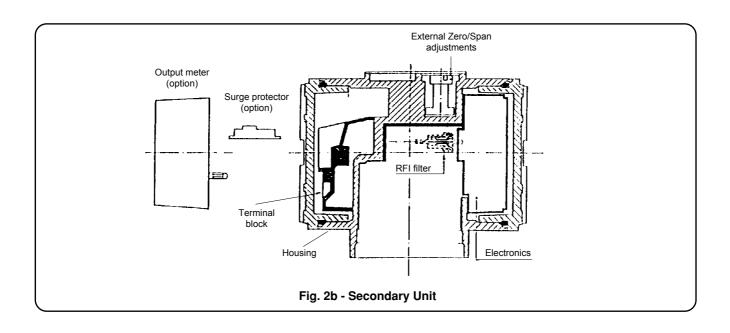
The principle of operation of the Primary Unit is as follows. The process fluid (liquid, gas or vapour) exerts pressure on to the sensor diaphragm via flexible, corrosion-resistant isolating diaphragms and capillary tubing containing the fill fluid (see Fig. 2a).

As the sensor diaphragm deflects in response to differential

pressure changes, it simultaneously produces variations in the gap between two fixed magnetic circuits (comprising coil and ferrite core) positioned on both sides of the measuring diaphragm. As a result, the inductance of each coil changes. The two inductance values L1 and L2, and the sensor temperature ST are combined in the primary electronics to provide a proprietary standardized signal. In the manufacturing process the sensor output characteristics are compared with reference pressures and temperatures: the "mapped" parameters are then stored in the memory of Primary electronics.

The measured values and the sensor parameters are transferred to the Secondary Unit, where a microprocessor computes precise primary output linearisation, compensating for the combined effects of sensor non linearity, of static pressure and temperature changes. In the permanent memory of the secondary electronics are stored the transmitter specific information:

- non modifiable data such as the serial number, the UID (Unique Identifier), the manufacturer's name and device type, the hardware and software version of the electronics.
- the modifiable data such as the final trimming and calibration, in other words, all data that can be changed by the user through the configuration devices.



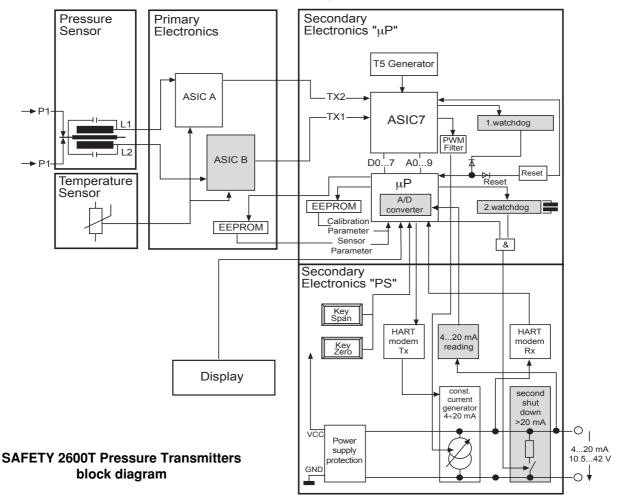
### PRINCIPLE OF OPERATION

2600T Safety Transmitter takes advantage of the intrinsic redundancy of the 2600T series differential inductive sensor. The two inductive signals are separately detected in the primary unit by two independent ASICs and separately elaborated internally to the electronics. Calculations follow independent flows and they are compared in the microcontroller the 4-20 mA signal into a digital form suitable to be compared in order to validate the output pressure signal. If a difference between the two measurements is detected the analog output is driven to a safety condition. Internal diagnostics algorithms are implemented to check correctness and validity of all processing variables and the correct working of memories.

A supplementary shut down circuitry provides a safe shut down when a fault occurs in the analog section of the electronics. The output stage is also checked by reading back the analog output signal. The feedback loop is obtained by an additional A/D converter put at the end of the output stage, which translates by the microcontroller.

### HARDWARE DESCRIPTION General hardware description

The electronic hardware structure is described in the following figure.

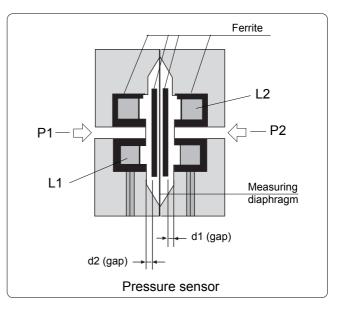


#### **Pressure Sensor**

The pressure sensor gives the primary input signal to the electronics. The input pressure is converted in a (micro) displacement "d" of a metal diaphragm (measuring diaphragm) whose stiffness determines the URL of the sensor. The diaphragm displacement changes the gap of a magnetic circuit, generating the variation of the inductive pick-up detector constituted of two inductances called L1 and L2. One of the inductance values increases the other decreases. The inductance value is measured by forming an oscillator with an extra capacitor (C1,C2). The oscillation is excited by a pulse and simultaneously measured by two ASIC5 (see the picture above). The fundamental frequency of oscillation relates to the inductance values with the following law: (T=2PI\*SQR(LC)).

#### **Temperature Sensor**

The temperature sensor measures the temperature of the pressure sensor. The resulting value is used by the temperature compensation purposes.



## PRINCIPLE OF OPERATION

#### **Primary Electronics**

electronic pulse-width signal. As help for added accuracy both temperatures and static pressure of the transducer are measured.

#### ASIC5

The ASIC5 components contain the basic pulse width converters The internal microprocessor 8 bit A/D converter provides to that convert the input frequency coming from the sensor in two redundant pulse-width signals proportional to the two inductance values L1 and L2. The two independent output time-duration signals from ASIC 5 are applied to the secondary unit through independent lines.

#### **EEPROM1 Memory**

This EEPROM memory is used by the " $\mu$ P" described later. It contains all the relevant information for the sensor characterization and for the transmitter calibration.

## Secondary Electronics "µP"

This unit uses auP and an ASIC to convert the basic measured data into correct scaled data. Compensation for temperature and static pressure are also performed. The output data value is converted into a pulse-width signal that is filtered and that activates the 4-20 mA transmitter. The bi-directional, digital communication using the standard "HART" protocol is implemented as part of this unit.

#### ASIC7

The main input to ASIC7 are the two independent pressure signals combined on two lines from ASIC5 called TX1 and TX2. The ASIC7 converts in two independent counter sections the pulse widths to two sets of five 24 bits numbers (A/D conversion). sensor value as FULL SCALE value. The screws with the The pulse-width information are stored in two different RAM locations and used by the  $\mu P$  to perform all the necessary calculations and consistency checks and to calculate the compensated output with correct scaling. Afterwards the  $\mu P$ writes the calculation results into three 8 bit registers in ASIC7.

#### Watchdog1

A watchdog function is implemented in the ASIC7. It interacts with the μP. In case of error at first the watchdog resets the P. After three retries it drives the PWM output in alarm condition (UP/DOWN scale).

#### **HART Modem**

A modem circuit for demodulation is implemented in the ASIC both for receiving and transmitting.

The  $\mu P$  performs all the calculations and the diagnostic functions. current. It drives also the supplementary shut down in case of errors in the analog part.

#### Reset

There are four reset functions for the µP. "Power On Reset", watchdog reset on ASIC7 request as described above and reset on power supply too low.

#### **PWM Filter**

This first order RC filter gives an average value of the pulse width signal from ASIC 7.

#### **T5 Time Generator**

The ASIC7 generates a temperature dependent current applied to the T5 generation circuit that provides a time duration signal (T5) used to measure the temperature in the secondary electronics.

#### Watchdog2

Main purpose of this unit is to convert the pressure signal to an A secondary watchdog is used to monitor the correct working of the main clock. In case the main clock doesn't work it gives a signal to the supplementary shutdown logic block that provides to force the output in safety condition.

#### 4-20 mA reading

convert to a digital value the analog feedback signal from the 4÷20 mA output current loop. The obtained value is internally compared with the digital value of the actual output current for diagnostic purposes.

#### **EEPROM2 Memory**

The EEPROM2 memory is used by the  $\mu\text{P}$  to store and read configuration data and data concerning calibration of the 4-20 mA generator.

#### Secondary Electronics "PS"

This unit contains the 4-20 mA transmitter, the power supply and the basic analog part of the "HART" protocol.

#### Constant Current Generator 4-20 mA

This block converts the filtered DC voltage representing the pressure into a 4-20 mA current.

#### Local keys

The pressure transmitter has two screws hidden under the nameplate. They can be used for setting ZERO and SPAN values in the unit. The screws turn a magnet, that closes a reed rely, that activates the uP. The ZERO gives the present sensor value as the reference point. The SPAN gives the present magnet can be removed to prevent unauthorized changes.

#### **HART Rx**

The HART modem receiving data are pre-filtered and buffered in this block.

#### Second shut-down

An additional current generator allows having an independent shutdown of the output signal. In case of a failure of the microprocessor due to a clock failure or of a failure in the analog output stage the second shut-down is activated forcing in this way the output signal to the up-scale alarm value.

#### 4÷20 mA reading

A buffer amplifier connected to the microcontroller reads a voltage in the analog output stage proportional to the PWM filtered voltage. It constitutes a feedback signal of the output

#### Display

Optional. Not Safety relevant.

## INSTALLATION

WARNING - For installation in Hazardous Areas, i.e. areas with dangerous concentrations of e.g. gases or dusts that may explode if ignited, the installation must be carried out in accordance with relative standards either EN 60079-14 or IEC 79-14 and/or with local authority regulations, for the relevant type of protection adopted. Together with safety information here and after enclosed see also the Addendum for "Ex Safety" aspects which is part of this instruction manual.

WARNING - In order to ensure operator safety and plant safety it is essential that installation is carried out by suitably trained personnel according to the technical data provided in the Data Sheet for the relevant model included in the supplementary documentation, in particular in the "Operative limits" section.

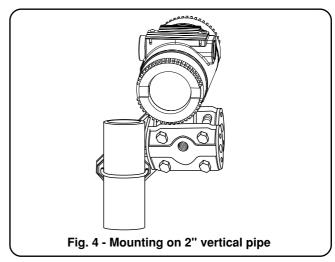
The transmitter may be mounted on a vertical or horizontal 2-inch pipe (figg. 4 and 5) by means of the same mounting bracket.

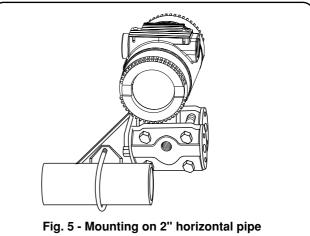
Note: for other installation details see the relevant Addendum.

**WARNING**: The transmitter when installed in accordance with this instruction manual will not be subjected to mechanical stresses.

warning: the transmitter should not be installed where it may be subjected to mechanical and thermal stresses or where it may be attached by existing or foreseable aggressive substances. ABB cannot guarantee that a construction material is suited to a particular process fluid under all possible process conditions. Therefore it is the user responsibility the selection of suitable wetted parts materials and filling fluid.

The secondary unit of the transmitter may be rotated through 360° approx. with respect to the primary unit without degrading performance or damaging the internal wiring. Do not force the primary unit to rotate; use the 2 mm Allen key supplied to unlocand lock the tang grub screw (see Fig. 7). This feature, obtained by unscrewing (one turn is sufficient) the Allen screw, is particularly useful for reaching optimum access to the electrical connections and visibility of the output indicator.

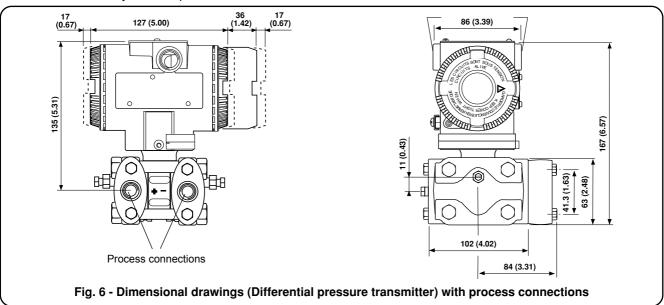




CAUTION - Proper location of the transmitter with respect to the process pipe will depend upon the service for which the instrument is used. Care should be exercised to identify correct process connections.

\*

**Note**: High side may be marked H or + Low side may be marked L or -



## **ELECTRICAL CONNECTIONS**

**WARNING** - For installation in Hazardous Areas, i.e. areas with danger of fire and/or explosion, prior to making electrical connections, ensure compliance with safety information on the Safety Marking plate. Failure to comply with this warning can result in fire or explosion.

Signal terminals are located in a separate compartment of the secondary unit housing. The housing incorporates two connection ports for cable glands or conduit fittings. They are protected with a temporary plastic plug for transit purpose which should be replaced with a suitable permanent plug in the unused port. Connections can be made by removing the cover (indicated in Fig. 7); first screw down the locking screw located below the cover, using a 3 mm Allen Key.

WARNING - For Hazardous Areas installations, the connection of cables and conduits to the transmitter shall be made in accordance with the requirements of the relevant type of protection. Cables and cable-glands must be in accordance with the type of protection. Unused openings for connection shall be closed with blanking elements suitable for the relevant type of protection. With the exception of intrinsically safe transmitters, the means provided for this shall be such that the blanking element can be removed only with the aid of tools. The blanking elements must be certified for the type of protection. See standards either EN 60079-14 or IEC 79-14. The transmitter connections must also guarantee the degree of protection of the transmitter enclosure, e.g. IPxx according to EN 60529 standard (or IEC529). See also the Addendum for "IP" protection (and Ex Safety) which is part of this instruction manual.

The signal cable should be connected to the terminals marked respectively (+) and (-). If an internal output meter - either with analog or digital indication - is installed, it should be removed in order to make the connection, simply by pulling it out from its socket. After the connections have been made, reinstall the output meter. Refer to the **Meters Option** addendum for details.

Secondary Unit Remove this cover to access terminals Grub screw Cover locking screws (in the position indicated by the arrows) Primary Unit Fig. 7 - Location of the locking screws and terminals

The power to the transmitter is supplied over the signal wiring and no additional wiring is required. The signal wiring does not need to be shielded but the use of a twisted pair is highly recommended. The cable shield should be grounded in one side only, to avoid dangerous earth paths.

**WARNING** - For Hazardous Areas installations, when the ambient temperature is higher than 70 °C, the cable used for the connections must be suitable for 5 °C above the ambient temperature.

Normal practice is to ground in the control room side, in which case the field side of the screen should be adequately protected to avoid contact with metallic objects. Signal wiring may be ungrounded (floating) or grounded at any place in the signal loop, but for intrinsically safe installations the wiring and grounding must follow the specific rules for this technique. The transmitter case may be grounded or ungrounded: a ground connection is provided internally (in the terminal compartment) and externally.

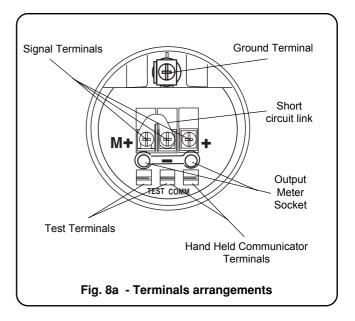
Do not run the signal wiring in close proximity to power cable or high power equipment; use dedicated conduits or trays for signal wiring.

CAUTION - Do not connect the powered signal wiring to the mA signal testing terminals as this could damage the by-pass diode.

After the connections have been completed check the integrity of the cover O-ring, screw down the cover and secure it by unscrewing the safety screw.

CAUTION - Unless absolutely necessary, avoid the removal on site of the protective cover which gives access to the electronic circuitry. Although the electronics are fully tropicalized they should not be subjected to humidity for long periods.

**WARNING** - For Hazardous Location installations, at least eight (8) threads on each cover must be engaged in order for the transmitter to meet (FLAME Proof - explosion-proof) requirements.

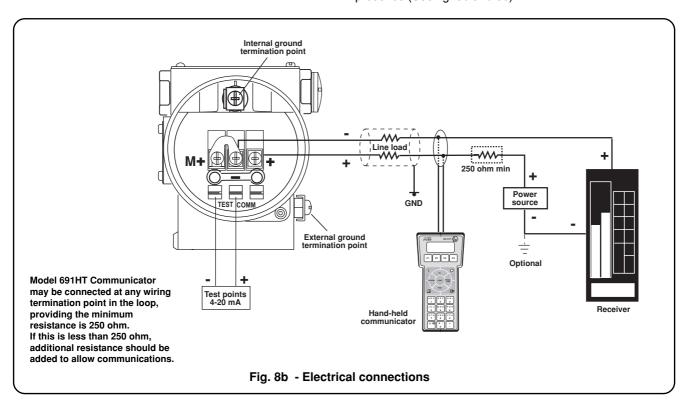


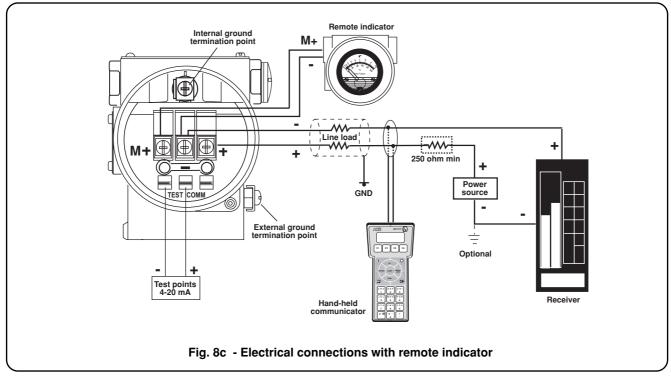
#### ... ELECTRICAL CONNECTIONS

WARNING: DO NOT ATTEMPT TO CONNECT AN AMPEROMETER BETWEEN A "TEST" TERMINAL AND A "COMM" TERMINAL. THE RESULT TO THE POWER SUPPLY IS A SHORT WHICH WILL BLOW FUSES AND POSSIBLY DAMAGE YOUR EQUIPMENT, ALSO CAUSING TO INTERRUPT FUNCTION OF OTHER DEVICES POWERED FROM SAME SUPPLY.

NOTE: If the use of the Hand Held Communicator is foreseen, a resistance of 250 ohms minimum must be included in the current loop, between the power supply and the connection point of the Hand Held Terminal, for communication purpose.

Here below is given an explanation regarding the possible connection of the terminal block to the power supply and a representation of the connection in case of remote indicator presence (See fig. 8b and 8c).





## **ELECTRICAL REQUIREMENTS**

The transmitter operates on a minimum voltage of 10.5 Vdc to a maximum of 42 Vdc and is protected against polarity inversion.



Note - The transmitter operates from 10.5 to 42 Vdc with no load (additional load allows operation over 42V dc). For Ex ia and intrinsically safe approval power supply must not exceed 30 Vdc.

In some countries the maximum power supply voltage is limited to a lower value.

Installing optional devices the minimum voltage increases to:

- 10.5 Vdc with no option
- 10.7 Vdc with output analog indicator
- 12.5 Vdc with LCD ProMeter
- 12.3 Vdc with surge protection
- 13.3 Vdc with LCD CoMeter
- 15.3 Vdc with no link on output indicator plug

The total loop resistance is indicated in the expression below.

R (k
$$\Omega$$
) = 
$$\frac{\text{Supply voltage - min. operating voltage (Vdc)}}{22.5}$$

The total loop resistance is the sum of the resistance of all elements of the loop, including wiring, conditioning resistor, safety barriers and additional indicators (excluding the equivalent resistance of the transmitter).

Where a configuration device (HART), such as the Hand Held Communicator or a Modem is likely to be used, a resistance of 250 ohm minimum should be present between the power supply and the point of insertion of these devices, to allow communication.

Several types of safety barriers, either passive or active, can be adjusted to measure. satisfactorily used in conjunction with the Smart 2600T transmitters. Nevertheless, in case of use of active barriers, check with the supplier if the model is suitable for use with smart transmitters allowing the connection of the configuration devices in the "safe" or non-hazardous area.

#### TRANSMITTER OUTPUT SIGNAL

The 2600T Safety transmitter provides both the analog  $4 \div 20$  mA and the digital HART communication. HART signals do not affect safety during trading operations. HART writings are permitted only in maintenance (out of safety) condition.

#### **Analog Signal**

Two-wire 4 to 20 mA dc, user-selectable for linear or square root output; power of 3/2 or 5/2, 5th order or two 2nd order switching point selectable programmable polynomial output can be also selected for version with HART communication.

#### **HART Signal**

Digital process variable (%, mA or engineering units) superimposed on the 4 to 20 mA signal, with protocol based on Bell 202 FSK standard.

#### **Output current limits (to NAMUR standard)**

- Low saturation: 3.8 mA (field configurable from 3.5 to 4mA)
- High saturation: 20.5 mA (field configurable from 20 to 22.5 mA)

## Transmitter failure mode (compliant to NE 43 NAMUR regulation)

The output signal can be user-selected to a value of 3.7 or 22 mA on gross transmitter failure contition, detected by self-diagnostics.



**WARNING** - The transmitter may be used as a safety accessory (as defined by the Pressure Equipment Directive 97/23/EC) i.e. as part of a shutdown system. In this case it is recommended to select the correct fail safe mode for the 4-20 mA signal (as per Namur NE43 recommendation).

See also the instructions relevant to fail safe selection (Up/Down scale mode) in the addendum to the instruction manual on "Use of hardware links on the secondary electronics".

## RANGE AND SPAN CONSIDERATION

The Smart 2600T Transmitter Specification Sheets provide all information concerning the Range and Span limits in relation to the model and the sensor code.

The terminology currently used to define the various parameters is as follows:

**URL**: Upper Range Limit of a specific sensor. The highest value of the measured value that the transmitter can be adjusted to measure.

**LRL**: Lower Range Limit of a specific sensor. The lowest value of the measured value that the transmitter can be adjusted to measure.

**URV**: Upper Range Value. The highest value of the measured value to which the transmitter is calibrated.

**LRV**: Lower Range Value. The lowest value of the measured value to which the transmitter is calibrated.

**SPAN**: The algebric difference between the Upper and Lower Range Values. The minimum span is the minimum value that can be used without degradation of the specified performance.

**TURN DOWN RATIO**: is the ratio between the maximum span and the calibrated span.

The transmitter can be calibrated with any range between the LRL and the URL with the following limitations:

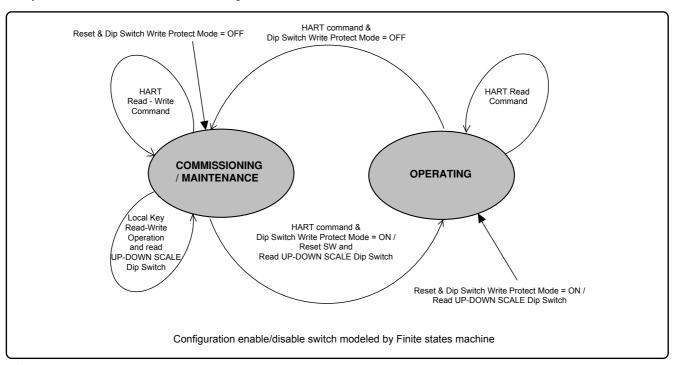
 $LRL \le LRV \le (URL - CAL SPAN)$   $CAL SPAN \ge MIN SPAN$  $URV \le URL$ 

## **COMMISSIONING AND CONFIGURATION ISSUES**

The 2600T Safety transmitters contain inside its non-volatile memories a number of parameters. Some of them, factory defined, are typical of the sensor and are not user-modifiable, the other are configuration parameters and can be modified by the user.

During the normal operation status, with the transmitter in safety conditions, all remote and local configuration shall be

disabled. The Safety 2600T pressure transmitter is protected against undesirable configuration changes by a dedicated hardware link placed on the secondary electronics board which is identified as Write Protect Mode Link (see fig. 9). The following figure described the maintenance-operating philosophy:

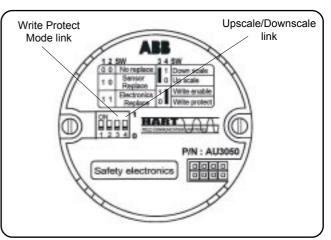


WARNING - The transmitter is considered in safety condition (normal operating mode) when the switch is in Write Protect (off). In that condition only reading commands are enabled.

The special procedure which shall be performed to put the transmitter in operating mode is described in the following section.

#### Operating mode enabling and disabling

Operating mode can be enabled/disabled depending on Switch 3 (Write) position at power on condition. The switch is located on the secondary electronics unit under the housing cover. To ensure safety operations of the device a specific HART command shall be performed in order to enable the condition changes.



(Switch 3) Write Protect Mode link position at Start-up (power on)	Transmitter status	Operations required to pass to the opposite condition
1 (ON)	Maintenance	<ol> <li>Switch in OFF position</li> <li>HART Command ("Change transmitter status to operating") or Power OFF/Power ON</li> </ol>
0	Operating	Switch in ON position     HART Command ("Change transmitter status to maintenance") or Power OFF/Power ON

Table 1

**WARNING** - After any configuration operation, the transmitter must be put in operating condition as described in Table 1. During this change a software reset is performed and the transmitter is not working for few seconds.

## **CALIBRATION**

Unlike conventional electronic transmitters, the use of a microprocessor and the presence of serial communications between the transmitter and the configuration device, allows the use of several different approaches in calibration and servicing. Different methods can be used to calibrate the Safety transmitter:

- i) using the zero and span calibration screws in the transmitter secondary unit.
- ii) using the Hand Held Communicator.
- iii) using the Personal Computer Configuration Software Package.

This chapter describes the first method; the others are described next or in the relevant Instruction Manuals of configuration tools. If the calibration screws are not fitted calibration must be done by method ii) or iii).

In the Safety 2600T Series it is also possible to apply a scaling to the reading of the transmitter.

The operation is called PV-scaling and is used to align the "zero" of the process with the "zero" reading of the transmitter. See the description in the Addendum for PV scaling operation.

Note: Unless otherwise specified the instrument is factory calibrated at maximum span with the LRV set to true zero. Instruments adjusted and tagged for a specific range will not require recalibration. Rezeroing of the transmitter may be required in order to compensate for zero shift arising from the installation.

#### **Preliminary operation**

Before commencing calibration ensure that:

- i) the required span, the upper and lower range value (URV & LRV) are within the span and range limits (URL & LRL) indicated on the nameplate (please refer to "Range and Span" consideration on the previous page).
- ii) the transmitter is properly powered and the electrical connections correctly made.
- iii) the Write Protect Mode link, located on the electronics module is in position ON (write allowed). Access to the link is gained by unscrewing the secondary unit housing cover at the opposite end to the terminal cover (See Fig. 9).
- iv) the Upscale/Downscale link is positioned to the required function: ON for Downscale OFF for Upscale (see Fig. 9).
  v) make the electrical connections, as indicated in Fig. 10.
  Connect a precision milliammeter as shown and remove the short circuit link.

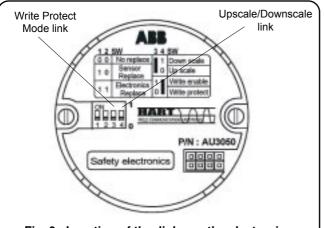
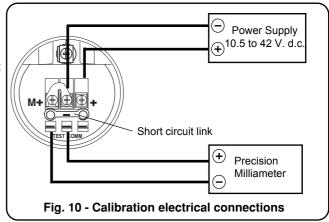
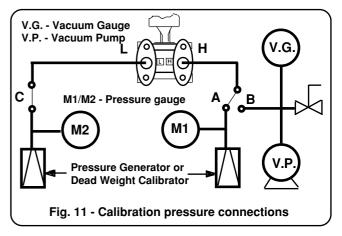


Fig. 9 Location of the links on the electronics

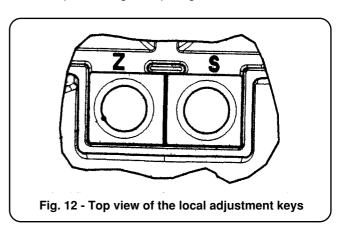


Set up an appropriate test rig in accordance with the required calibration. Figure 11 shows a complete test rig that can be selectively used to suit the calibration.



Note that calibration accuracy is strictly related to the accuracy of the test equipment: the use of a dead weight tester is highly recommended.

The local adjustment keys are located behind the Nameplate. To gain access slacken the nameplate screw and rotate 90°; proceed in the reverse mode when the calibration procedure has been completed. Fig. 12 shows the keys: they provide two large plastic heads that can be pushed, with spring return to normal. The local adjustment can be removed after the calibration, to avoid improper use by inserting a screwdriver blade below the plastic flange and pulling out.



## ... CALIBRATION

#### Zero and span - true zero procedure Differential pressure, gauge and level.

- Switch on the power supply.
- With no pressure applied to the transmitters, the value read on the digital milliammeter should be 4 mA; if it is not 4 mA turn pressure to be elevated. Allow time for pressure stabilization the zero screw for at least 1 second. After this operation the reading should move to 4 mA: if no change occurs repeat the operation.
- range value (URV) and allow time for the pressure to stabilize.
- Turn the span screw for at least 1 second: after this operation the reading on digital milliammeter should be 20 mA and the calibration procedure is complete. If no change occurs either the calibration procedure was not correctly performed or the span exceeds the limit; correct and repeat the operation.

#### **Absolute pressure**

- Switch on the power supply.
- Connect a vacuum source to the process connection and draw the maximum possible vacuum obtainable. The value read on the digital milliammeter should be 4 mA; if it is not turn the zero screw for at least 1 second. After this operation the reading should move to 4 mA: if no change occurs repeat the operation.
- If the value of the calibration span (UR V) is less than the atmospheric pressure gently open the vent valve so increasing the pressure to the Upper Range Value. If the calibration span (URV) is greater than the atmospheric pressure then connect the pressure connection to a pressure source and generate a pressure corresponding to the URV. Allow time for the pressure to stabilize.
- Turn the span screw for at least 1 second: after this operation the reading on digital milliammeter should be 20 mA and the calibration procedure is complete. If no change occurs the calibration procedure was not correctly performed or the span

## **Zero suppression procedure** Differential pressure gauge and level.

Two different methods (a) or (b) can be used:

a) After completion of the zero and span procedure above. apply to the H (high) connection a pressure equal to the pressure to be suppressed. Allow time for pressure stabilization and then turn the zero screw for at least 1 second. After this operation the digital milliammeter reading should be 4mA and the Upper Range Value automatically moved to a value equal to the sum of the pressure to be suppressed and the previous calibrated span.

b) Use the zero and span procedure above but apply pressures equal to the Lower Range Value (LRV) and then to Upper Range Value (URV), and turning, for at least 1 second, the zero and span screws respectively.

#### Absolute pressure

Use the zero and span procedure as previously described, but apply to the process connection absolute pressures equal to the Lower Range Value (LRV) and then to the Upper Range Value (URV), turning, for at least 1 second, the zero and span screws respectively.

#### Zero elevation procedure Differential pressure and level

Two different methods (a) or (b) can be used :

a) After completion of the zero and span procedure above apply to the L (low) connection a pressure equal to the and then turn the zero screw for at least 1 second. After this operation the digital milliammeter reading should be 4mA and the Upper Range Value (URV) is automatically moved to a -Apply to the H ( high ) connection a pressure equal to the upper value equal to the sum of the pressure to be elevated and the previous calibrated span.

> b) Use the zero and span procedure above but apply pressures equal to the Lower Range Value (LRV) and then equal to the Upper Range Value (URV) and turning, for at least 1 second, the zero and span screws respectively. The LRV pressure will be applied to the L connection whereas the URV will be applied to the L or to the H connection depending upon the whether the range is all negative or crosses zero.

## Gauge pressure

Apply to the process connection, pressures equal to the LRV and then equal to the upper range value (URV) and correspondingly turn the zero and span screws respectively.

\*Note - If during the calibration procedure the readings on the digital milliammeter are outside its inherent accuracy, output trimming of the transmitter may be requested. This operation can only be performed using the Hand Held Terminal Communicator or the Personal Computer Configurator. If this equipment is not available the transmitter should be returned to a Service Center for recalibration.

In some cases, expecially for tank level measurement, the calibration can also be obtained automatically by the indication of the actual output percentage, without any calculation for LRV and URV. The operation is called Output % Reranging exceeds the limit; apply the correction and repeat the operation and can be performed using a HART configuration tool (see Output % Reranging in the ADDENDUM FOR FLANGE-MOUNTED TRANSMITTER).

> WARNING. In order to ensure the correct operation of the transmitter, after the calibration procedure the device must be put in operating condition as described in Table 1, in the section Commissioning and Configuration Issues.

## PRE-STARTUP ACCEPTANCE TEST

After the installation of the device in order to validate the required safety functionality of the system together with the target equipment according to the Safety Requirement Specification a Pre-Startup Acceptance test shall be performed as following:

- 1. Put the Write Protect Mode switch in operating position
- Power-on the transmitter: the transmitter performs automatically a self-test that consists in the operations below:
  - Switch-on of the Secondary output
  - RAM test
  - Test of the analog output stage and of the feedback A/D converter

In case the first condition wouldn't happen, the transmitter shall be considered failed and not possible to use. In case the second test would fail the transmitter will drive the output to the selected alarm status. In this case a correction action consists in the re-calibration of the A/D converter. After the correction action the pre-startup test shall be repeated.

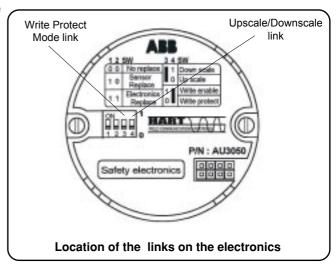
- 3. Enable the transmitter maintenance mode by raising up to dip switch nr. 4 (write enable)
- 4. Perform the Hart Command "Change Transmitter status to Maintenance"
- 5. Perform the Hart Command "Clock monitor test". The transmitter simulates a clock failure and put the output to Up-scale by the supplementary output stage. In case this condition wouldn't happen, the transmitter shall be considered failed and not possible to use
- 6. Disable the transmitter maintenance mode by lowering the dip switch nr. 4 (write protect)
- 7. Put the Operating/maintenance switch in operating condition
- 8. Power-on the transmitter.

A pre-startup acceptance test report shall be produced to record the test results.

## **PROOF TESTS**

To maintain the claimed Safety Integrity Level (SIL 2) a proof test procedure is requested every 10 years. The proof tests consists in the following operations:

- 1. Put the Write Protect Mode switch in Write Enable condition.
- 2. Perform the Hart Command "Change Transmitter status to Maintenance"
- Perform the Hart Command "Clock monitor test". The transmitter must go to up-scale setting the secondary output stage. To recover from the alarm status a power-off, power-on operation is required.
- 4. Power-off the transmitter
- 5. Put the Write Protect Mode switch in Write Disable condition.
- 6. Power-on the transmitter. The transmitter must go first to up-scale setting the secondary output stage, then finally the output must provide the actual pressure value.



## SAFETY RELATED PARAMETERS

The Safety 2600T pressure transmitters product meets the SIL2 requirements of IEC 61508 in low as well as high demand mode of operation. The total PFD in low demand mode for 10 years proof test interval is equal to the 5.5% of the range defined in IEC 61508-1. The relevant numbers are stated in the below tables.

#### Safety related parameters (electronics)

outoty rotatou paramotoro (otootromoo)			
Safe Detected Failure Rate (Lambda SD)	103	FIT	
Safe Undetected Failure Rate (Lambda SU)	235	FIT	
Dangerous Detected Failure Rate (Lambda DD)	490	FIT	
Dangerous Undetected Failure Rate (Lambda DU)	11	FIT	
Diagnostic Coverage (DC)	97.75	percent	
Safe Failure Fraction (SFF)	98.66	percent	
T1 (proof test interval)	1 vear	10 years	

T1 (proof test interval)	1 year	10 years
MMTR (Mean Time to Repair)		8h
PFD (avg)	5.3E-05	5E-04

#### Safety related parameters (electronics and mechanics)

Safe Detected Failure Rate (Lambda SD)	112	FIT
Safe Undetected Failure Rate (Lambda SU)	275	FIT
Dangerous Detected Failure Rate (Lambda DD)	549	FIT
Dangerous Undetected Failure Rate (Lambda DU)	61	FIT
Diagnostic Coverage (DC)	89.96	percent
Safe Failure Fraction (SFF)	93.86	percent

T1 (proof test interval)	1 year	10 years
MMTR (Mean Time to Repair)	8h	8h
PFD (avg)	2.7E-04	2.7E-03

## DISMANTLING AND REASSEMBLY

WARNING - Process fluids and/or pressure retained in the transmitter primary unit can cause severe injury and death or damage to the equipment. It is the user responsibility to make sure that no pressure is applied before removing the instrument from service or when draining or venting.

#### Dangerous fluids.

In case of toxic or otherwise dangerous process fluid, take any precautions as recommended in the relevant Material Safety Data Sheet.

CAUTION - Dismantling and reassembly should not be carried out on site because of the risk of damage to components and printed circuits as a result of adverse environmental conditions such as humidity,dust,etc. The dismantling and reassembly procedures given below should be carried out in the listed order to avoid instrument damage.

### Required tools

2 mm Allen key 3 mm Allen key Small Phillips screwdriver Small flat-bladed screwdriver 17 mm spanner 17 mm torque wrench

- (Range > 52 Nm - 39 foot lbs)

#### Dismantling

- a) Screwdown completely the cover locking screw, electronics side, using the 3 mm Allen key
- b) Unscrew and remove the covers
- Unscrew the two fixing screws and remove the secondary electronic assembly
- d) Unplug the sensor cable
- e) Remove the tang grub screw using the 2 mm Allen key
- f) Unscrew the housing taking care not to damage the sensor cable or the connector
- g) Loosen and remove the four flange fixing bolts using a 17 mm. spanner.

#### Reassembly

Check that the "O" rings are not damaged: if in replace.

WARNING - Assembling flanges with incorrect fixing bolts and nuts and improper "O rings" can cause fracture or overstressing of bolts and release of pressurized process material. Use only official spare parts (\*) included in the supplementary documentation, follow the reassembly procedure herebelow described and do not exceed the specified torque limits. DO NOT REMOVE the "O ring" fitted in the sensor neck: it provides the housing a degree of protection.

a) Refit the flange fixing bolts with a torque of 20 Nm (15 ft lbs) using a 17 mm. torque wrench.

Note: 1 Nm is equivalent to 0.738 ft lbs (8.85 in lbs

- b) Insert the sensor cable in its recess at the bottom of the housing.
- c) Screw the housing down completely until the nesting of housing/sensor assy is reached, then unscrew by one complete turn maximum. Rotate the topwork in the desired position and lock it with the tang grub screw previously removed.
- d) Plug the sensor cable to the secondary electronics. Fix the electronic circuit by its screws.
- e) Refit the covers and tighten securely.

**WARNING -** For Hazardous Location installations, at least eight (8) threads on the cover must be engaged in order to meet the flameproof (explosion-proof) requirements.

f) Unscrew the cover locking screw to secure the covers. This is mandatory to meet "Flameproof requirements" for Hazardous Areas installation.

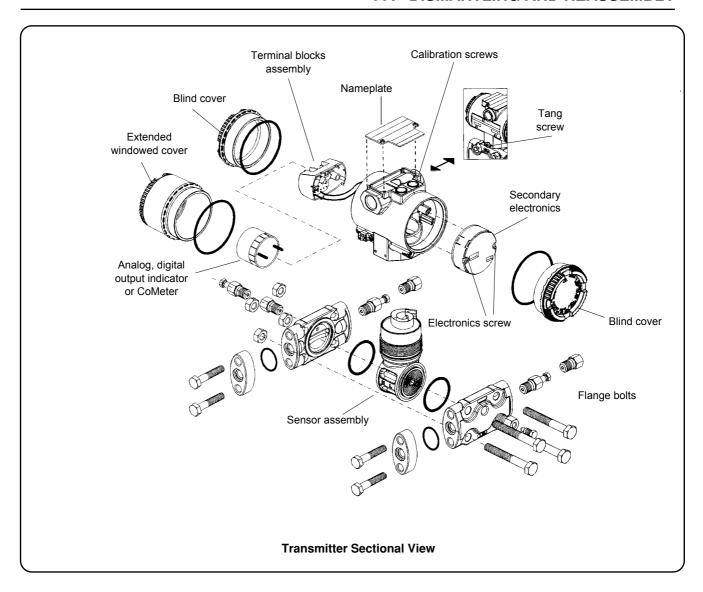


#### PRESSURE TEST WARNING

Once reassembled the process flanges and the transducer, a pressure test is required. At this purpose, apply a hydrostatic pressure of the maximum overrange pressure rating to both process connections simultaneously. Wait for one minute, then verify that no leakages occurred, otherwise repeat the assembly procedure and the pressure test.

(\*) The spare parts list is available at: www.abb.com - searching for: SL262\_4D.pdf or from local ABB representatives.

## ... DISMANTLING AND REASSEMBLY



## SIMPLE FAULT FINDING (HART)

This part is applicable only for a quick fault finding in the case that the Hand Held Terminal or the P.C. Configurator Package are not available.

If the transmitter does not appear to be working satisfactory, carry out the following fault finding checks before contacting our nearest. Service Centre.

If the instrument is to be returned for repair, ensure that it is adequately packed using the original polystyrene box or **laigh**sity chip foam: **the trouble sheet/returning form should be sent with the instrument, filled in all its parts.** If the transmitter needs to be dismantled follow the procedures as described in the previous section.

WARNING: If the transmitter forms part of a control loop, the plant must be placed under local manual control while the instrument is examined or taken out of service. Take all precautions to avoid damages caused by pressure or dangerous fluids release.

#### **Equipment needed**

Voltmeter, milliammeter (0 to 100 mA d.c.), solvent contact cleaner.

#### High, Low or Irregular Output No output Start (power off) Start (power off) Repair or replace Check the transmitter Repair or replace Check the transmitter Faulty Faulty power supply (\*) power supply power supply (\*) power supply OK Check for trapped gas Remedy Clean connectors in liquid lines and liquid Present Reassemble, switch on and Stop in dry lines check instrument operation OK Faulty Check for sediment Clean out Present in process flange (\*\*) Fit replacement Stop electronic circuit Still faulty Disconnect sensor connector from the Fit replacement electronic circuit. transducer assembly Stop OK Clean connector. Reassemble, switch on and check instrument Stop operation Faulty Fit replacement Stop electronic circuit Still faulty WARNING - If the transmitter needs to be repaired, the faulty unit/assembly must be replaced by an equivalent unit/assembly. Fit replacement Stop transducer assembly Stop

- (\*) If the source of the problem is suspected to be the power supply, check it by disconnecting the wires from the transmitter and testing the volts available at the wires.
- (\*\*) If there are sediments in process flanges they must be cleaned, if inevitable flanges have to be removed. Before reassembly pay attention to the O-ring: PTFE O-ring probably requires to be substituted. Refer to dismantling and reassembly section for these operations.



## TROUBLE SHEET

	WARRANTY REPA	WR 🔲	REI	PAIR ORDER			
Rejection or discrept	ancy reports			Copy attached		Not available	
IDENTIFICATION	/						
Customer							
Purchase order No.							
Plant							
Name of person to co	ontact						10.
Instrument tag No.							
Model							
Serial No.	-						
OPERATING CO. Specify location, environm.	NDITIONS nantal conditions, type of s	service and app	roximate num	ber of operating hour	s or date o	f installation if know	97.
S.	2						
REASON FOR RE	ETURN						
· DANGEROUS FLU							
In case of toxic or o	otherwise dangerous	process flui	ld, please a	ttach the relevan	t Materia	l Safety Data Si	hoot.
Trouble found during		Install	ation	Commissionin	g $\square$	Maintenance	
Trouble found during				At start u		On service	
Shipping information	for the return of the e	equipment					
Material returned for factory	repair, should be sent to	the nearest AB	B Sarvice Cer	nter, transportation ci	hargas prop	said by the Purchs.	sec
Please enclose this sho	eet duly completed to	o cover lette	r and packli	ng list			
Date	Signature			Originator			
Date	- January C			January			

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## ADDENDUM FOR "METERS" OPTION OF THE TRANSMITTERS

#### **GENERAL DESCRIPTION**

This option provides three different indications (meters) inside the transmitter housing. The "output meters" can be mounted on the terminal block (field terminals) side; one is of "analog" type, the second is of "digital" type (LCD, ProMeter) and the tird is the CoMeter. They are operated by the output signal of the transmitter he meters can be rotated to exactly match the mounting position of the transmitter. The above mentioned CoMeter (abbreviation of Communication Meter) can be used both as a display and as a configuration tool for the Safety 2600T.

#### **ANALOG OUTPUT METER**

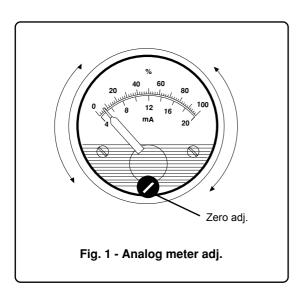
The analog output meter provides a 90scale indication. It has either a 0 to 100 linear scale or a 0 to 10 square root scale.

#### **ANALOG OUTPUT METER CALIBRATION**

The calibration of the analog type meter only involves zeroing. Fig. 1 shows the analog output meter and the location of the zero adjustment.

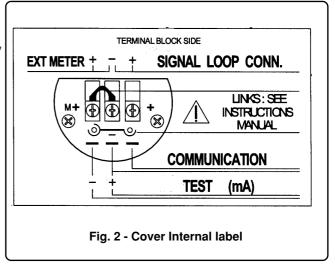
The calibration is quite simple using one of the following methods:

- with the loop unpowered adjust the zero screw to read exactly the **true zero** mark on the scale (Fig. 1).
- with the transmitter transmitting 4 mA adjust the zero screw to read exactly the **live zero** of the scale.



#### METER INSTALLATION OR REPLACEMENT

WARNING - If the transmitter is not certified as Intrinsic Safety type, DO NOT REMOVE ANY COVER in areas classified as "HAZARDOUS LOCATIONS: CAN RESULTS IN HAZARD OF FIRE AND EXPLOSION". Contact your Safety Dpt. in order to establish correct installation procedure.



To install (or to replace) the meter, use the following procedure:

- 1) If the transmitter is part of a control loop, put the loop in manual.
- Remove the cover on the terminal block side; inside of which is affixed the label shown in Fig. 2.
- Remove the link shown on the label by pushing down at its left extremity and then its right. Alternatively it can be removed on the left side only in preparation for a further refit.
- 4) Plug the meter into the socket. The digital indication meter can rotate, for easy viewing, in 15 ° steps, 90° degree clockwise and 255° counterclockwise. Further rotation causes damage to the meter stops or to the "banana" connections and should be avoided. Note that considerable effort must be applied for 15 ° rotation. The analog output meter can also rotate for easy viewing.
- 5) Check that the cover O-ring gasket is properly in place, screw on the extended windowed cover and tighten properly.

To remove the meter simply pull it out from the socket and fit a replacement following the above procedure.

CAUTION - If the meter is removed, ensure that it is replaced immediately by another one or with the proper link provided. This operation is important for I.S. loop operation.

The name **CoMeter** is an acronym for **COMMUNICATING METER.** The name **ProMeter** stands for **PROGRAMMABLE METER.** 

It can be connected, plug & play, into the standard terminal block of the 2600T Series Pressure Transmitter.

It is capable to provide both reading and configuration operations, when used in connection with the analog-only version, the ProMeter is only indicator. The LCD display has three lines; the first one is used for 5 numeric characters, up to 99999, plus a minus (-) sign on the left and a star (\*) sign, up on the right, to indicate HART communication is in progress; the second line is a 10 segments bargraph used to show the output, from 0% to 100% in 10% steps;

the third line is used for seven alphanumeric characters to display units or messages.

In addition to the display the plastic membrane has 4 push buttons used for programming and for menus navigation. And more precisely, they are:

top left position: ESCAPE key

top right position: ENTER key

bottom left position: NEXT key

bottom right position: PREVIOUS key

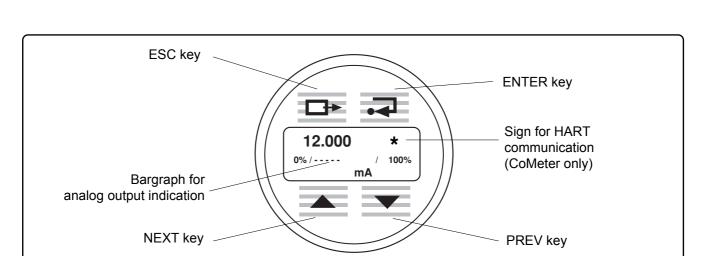


Fig. 3 - CoMeter and ProMeter

The normal operating condition for CoMeter and ProMeter is to display the analog output signal of the transmitter, expressed in milliAmpere (this is the default setting), or in percentage or in engineering unit, with all the units available as for the HART Communication Protocol.

In addition to the indicator functionality, the CoMeter can be used as a configuration tool, where both the CoMeter itself and the transmitter can be configured. ProMeter is programmable only. In the CoMeter, in fact, two are the main menu: ConF METER" and "ConF XMTR"

#### **ACCESS TO CONFIGURATION**

To enter these menù in both indicators, the keys **PREV** and **NEXT** must be pressed simultaneously for 3 seconds, then the user can switch between the XMTR and the METER configuration using the NEXT and the PREV key. In the ProMeter entry is directly in Manual Configuration, as shown in the next page.

**NOTE**: when the Configuration action is finished, remember to press the **ESC** key to return to display the previous selected value.

#### **Conf METER - METER CONFIGURATION**

#### **PASSWORD**

The access to the configuration menus can be protected by a 5 digits numeric password.

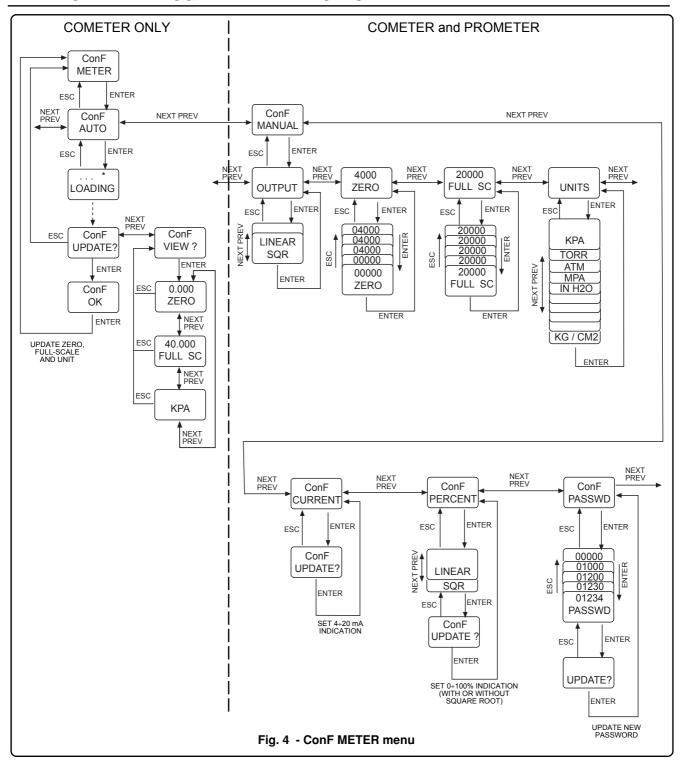
It is under the ConF METER menu that the password can be defined and enabled.

See figure 4 for the access to the **ConF PASSWORD**" menu. Once you have entered the "ConF PASSWORD" menu the cursor is blinking on the most significant digit.

Press **ENTER**, if you want to change the digits, initially set to zero (0).

Use the **NEXT** and **PREV** key to increase or decrease the value of the single digit, use the **ENTER** key to move the cursor to the next digit, use the **ESC** key to move back to the previous digit. When the string "**UPDATE?**" appears on the display you can use the **ENTER** key to accept the new password or the **ESC** key to abort the password definition.

When all digits are set to zero, the password is disabled.



The other options under ConF METER menu are:

## **ConF AUTO**

By selecting this option, the CoMeter is automatically updated with the LRV, URV and Unit of the HART transmitter connected. well as to decide for a LINEAR on SQR output function. LRV Before accepting the transmitter configuration by pressing ENTER at the request 'ConF UPDATE?", it is possible to view the LRV (ZERO), the URV (FULL SC) and the UNIT. If the output transfer function of the transmitter is not linear. ProMeter and CoMeter show the messageConFNO LIN and the user cannot update the configuration.

It is necessary to change the output transfer function of the transmitter to linear.

See Fig. 4 - "ConF METER" menu, for ConF AUTO procedure.

#### ConF MANUAL

The selection of MANUAL configuration allows the user to define manually CoMeter and ProMeter configuration, i.e. define the LRV (ZERO), the URV (FULL SC), and the UNIT, as and URV can have a value between -99999 and +99999. Refer to Fig. 4 - ConF METER menu for detail on the procedure. For having the CoMeter to display the analog output current or the output percentage, select respectively:

#### Conf CURRENT and Conf PERCENT

Under **ConF PERCENT** option, the user can decide for linear or SQR output. When SQR output is selected, the output is linear from 0 to 20% (to 4% of input).

Refer to Fig. 4 - ConF METER for details on the procedures.

## ConF XMTR - TRANSMITTER CONFIGURATION (CoMeter only)

Four are the operations under the ConF XMTR menu: **CONF, TRIM, REVIEW** and **PV**.

By pressing ENTER on the ConF XMTR menu, the string **LOADING** appears on the display, with the blinking star (\*) indicating communication activity, i.e. the CoMeter is reading the transmitter information.

Then the **CONF** option appears.

Using PREV or NEXT key, the user can select **CONF**, **TRIM**, **REVIEW** or **PV** option, and with the ENTER key he moves into the menu.

When entering CONF and TRIM menu a message " **LOOP IN\_MAN**" appears to remind that a modification can change the transmitter output, so for security the loop should be put in Manual.

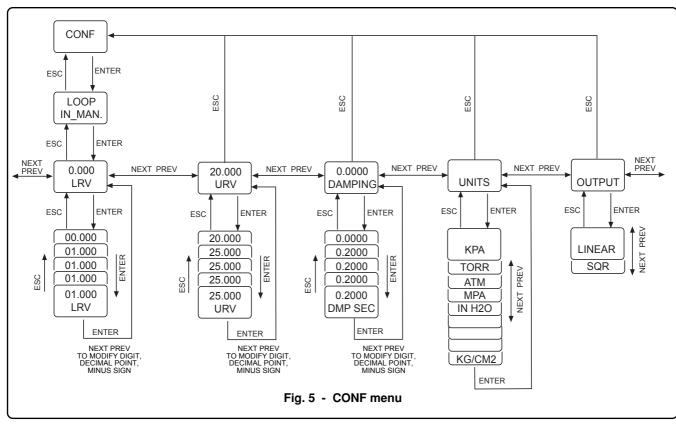
See below a list of the available operation under the selected option:

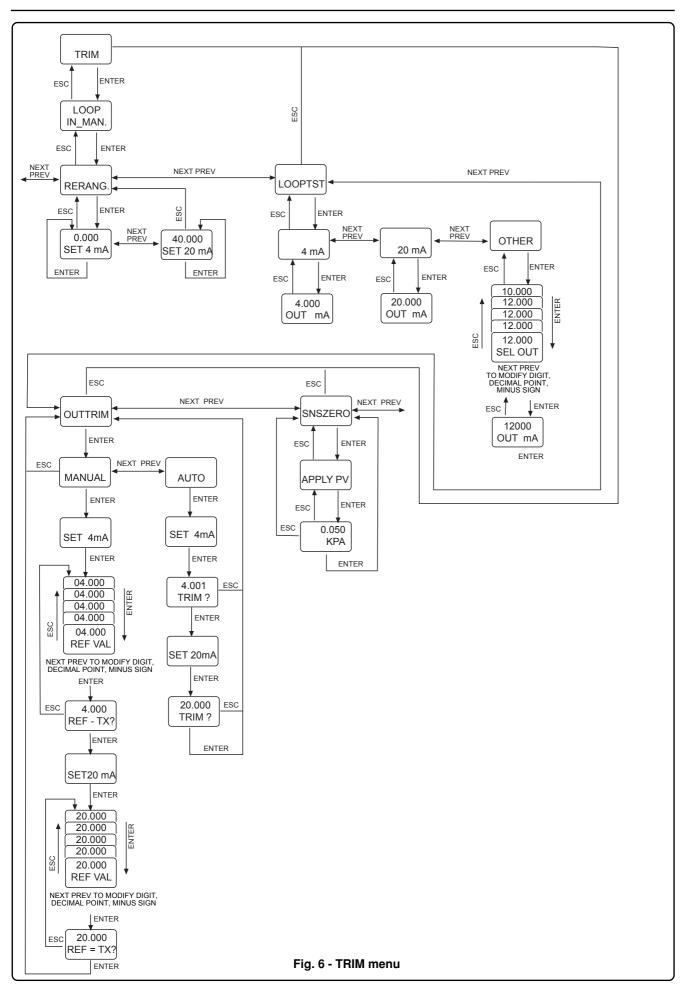
CONF menu	TRIM menu	REVIEW menu	PV menu
Change LRV Change URV Change DAMPING Change UNITS Change OUTPUT	Reranging (RERANG.) Loop test (LOOPTST) Output trim (OUTTRIM) Zero adjustment (SNSZERO)	TAG 8 Final Assembly Nr. (XMTR N.) Sensor Serial Nr. (SENS N.) Up/Down scale (UP/DOWN) UNITS LRV URV LRL (See Sensor Units) URL (See Sensor Units) DAMPING OUTPUT	Primary variable (PRIMARY) Secondary variable (2ND) Tertiary variable (3RD) Fourth variable (4TH)

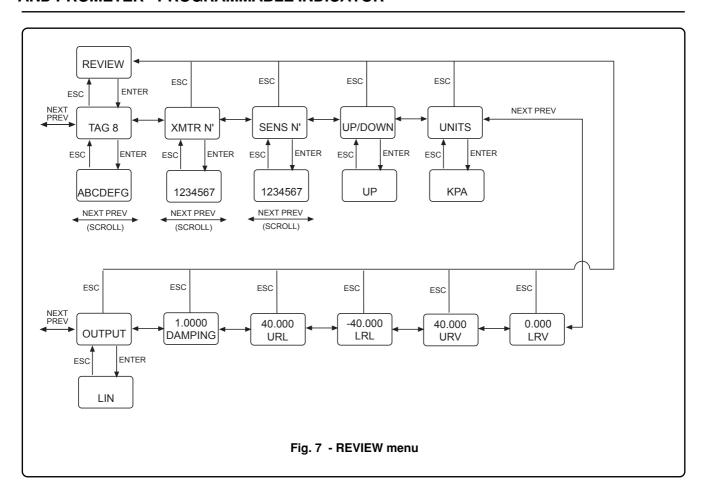
Use PREV or NEXT key to scroll through the options and ENTER key to change or view the values.

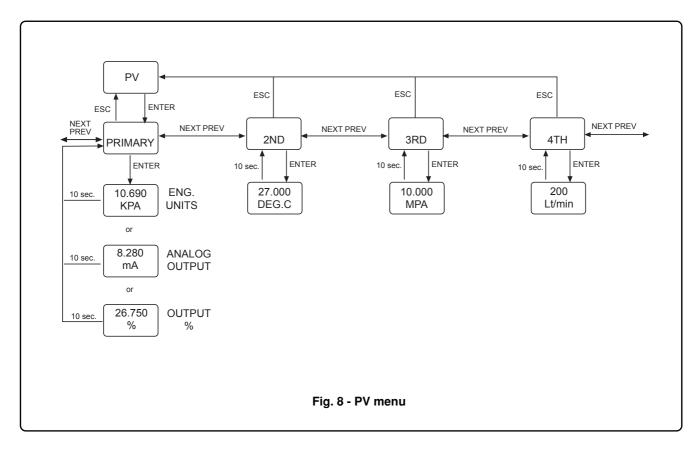
The procedure to change the numeric value remains the one already explained for PASSWORD operation, i.e., the cursor starts blinking on the most significant digit, then use the NEXT and PREV key to increase or decrease the value of the single dightet minus sign(-)automatically appears or disappears when the value increases above 9 or decreases below 0, as well as for the decimal point(.). Use the ENTER key to move the cursor to the next digit, use the ESC key to move back to the previous digit.

An **ENTER** on the last digit will cause the value to be sent to the transmitter. Refer to figures 5, 6, 7 and 8 for details.









### ADDENDUM FOR PV-SCALING OPERATION

PV-scaling operation can be used to align the "zero" of the process with the "zero" reading of the transmitter. A configuration similar effect as per the previous example: tool must be use to perform this operation through digital communication.

1) PV scaling for analog + HART Safety version

There are two different ways to perform a PV-scaling.

Method 1: apply to the transmitter a pressure that corresponds to the scaling value (offset) you have to apply to the reading and perform the operation using the configuration tools. The operation is called SET PV ZERO (see example 1).

Method 2: calculate the scaling value (offset) and apply it to the applied as offset. transmitter following the operation available on the configuration tool. With this method it is possible to perform a scaling operation even for a value different scaling, i.e. setting the offset to 0. then zero. The operation is called SET PV VALUE (see example 2).

Effect of the PV-scaling operation:

An example can better explain the effect of the scaling action.

Example n° 1

the transmitter is calibrated at:

LRV = 0 mbar

URV = 200 mbar

the transmitter model has the following limits of operation:

LRL = -400 mbar

URL = +400 mbar

For the effect of a transmitter's capillary, connected to a tank, there is a pressure of 80 mbar when the tank is empty, i.e. the transmitter's reading is 80 mbar.

In order to eliminate the pressure caused by the fluid inside the capillary, you can perform a PV scaling for compensating/ scaling the reading for these 80 mbar. The result of this operation is:

the transmitter's reading is now 0 mbar.

offset is -80 mbar and must be considered that while the limits of the transmitter remains:

 $LRL = -400 \, mbar$ 

 $URL = +400 \, mbar$ 

and the calibration does not change

LRV = 0 mbar

URV = 200 mbar

The configuration tools allows you to evaluate the new operative limits:

operative LRL = -480 mbar

operative URL = +320 mbar

Example n° 2

the transmitter is calibrated at:

LRV = 0 mbar

URV = 200 mbar

the transmitter model has the following limits of operation:

LRL = -400 mbar

URL = +400 mbar

the transmitter is reading: PV = 100 mbar

and you know the process value is 50 mbar.

You can apply this 50 mbar for your PV scaling operation, with

PV reading = 50 mbar

offset = 50 mbar so that while the limits of the transmitter remains:

 $LRL = -400 \, mbar$ 

URL = +400 mbar

with no change for the calibration, the configuration tools allows you to display the new operative limits:

operative LRL = -450 mbar operative URL = +350 mbar

When requested it is possible to reset the value actually

When an offset is defined, the trimming operations are disabled and can be rehabilitated only by eliminating the

WARNING. In order to ensure the correct operation of the transmitter, after the calibration procedure the device must be put in operating condition as described in Section Commissioning and Configuration Issues.

## ADDENDUM FOR "SURGE PROTECTION" OPTION OF THE TRANSMITTERS



#### **WARNING - Note for Hazardous Area Installation**

For the Pressure Transmitter with surge protector must be additional considered:

- 1 The transmitter has to be supplied from a voltage source which is safely separated from mains (galvanic separation).
- 2 The potential equalization for the entire cable link must be guaranteed since the intrinsic safety circuit of the transmitter is grounded.

#### **GENERAL DESCRIPTION**

This option provides a built-in surge protection circuit.

The surge protector is designed to dissipate large quantities of electrical energy which have been induced in a transmissional The option is suitable to protect up to 2500 V (5 kA discharge current) of 8µs rise time/20µs decay to half value.

These large quantities of energy can be induced in the signal transmission line by lightning discharge in the area or by nearby electrical equipment.

The dissipation of this energy prevents damage to transmitter circuitry connected to the transmission line.

#### The surge protector will not protect the instrument in case of a direct lightning strike.

The surge protector board is located inside the terminal block of the transmitter (see drawing).

The circuit is designed to operate and recover automatically. It does not require periodic testing or adjustment.

#### FITTING PROCEDURE (See Fig. 1)



#### CAUTION: This procedure should not be carried out on the field site.

- a) Remove the transmitter cover of the field connections side.
- b) Unplug the built-in indicator, if present.
- c) Unscrew the two Phillips screws (M 4 x 18 mm) which secure the terminal block and pull it off the housing.
- d) Unweld the + and wires which connect the two RF (radio frequency) filters, on the back of the terminal block.
- e) Fit properly the surge protector p.c. board and secure it by a self-tapping screw (M 2.9 x 6mm)
- f) Secure the two +/- eyelet terminals to +/- holes on the back of the terminal block, by a welding operation.
- g) Secure the two +/- wire eyelet terminals of the RF filters to the +/- bushes of the p.c. board by a welding operation.
- h) Connect the wire eyelet terminal of the Surge Protector to the dedicated ground connection below terminal block, using a provided self tapping screw M4x8 mm and relevant washers.
- i) Reinstall the terminal block and stick on the notice label in the proper position.
- I) Plug the built-in indicator, if used.
- m) Refit the cover.

Refer to Fig. 1 and also follows the indication in the figures 2a and 2b.

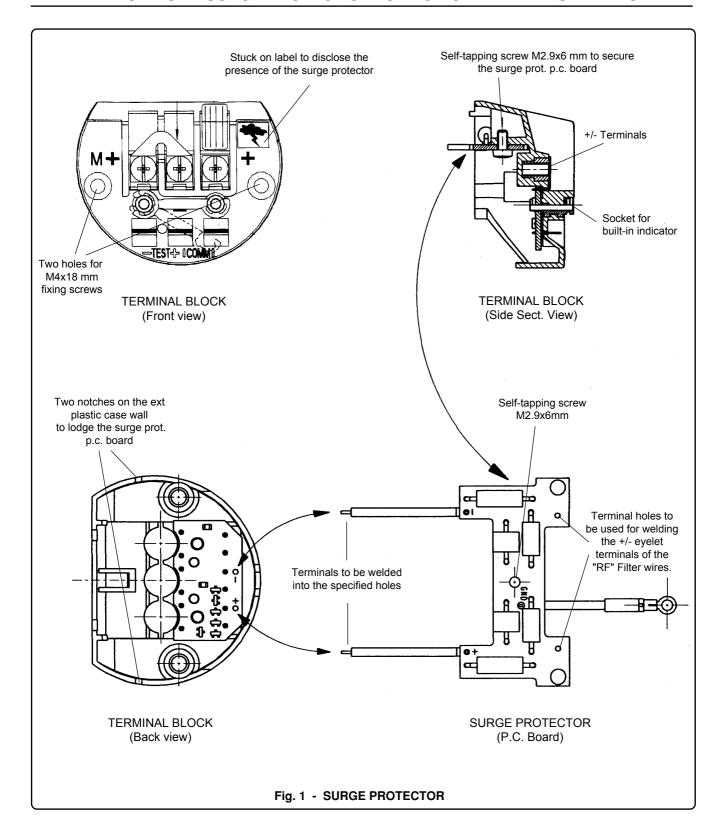
In the first one (2a) you can see the terminal block connection when there is no surge protector applied.

In the latter (2b) you can see the terminal block connection when surge protector is in!

NOTE - The Surge Protector is suitably provided with the necessary installation screws and the notice label.

Adding the unit to an existing transmitter will affect the power supply requirement for a minimum added operating voltage of 1.8 V d.c.

## ... ADDENDUM FOR "SURGE PROTECTION" OPTION OF THE TRANSMITTERS



## ... ADDENDUM FOR "SURGE PROTECTION" OPTION OF THE TRANSMITTERS

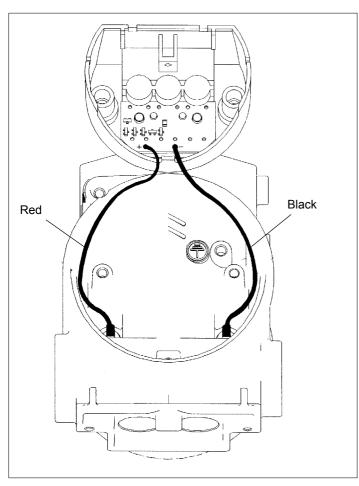
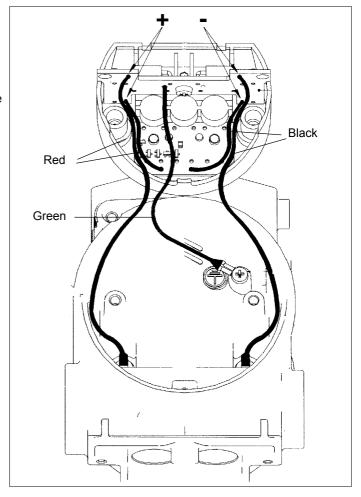


Fig. 2a Connection for terminal block and housing.

Note: Before to fix the terminal block to the housing put the two wires in the position as shown above, in order to avoid any damages.

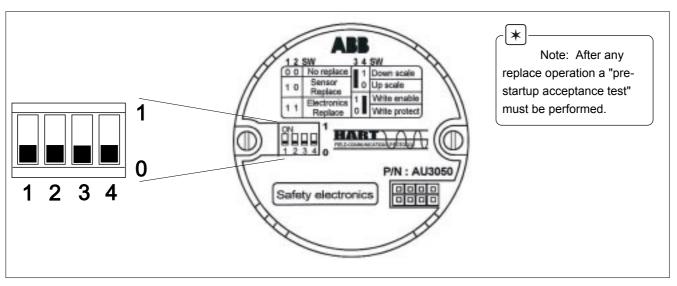
# Fig. 2b Connection for terminal block and housing, with surge protection.

Note: Before to fix the terminal block to the housing put the two wires in the position as shown above, in order to avoid any damages.

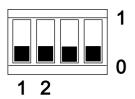


## ADDENDUM USE OF HARDWARE LINKS ON THE SECONDARY ELECTRONIC

The secondary electronic is shown in the figure. There are 4 dip switches located on the secondary electronics as indicatedword they are used for settings when integral digital display is not available.



Switches 1 and 2 are used for Electronics or Transducer replace; Switch is for Write Protect mode selection; Switch is for Up/Down Scale selection. Here below a description of the operations.



#### **REPLACE**

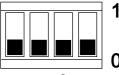
Usually switches 1 and 2 are down in "0" position. They are moved when a replace operation is required.



Switch 1 up in "1" position is required before power up the transmitter, when a replace is being performed. Switch 2 down in "0" position allows the replace of the transducer.



Switch 2 up in "1" position allows the replace of the secondary electronics. It must be moved in this position, when electronics replace is being performed, before power up the transmitter.



AFTER ANY REPLACE OPERATION IT IS RECOMMENDED TO MOVE DOWN IN "0" POSITION THE RELEVANT SWITCHES.



4

#### WRITE PROTECT mode

With the switch 3 up in "0" position the write protect mode is active. It is a way to protect the device from any change: configuration data and parameters cannot be modified.

#### **UP/DOWN SCALE mode**

The switch 4 defines the fail safe output condition in case of transmitter failure:

- In the ON position the output is Down (below 4 mA)
- In the OFF position the output is UP (above 20 mA)

NOTE: Typically the Up/Down scale mode is activated when there is a failure in the physical elements of the sensor and on the electronics of the device, and more precisely:

- 1) Values in the sensor database are corrupted;
- 2) EEprom of Primary Electronic (sensor) is failed;
- 3) Values of Primary variables are out of limits;
- 4) Digital to analog converter (DAC) circuit is out of range.
- 5) ASIC (Integrated circuit) of sensor is failed.
- 6) ASIC (Integrated circuit) of electronics is failed.

# ADDENDUM FOR DIFFERENTIAL PRESSURE TRANSMITTERS: SELECTABLE OUTPUT FUNCTIONS

#### **GENERAL DESCRIPTION**

The 2600T Series Differential Pressure Transmitter provides a selection of output functions, as follows:

**Linear** for differential pressure or level measurements

**Sq. Root (x)** for flow measurements using restriction type primary element, like orifice plate,

integral orifice, Venturi or Dall tube and similar.

**Sq. Root** (**x**³) for open channel flow measurements using rectangular or trapezoidal weir **Sq. Root** (**x**⁵) for open channel flow measurements using V-notch (triangular) weir.

**Polynomial** for input linearization using a 5th-order polynomial function

for input linearization using 2 polynomial functions of 2nd order

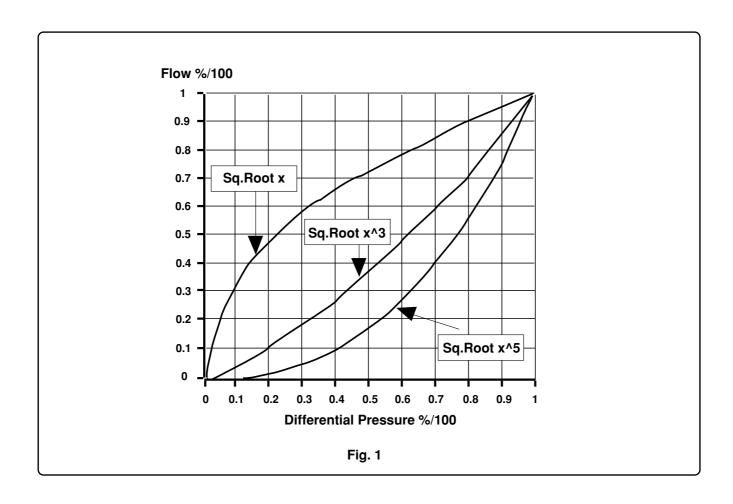
**Costant current** for loop or associated equipment test.

where |x| and output are in the range 0 to 1 (0% to 100%).

Figure 1 shows the Input/output relationships with the different Square Root Options applied.

These output functions can be activated using a Configuration Tool like the Hand Held Communicator, a HART Universal Communicator or a Personal Computer, carrying the Smart Configuration Program, connected to the transmitter via a Bell 202 modem (see the relevant Operating Instructions).

The output of the transmitter is actually the analog signal 4 to 20 mA and the digital signal read in engineering units orirtheoral display.



## ADDENDUM FOR DIFFERENTIAL PRESSURE TRANSMITTERS: SELECTABLE OUTPUT FUNCTIONS

#### 1.0 LINEAR

Using this function, the relationship between the input (measured value), expressed in % of the calibrated span and the output is linear, e.g. at 0% input, corresponds 0% output (4mA), at 50% input corresponds 50% output (12mA) and at 100% input corresponds 100% output (20mA).

#### 2.0 SQUARE ROOT (X)

Using this function, the output (in % of the span) is proportional to the square root of the input signal in % of the caliberatspan: the instrument, e.g., gives an analog output proportional to the rate of flow.

To avoid the extremely high gain with the input approaching zero, the transmitter output is linear with the input up to 4%, programmable in order to ensure a more stable output near zero. This also allows an easier zero adjustment and performs a reduced zero error for ambient temperature variations.

An explanation is given in fig. 2 For an input variation from 0 to 0.5% the output varies linearly. For input variation greaterthen 0.5% up to a value programmable from 1 to 4%, the output still varies linearly. Then at input values greater then 4% the output follows the applied transfer function. In the figure it is also indicated the default selection.

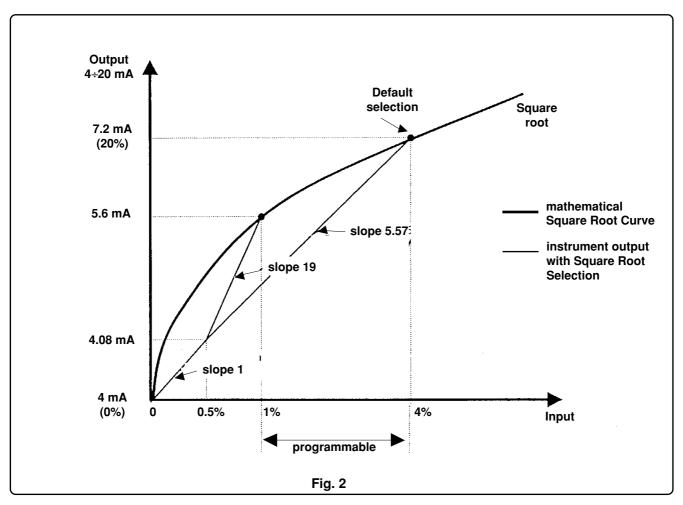
To convert from a pressure value within the calibrated span to a percent of flow, first express the pressure as a percentitorated span, then take the square root of this pressure percentage and multiply by 10.

Example: Transmitter calibrated 0÷400 mbar - with 196 mbar, pressure input, the percentage of flow is determined as follows:

$$\frac{196}{400} \times 100 = 49\% \text{ of calibrated pressure}$$

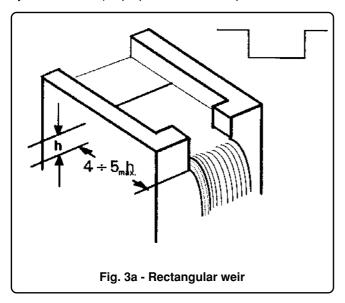
 $\sqrt{49}$  x 10 = 70% of calibrated flow

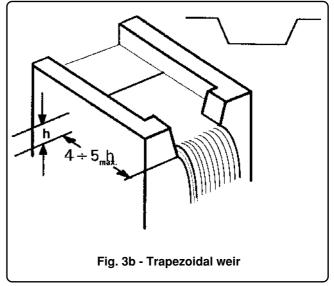
To convert from a percentage of the calibrated flow to the equivalent output current (see figure), first divide the percentage by 100, then multiply this figure by the 16 mA adding also the live zero 4 mA.



### 3.0 SQUARE ROOT (X3)

This function, as mentioned before, can be used for open channel flow measurement using ISO 1438 rectangular weirs (Hamilton Smith, Kindsvater-Carter, Rehbock formulas) or trapezoidal weirs (Cippoletti formulas) (see Fig. 3a and 3b) and ISO 1438 Ventur flumes. In these types of devices the relationship between the flow and the developed head h (the differential pressure mesured by the transmitter) is proportional to  $\Re^2$  or square root of  $\Re^2$ . Other types of Venturi or Parshall flume do not follow this relationship.



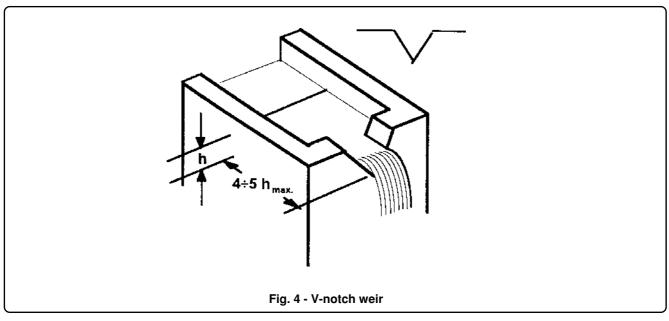


Using this function, the output (in % of the span) is proportional to the square root of the third power of the input signaln % of the calibrated span: the instrument, e.g., gives an output proportional to the rate of flow calculated using the above mentioned formulas.

### 4.0 SQUARE ROOT (X5)

This function can be used for open channel flow measurement using ISO 1438 V-notch (triangular) weirs (see Fig. 4) where the relationship between the flow and the developed head h (the differential pressure measured by the transmitter) is proportional to  $h^{5/2}$  or square root of  $h^5$ .

Using this function, the output (in % of the span) is proportional to the square root of the fifth power of the input signal in % of the calibrated span: the instrument, e.g., gives an output proportional to the rate of flow calculated using the Kingsvater-Shen formula.



### 5.0 POLYNOMIAL 1 (5th order)

The polynomial function, applied to the transmitter input (x) expressed in % of the calibrated span, has the following form:

Out = 
$$\pm A_1 \pm A_1(x) \pm A_2(x^2) \pm A_3(x^3) \pm A_4(x^4) \pm A_5(x^5)$$

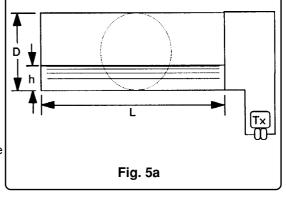
where (x) and Out should be normalized in the range 0 to 1 for calculation purpose, with following Out meaning:

Out = 0 means Analog out 4 mA

Out = 1 means Analog out 20 mA

This function can be used for linearization purpose: the user can plot the characteristic curve of the input and find, using a mathematical method, the parameters of the polynomium that better approximate the plotted curve. Check, after the calculation, if the maximum error is compatible with the application.

The following are some application examples.



### 5.1 CYLINDRICAL VESSEL

Using the polynomial function applied to a level transmitter installed in a horizontal cylindrical vessel it is possible to transmit the measure of level in term of partial volume. Some different cases should be considered:

a) Cilindrical vessel with flat ends (not often used. Fig. 5a). Transmitter measuring the whole vessel heigth.

The following polynomium gives the area of the circular section in relation to the heigth h (heigth of the liquid in the vessel).

Out = 
$$-0.02 + 0.297 \text{ h} + 2.83 \text{ h}^2 - 4.255 \text{ h}^3 + 3.5525 \text{ h}^4 - 1.421 \text{ h}^5$$

Being both the input h and the output Out normalized, i.e. in the range 0 to 1 (or 0% to 100%), the vessel diameter corresponding to a circular area equal to 1 (100%) will be "normalized" by a "K" factor of the following value :

$$K = 2 \cdot \sqrt{1/\pi} = 1.12838$$

The volume of the liquid contained in the vessel, at height = h will be  $V = Out \cdot (d/1.12838)^2 \cdot L$ 

where d = vessel diameter and L = vessel length.

The non conformity error is within 0.1% between 0.5% and 99.5% of h, 0.2% at 0% and 100%.

b) Cilindrical vessel with hemispherical ends (see Fig. 5b). Transmitter measuring the whole vessel heigth.

The same polynomium can be used also for the cylindrical vessel with hemispherical ends. To obtain the volume contained in the vessel can be used the following empyrical formula:

$$V = Out \cdot (d/1.12838)^2 \cdot (L + 2/3 d)$$

The non conformity error depends on the ratio between diameter and length of the vessel: for ratio  $\ge 5$  to 1 the error is  $\le 0.25\%$ . The polynomium found with mathematical method gives an error  $\ge 0.15\%$ .

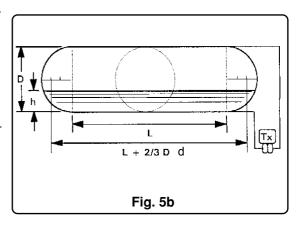
c) Cilindrical vessel with elliptical or pseudoelliptical ends (see Fig. 5c). Transmitter measuring the whole vessel heigth.

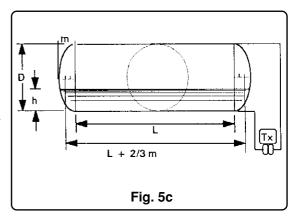
The same polynomium can be used also for the cylindrical vessel with elliptical or pseudoellipticall ends. To obtain the volume contained in the vessel can be used the following empyrical formula:

$$V = Out \cdot (d/1.12838)^2 \cdot (L + 2/3 \text{ m})$$

where m is the length of the minor ellipse axis (see Fig.5c)

The non conformity error depends on the ratio between the diameter and the length of the vessel: for ratio ≥5 to 1 the error is ≤0.25%. The polynomium found with mathematical method gives an error ef0.15%.





### 5.2 SPHERICAL TANK

Spherical tank (see Fig.5d). Transmitter measuring the whole vessel height.

The following polynomium gives the volume of the spherical section in relation to the height h of the liquid in the tank.

Out = 
$$3 h^2 - 2 h^3$$

This formula is geometrical and then his conformity is perfect.

Being both the input h and the output Out normalized, i.e. in the range 0 to 1 (or 0% to 100%), the sphere diameter D corresponding to a volume equal to 1 (100%) will be "normalized" by a "K" factor of the following value:

$$K = 2 \cdot \sqrt[3]{(4 \pi)} = 1.2407$$

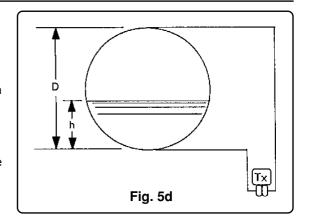
The volume of the liquid contained in the tank, at height = h will be  $V = Out \cdot (D/1.2407)^3$ 

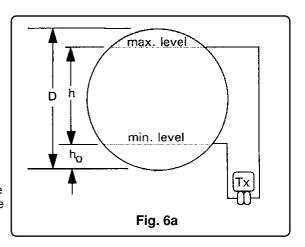
where D = sphere diameter.



Cases a) to d) but with partial level measurement (Fig. 6a) In these cases two methods can be used:

- 1) Plot the changes in volume in relation to the level changes and, using a mathematical method, find the relevant polynomium.
- 2) Use the polynomium coefficients for cases a) to d) and calibrate the transmitter range to cover the full diameter of the vessel or tank: the changes in volume for the h changes between h₀ and h max will be correct. Of course the transmitter will transmit, when the level is ≤h₀, the volume corresponding to h₀ the same apply for leve⊾h max. All transmitted volumes are % of the total volume of the vessel.





If it is required the partial volume starting from  $\hbar$ .e. the volume at  $\hbar = 0$ ) then the  $\hbar$ -coefficient should be equal to the polynomium solved for  $h_0$  with negative sign: for example for  $h_0 = 20\%$ 

$$A_0 = -0.02 + 0.297 \cdot 0.2 + 2.83 \cdot 0.2^2 - 4.255 \cdot 0.2^3 + 3.5525 \cdot 0.2^4 - 1.421 \cdot 0.2^5 = -0.14179$$

The polynomium coefficients for the example will be:

$$A_0$$
  $A_1$   $A_2$   $A_3$   $A_4$   $A_5$  Out = -0.14179 + 0.297 h + 2.83 h<sup>2</sup> - 4.255 h<sup>3</sup> + 3.5525 h<sup>4</sup> -1.421 h<sup>5</sup>



Note: The accuracy of all above numerical values can not be guaranteed.



### General notes for level measurement

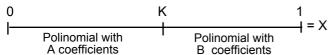
The level transmitter calibration is effected by the transmitter installation conditions, i.e. if the reference connection is empty (dry leg) or liquid filled (wet leg). In the first case (dry leg) the calibration in affected by the specific gravity of the measured liquid and the atmosphere above the liquid at process condition, whereas in the second case (wet leg), it is affected by the specific gravity of the liquid in the connecting pipe(s).

### 6.0 POLYNOMIAL 2 (Two polinomial functions of 2nd order) -

Analog Output transfer function can also be defined as a two polinomial function. Both polinomials are of 2nd order. So two different polinomial functions are used:

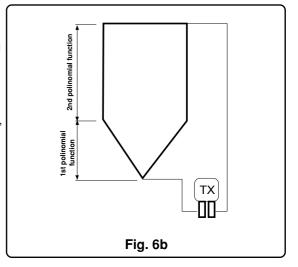
Out = 
$$[\pm A_0 + A_1(x^1) \pm A_2(x^2)] + [\pm B_0 + B_1(x^1) \pm B_2(x^2)]$$

Here the polinomial with A coefficients is used for X from 0 to a K value, and the second one with B coefficients for X greater than the K value.



Ax and Bx terms of the polinomials have to be calculated according to the shape of the vessel.

A PC based software tool is available for polinomial coefficients definition.



### 7.0 CONSTANT CURRENT

This output function, activated by a Configuration Tool, can be used to test the transmitter output, the integrity of the transmission loop and the calibration of associated equipment like receivers, recorders, etc. When this function is activated the transmitter acts like a costant current generator: using the configuration tool the user can specify a fixed output current of 4 mA, 20 mA or any value between 4 and 20 mA.

Flange-mounted transmitters are suitable for open or closed tank service.

The process fluid mayor may not, be corrosive, viscous, dirty and with suspended solids; each case requires a proper transmit 2600T Series provides a model for tank service.

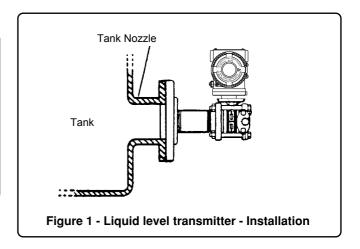
They includes two main application variants: one is dedicated to liquid level measurement and the other is marketed **derein**tial pressure transmitter but it is particularly suitable for liquid level measurement.

Liquid level transmitter is mounted to a tank as shown in Figure 1.

The ambient temperature of the transmitter mounting location must be between -40°C and +85°C (-40 and +185°F).

The process temperature can instead be between -40C and +320°C (-40 and +608°F). The process interface and fill fluid of the transmitter must be selected amongst the various options provided according to the specific range of temperature.

DANGER - For installation in Hazardous Areas, i.e. areas with danger of fire and/or explosion, irrespective of the protection mode used, the installation must carried out in accordance with local regulations. Ensure also that the temperature of the transmitter does not exceed the value indicated in the Safety Marking plate. In this connection, consider that process temperature above 85°C (185°F) requires derating the ambient limits by 1.5:1 ratio.



The liquid level transmitter has been designed to connect to a flanged tank nozzle, or similar ANSI (DIN) fitting. Standard connections for 2/3-inch Class 150/300/600 flanges, and equivalent DIN, are available.

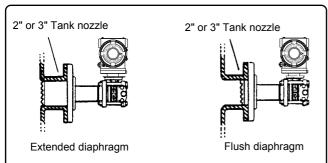


Figure 2 - Liquid level transmitter - Diaphragm options

Flush and extended diaphragm options are also available, Figure 2.

The flush diaphragm is suitable for applications where the process is free of suspended solids.

The extended diaphragm eliminates the pocket at the transmitter connection and is typically used for slurries and viscous liquids.

It is recommended that the liquid level transmitter be mounted with the process diaphragm vertical and with the housing above the primary transducer as described in the pictures.

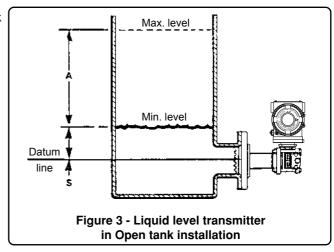
Operation is not affected by mounting in other positions, however, some rezeroing may be required.

The transmitter is insensitive to level changes over the lower half of the diaphragm, so it is important to locate the transdatum line with the center line of the tank nozzle. The nozzle also must be located so that the minimum level is always at or abovened datum line.

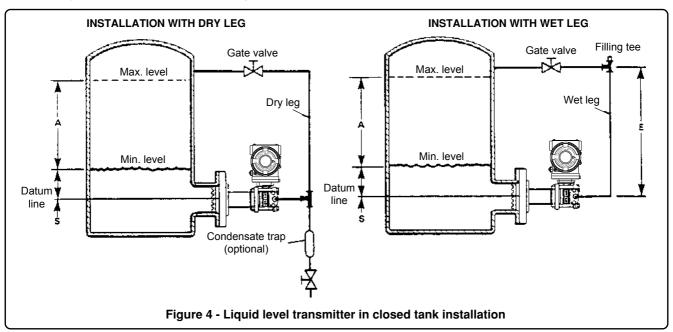
The liquid level transmitter can be used to measure liquid level in either open or closed (pressurized) tanks.

In open tank applications, mounting the transmitter on the tank nozzle provides the HI side process connection, with the LO side being vented to atmosphere. The hydraulic head pressure acting against the process diaphragm is a direct measurement of the liquid level. The effect of atmospheric pressure is canceled because this pressure is applied to both sides of the transmitter.

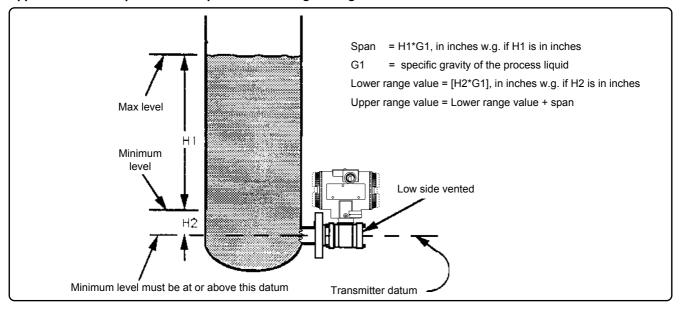
A recommended open tank installation is shown in Figure 3.



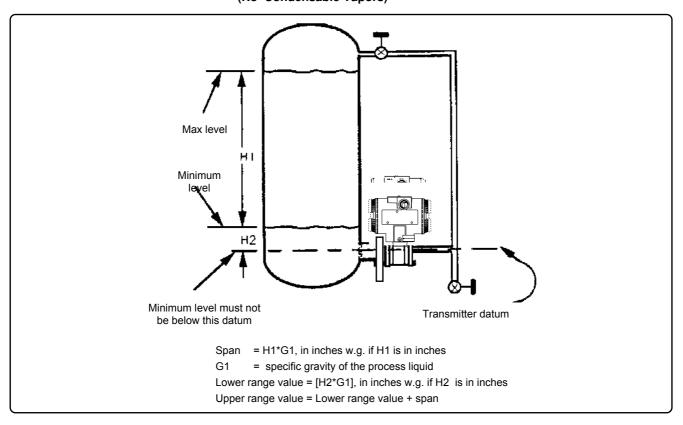
In the closed tank application, Figure 4, the effect of tank pressure is canceled by connecting the HI side and LO sidepoint tank transducer to the tank. The HI side connection is made by mounting the transmitter on the tank nozzle. A compensating leg connects to the LO side near the top of the tank. It is important to ensure that this leg is either completely free of liquid (y leg) or completely filled to a constant level (wet leg).



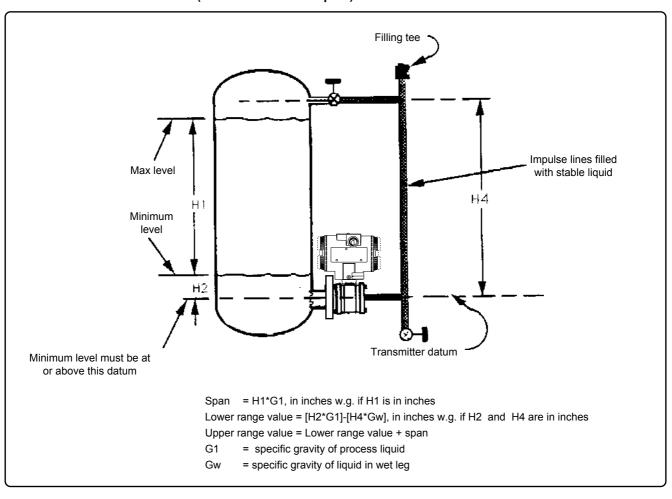
For a better understanding, three applications of liquid level measure are shown, as follows:

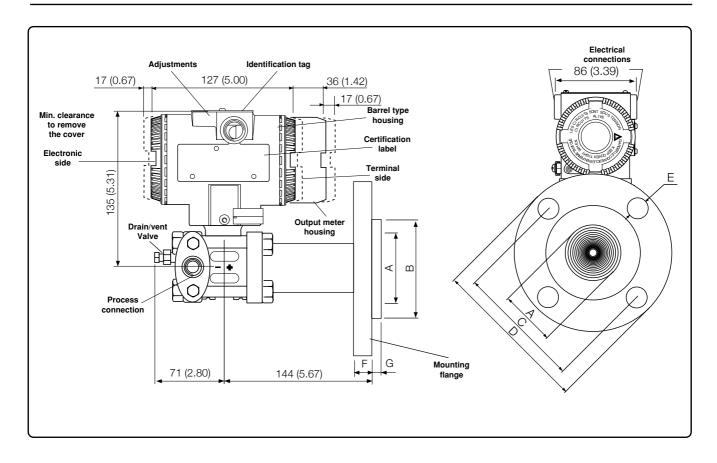


## Application n° 2 : Liquid Level - Closed Tank Using a Flange-Mounted Transmitter (No Condensable Vapors)



Application n° 3 : Liquid Level - Closed Tank Using a Flange-Mounted Transmitter and a Wet Leg (With Condensable Vapors)





Size/Rating		Dimensions mm (in)								
	A (dia)		B (dia)	C (dia)	D (dia)	E (dia)	F	G	N° of holes	
	flush	extended	2 (414)	- (ala)	2 (4.2)	_ (a.c.)				
2in ASME CL 150	60 (2.36)	48 (1.9)	92.1 (3.62)	120.65 (4.75)	152.4 (6)	20 (0.79)	19.05 (0.75)	9.5 (0.37)	4	
2in ASME CL 300	60 (2.36)	48 (1.9)	92.1 (3.62)	127 (5)	165.1 (6.5)	20 (0.79)	22.35 (0.88)	9.5 (0.37)	8	
2in ASME CL 600	60 (2.36)	NA	92.1 (3.62)	127 (5)	165.1 (6.5)	20 (0.79)	25.4 (1)	9.5 (0.37)	8	
2in ASME CL 900	60 (2.36)	NA	92.1 (3.62)	165 (6.5)	215.9 (8.5)	26 (1.02)	38.1 (1.5)	9.5 (0.37)	8	
3in ASME CL 150	89 (3.5)	72 (2.83)	127 (5)	152.4 (6)	190.5 (7.5)	20 (0.79)	23.87 (0.94)	9.5 (0.37)	4	
3in ASME CL 300	89 (3.5)	72 (2.83)	127 (5)	168.15 (6.62)	209.55 (8.25)	22 (0.86)	28.44 (1.12)	9.5 (0.37)	8	
3in ASME CL 600	89 (3.5)	NA	127 (5)	168.15 (6.62)	209.55 (8.25)	22 (0.86)	31.75 (1.25)	9.5 (0.37)	8	
3in ASME CL 900	89 (3.5)	NA	127 (5)	190.5 (7.5)	241 (9.48)	26 (1.02)	38.1 (1.50)	9.5 (0.37)	8	
4in ASME CL 150	89 (3.5)	94 (3.7)	157.2 (6.2)	190.5 (7.5)	228.6 (9)	20 (0.79)	24 (0.94)	9.5 (0.37)	8	
4in ASME CL 300	89 (3.5)	94 (3.7)	157.2 (6.2)	200.2 (7.88)	254 (10)	22 (0.86)	32 (1.26)	9.5 (0.37)	8	

Size/Rating		Dimensions mm (in)								
	A (dia)		B (dia)	C (dia)	D (dia)	E (dia)	F	G	N° of holes	
	flush	extended	D (ula)	C (dia)	D (dia)	E (Gla)	"	"		
DN50 EN PN16	60 (2.36)	48 (1.9)	102 (4.02)	125 (4.92)	165 (6.5)	18 (0.71)	20 (0.79)	9.5 (0.37)	4	
DN50 EN PN40	60 (2.36)	48 (1.9)	102 (4.02)	125 (4.92)	165 (6.5)	18 (0.71)	20 (0.79)	9.5 (0.37)	4	
DN50 EN PN63	60 (2.36)	NA	102 (4.02)	135 (5.31)	180 (7.08)	22 (0.86)	26 (1.02)	9.5 (0.37)	4	
DN50 EN PN100	60 (2.36)	NA	102 (4.02)	145 (5.71)	195 (7.67)	26 (1.02)	28 (1.1)	9.5 (0.37)	4	
DN80 EN PN16	89 (3.5)	72 (2.83)	138 (5.43)	160 (6.3)	200 (7.87)	18 (0.71)	20 (0.79)	9.5 (0.37)	8	
DN80 EN PN40	89 (3.5)	72 (2.83)	138 (5.43)	160 (6.3)	200 (7.87)	18 (0.71)	24 (0.94)	9.5 (0.37)	8	
DN80 EN PN63	89 (3.5)	NA	138 (5.43)	170 (6.7)	215 (8.46)	22 (0.86)	28 (1.1)	9.5 (0.37)	8	
DN80 EN PN100	89 (3.5)	NA	138 (5.43)	180 (7.08)	230 (9.05)	26 (1.02)	32 (1.26)	9.5 (0.37)	8	
DN100 EN PN16	89 (3.5)	94 (3.7)	158 (6.22)	180 (7.08)	220 (8.66)	18 (0.71)	20 (0.79)	9.5 (0.37)	8	
DN100 EN PN40	89 (3.5)	94 (3.7)	162 (6.38)	190 (7.48)	235 (9.25)	22 (0.86)	24 (0.94)	9.5 (0.37)	8	

Note: dimensions are expressed in mm. (Between parenthesis the same dimensions expressed in inches).

### Sensor trimming

If a sensor trimming operation is requested for level transmitters, follow the relevant procedure of the Hand Held Communicator and PC Software instructions.

If the result is not satisfactory after having carried out either the ZERO TRIMMING or the FULL TRIMMING, the operation must be repeated with a special variation for these transmitters.

This special procedure dedicated to the level transmitters is as follows:

a) LOW TRIM (low value) for FULL TRIM operation, or ZERO TRIM, only.

A standard operation must be performed according to the procedure. If the result is not satisfactory the operation must be repeated with a similar procedure but with a new value which has to be entered. This value must be calculated, as follows, taking in consideration the error with reversed sign:

new 
$$V$$
 entered =  $V$  applied -  $(V$  displayed -  $V$  applied)\* (\*) error

- 1st Example: Trimming at 10 mbar (applied value)

- 2nd Example: Trimming at true zero (0 mbar)

If the displayed value (via HART) after the first operation, is 10.2 mbar, then the error is +0.2 (10.2 - 10).

The new value to be therefore entered is 9.8 mbar (10 - 0.2).

If the displayed value (via HART) after the first operation, is -0.5 mbar, the operation must be repeated entering + 0.5 mbar.

\* Note: The LOW TRIM and ZERO TRIM operations affect the span as they do not change the upper range value previously set. So a high trimming operation according to point b, is highly recommended.

b) HIGH TRIM (high value) for FULL TRIM operation.

A standard operation must be performed according to the procedure. If the result is not satisfactory the operation must be repeated with a procedure similar to that shown at point a above. (new calculated value with error taken with reversed sign).

### **Output % Reranging**

Sometimes, in case of tank level measurement, it becomes difficult to calculate the LRV or the URV of the transmitter, or topism the tank for zero adjustment. So, not only with flange-mounted, but also with differential pressure transmitters using remotels, the Output % Reranging operation helps the user during transmitter calibration.

When it is knows the level of the tank, expressed in percentage, the liquid level, it is possible to input this percentage that automatically the transmitter recalculates its LRV and URV according to the new percentage value.

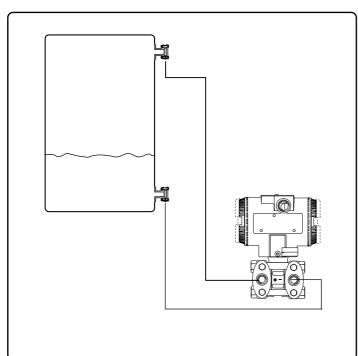
This can be done using a HART configuration tool on a 2600T Transmitter.

Two options are available as Output % Reranging operation:

where both LRV and URV are adjusted 1) OP Range Low

2) OP Range High where only URV is change in accordance with the new input percentage

As example:



Actual level measured by the transmitter:

Transmitter output = 27%

Calibration: LRV = -125 mbar

URV = +340 mbar

a) New input level measurement (Option 1) = 30%

New calibration: LRV = -139.5 mbar

URV = +325.5 mbar

The transmitter output is now = 30%

Starting again from the initial settings:

Transmitter output = 27%

Calibration: LRV = -125 mbar

URV = +340 mbar

b) New input level measurement (Option 2) = 30%

New calibration: LRV = -125 mbar URV = +291.5 mbar

The transmitter output is now = 30%

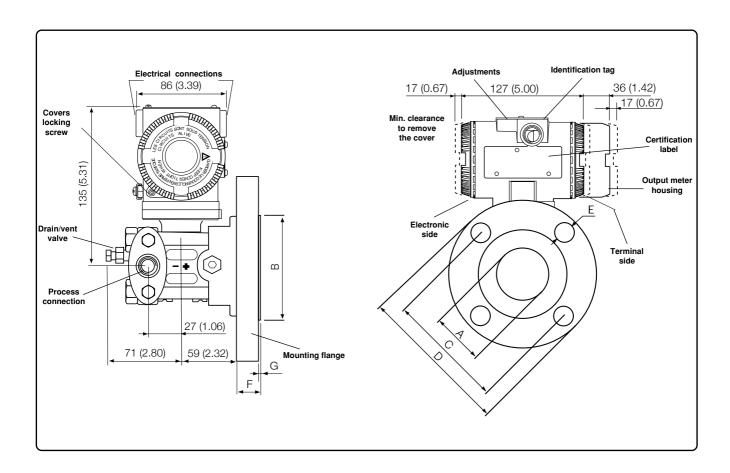
These models of differential transmitter are suitable for liquid level measurement.

The fluid, in this case, must be clean, free of solids and not viscous. This is because the process diaphragm is recessed into the flange face.

The differential transmitter has been designed to connect to a flanged tank nozzle, or similar ASME (EN) fitting.

Standard connections for 2/3-inch Class 150/300, and equivalent EN, are available (see Figures 1 and 2).

This model is specifically dedicated to closed (pressurized) tanks (see Figure 4 and Applications n°2 and n°3).



Rating	Size	Dimensions mm (in)							
		A (dia)	B (dia)	C (dia)	D (dia)	E (dia)	F	G	N° of holes
ASME 150 R.F.	2in	53 (2.09)	92 (3.62)	120.5 (4.74)	152.5 (6)	20 (0.79)	19.5 (0.77)	1.6 (0.07)	4
ASME 150 R.F.	3in	77 (3.04)	127 (5)	152.5 (6)	190.5 (7.5)	20 (0.79)	24 (0.94)	1.6 (0.07)	4
ASME 300 R.F.	2in	53 (2.09)	92 (3.62)	127 (5)	165 (6.5)	20 (0.79)	22.5 (0.89)	1.6 (0.07)	8
ASME 300 R.F.	3in	77 (3.04)	127 (5)	168.5 (6.63)	210 (8.26)	22 (0.86)	28.5 (1.12)	1.6 (0.07)	8
EN PN 16 Type B1	DN50	53 (2.09)	102 (4.02)	125 (4.92)	165 (6.5)	18 (0.71)	20 (0.79)	3 (0.12)	4
EN PN 16 Type B1	DN80	77 (3.04)	138 (5.43)	160 (6.3)	200 (7.87)	18 (0.71)	20 (0.79)	2 (0.08)	8
EN PN 40 Type B1	DN50	53 (2.09)	102 (4.02)	125 (4.92)	165 (6.5)	18 (0.71)	20 (0.79)	3 (0.12)	4
EN PN 40 Type B1	DN80	77 (3.04)	138 (5.43)	160 (6.3)	200 (7.87)	18 (0.71)	24 (0.94)	2 (0.08)	8

## ADDENDUM FOR "EX SAFETY" ASPECTS AND "IP" PROTECTION (EUROPE)

According to ATEX Directive (European Directive 94/9/EC of 23 March 1994) and relative European Standards which can assure compliance with Essential Safety Requirements, i.e., EN 60079-0 (General requirements), EN 60079-1 (Flameproof enclosures "d"), EN 60079-11 (Intrinsic safety "i"), EN 60079-26 (Equipments, group II, category 1G) for GAS and EN 61241-0 (General requirements), EN 61241-1 (Flameproof enclosures "d"), EN 61241-11 (Intrinsic safety "i") for DUST. The pressure transmitters of the 2600T SERIES have been certified for the following group, categories, media of dangerous atmosphere, temperature classes, types of protection. Examples of application are also shown below by simple sketches.

### Certificate ATEX II 1G Ex ia IIC T6

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

II: Group for surface areas (not mines)

1: Category

G: Gas (dangerous media)

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

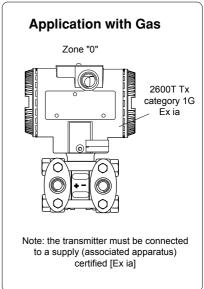
The other marking refers to the protection type used according to relevant EN standards:

Ex ia : Intrinsic safety, protection level "a"

IIC : Gas group

T6 : Temperature class of the transmitter (which corresponds to 85°C max) with a Ta (ambient temperature) +40°C

About the applications, this transmitter can be used in "Zone 0" (Gas) as it is shown on the picture.



### Certificate ATEX II 1/2G Ex ia IIC T6

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

II: Group for surface areas (not mines)

1/2: Category

G: Gas (dangerous media)

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

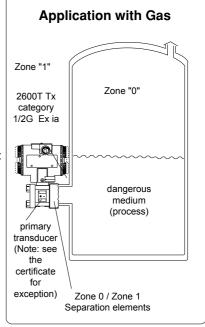
The other marking refers to the protection type used according to relevant EN standards:

Ex ia : Intrinsic safety, protection level "a"

IIC : Gas group

T6 : Temperature class of the transmitter (which corresponds to 85°C max) with a Ta (ambient temperature) +40°C

About the applications, this transmitter can be used in "Zone 0" (Gas) and "Zone 1" as it is shown on the picture.



## . ADDENDUM FOR "EX SAFETY" ASPECTS AND "IP" PROTECTION (EUROPE)

### Certificate ATEX II 1D Ex iaD 20 T95°C

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

Group for surface areas (not mines)

1: Category

D: Dust (dangerous media)

T95°C: Maximum surface temperature of the transmitter enclosure with a Ta

> (ambient temperature) +75°C for Dust (not Gas). For application with dust layer between 5 and 50 mm, maximum surface temperature must

be consider according to IEC 61241-14 chapter 6.3.3.3.

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

The other marking refers to the protection type used according to relevant EN standards: Ex iaD 20 : Construction with inside intrinsic safety electronics suitable for Dust -Zone 20

About the applications, this transmitter can be used in "Zone 20" (Dust) classified area (continuous hazard) as it is shown on the picture.

# **Application with Dust** Zone "20" 2600T Tx category 1D Ex iaD Note: the protection is mainly assured by the "IP degree" associated to the low power from the supply certfied [Ex ia]

### Certificate ATEX II 1/2D Ex iaD 21 T95°C

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

II : Group for surface areas (not mines)

1/2: Category

D: Dust (dangerous media)

T95°C: Maximum surface temperature of the transmitter enclosure with a Ta

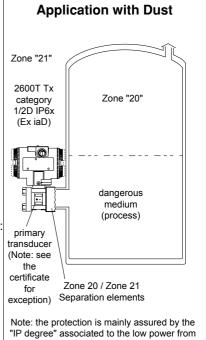
(ambient temperature) +75°C for Dust (not Gas). For application with dust layer between 5 and 50 mm, maximum surface temperature must

be consider according to IEC 61241-14 chapter 6.3.3.3.

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

The other marking refers to the protection type used according to relevant EN standards Ex iaD 21: Construction with inside intrinsic safety electronics suitable for Dust -Zone 21.

About the applications, this transmitter can be used in "Zone 20" (Dust) and "Zone 21" classified area (continuous hazard) as it is shown on the picture.



the supply. This can either be [b] or [ia] .

## ... ADDENDUM FOR "EX SAFETY" ASPECTS AND "IP" PROTECTION (EUROPE)

### Certificate ATEX II 1/2G Ex d IIC T6

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

II: Group for surface areas (not mines)

1/2 : Category

G: Gas (dangerous media)

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

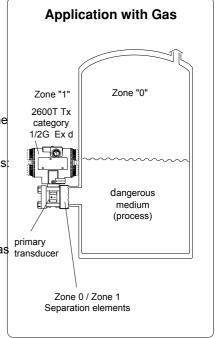
The other marking refers to the protection type used according to relevant EN standards

Ex d: Flameproof IIC: Gas group

T6 : Temperature class of the transmitter (which corresponds to 85°C max)

with a Ta (ambient temperature) +40°C

About the applications, this transmitter can be used in "Zone 0" (Gas) and "Zone 1" as transducer it is shown on the picture.



### Certificate ATEX II 1/2D Ex tD A21 IP67 T85°C

ZELM Certificate number ZELM 08 ATEX 0361 X

The meaning of ATEX code is as follows:

II: Group for surface areas (not mines)

1/2: Category

D: Dust (dangerous media)

T85°C: Maximum surface temperature of the transmitter enclosure with a Ta

(ambient temperature) +75°C for Dust (not Gas). For application with dust layer between 5 and 50 mm, maximum surface temperature must

be consider according to IEC 61241-14 chapter 6.3.3.3.

(Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the surveillance for the production of the transmitter)

The other marking refers to the protection type used according to relevant EN standards Ex tD A21: Construction with flameproof of protection method suitable for Dust - Zone 21

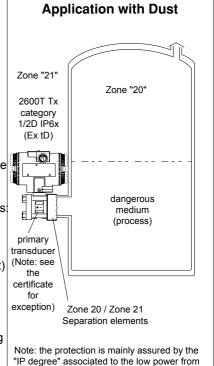
About the applications, this transmitter can be used in "Zone 20" and "Zone 21" (Dust) classified area (continuous hazard) as it is shown on the picture.

### IP code

About the degree of protection provided by the enclosure of the pressure transmitterthe 2600T SERIES has been certified IP67 according to EN 60529 standard (corresponding to IEC 529).

The first characteristic numeral indicates the protection of the inside electronics against ingress of solid forein objects including dusts. The assigned "6" means an enclosure dust-tight (no ingress of dust).

The second characteristic numeral indicates the protection of the inside electronics against ingress of water. The assigned "7" means an enclosure water-protected against a temporary immersion in water under standardized conditions of pressure and time.



the supply certfied (Ex ia).

## ... ADDENDUM FOR "EX SAFETY" ASPECTS AND "IP" PROTECTION (IECEX)

### Certificate IECEx Ex d IIC T6 Ga/Gb

ZELM Certificate number IECEx ZLM 11.0006X

The marking refers to the protection type used according to relevant EN standards:

Ex d: Flameproof IIC: Gas group

T6: Temperature class of the transmitter (which corresponds to

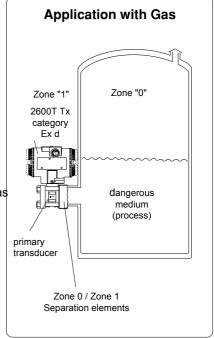
 $85^{\circ}\text{C}$  max) with a Ta (ambient temperature) from -40°C to

+75°C

Ga/Gb: protection level (EPL for Gas)

ambient temperature : (-40°C < Ta < +75°C)

About the applications, this transmitter can be used in "Zone 0" (Gas) and "Zone 1" as it is shown on the picture.



### Certificate IECEx Ex d tb IIIC T85°C Da/Db

ZELM Certificate number IECEx ZLM 11.0006X

The marking refers to the protection type used according to relevant EN standards:

Ex d: Flameproof

tb : Protection by enclosure
IIIC : conductive Dust Group
T85°C : class temperature for Dust
Da/Db : protection level (EPL for Dust)

ambient temperature : (-40°C < Ta < +75°C)

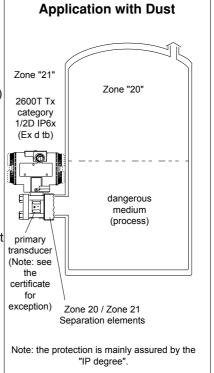
About the applications, this transmitter can be used in "Zone 20" and "Zone 21" (Dust) classified area (continuous hazard) as it is shown on the picture.

### IP code

About the degree of protection provided by the enclosure of the pressure transmitterthe 2600T SERIES has been certified IP67 according to IEC 60529 standard.

The first characteristic numeral indicates the protection of the inside electronics against ingress of solid forein objects including dusts. The assigned "6" means an enclosure dust-tight (no ingress of dust).

The second characteristic numeral indicates the protection of the inside electronics against ingress of water. The assigned "7" means an enclosure water-protected against a temporary immersion in water under standardized conditions of pressure and time.



## ... ADDENDUM FOR "EX SAFETY" ASPECTS AND "IP" PROTECTION (EUROPE)

## Certificate ATEX II 1/2 G Ex d IIC T4/T5/T6 or II 1/2 D Ex tD A21 IP67 T85°C (-40°C ≤ Ta <+85°C)

CESI Certificate number CESI 02 ATEX 027

The meaning of ATEX code is as follows:

II : Group for surface areas (not mines)

1/2 : Category - It means that only a part of the transmitter complies with category 1 and a second part complies with

category 2 (see next application sketch)

G : Gas (dangerous media)
D : Dust (dangerous media)

T85°C : Maximum surface temperature of the transmitter enclosure with a Ta (ambient temperature) +75°C

for Dust (not Gas). For application with dust layer between 5 and 50 mm, maximum surface temperature must be

consider according to IEC 61241-14 chapter 6.3.3.3.

Note: the number close to the CE marking of the transmitter safety label identifies the Notified Body which carries out the Surveillance for the production of the transmitter.

The other marking refers to the protection type used according to relevant EN Standards:

Ex d: Flameproof

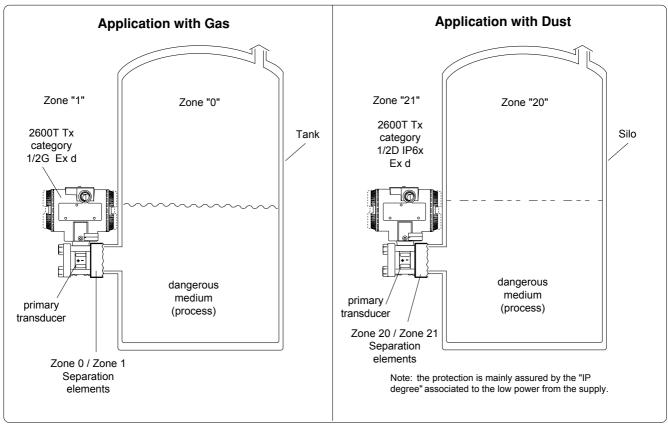
Ex tD A21 : Construction with flameproof of protection method suitable for Dust - Zone 21

IIC: Gas group

T6: Temperature class of the transmitter (which corresponds to 85°C max) with a Ta (ambient temperature) +40°C

T4: Temperature class of the transmitter (which corresponds to 135°C max) with a Ta (ambient temperature) +85°C

About the applications, this transmitter can be used in Zone "0" (Gas) classified areas (continuous hazard) with its "process part" only, whereas the remaining part of the transmitter , i.e. its enclosure, can be used in Zone 1 (Gas), only (see sketch below). Reason of this is the process part of the transmitter (normally called primary transducer) that provides inside separior elements to seal off the electrical sensor from the continuously hazardous process, according to the EN50284 and EN50018. About Dust application, the transmitter is suitable for "Zone 21" according to the EN 50281 as it is shown on the relevant paof the sketch:



IP code

About the degree of protection provided by the enclosure of the pressure transmitter, the 2600T SERIES has been certified IP67 according to EN 60529 standard (corresponding to IEC 529).

The first characteristic numeral indicates the protection of the inside electronics against ingress of solid forein objects inc luding dusts. The assigned "6" means an enclosure dust-tight (no ingress of dust).

The second characteristic numeral indicates the protection of the inside electronics against ingress of water . The assigned "7" means an enclosure water-protected against a temporary immersion in water under standardized conditions of pressure and time.

## ADDENDUM FOR "EX SAFETY" ASPECTS (NORTH AMERICA)

According to Factory Mutual Standards which can assure compliance with Essential Safety Requirements

FM 3600 : Electrical Equipment for use in Hazardous (Classified) Locations, General Requirements.

**FM 3610**: Intrinsically Safe Apparatus and Associated Apparatus for Use in Class I, II, III, Division 1, and Class I, Zone 0 & 1 Hazardous (Classified) Locations.

**FM 3611**: Nonincendive Electrical Equipment for Use in Class I and II, Division 2 and Class III Division 1 and 2 Hazardous (Classified) Locations.

FM 3615: Explosionproof Electrical Equipment.

FM 3810: Electrical and Electronic Test, Measuring and Process Control Equipment.

NEMA 250: Enclosure for Electrical Equipment (1000 Volts Maximum)

The 2600T Series pressure transmitters have been certified by Factory Mutual for the following Class, Divisions and Gas groups, hazardous classified locations, temperature class and types of protection.

- Explosionproof for Class I, Division 1, Groups A, B, C and D, hazardous (classified) locations.
- Dust Ignition proof for Class II, III Division 1, Groups E, F and G, hazardous (classified) locations.
- Suitable for Class II, III, Division 2, Groups F and G, hazardous (classified) locations.
- NonIncendive for Class I, Division 2, Groups A, B, C and D, in accordance with Nonincendive field wiring requirements for hazardous (classified) locations.
- Intrinsically Safe for use in Class I, II and III, Division 1, Groups A, B, C, D, E, F, and G in accordance with Entity exquirts for hazardous (classified) locations.
- · Temperature class T4 to T6 (dependent on the maximum input current and the maximum ambient temperature).
- Ambient Temperature range -40 °C to +85 °C (dependent on the maximum input current and the maximum temperature class).
- Electrical Supply range Minimum 10.5 Volts, Maximum 42 Volts (dependent on the type of protection, maximum ambient temperature, maximum temperature class and communication protocol).
- · Type 4X applications Indoors/Outdoors.

For a correct installation in field of 2600T Series pressure transmitters please see the related control drawing.

Note that the associated apparatus must be FM approved.

## ADDENDUM FOR "EX SAFETY" ASPECTS (NORTH AMERICA)

According to CSA International Standards which can assure compliance with Essential Safety Requirements

### C22.2

0-M1991: General Requirements - Canadian Electrical Code Part II.

0.4-M1982: Bounding and Grounding of Electrical Equipment (Protective Grounding)

0.5-M1982: Threaded Conduit Entries

**25-M1966**: Enclosures for use in Class II Groups E, F and G Hazardous Locations. **30-M1986**: Explosion-proof Enclosures for use in Class I Hazardous Locations.

94-M1991: Special Purpose Enclosures.

213-M1987: Non-Incendive Electrical Equipment for use in Class I Division 2 Hazardous Locations.

157-M1992: Intrinsically Safe and Non-Incendive Equipment for use in Hazardous Locations.

### CAN/CSA C22.2 No.1010.1-92

Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use, Part 1 : General Requirements (includes Amendment 1)

### CAN/CSA C22.2 No.1010.1B-97

Amendment 2 to CAN/CSA C22.2 No 1010.1-92

### CAN/CSA E60079-0-00

Electrical apparatus for explosive gas atmosphere. Part 0: General Requirements.

### CAN/CSA E60079-1-01

Electrical apparatus for explosive gas atmosphere. Part 1 : Construction and verification test of flameproof enclosure of electrical apparatus.

### CAN/CSA E60079-11-02

Electrical apparatus for explosive gas atmosphere. Part 11: Intrinsic Safety "i"

The 2600T Series pressure transmitters have been certified by CSA International for the following Class, Divisions and Gas groups, hazardous classified locations, temperature class and types of protection.

- Explosionproof for Class I, Division 1 and 2, Groups A, B, C and D; Class II Groups E, F and G; Class III; Enclosure Type 4X Ex d IIC.
- Non incendive for Class I, Division 2, Groups A, B, C and D; Class II Groups E, F and G; Class III; Enclosure Type 4X Ex nL IIC.
- Intrinsically Safe for Class I, Division 1 and 2, Groups A, B, C and D; Class II Groups E, F and G; Class III; Enclosure Type 4X Ex ia IIC.
- Temperature class T4 to T6 (dependent on the maximum input current and the maximum ambient temperature).
- Ambient Temperature range -40°C to +85°C (dependent on the maximum input current and the maximum temperature class).
- Electrical Supply range Minimum 10.5 Volts, Maximum 42 Volts (dependent on the type of protection, maximum ambient temperature, maximum temperature class and communication protocol).
- Type 4X applications Indoors & Outdoors.
- Pollution Degree I
- Installation Category II
- Altitude 2000 m
- Humidity 0 to 80%

For a correct installation in field of 2600T Series pressure transmitters please see the related control drawing.

Note that the associated apparatus must be CSA approved.



## EC DECLARATION OF CONFORMITY

We:

ABB S.p.A. - ABB SACE Division **Business Unit Instrumentation** 

Via Statale, 113 22016 Lenno (Como)

Italy

declares under our sole responsibility that the products:

2600T EN Series (Transmitters models 262/264/266/268, Hand Held Terminal, Field Indicator) in all the communication configurations (4÷20 mA + HART®, Profibus, Foundation Fieldbus, Safety)

## are in conformity with the following standards:

EN 61000-6-3 (2001)

Electromagnetic compatibility (EMC) - Generic standards - Emission

standard for residential, commercial and light-industrial environments

according to:

EN55022

(2001)

EN 61000-6-2 (2001)

Electromagnetic compatibility (EMC) - Generic standards - Immunity for

industrial environments

according to:

EN 61000-4-2 (2001)

EN 61000-4-3 (2002)EN 61000-4-4 (2001)EN 61000-4-5 (2001)

EN 61000-4-6 (2001)

following the provisions of the EMC Directives 89/336/EEC and 93/68/EEC.

ABB S.p.A. - ABB SACE Division Business Unit Instrumentation

Eugenio Volonterio Technical Manager

Lenno, 14th May 2008

ABB S.p.A.

ABB SACE Division

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## PRODUCTS & CUSTOMER SUPPORT

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  - Food & Beverage
  - Manufacturing
  - Metals and Minerals
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  - Pulp and Paper

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- · Circular Chart, Strip Chart and Paperless Recorders
- Paperless Recorders
- Process Indicators

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- · Systems Integration

## **Transmitters**

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- Temperature
- Level
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- Actuators
- Positioners

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- Zirconia oxygen analyzers, katharometers, hydrogen purity and purge-gas monitors, thermal conductivity.

## **Customer Support**

We provide a comprehensive after sales service via a Worldwide Service Organization. Contact one of the following offices for details on your nearest Service and Repair Centre.

### Italy

ABB S.p.A.

**Business Unit Measurement Products** 

Tel: +39 0344 58111 Fax: +39 0344 56278

### **United Kingdom**

**ABB Limited** 

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### **United States of America**

ABB Inc.

Tel: +1 (0) 755 883 4366 Fax: +1 (0) 755 883 4373

### **Client Warranty**

Prior to installation, the equipment referred to in this manual must be stored in a clean, dry environment, in accordance with the Company's published specification.

Periodic checks must be made on the equipment's condition. In the event of a failure under warranty, the following documentation must be provided as substantiation:

- A listing evidencing process operation and alarm logs at time of failure.
- Copies of all storage, installation, operating and maintenance records relating to the alleged faulty unit.

ABB has Sales & Customer Support expertise in over 100 countries worldwide

www.abb.com/instrumentation

The Company's policy is one of continuous product improvement and the right is reserved to modify the information contained herein without notice.

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