

ABB INDUSTRIAL DRIVES

ACS880-1607LC DC/DC-converter units

Hardware manual



ACS880-1607LC DC/DC-converter units

Hardware manual

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Further information



1

Introduction to the manual

Contents of this chapter

This chapter gives basic information on the manual.

Applicability

The manual is applicable to ACS880-1607LC DC/DC-converter units that form a part of an ACS880 multidrives system.

Safety instructions

Obey all safety instructions of the drive.

- Read the **complete safety instructions** before you install, commission, use or service the drive. The complete safety instructions are given in [ACS880 liquid-cooled multidrives cabinets and modules safety instructions \(3AXD50000048633 \[English\]\)](#).
- Read the warnings of the software function before you take the function in use or change its default parameter settings. Read the warnings of the parameter before you change its default setting. Refer to the firmware manual.

Target audience

This manual is intended for people who plan the installation, install, commission, and do maintenance work on the drive, or create instructions for the end user of the drive concerning the installation and maintenance of the drive.

Read the manual before you do work on the drive. You are expected to know the fundamentals of electricity, wiring, electrical components, and electrical schematic symbols.

Categorization by frame size and option module

Some descriptions, instructions and technical data which concern only certain module or frame sizes are marked with the size identifier (such as "2×R8i", etc.). The marking derives from the quantity and basic construction of the converter modules that form the converter unit. For example, frame size "2×R8i" indicates that the converter unit consists of two frame size R8i converter modules connected in parallel.

The frame size is marked on the type designation labels. The frame size of each drive module is also shown in the rating tables.

The instructions and technical data which concern only certain optional selections are marked with option codes (such as +E205). The options included in the drive can be identified from the option codes visible on the type designation label.

There are two versions of frame size 2×R7i with different cabinet constructions. Refer to [Frame 2×R7i versions \(page 49\)](#).

Use of component designations

Some device names in the manual include the component designation in brackets (for example, [Q20]). This will help you to identify the components in the circuit diagrams.

Terms and abbreviations

Term	Description
BAMU	Auxiliary measurement unit
BCU	Type of control unit
BDCL	Series of L-filters, for example BDCL-14-5
CIO	I/O module for controlling cooling fans
Control unit	Enclosure that contains the control board and related connector boards. The term is also used as a synonym for the control board.
Cubicle	One section of a cabinet-installed drive. A cubicle is typically behind a door of its own.
DC/DC-converter	Charges or discharges an external energy storage (such as a battery or capacitor bank) from or into the DC bus
DC/DC-converter module	Converter power electronics, related components and DC capacitors enclosed in a metal frame or enclosure. Intended for cabinet installation.
DC/DC-converter unit	DC/DC-converter module(s) under control of one control unit, and related components
DDC	DC/DC-converter unit
DI	Digital input
DOL	Direct-on-line
Drive	Frequency converter for controlling AC motors
Energy storage	Device that stores electrical energy, for example, a battery or a super capacitor.
Frame, frame size	Physical size of the drive or power module
INU	Inverter unit
Inverter	Converts direct current and voltage to alternating current and voltage.
Inverter unit	Inverter module(s) under control of one control unit, and related components. One inverter unit typically controls one motor.
Multidrive	Drive for controlling several motors which are typically coupled to the same machinery. Includes one supply unit, and one or several inverter units.

Term	Description
Parameter	In the drive or converter control program, parameter is a user-adjustable setting, or a read-only monitoring signal. In some (for example fieldbus) contexts, a value that can be accessed as an object. For example, variable, constant, or signal.
PLC	Programmable logic controller
Supply unit	Supply module(s) under control of one control unit, and related components.
UCU	Type of control unit
USCA-02	Adapter for installing F-series option modules onto the UCU control unit.

Related documents

For more documentation, go to www.abb.com/drives/documents.



[Manuals for ACS880 multidrives cabinets](#)

2

Operation principle and hardware description

Contents of this chapter

This chapter describes the DC/DC-converter operation basics and the hardware of the converter.

Operation principle

The DC/DC-converter unit (DDC) transfers energy from a common DC bus of a drive into an external energy storage and discharges energy back to the DC bus. The energy storage can be, for example, a battery or super capacitor. The energy storage is not included in the converter unit delivery.

The DC/DC-converter unit has a single converter module or parallel converter modules under the command of one control unit. Parallel DC/DC-converter modules must have a common energy storage. Each parallel module must have the output cabling of its own. ABB also recommends that you use identical cablings (cable type, cross-sectional area, and length) and have identical load for each module. For other solutions, contact ABB.

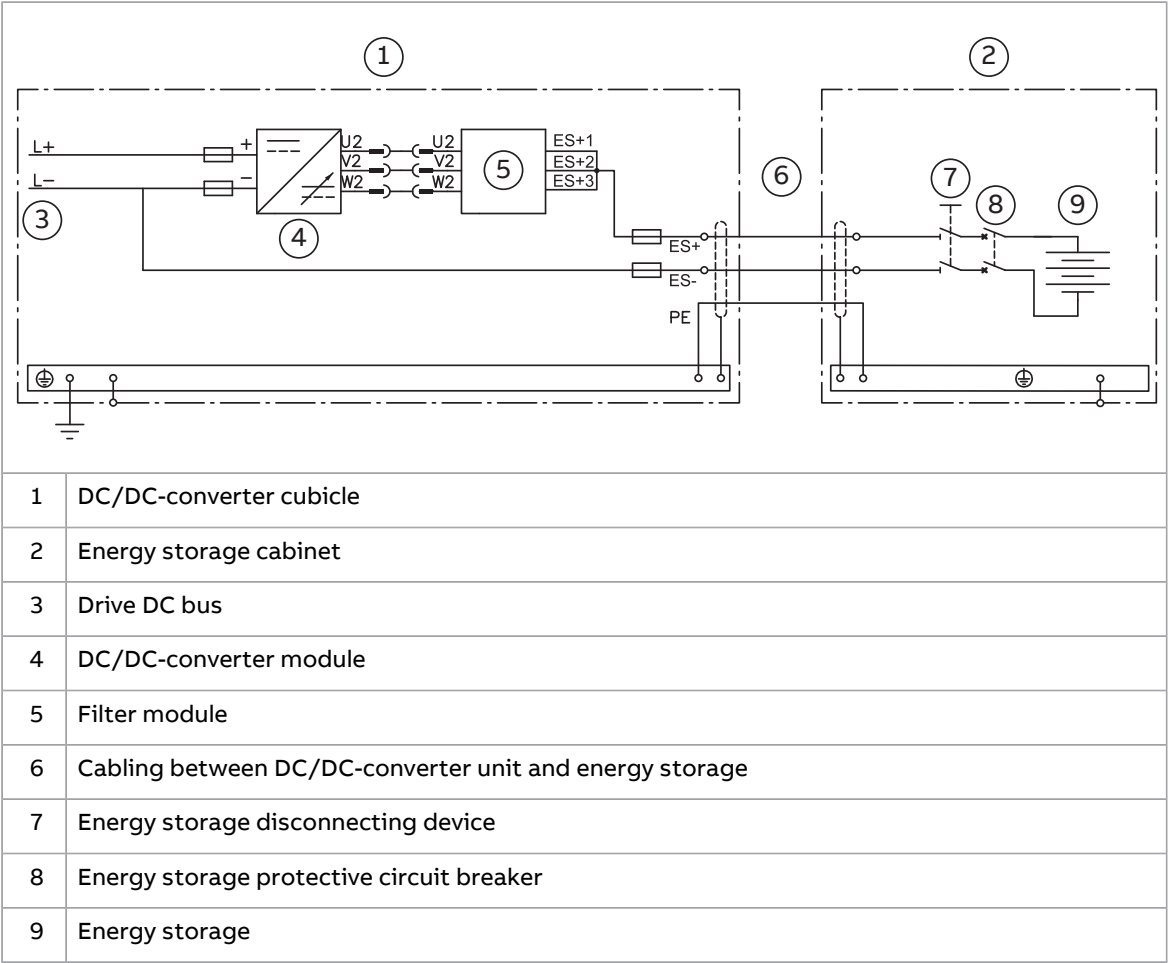
Typically, the DC/DC-converter is used in marine applications for heave compensation, peak load compensation, propulsion supply in harbors, energy storing instead of an additional generator and so on. The DC/DC-converter can also be used in automotive applications such as electric car charging systems and also in several other applications where energy storing and reuse is needed.

■ Main circuit diagram

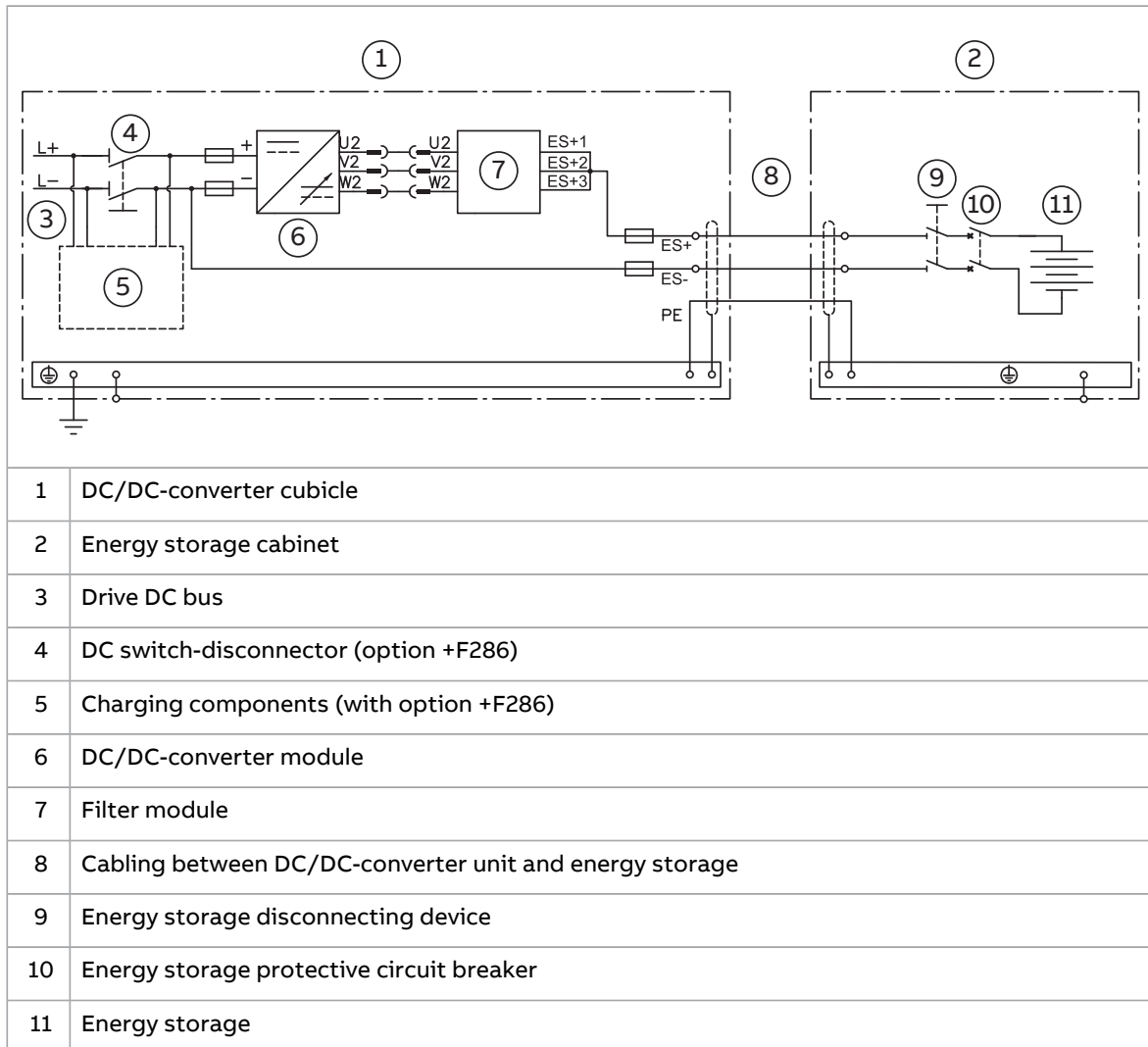
The DC/DC-converter has output DC fuses and DC fuses on the drive DC bus side. A DC switch-disconnector is available as option +F286.

16 Operation principle and hardware description

This figure shows a simplified main circuit diagram of a DC/DC-converter without a DC switch-disconnector or charging circuit.

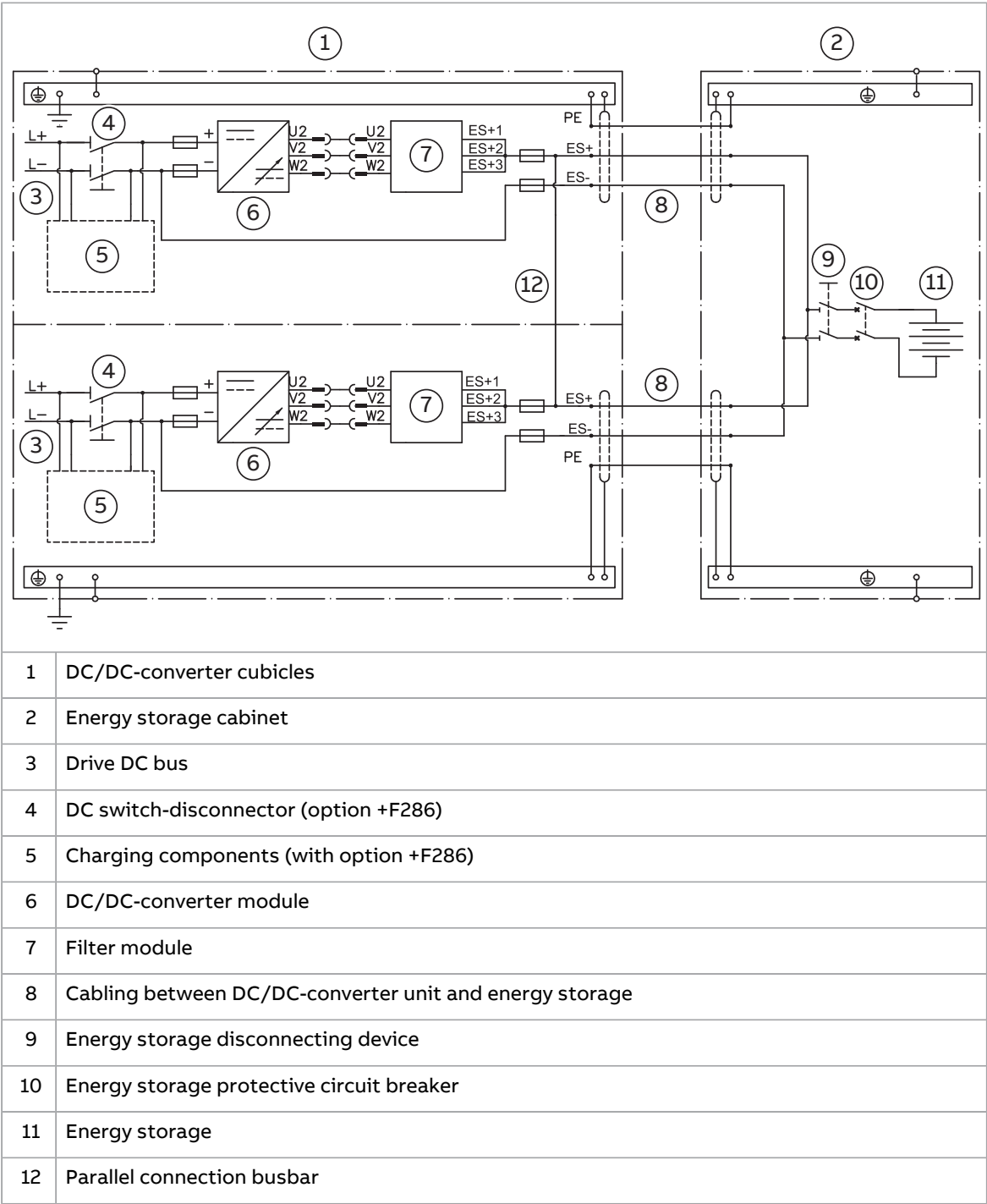


This figure shows a simplified main circuit diagram of a DC/DC-converter with the DC switch-disconnector (option +F286) and charging circuit.

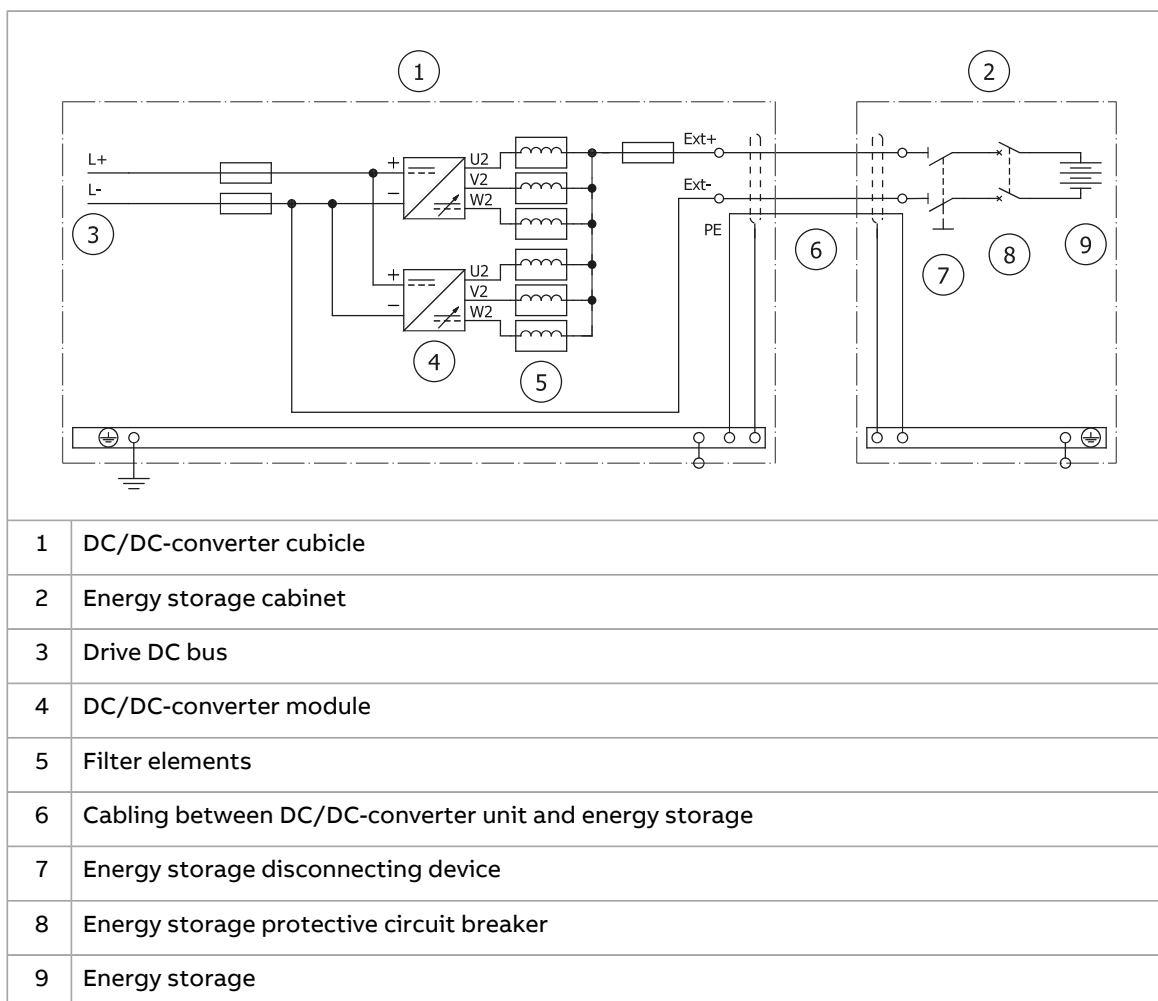


18 Operation principle and hardware description

This figure shows a simplified main circuit diagram of parallel-connected DC/DC-converter modules with the DC switch-disconnector (option +F286) and charging circuit. Also the energy storage and related cabling and equipment are visible.

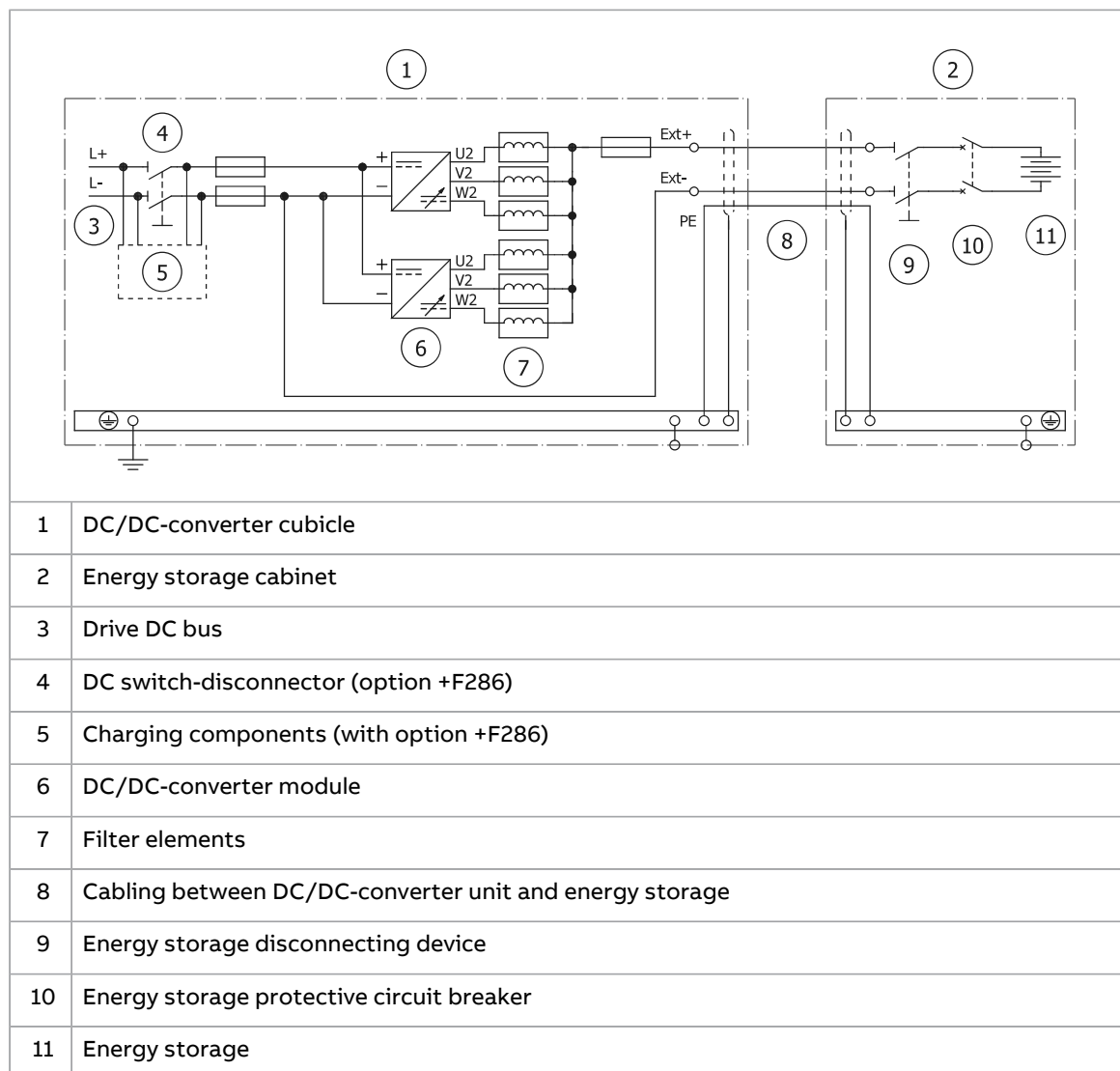


This figure shows a simplified main circuit diagram of a DC/DC-converter without a DC switch-disconnector or charging circuit used in frame 2×R7i in one cubicle.



20 Operation principle and hardware description

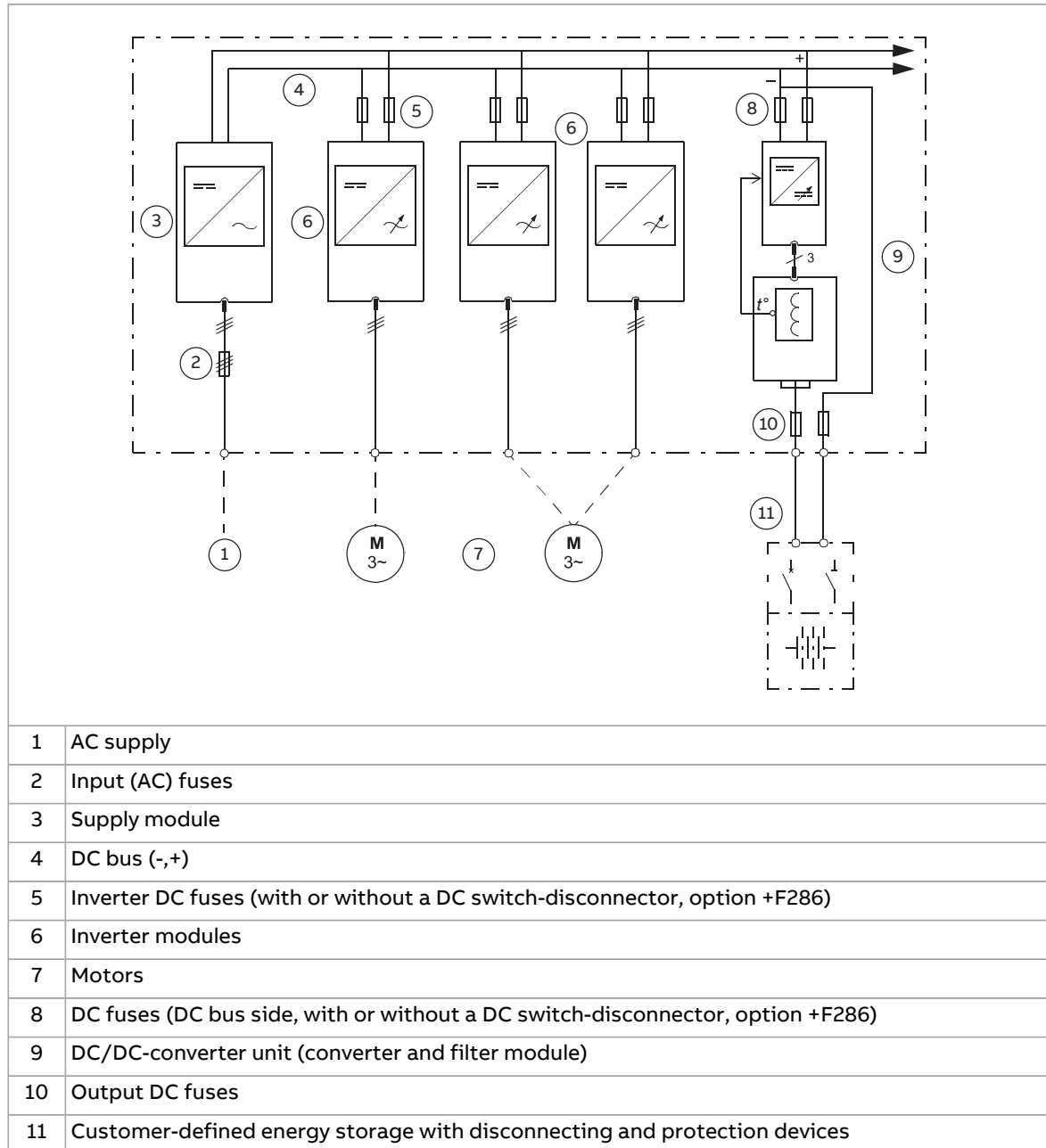
This figure shows a simplified main circuit diagram of a DC/DC-converter with the DC switch-disconnector (option +F286) and charging circuit used in frame 2×R7i in one cubicle.



Overview diagram of a drive with a DC/DC-converter unit

This diagram shows a possible application of a converter unit in an example system. The DC/DC-converter unit includes a DC/DC-converter module and a filter module.

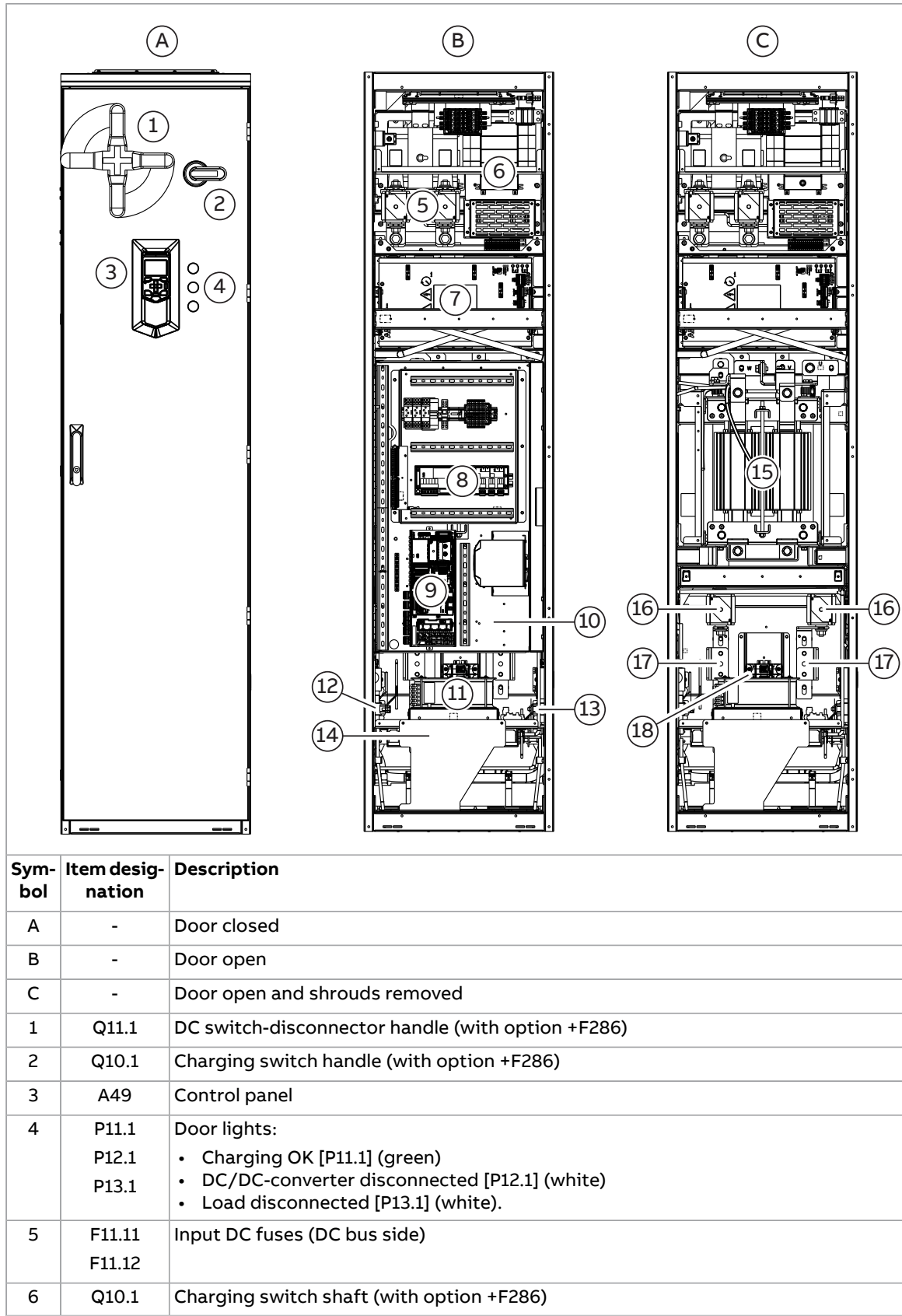
Note: Frame 2×R7i in one cubicle does not include a filter module. This version uses separate components instead.



Converter unit hardware

■ Cabinet layout – Frame R7i converter module

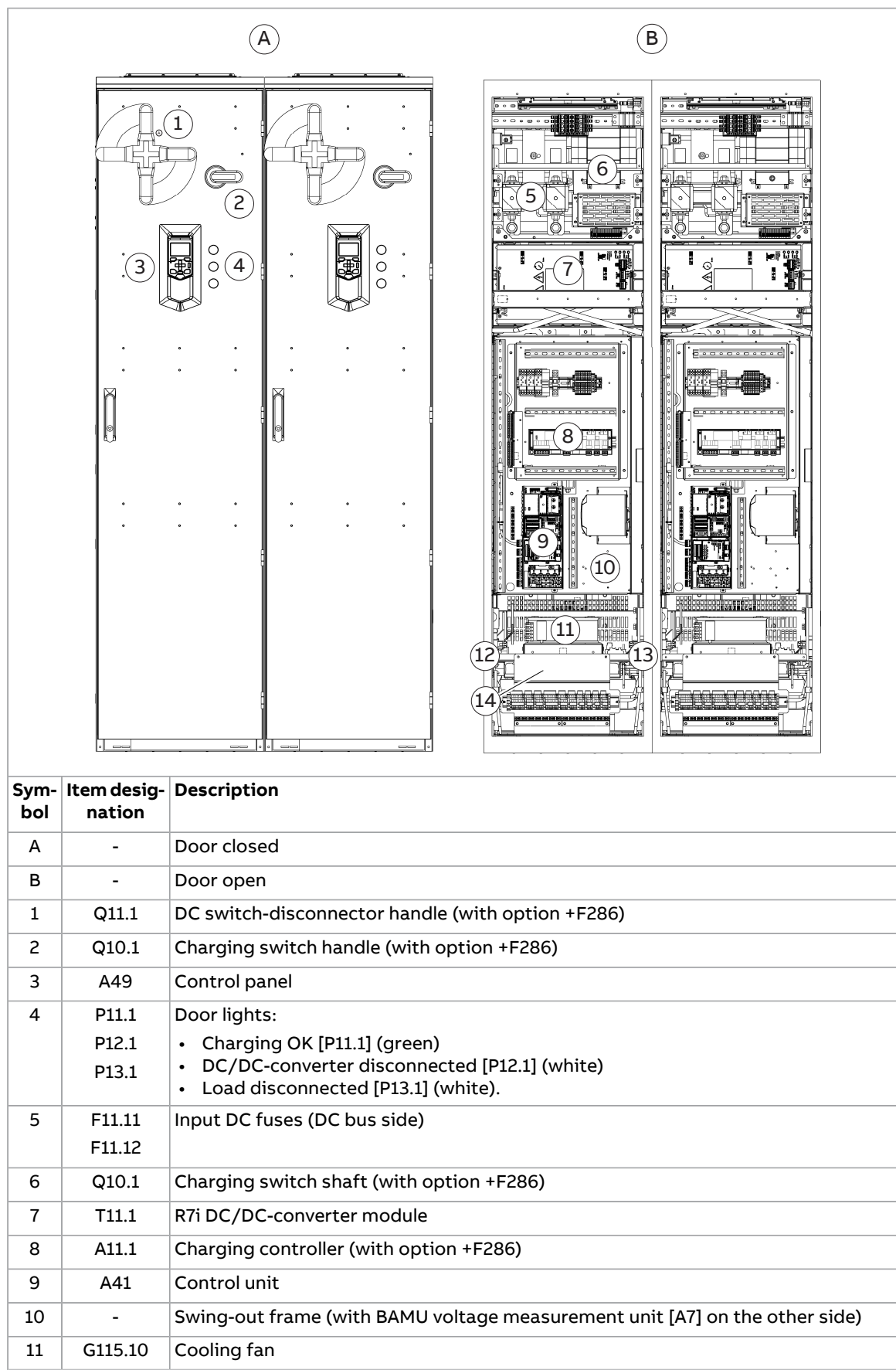
This figure shows an example converter unit cubicle.



7	T11.1	R7i DC/DC-converter module
8	A11.1	Charging controller (with option +F286)
9	A41	Control unit
10	-	Swing-out frame (with BAMU voltage measurement unit [A7] on the other side)
11	G115.10	Cooling fan
12	-	Inlet manifold with stop and drain valves
13	-	Outlet manifold with stop and drain valves
14	-	Heat exchanger (behind shrouding)
15	R13.1	BDCL filter module
16	F13.11 F13.12	Output DC fuses
17	ES+, ES-	Energy storage connection
18	F7	BAMU voltage measurement unit fuses

■ Cabinet layout – Frame 2×R7i in two cubicles converter module

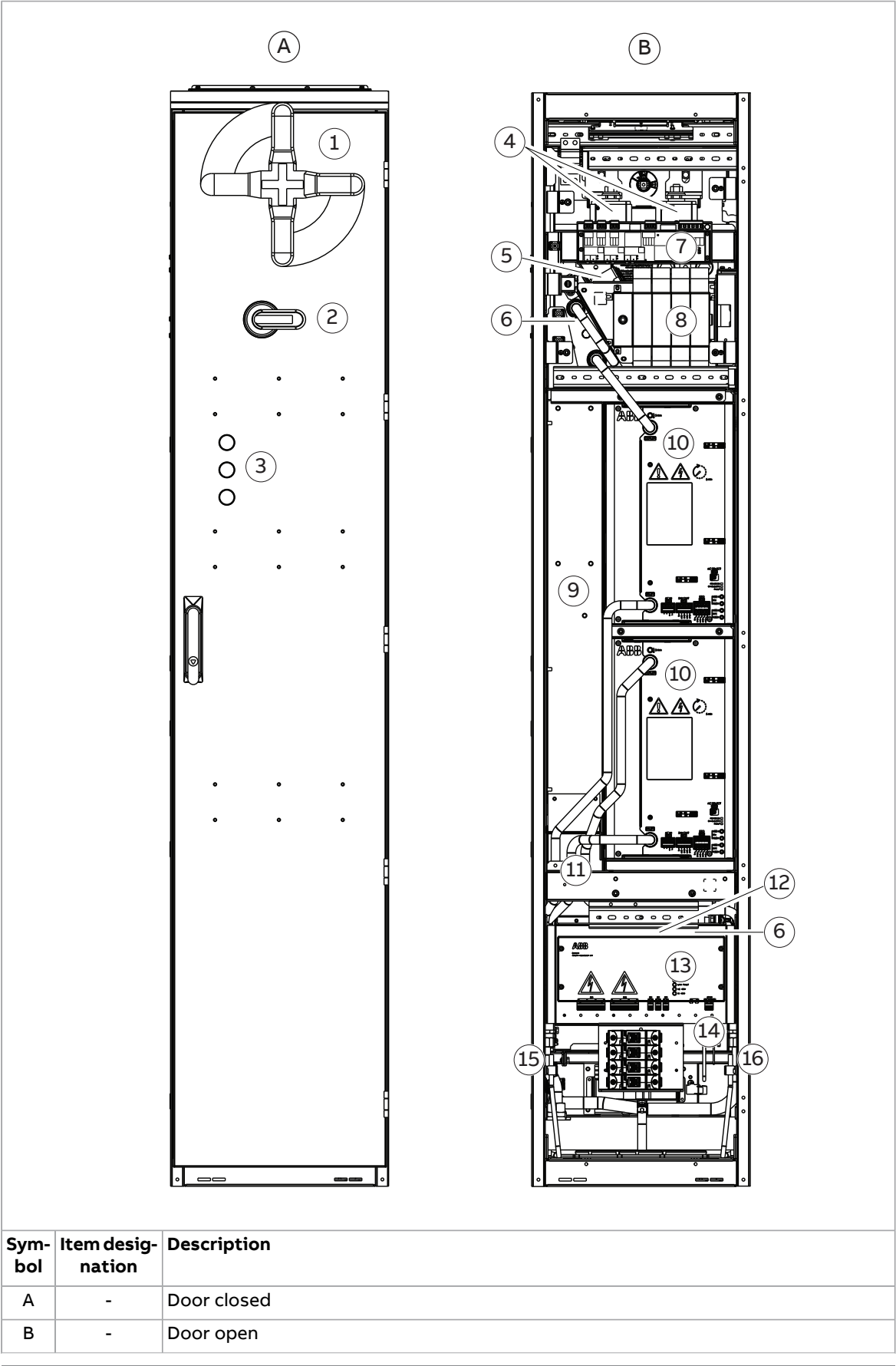
This figure shows an example converter unit cubicle.



12	-	Inlet manifold with stop and drain valves
13	-	Outlet manifold with stop and drain valves
14	-	Heat exchanger (behind shrouding)

■ **Cabinet layout – Frame 2×R7i in one cubicle converter module**

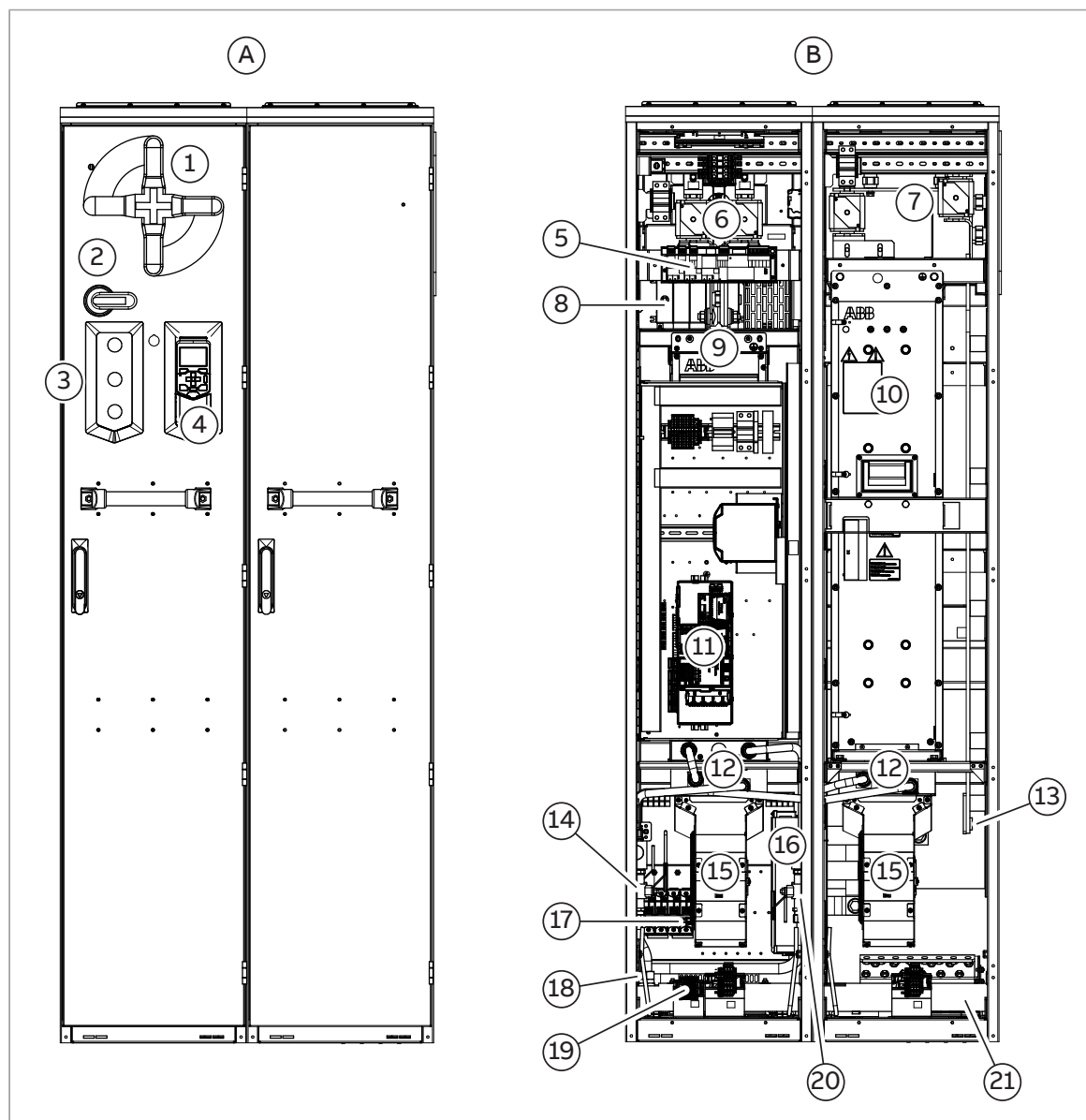
This figure shows an example converter unit cubicle.



1	Q11.1	DC switch-disconnector handle (with option +F286)
2	-	Charging switch handle (with option +F286)
3	P11.1 P12.1 P13.1	Door lights: • Charging OK (green) • DC/DC-converter disconnected (white) • Load disconnected (white).
4	F11.xx	Converter fuse (DC bus side)
5		Top fan
6	-	Heat exchanger (behind shrouding)
7	A11.1	BSFC charging controller
8		Charging switch (with option +F286)
9	R13.x, R14.x	Six BDCL-12 filter elements inside an assembly kit
10	T11.1, T11.2	R7i DC/DC-converter module
11	F13	Output fuse
12		Bottom fan
13	A7	BAMU voltage measurement unit
14	ES+, ES-	Energy storage connection
15	-	Inlet manifold with stop and drain valves
16	-	Outlet manifold with stop and drain valves

■ Cabinet layout – Frame R8i converter module

This figure shows an example converter unit cubicle.



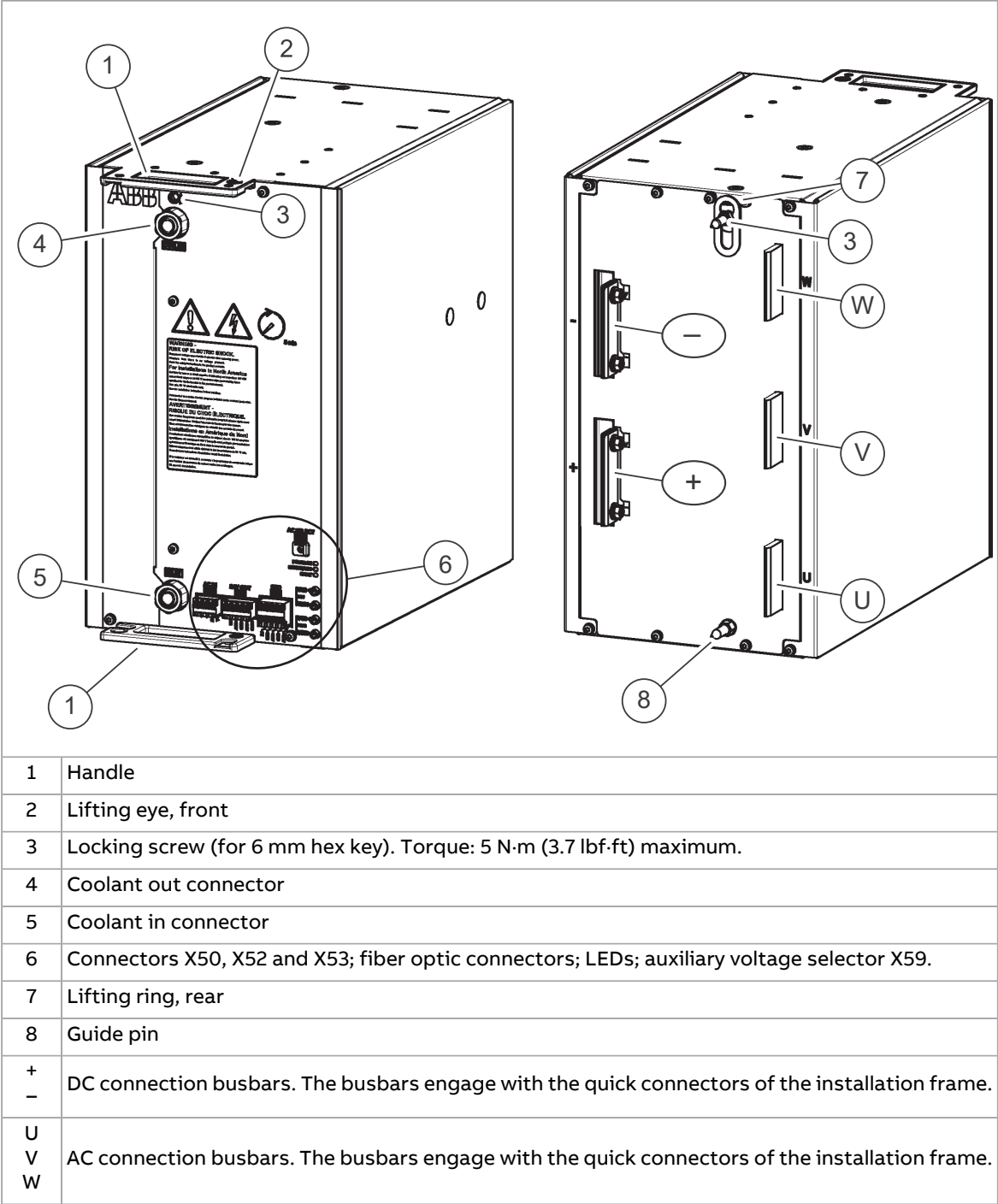
Sym- bol	Item desig- nation	Description
A	-	Doors closed
B	-	Doors open and shrouds removed
1	Q11.1	DC switch-disconnector handle (with option +F286)
2	-	Charging switch handle (with option +F286)
3	P11.1...P13.1	Door lights: • Charging OK ([P11.x], green) • DC/DC-converter disconnected ([P12.x], white) • Load disconnected ([P13.x], white).
4	-	Control panel
5	A11.1	Charging controller (with option +F286). Charging resistors [R1.x...R4.x] are behind the charging controller.
6	F11.xx	Input DC fuses (DC bus side)

7	F13.xx	Output DC fuses
8	Q10.1	Charging switch shaft (with option +F286)
9	T11.1	R8i DC/DC-converter module
10	R13.1	BDCL filter module
11	A41	Control unit
12	-	Heat exchanger
13	ES+, ES-	Energy storage connection
14	-	Inlet manifold with stop and drain valves
15	-	Module cooling fans
16	-	Auxiliary measurement unit
17	-	Auxiliary measurement unit fuses
18	-	Coolant IN Coolant OUT (back)
19	X33.1	Connection from the energy storage disconnecting device to the load disconnected indicator [P13.x]
20	-	Outlet manifold with stop and drain valves
21	-	Cable entries for energy storage cables

Converter module hardware

■ Frame R7i

Module layout



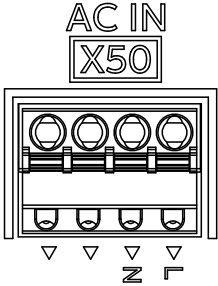
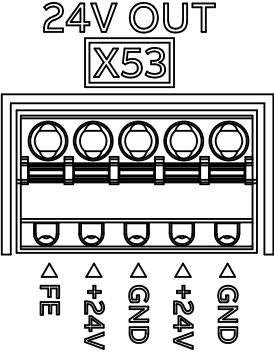
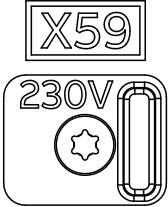
Coolant connectors

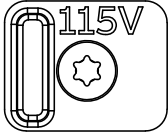
The coolant pipe inlet and outlet connectors are located at the bottom front and top front of the module respectively. The connectors are for 16/13 millimeter PA (polyamide) pipe.

Connectors X50, X52 and X53; Auxiliary voltage selector X59

R7i modules contain a power supply board that provides 24 V DC for the circuit boards of the module.

The power supply board of the module is powered internally from the DC bus.

	Auxiliary voltage input for internal power supply of module. Voltage selected by X59.
	24 V DC output (for eg. control unit)
	Auxiliary voltage: 230 V AC

AC SELECT X59 115V 	Auxiliary voltage: 115 V AC
---	-----------------------------

Fiber optic connectors

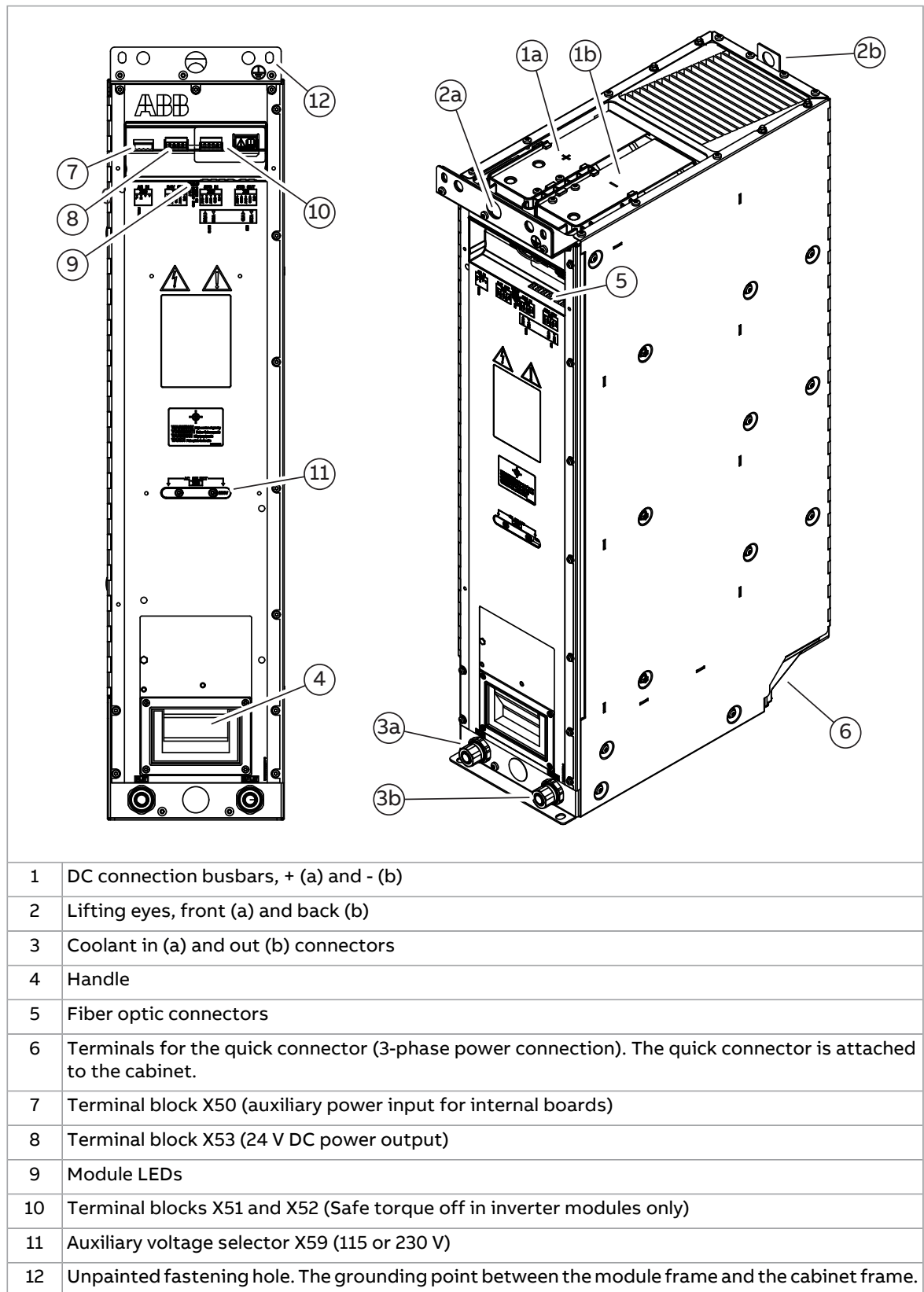
Control unit connection.	V20	
	V10	
Charging controller connection.	V60	
	V50	

LEDs

LED	Color	Indication
FAULT	Continuous red	There is an active fault in the module.
ENABLE / STO	Continuous green	The module is ready for use.
ENABLE / STO	Continuous yellow	XSTO connectors are de-energized.
POWER OK	Continuous green	Supply voltage of the internal circuit boards is sufficient (> 21 V).

■ Frame R8i

Module layout



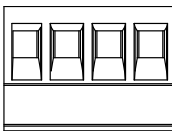
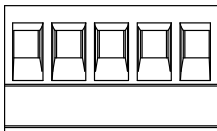
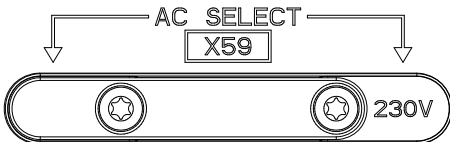
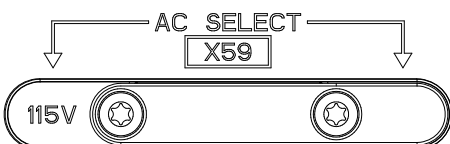
Coolant connectors

The coolant pipe inlet and outlet connectors are located at the bottom front of the module. The connectors are for 16/13 millimeter PA (polyamide) pipe.

Connectors X50...X59

R8i modules contain a power supply (BDPS) that provides 24 V DC for the circuit boards of the module.

The BDPS is powered internally from the DC bus.

	<table><tr><th colspan="3">AC IN</th></tr><tr><th colspan="3">X50</th></tr><tr><td>L</td><td>N</td><td></td></tr><tr><td colspan="2">POWER</td><td></td></tr></table>	AC IN			X50			L	N		POWER			Auxiliary voltage inputs for internal power supply (BDPS)			
AC IN																	
X50																	
L	N																
POWER																	
	<table><tr><th colspan="5">24V OUT</th></tr><tr><th colspan="5">X53</th></tr><tr><td>GND</td><td>+24V</td><td>GND</td><td>+24V</td><td>FE</td></tr></table>	24V OUT					X53					GND	+24V	GND	+24V	FE	24 V DC output (for eg. control unit)
24V OUT																	
X53																	
GND	+24V	GND	+24V	FE													
			Auxiliary voltage: 230 V AC														
			Auxiliary voltage: 115 V AC														

Fibre optic connectors

Control unit connection.	V20	
	V10	
Charging controller BSFC connection.	V60	
	V50	

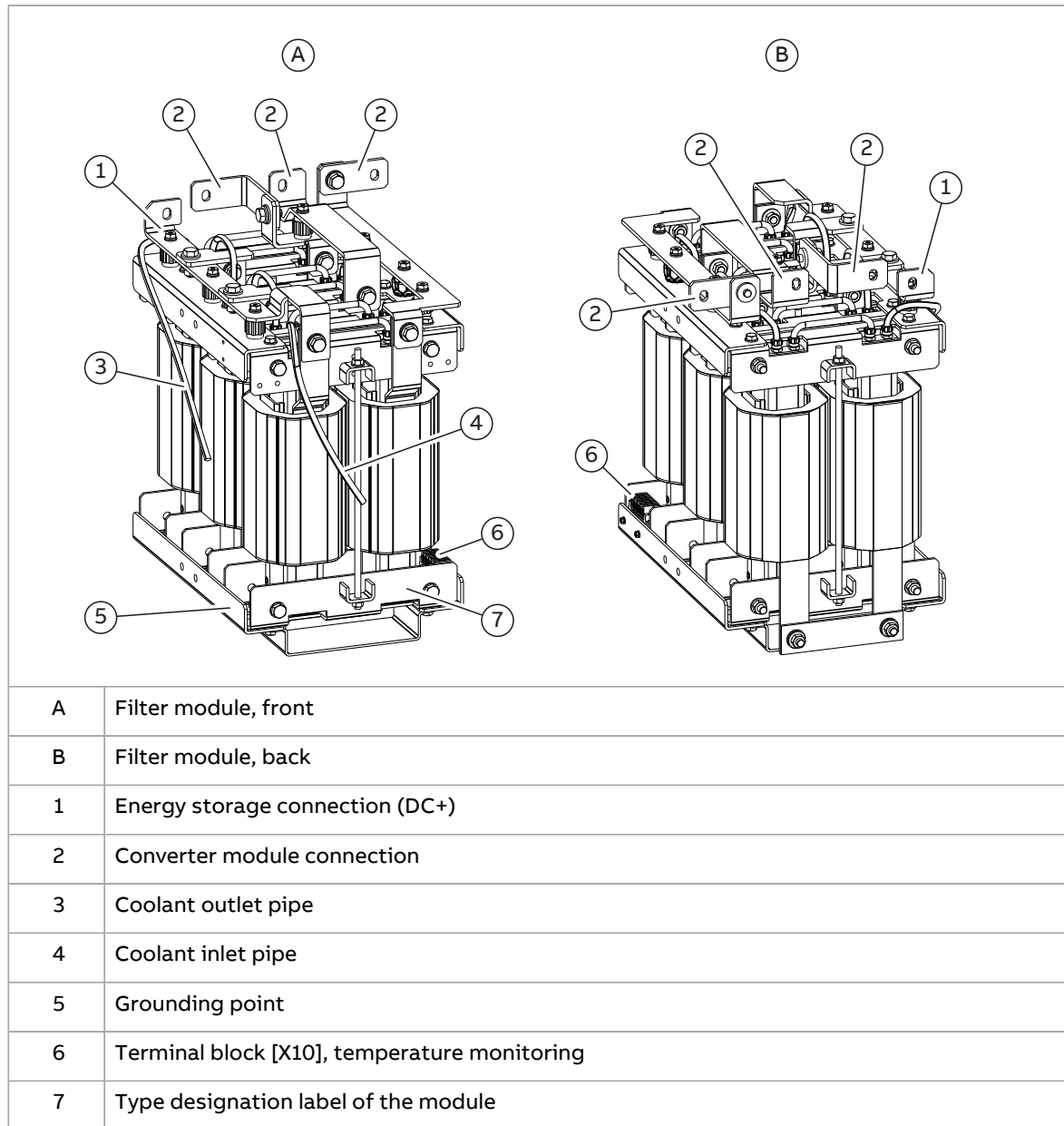
LEDs

LED	Color	Indication
FAULT	Continuous red	There is an active fault in the module.
ENABLE / STO	Continuous green	The module is ready for use.
ENABLE / STO	Continuous yellow	XSTO connectors are de-energized.
POWER OK	Continuous green	Supply voltage of the internal circuit boards is sufficient (> 21 V).

BDCL filter

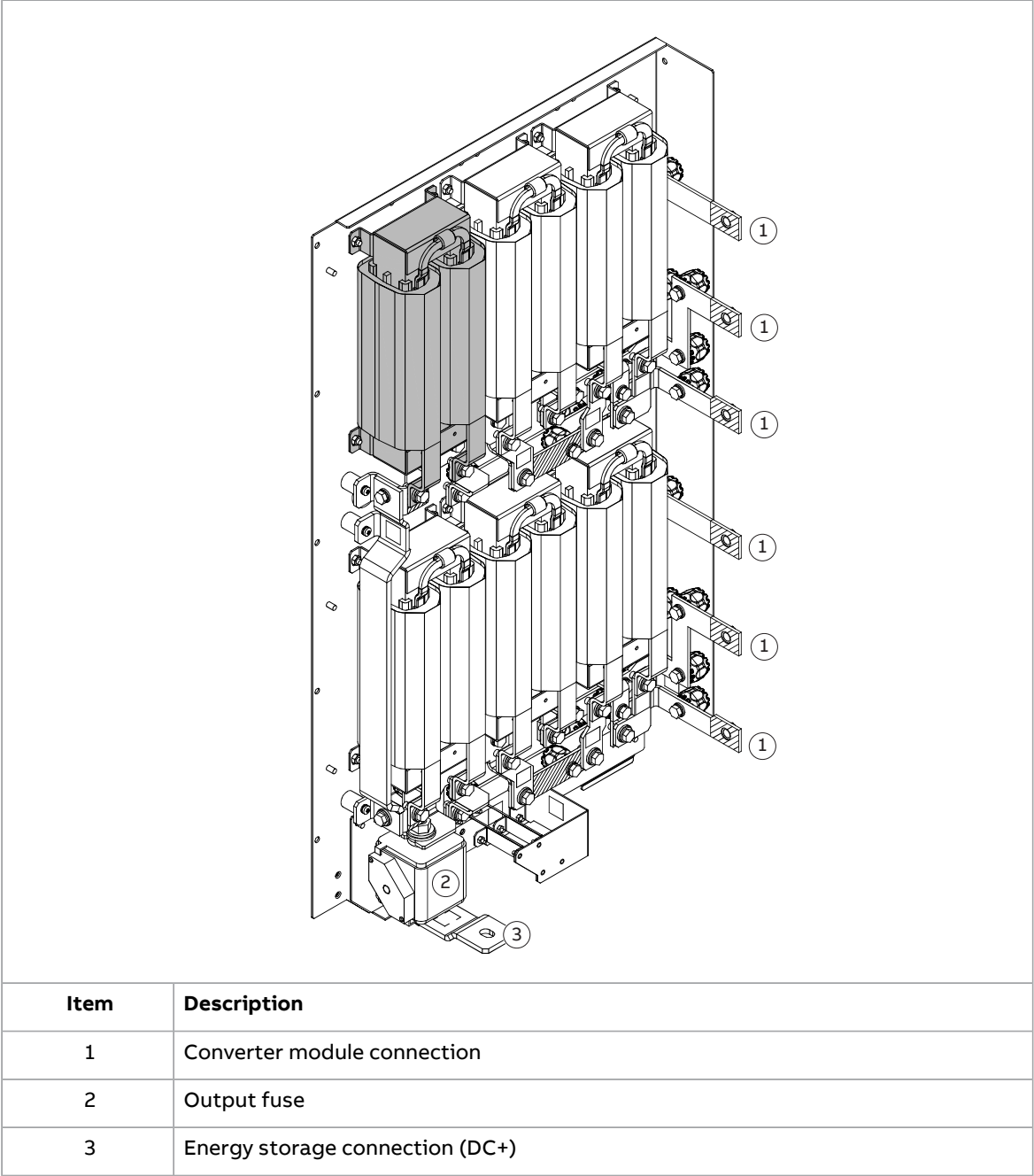
■ BDCL-13LC-7 filter module for frame R7i converter module

Units with frame 2×R7i in two cubicles converter module also use this filter module. Each converter module has one filter.

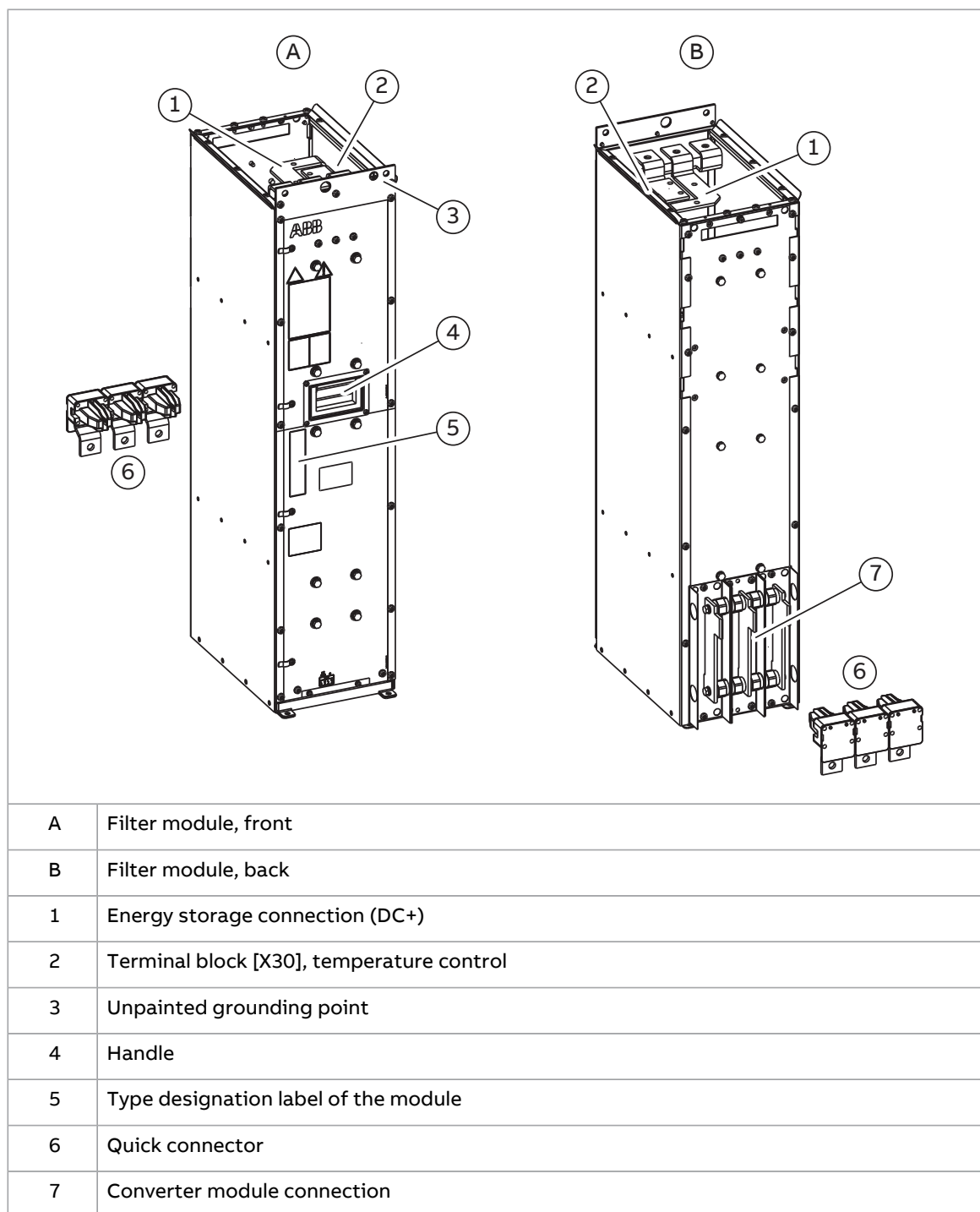


■ **BDCL-12 filter elements for frame 2×R7i in one cubicle converter module**

The diagram below shows six BDCL-12 filter elements. One filter element is highlighted.



■ BDCL-14LC and -15LC filter modules for frame R8i converter module



■ Overheating protection of the filter

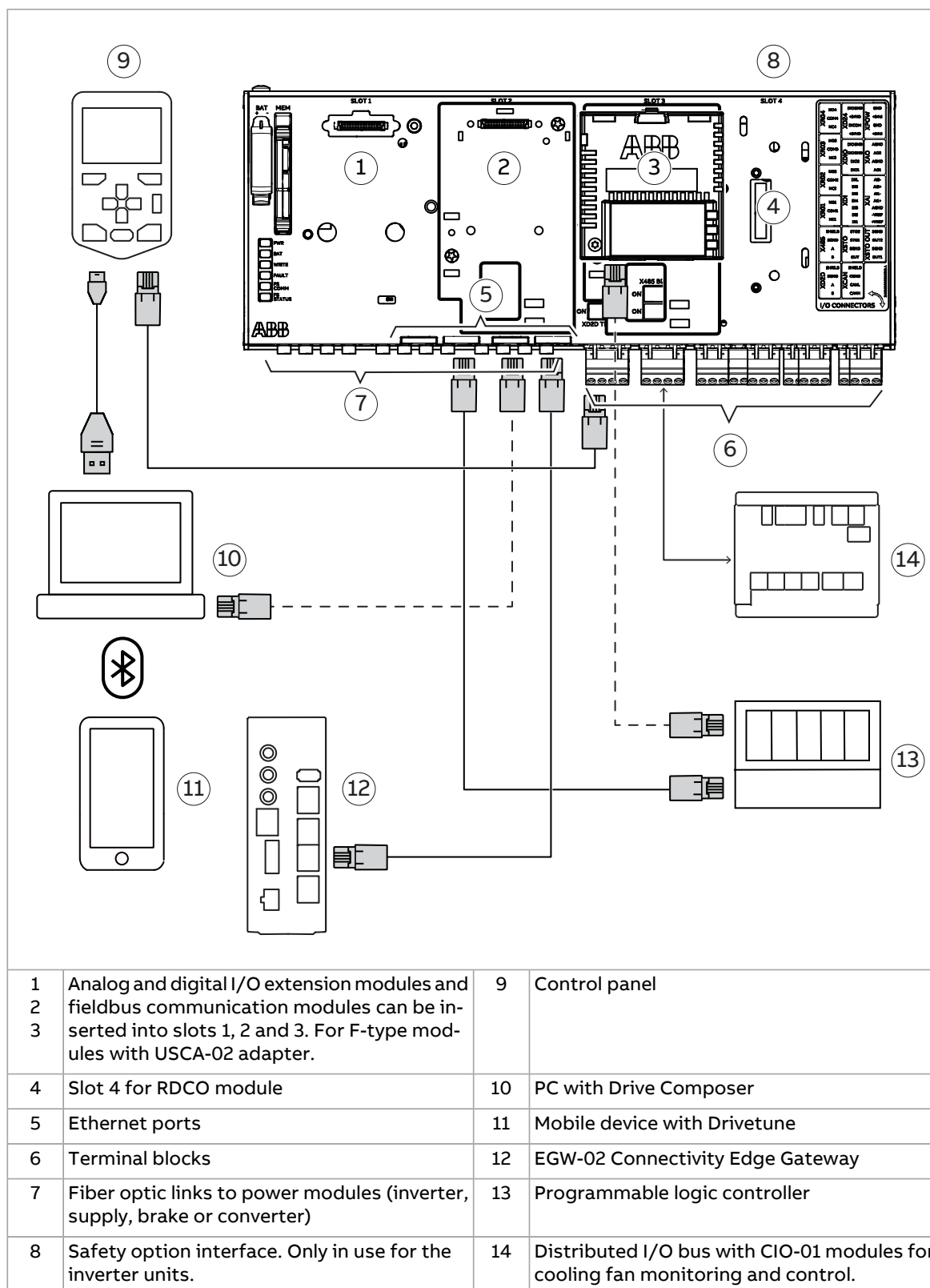
By default, the BDCL filter is protected against overheating (caused by, for example, a fan malfunction or loss of coolant flow) with a thermistor and the temperature monitoring function of the control program. If the filter temperature becomes too high, the temperature monitoring function stops the DC/DC-converter automatically.

Control unit

DC/DC-converter units use a UCU or BCU control unit. The control unit has inputs, outputs, and slots for option modules. A fiber optic link connects the control unit to each converter module.

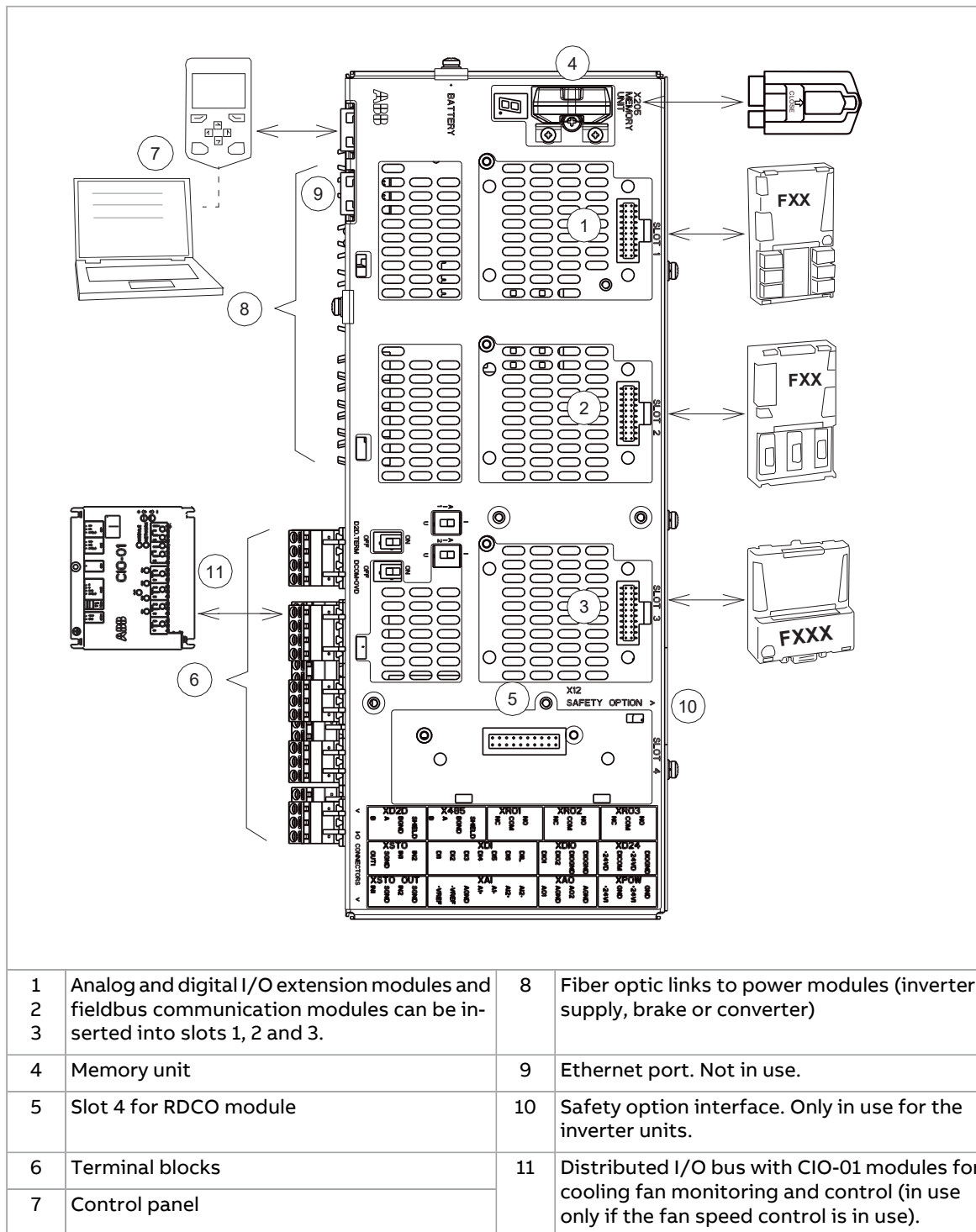
Overview of the control connections of the UCU-22, UCU-23 and UCU-24 control unit

The diagram shows the possible control connections and interfaces of the UCU-22, UCU-23 and UCU-24 control units.



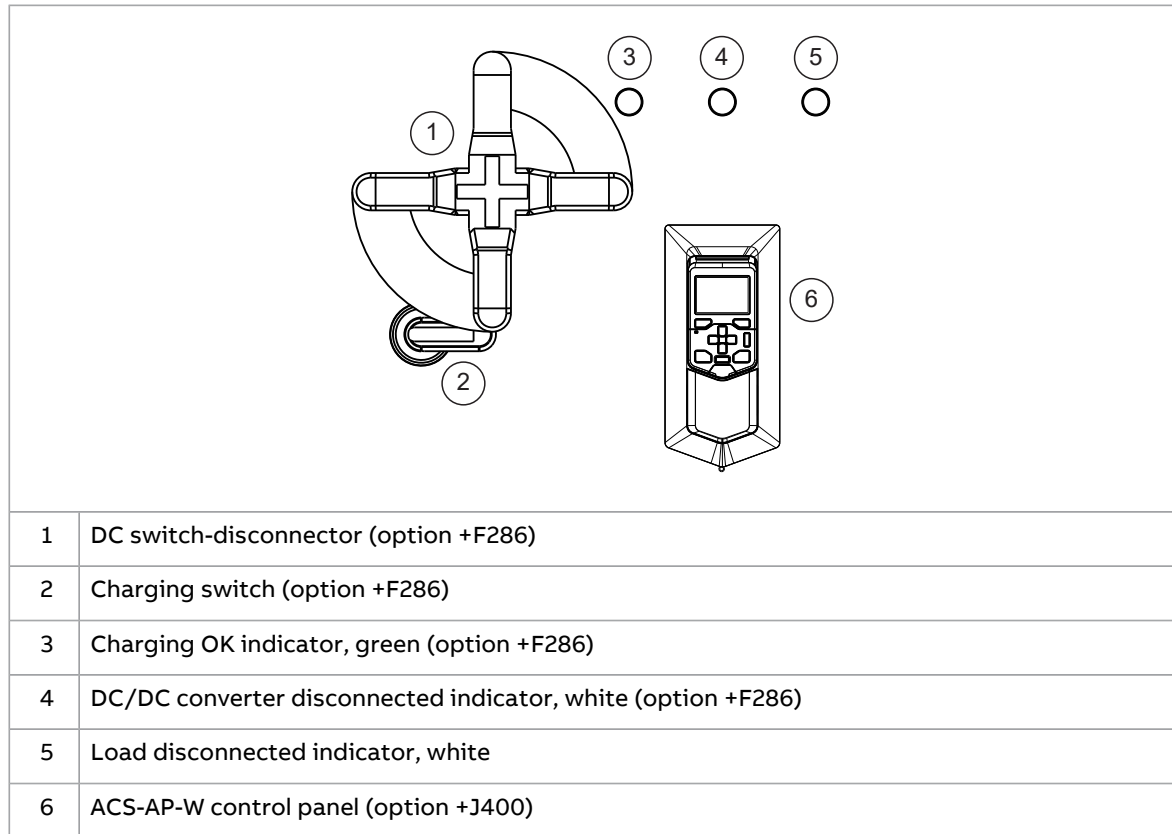
Overview of the control connections of the BCU control unit

The diagram shows the possible control connections, and interfaces of the BCU control unit.



Converter unit control devices

This figure shows an example of the door control devices of the DC/DC converter. The selection and exact location of control devices varies in different deliveries.



■ DC switch-disconnector

The DC switch-disconnector [Q11] is optional (option +F286). The DC switch-disconnector has an operating handle on the cabinet door. A converter unit with a DC switch-disconnector also has a charging circuit including a charging switch on the door.

The DC switch-disconnector allows the isolation of the unit from the DC bus. Before the unit is connected to the DC bus, the capacitors of the converter modules must be charged through a charging circuit.

■ Charging switch

A converter unit with a DC switch-disconnector ([Q11], option +F286) also has a charging circuit and a charging switch [Q10] on the cubicle door. Before closing the DC switch-disconnector, close the charging switch. After the precharging is completed, the Charging OK indicator [P11] (green) on the cabinet door comes on, and you can close the DC switch-disconnector [Q11], and open the charging switch.

■ Door lights

The load disconnected indicator ([P13], white) is always installed on the cabinet door. This indicator shows the state of the energy storage disconnecting device (customer-defined).

The charging OK indicator ([P11], green) and DC/DC converter disconnected indicator ([P12], white) are installed when the converter has the DC switch-disconnector (option +F286).

■ Control panel [A49]

The control panel is the user interface of the unit. An example control panel is shown below.



With the control panel, the user can:

- start and stop the unit
- view and reset the fault and warning messages, and view the fault history
- view actual signals
- change parameter settings
- change between local (control panel) and remote (external device) control.

■ PC connection

There is an USB connector on the front of the panel that can be used to connect a PC to the converter. When a PC is connected to the control panel, the control panel keypad is disabled.

■ Fieldbus control

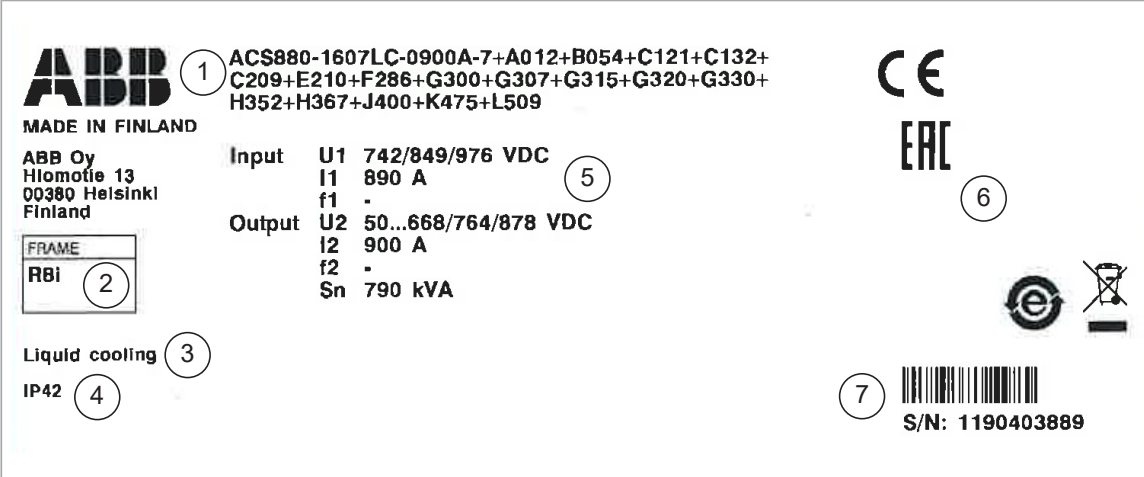
You can control the converter unit through a fieldbus interface if the unit is equipped with an optional fieldbus adapter, and when you have configured the control program for the fieldbus control with parameters. For more information on parameters, refer to [ACS880 DC/DC converter control program firmware manual \(3AXD50000024671 \[English\]\)](#).

Type designation labels

■ Type designation label of the DC/DC-converter unit

Each converter unit has a type designation label attached onto the inside of the cubicle door. The type designation label includes the ratings, applicable markings, type designation and serial number of the unit.

An example label is shown below.

 ABB ① ACS880-1607LC-0900A-7+A012+B054+C121+C132+C209+E210+F286+G300+G307+G315+G320+G330+H352+H367+J400+K475+L509 MADE IN FINLAND ABB Oy Himontie 13 00380 Helsinki Finland Input U1 742/849/976 VDC I1 890 A ⑤ f1 - Output U2 50...668/764/878 VDC I2 900 A f2 - Sn 790 kVA FRAME RBI ② Liquid cooling ③ IP42 ④ CE EAC ⑥ ⑦  S/N: 1190403889	
1	Type designation
2	Frame size
3	Cooling system and other additional data
4	Degree of protection
5	Ratings
6	Valid markings. Refer to ACS880 liquid-cooled multidrives cabinets and modules electrical planning instructions (3AXD50000048634 [English]) .
7	Serial number. The first digit of the serial number refers to the manufacturing plant. The next four digits refer to the unit's manufacturing year and week, respectively. The remaining digits complete the serial number so that there are no two units with the same number.

■ Type designation label of the BDCL filter

Each filter module or element has a type designation label attached to it.

Example labels are shown below.

 MADE IN FINLAND ABB Oy ² Hiomotie 13 00380 Helsinki Finland Air cooling IP00 ³ 10.5 kg	BDCL-12 Rev. A ¹ Un 566/707/976 V DC In 183/183/133 A fn - 3AXD50001204525 ⁵ S/N XXXXXXXXXXXX ⁶	   
 MADE IN FINLAND ABB Oy ² Hiomotie 13 00380 Helsinki Finland Liquid cooling ³ IP00	BDCL-13LC-7 ¹ Rev. A Un 566/707/976 V DC In 550/550/400 A fn - 3AXD50000889990 ⁵ S/N XXXXXXXXXXXX ⁶	 ⁷ 
 MADE IN ESTONIA ABB Oy ² Hiomotie 13 00380 Helsinki Finland IP00 ³	BDCL-15LC-7 ¹ Rev. A Un 742/849/976 V DC In 900 A fn - 3AJA0000190873 ⁵	 ⁷ 
1	Type designation	
2	Manufacturer information	
3	Degree of protection	
4	Ratings	
5	Code of the filter module or element	
6	Serial number	
7	Valid markings. See ACS880 liquid-cooled multidrives cabinets and modules electrical planning instructions (3AXD50000048634 [English]) .	

Type designation key

■ Type designation key of the converter unit

The type designation contains information on the specifications and configuration of the converter unit. The first digits from left express the basic unit type. The optional selections are given thereafter, separated by plus signs, for example, +E202. Codes preceded by a zero (eg. +0J400) indicate the absence of the specified feature. The main selections are described below. Not all selections are available for all types. For more information, refer to the ordering instructions available separately on request.

Code	Description
Basic code	
ACS880	Product series
1607LC	Construction: cabinet-installed liquid-cooled DC/DC-converter unit. When no options are selected: Supply frequency 50 Hz, control voltage 230 V AC, IP42, EN/IEC industrial cabinet construction, power and control cabling through the bottom of the cabinet, DC busbar material tin or nickel plated copper, cable supply conductors, speed-controlled cooling fans, standard wiring material, ACS880 DC/DC-converter control program, complete documentation in English on a memory stick.
Size	
xxxxx	Refer to the ratings table in the technical data.
Voltage range	
5	DC voltage corresponding AC input voltages 3 ~ 380...500 V. This is indicated in the type designation label as typical input voltage level 566 / 679 / 707 V DC.
7	DC voltage corresponding AC input voltages 3 ~ 525...690 V. This is indicated in the type designation label as typical input voltage level 742 / 849 / 976 V DC.

Option codes

Code	Description
A012	50 Hz supply frequency
A013	60 Hz supply frequency
B054	IP42 (UL Type 1 Filtered)
B055	IP54 (UL Type 12)
C121	Marine construction
C132	Marine type approval. Refer to ACS880...+C132 marine type-approved cabinet-built drives supplement (3AXD50000039629 [English]) .
C164	Plinth height 100 mm
C176	Door hinges on the left
C179	Plinth height 200 mm
C205	Marine product certification issued by DNV
C206	Marine product certification issued by the American Bureau of Shipping (ABS)
C207	Marine product certification issued by Lloyd's Register (LR)
C209	Marine product certification issued by Bureau Veritas
C228	Marine product certification issued by China Classification Society (CCS)
C229	Marine product certification issued by Russian Maritime Register of Shipping (RS)
E205	du/dt filtering
E208	Common mode filtering

Code	Description
E210	EMC/RFI filter for 2nd environment TN (grounded) or IT (ungrounded) system, category C3
F272	Internal charging circuit
F276	Capability of ride-through in voltage break max. 3 s. without tripping
F286	DC switch-disconnector
F290	DC switch-disconnector in DC feeder unit
G300	Cabinet and module heating elements (external supply)
G301	Cabinet lighting
G304	Control (auxiliary) voltage 115 V AC
G314	Aluminum busbars
G315	Nickel-plated or tin-plated copper DC busbars
G320	Control (auxiliary) voltage 230 V AC
G330	Halogen-free wiring and materials
G338	Wire marking class A1
G339	Wire marking class A2
G340	Wire marking class A3
G341	Wire marking class B1
G342	Wire marking class C1
G353	Current transducers
G442	BAMU auxiliary measurement unit
G453	Common mode filter temperature monitoring
H352	Power cabling exit from bottom
H353	Power cabling exit from top
H358	Cable gland plates (3 mm steel, undrilled)
H364	Cable gland plates (3 mm aluminum, undrilled)
H365	Cable gland plates (6 mm brass, undrilled)
H367	Control cabling through the floor of the cabinet
H368	Control cabling through the roof of the cabinet
H390	Cable entry, 72 mm diameter
H394	Cable entry, Roxtec frame without sealing components
K490	FEIP-21 Ethernet adapter module for EtherNet/IP™
K491	FMBT-21 Ethernet adapter module for Modbus TCP
K492	FPNO-21 Ethernet adapter module for PROFINET IO
P913	Special color (RAL Classic)
P966	Special color (other than RAL Classic)
R700	Printed documents in English
R701	Printed documents in German ¹⁾
R702	Printed documents in Italian ¹⁾
R705	Printed documents in Swedish ¹⁾
R706	Printed documents in Finnish ¹⁾
R707	Printed documents in French ¹⁾
R708	Printed documents in Spanish ¹⁾
R711	Printed documents in Russian ¹⁾

Code	Description
R712	Printed documents in Chinese ¹⁾
V112	Module auxiliary and fan power supply connector change

¹⁾ The delivery can include documents in English if the requested language is not available.

■ Type designation key of the converter module

The type designation contains information on the specifications and configuration of the module. The first digits from left express the basic unit type. The optional selections are given thereafter, separated by plus signs, for example, +E205.

Code	Description
Basic code	
ACS880	Product series
104LC	Construction: Liquid-cooled inverter, supply, converter or brake module.
Size	
xxxxx	Refer to the ratings table in the technical data.
Voltage range	
5	DC voltage corresponding AC input voltages 3 ~ 380...500 V. This is indicated in the type designation label as typical input voltage level 566 / 679 / 707 V DC.
7	DC voltage corresponding AC input voltages 3 ~ 525...690 V. This is indicated in the type designation label as typical input voltage level 742 / 849 / 976 V DC.
Option codes	
C132	Marine type approval
C209	Marine product certification issued by Bureau Veritas
E205	Internal du/dt filtering

■ Type designation key of the filter

The type designation contains information on the specifications and configuration of the filter module or element. The digits express the module type or element.

Code	Description
Basic code	
BDCL-12	BDCL-12 filter element
BDCL-13LC	Liquid-cooled BDCL-13 filter module
BDCL-14LC	Liquid-cooled BDCL-14 filter module
BDCL-15LC	Liquid-cooled BDCL-15 filter module
Voltage range	
7	(No voltage range for BDCL-12.) <u>BDCL-13LC</u> : DC voltage corresponding AC input voltages 3 ~ 380...690 V. This is indicated in the type designation label as typical input voltage level 566 / 707 / 976 V DC. <u>BDCL-14LC and BDCL-15LC</u> : DC voltage corresponding AC input voltages 3 ~ 525...690 V. This is indicated in the type designation label as typical input voltage level 742 / 849 / 976 V DC.
Option codes	
G304	115 V auxiliary voltage supply
V112	Module auxiliary and fan power supply connector version. Type of the connector is not mechanically backwards compatible with a module without option +V112.

Frame 2×R7i versions

There are two versions of frame size 2×R7i:

- Frame 2×R7i in two cubicles
- Frame 2×R7i in one cubicle

The two versions are different in several ways:

Item	Frame 2×R7i in two cubicles	Frame 2×R7i in one cubicle
Cabinet layout	Two 500 mm cubicles.	One 400 mm cubicle.
	Refer to Converter unit hardware (page 22) .	
BDCL filters	One BDCL-13LC-7 filter module per cubicle	Six BDCL-12 filter elements inside an assembly kit
	Refer to BDCL filter (page 35) .	

The table below shows the type codes for the two versions.

ACS880-1607LC-...	Frame 2×R7i in two cubicles	Frame 2×R7i in one cubicle
$U_n = 500\text{ V}$		
0700A-5	X	
0701A-5		X
0900A-5	X	
0901A-5		X
1100A-5	X	
1101A-5		X
$U_n = 690\text{ V}$		
0599A-7	X	
0601A-7		X
0799A-7	X	
0801A-7		X

3

Mechanical installation



Contents of this chapter

This chapter gives information on the mechanical installation of the converter units.

DC/DC-converter units

For instructions how to examine the installation site, move the unit and install the cabinet, refer to [ACS880 liquid-cooled multidrives cabinets mechanical installation instructions \(3AXD50000048635 \[English\]\)](#).

Energy storage

Obey the instructions of the energy storage manufacturer.

Internal cooling system

See chapter [Internal cooling circuit](#).

4

Guidelines for planning electrical installation

Contents of this chapter

This chapter contains electrical planning instructions.

Limitation of liability

The installation must always be designed and made according to applicable local laws and regulations. ABB does not assume any liability whatsoever for any installation that breaches the local laws and/or other regulations. Furthermore, if the recommendations given by ABB are not followed, the drive may experience problems that the warranty does not cover.

■ North America

Installations must be compliant with NFPA 70 (NEC)¹⁾ and/or Canadian Electrical Code (CE code), along with state and local codes for your location and application.

¹⁾ National Fire Protection Association 70 (National Electric Code).

ABB is not responsible for the energy storage selection or protection of the energy storage.

Generic guidelines

Refer to [ACS880 liquid-cooled multidrives cabinets and modules electrical planning instructions \(3AXD50000048634 \[English\]\)](#) for the generic guidelines for planning the electrical installation (selecting cables, routing cables, etc.) of multidrives cabinets and modules.

Selecting the energy storage

The energy storage is not included in the drive delivery. The customer (or the system integrator) must acquire a suitable energy storage system. The customer (or the system integrator) is also responsible for the protection of the energy storage.

Additional guidelines:

- Connect parallel modules (if any) to the same energy storage.
 - Dimension the energy storage so that it withstands the required current cycles and the stored energy is sufficient. Take the depth of discharge into account in energy storage lifetime calculations.
 - Make sure that the energy storage withstands the current ripple of the converter. See the technical data.
 - The output voltage (energy storage voltage) is not allowed to exceed the drive DC bus voltage. Add sufficient voltage margin in the design to prevent this in case of voltage dips or grid faults.
 - The recommended energy storage operating voltage is:
 $U_{ES} = 150 \text{ V} \dots 80\% \text{ of } U_{DC}$
 - Typical DC voltage values:
 - with diode supply units:
 $U_{DC} = 1.35 \times U_{AC}$
 - with IGBT supply units:
 $U_{DC} = 1.41 \times U_{AC}$ (can be changed with supply unit parameter group 123 DC volt ref.
 - where
 U_{DC} = Drive DC voltage (in the DC bus)
 U_{AC} = Drive input voltage (AC)
 - ABB recommends to measure the energy storage voltage. If the energy storage is a super capacitor, voltage measurement is obligatory unless the capacitor withstands the maximum DC voltage of the drive or contains internal overvoltage protection.
 If the converter has the optional BAMU voltage/current measurement unit, the converter measures its output voltage (and thus also the energy storage voltage) automatically.
 If the converter does not have a BAMU, you must arrange the voltage measurement separately, and send the measured value to the converter control program, for example, through fieldbus communication or by some other means.
 For more information, see section Energy storage voltage measurement and estimation and parameter description in [ACS880 DC/DC-converter control program firmware manual \(3AXD50000024671 \[English\]\)](#).
 - Equip the energy storage with a circuit breaker capable of opening the circuit if there is a failure in the energy storage or cable. See [Selecting a protective device for the energy storage](#) and [Energy storage disconnecting \(isolating\) device](#).
-

Implementing protections for the energy storage

■ General principles

The requirements for the customer-defined protections at the energy storage end:

- disconnecting device between the drive and energy storage system (for example, isolation disconnect switch, withdrawable circuit breaker)
- overload and short circuit protection for the cabling (for example, circuit breaker with thermal or electromagnetic trip unit)
- overload and short circuit protection for the energy storage elements itself (for example, integrated overload protection in batteries).

■ Selecting a protective device for the energy storage

The customer (or the system integrator) must equip the energy storage with a protective device. The protective device is not included in the drive delivery.

The protective device must provide an overload and short-circuit protection for the energy storage. If there is no other protection device for the cables at the energy storage end, the protective device of the energy storage must also provide the overload and short-circuit protection for the cable(s).

The customer (or the system integrator) must verify the operation of the protective device by short circuit calculations taking into account the impedances of the drive, filter (if any), cabling and energy storage, and minimum and maximum state of charge of the energy storage. The customer (or the system integrator) must take into account the impact of aging to storage impedances.

■ Energy storage disconnecting (isolating) device

The customer (or the system integrator) must equip the energy storage with an disconnecting (isolating) device. The disconnecting device is not included in the drive delivery.

■ Overload protection of the system by the DC/DC-converter

There is a thermal protection function in the DC/DC-converter control program. For more information on the thermal protection function, see the firmware manual.

■ Protecting the energy storage cable

There must be protective devices on the two ends of the energy storage cable:

- output DC fuses in the DC/DC-converter unit (installed by ABB the factory)
- energy storage protective device (must be acquired and installed by the customer or system integrator).

On the converter side of the cable, the output DC fuses protect the DC/DC-converter and the cable in a short-circuit situation.

On the energy storage side of the cable, the energy storage protective device protects the energy storage and the cable in a short-circuit or overload situation.

■ Energy storage discharging device

When necessary, the customer (or the system integrator) must equip the energy storage with a discharging device. If the energy storage is a super capacitor, ABB recommends that you install a discharging device.

Implementing earth fault protection

If the converter unit does not have a built-in earth fault protection system, the customer (or the system integrator) must install an earth fault protection device and connect it to the converter unit.

The DC/DC-converter control program can be configured to trip on a fault or give a warning when external earth leakage is detected. For more information, refer to the firmware manual.

Implementing an interlocking between the disconnecting devices

The customer (or the system integrator) must implement an interlocking circuit between the DC switch-disconnector of the drive [Q11] and the energy storage disconnecter (isolator). The user must not be able to close the energy storage disconnecter (isolator) before closing the DC switch-disconnector of the drive [Q11].

Selecting and routing the energy storage cables

■ Cable selection procedure

Select each power cable as follows. Obey the local regulations.

1. Select the cable type. Obey the general guidelines and recommendations for the drive power cabling.
2. Select the cable size.
Cabinet-installed multidrives: Refer to the listing of typical power cable sizes given in the technical data of the multidrives unit hardware manual.
3. Make sure that the short-circuit rating of the cable is sufficient. Take into account the disconnection time of the protective device. If the rating is not sufficient, select a larger cable, increase the number of parallel cables or change the cable to a type with higher conductor temperature rating.
4. Select the cable lugs.
5. Make sure that the cable can enter the cabinet through the cable entry plate.
Cabinet-installed multidrives: Refer to the dimension drawings of the drive delivery or technical data in the multidrives unit hardware manual. For special cable entry solutions, consult ABB.
6. Make sure that there is sufficient space to install the cable(s) and cable lugs to the terminals.
Cabinet-installed multidrives: Refer to the terminal and cable entry data given in the technical data of the multidrives unit hardware manual.

■ Recommended cables

The customer (or the system integrator) must acquire and connect the energy storage cables. It is possible to use shielded cables with 2, 3 or 4 conductors. ABB recommends that you use shielded cables with 4 conductors.

Refer to the table below for the cables and possible configurations.

Cable type	Positive	Negative	PE (ground)
2-conductor shielded cable	1 conductor	1 conductor	Shield ¹⁾
3-conductor shielded cable	1 conductor	1 conductor	1 conductor + shield
4-conductor shielded cable	2 conductors	2 conductors	Shield ¹⁾

¹⁾ The shield must meet the requirements of IEC 61439-1. If the shield does not meet the requirements, an additional PE conductor or cable is required.

ABB does not recommend that you use single core cables. If it is necessary to use single core cables, obey these guidelines:

- Use shielded cables. Ground the cable shields only at one end.
- Put the cables in groups of 2 or 4.
- Attach the cables according to the requirements to withstand the apparent short circuit forces.

■ Typical cable sizes

Refer to the technical data.

■ Minimizing electromagnetic interference

The customer (or the system integrator) must obey these rules in order to minimize the electromagnetic interference caused by rapid current changes in the energy storage cables:

- Shield the energy storage cabling completely, either by using shielded cable or a metallic enclosure. Unshielded single-core cable can only be used if it is routed inside a cabinet that efficiently suppresses radiated emissions.
- Install the cables away from other cable routes.
- Avoid long parallel runs with other cables. The minimum recommended separation distance for parallel cabling is 0.3 m (1 ft).
- Cross other cables at right angles.

Keep the cable as short as possible in order to minimize the radiated emissions and stress on converter IGBT semiconductors. The longer the cable, the higher the radiated emissions, inductive load and voltage peaks over the IGBTs of the DC/DC-converter.

■ Maximum cable length

Refer to the technical data.

■ EMC compliance of the complete installation

ABB has not verified that the EMC requirements are fulfilled with external energy storage and its cabling. The EMC compliance of the complete installation must be considered by the customer (or the system integrator).

Parallel connection

It is possible to connect multiple DC/DC-converter units in parallel. In a parallel connection, the inputs of the units must be connected together, and the outputs of the units must be connected together. The inputs are connected through the common DC bus of the drive as standard. The outputs (ES+ to ES+, ES- to ES-) must be connected together at the energy storage end by the customer (or the system integrator).

The customer (or the system integrator) must make sure that the load sharing is even between the parallel units. Depending on the case, this can require additional parameter tuning in DC/DC-converter control programs of both units:

- If the operating mode selection (parameter 197.13) is Power or Add: The load between the units is inherently shared according to the power or current references. No additional settings are required.
- If the operating mode selection (parameter 197.13) is DC voltage: Tune the load sharing using the droop control function.
- Master/follower operation of the parallel units: The control program does not support the master/follower link between several units. However, it is possible to implement the Master/follower operation with an external PLC. In that case, one DC/DC-converter unit, the master unit, operates in the DC voltage control mode and the other unit(s) in power control mode. The external PLC reads the output current reference of the master unit, and uses it as the current reference of the follower units.

The load sharing during an overvoltage or undervoltage control of the DC/DC-converter can require tuning of the DC voltage offset value between the parallel units. See the firmware manual for details.

The customer (or the system integrator) must pay special attention to the protection concept in case of parallel units. The protection must operate reliably in all possible fault cases.

5

Electrical installation

Contents of this chapter

This chapter contains instructions on wiring the converter units.

Note: The instructions do not cover all possible cabinet constructions and energy storage media.

Electrical safety precautions

These electrical safety precautions are for all persons who do work on the drive, motor cable or motor.

This procedure gives information on how to de-energize the drive and make it safe to do work on it. The procedure does not include all possible drive configurations. Each drive is made to order. Always refer to the circuit diagrams of the drive delivery.



▲WARNING Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation or maintenance work. Do these steps before you do installation or maintenance work.

1. Prepare for the work.
 - Make sure that you have a work order.
 - Do an on-site risk assessment or job hazard analysis.
 - Make sure that you have the correct tools available.
 - Make sure that the workers are qualified.
-



- Select the correct personal protective equipment (PPE).
 - Stop the drive and motor(s).
2. Clearly identify the work location and equipment.
 3. Disconnect all possible voltage sources. Make sure that connection is not possible. Lock out and tag out.
 - Open the disconnecting device of the energy storage connected to the DC/DC converter unit. The disconnecting device is outside the drive cabinet. Then open the DC switch-disconnector ([Q11], option +F286 or +F290) of the unit.
 - Open the main disconnecting device of the drive [Q1].
 - Open the DC switch-disconnectors [Q11] in the multidrives units if they are present.
 - Open the line-up charging switch [Q3] if it is present. Open also the unit charging switches [Q10] in the multidrives units if they are present.
 - Open the disconnecter of the supply transformer. (The main disconnecting device in the drive cabinet does not disconnect the voltage from the AC input power busbars of the drive cabinet.)
 - Open the auxiliary voltage switch-disconnector (if it is present), and all other possible disconnecting devices that isolate the drive from dangerous voltage sources.
 - In the liquid cooling unit (if present), open the switch-disconnector of the cooling pumps.
 - If there is a permanent magnet motor connected to the drive, disconnect the motor from the drive with a safety switch or by other means.
 - Open the main isolating device of the drive.
 - Disconnect all dangerous external voltages from the control circuits.
 - After you disconnect power from the drive, wait 5 minutes to let the intermediate circuit capacitors discharge before you continue.
 4. Protect other energized parts in the work location against contact and take special precautions when close to bare conductors.
 5. Measure that the installation is de-energized. Use a high-quality voltage tester. If the measurement requires that you remove shrouding or other cabinet structures, obey the local laws and regulations applicable to live electrical work. This includes, but is not limited to, electric shock and arc protection.
 - Before and after you measure the installation, verify the operation of the voltage tester on a known voltage source.
 - Make sure that the voltage between the input power terminals of the drive (L1, L2, L3) and the grounding (PE) busbar is zero.
 - Make sure that the voltage between the output power terminals of the drive (U, V, W) and the grounding (PE) busbar is zero.

Important! Repeat the measurement with the DC voltage setting of the voltage tester. Measure between each phase and ground. There is a risk of dangerous DC voltage charging due to leakage capacitances of the motor circuit. This voltage can remain charged for a long time after the drive power-off. The measurement discharges the voltage.

 - Make sure that the voltage between the drive DC busbars and the grounding (PE) busbar is zero.
 - Make sure that the voltage between the energy storage terminals of the DC/DC converter unit (ES+ and ES-) and the grounding (PE) busbar is zero.





⚠WARNING The busbars inside the cabinet of liquid-cooled drives are partially coated. Measurements made through the coating are potentially unreliable, so only measure at uncoated portions. Note that the coating does not constitute a safe or touch-proof insulation.

- 6. Install temporary grounding as required by the local regulations.
- 7. Ask for a permit to work from the person that is responsible for the electrical installation work.

Use of fasteners in cable lug connections

Use the bolts, nuts and washers include in the delivery. Install all the fasteners in the correct order. See the figure below. Tighten the cable lug to the torque specified for the connection.

Cable lug on one side of the busbar

Cable lugs on both sides of the busbar

1	Bolt	4	Cable lug
2	Plain washer	5	Spring washer
3	Busbar	6	Nut

Measuring the insulation resistance of the DC cabling



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

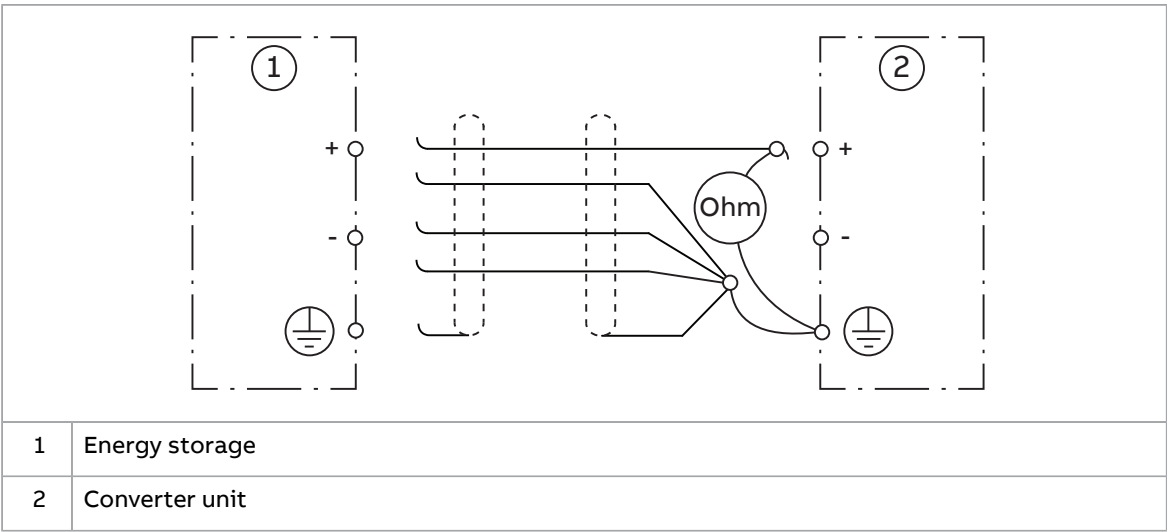


⚠ WARNING Before you measure the insulation resistance of the DC cabling, open the DC switch-disconnector [Q11] of the converter unit. Also make sure that the charging switch [Q10] is open.

NOTICE Do not do voltage withstand or insulation resistance tests on the drive. The tests can cause damage to the drive. Every drive is tested for insulation between the main circuit and the chassis at the factory. Also, there are voltage-limiting circuits inside the drive which cut down the testing voltage automatically.

Measure the insulation resistance of the DC cabling as follows:

1. Make sure that the cable is disconnected at the drive end and at the other end. All conductors and the cable shield must be disconnected.
2. At the drive end, connect all conductors and shield of the cable together and to the grounding busbar (PE).
3. Disconnect one conductor and measure the insulation resistance between the conductor and the grounding busbar (PE). Use a measuring voltage of 1 kV DC. The insulation resistance must be higher than 1 Mohm.
4. Disconnect another conductor and measure its insulation resistance. Do this for all remaining conductors (including the cable shield).

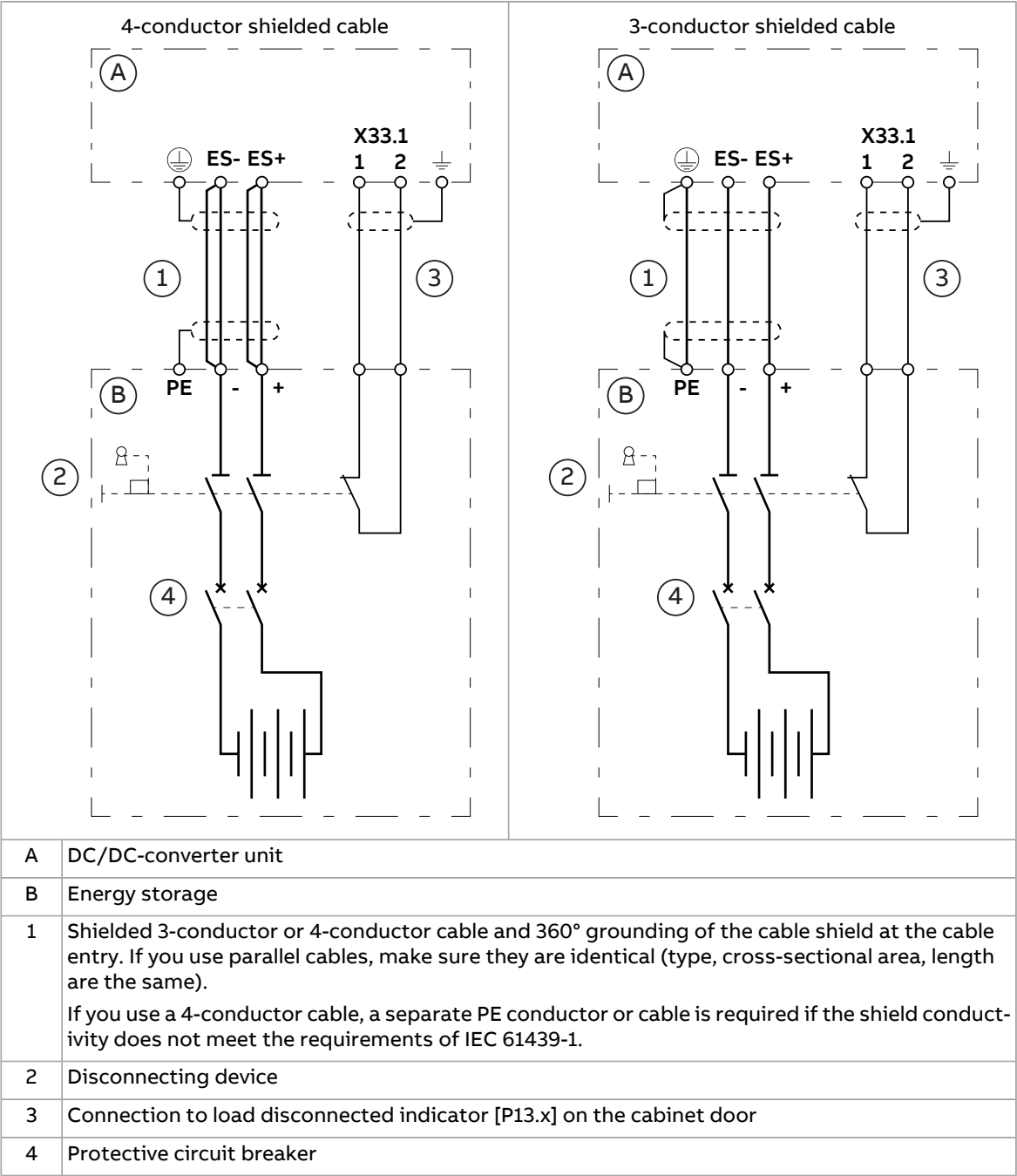


Connecting the energy storage cable and load disconnected indicator cable

■ Connection diagram

If the converter unit has parallel modules, each module must have its own output cables. The cables must also be identical (cable type, cross-sectional area, and length must be the same).

This diagram shows the connections between the DC/DC-converter unit and an energy storage.



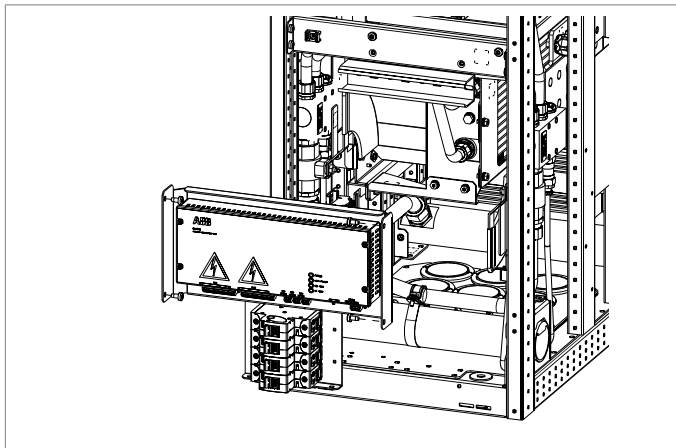
■ Connection procedure of the energy storage cables



⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

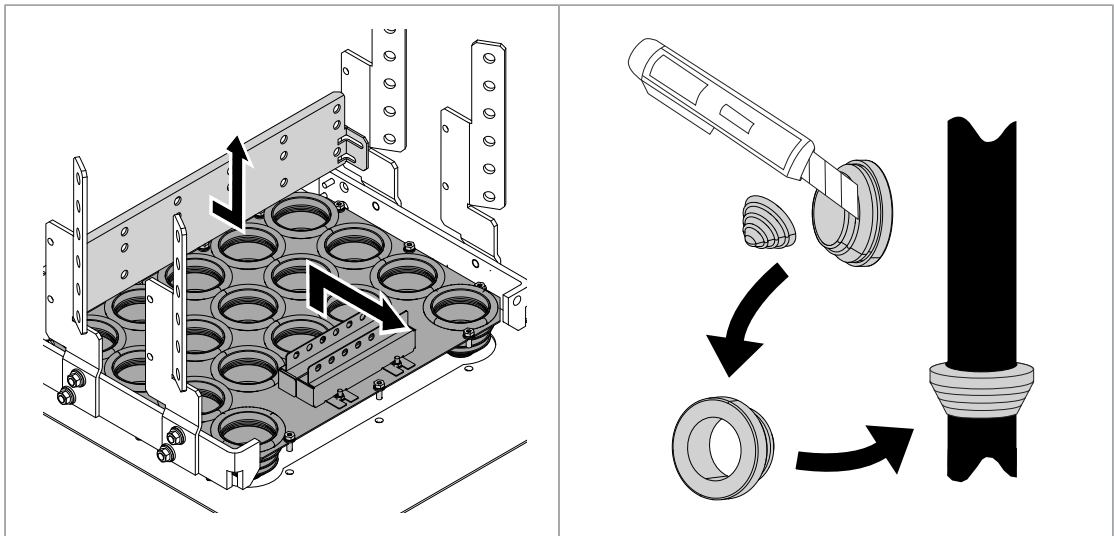
This section describes the power cable connecting procedure for a bottom cable entry with the standard cable entry plate. The standard cable entry plate has conductive sleeves for 360° grounding of the cable shields. If the drive or unit has another type of cable entry plate, such as a Roxtec cable entry plate (option +H394), or cable gland plate (option +H358), refer also to the instruction of the related non-ABB installation accessories. For example, the Roxtec instructions or the instructions by the cable gland manufacturer.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the door of the DC/DC-converter cubicle and remove the shrouding (if any).
3. Frame 2×R7i in one cubicle: Remove the BAMU measurement unit.

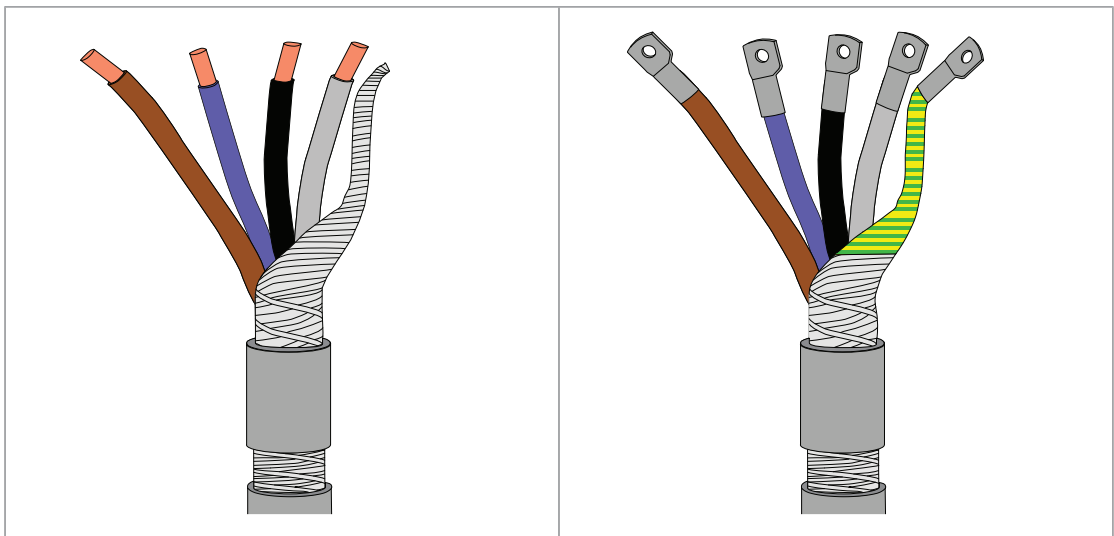


4. Frame 2×R7i in one cubicle: If necessary for more space, remove also the heat exchanger and bottom fan. Refer to [Bottom fan replacement \(page 121\)](#).

5. **IP54 cabinet:** Remove the rear horizontal cable support and the cable entry plate.
IP54 cabinet: Remove a sealing grommet from the cable entry plate for each cable.
 Cut hole into the rubber grommet and slide it onto the cable.

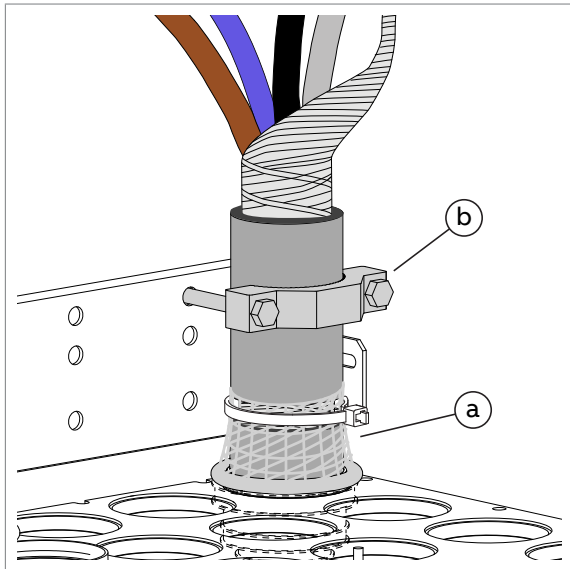


6. Lead the cables inside the cabinet through the cable entry plate. If there are several cables, use the rear 3 holes first.
IP54 cabinet: Attach the sealing grommets to the cable entry plate. Attach also the cable entry plate, and the cable support.
7. For each cable, strip off 3...5 cm (1.2 ... 2 inches) of the outer insulation above the cable entry plate. Strip also the end of the cable, and the end of the conductors. Twist the shield to form a PE conductor, and mark it with yellow-green tape or heat-shrink tubing.
8. For each cable, attach cable lugs at the end of the PE conductor (twisted shield) and other conductors.

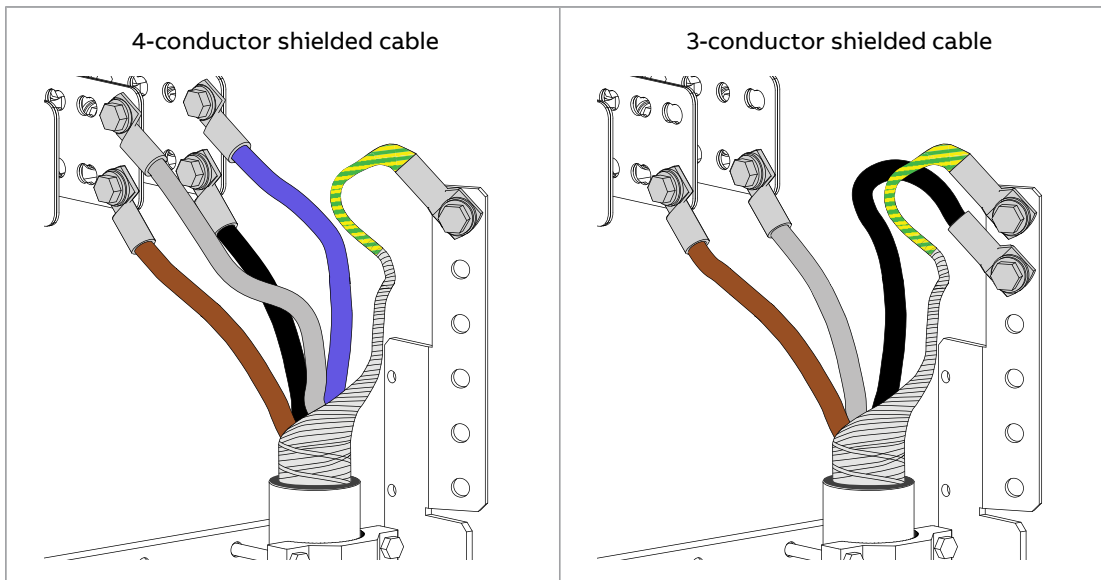


NOTICE Apply grease to stripped aluminum conductors before you attach them to non-coated aluminum cable lugs. Obey the grease manufacturer's instructions. Aluminum-aluminum contact can cause oxidation in the contact surfaces.

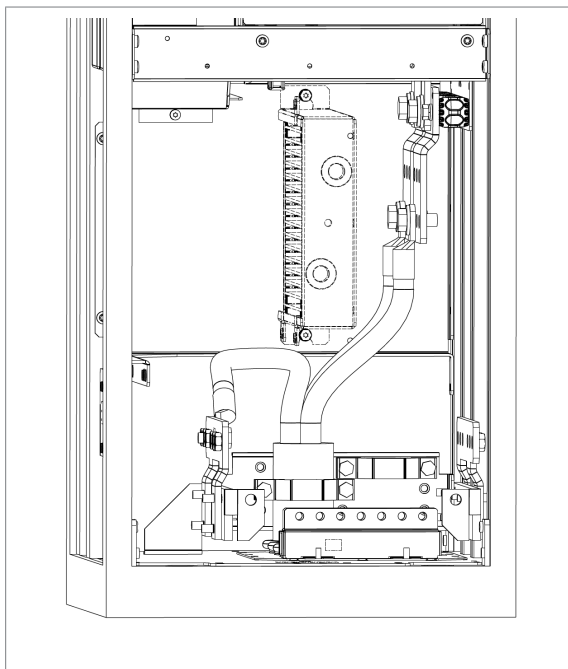
9. For each cable, attach the conductive sleeve (a) to the bare cable shield with a cable tie. Attach the cable to the support bracket with a clamp (b).



10. For each cable, connect the positive conductor(s) to terminal ES+, and the negative conductor(s) to terminal ES-. Connect the cable shield to the PE busbar. If you use a 3-conductor cable, connect one conductor to the PE busbar. Use the bolts, nuts, and washers included in the delivery, and the connection method specified in [Use of fasteners in cable lug connections \(page 61\)](#). Tighten the fasteners to the torque given in the technical data.



11. Frame 2×R7i in one cubicle: If you removed also the heat exchanger, make sure that you bend the cables. The cables must not touch the heat exchanger.



12. If there are more than 3 cables, attach additional cable support brackets for them. Frame 2×R7i: If there are more than 2 cables, attach additional cable support brackets for them.
13. Lead the load disconnected indicator cable inside the cubicle and connect it to the applicable terminals. For more information, refer to the control cable connection instructions.
14. Install the shrouding and components removed earlier and close the cubicle doors.
15. At the energy storage, connect the cables according to the instructions of the energy storage manufacturer.

Connecting the control cables

Refer to the control unit chapter for the default I/O connections. Note that the default I/O connections can be affected by some options. Refer to the circuit diagrams delivered with the drive for the actual wiring.

■ Control cable connection procedure



▲WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

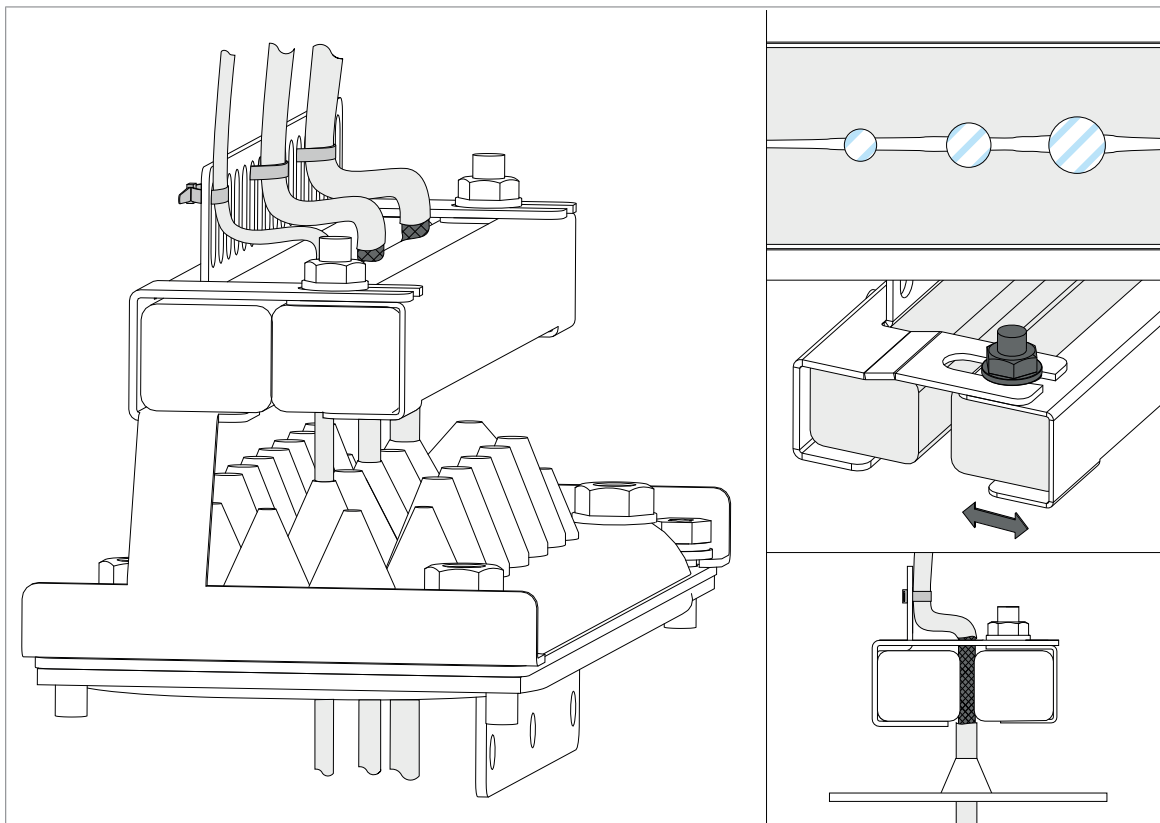
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Put the control cables into the cabinet as described in section [Grounding the outer shields of the control cables 360° at the cabinet entry \(page 68\)](#).

3. Route the control cables as described in section [Routing the control cables inside the cabinet \(page 69\)](#).
4. Connect the control cables as described in section [Connecting control cabling \(page 69\)](#).

Grounding the outer shields of the control cables 360° at the cabinet entry

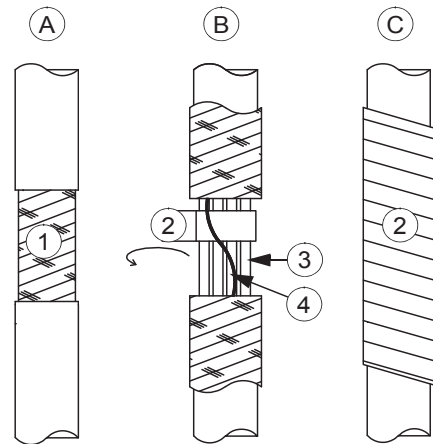
Ground the outer shields of all control cables 360° with the EMI conductive cushions at the cabinet entry. The grounding principle is the same for top and bottom entry cables. The figures show the bottom entry. The actual design details can vary.

1. If necessary, temporarily remove the shrouding in front of the cable entry.
2. Put the cables in sequence from the smallest to the largest. This will help to achieve a good contact with the cushions.
3. Loosen the tightening bolts of the EMI conductive cushions and pull them apart.
4. Cut holes in the grommets and put the cables through the grommets.
5. Peel the insulation from the part of the cable that will be in contact with the EMI conductive cushion.
6. Put the cables between the cushions and attach them with cable ties for strain relief.
7. Move the cushions back together.
8. Tighten the bolts to make sure that the EMI conductive cushions press tightly around the peeled part of the cables.



If the outer surface of the shield is non-conductive:

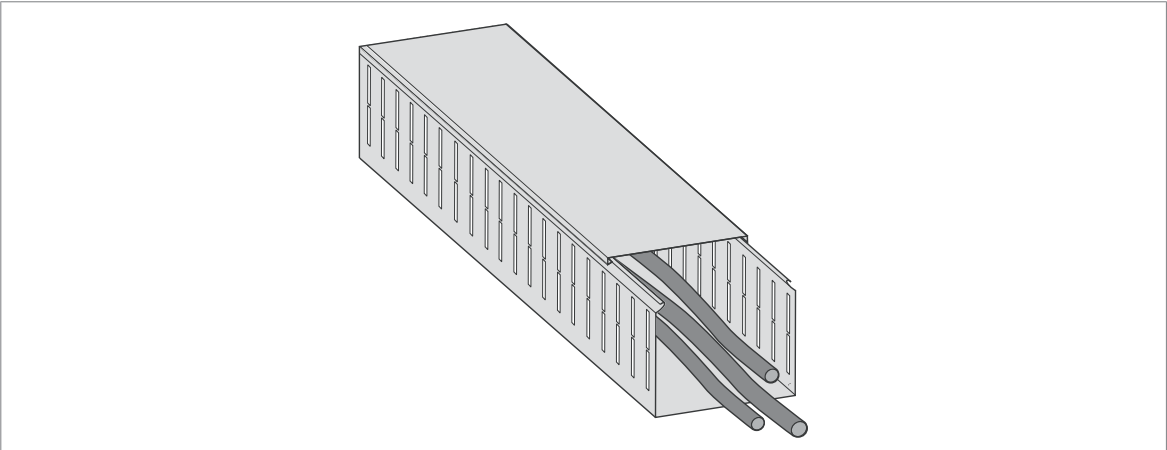
- Cut the shield at the midpoint of the peeled part. Be careful not to cut the conductors or the grounding wire.
- Turn the conductive side of the shield inside out over the insulation.
- Cover the exposed shield and the peeled cable with copper foil to keep the shielding continuous.



A	Stripped cable
B	Conductive surface of the shield exposed
C	Stripped part covered with copper foil
1	Cable shield
2	Copper foil
3	Shielded twisted pair
4	Grounding wire

Routing the control cables inside the cabinet

Use the existing trunking in the cabinet where possible. Use sleeving if cables are laid against sharp edges. When running cables to or from a swing-out frame, leave enough slack at the hinge to allow the frame to open fully.



Connecting control cabling

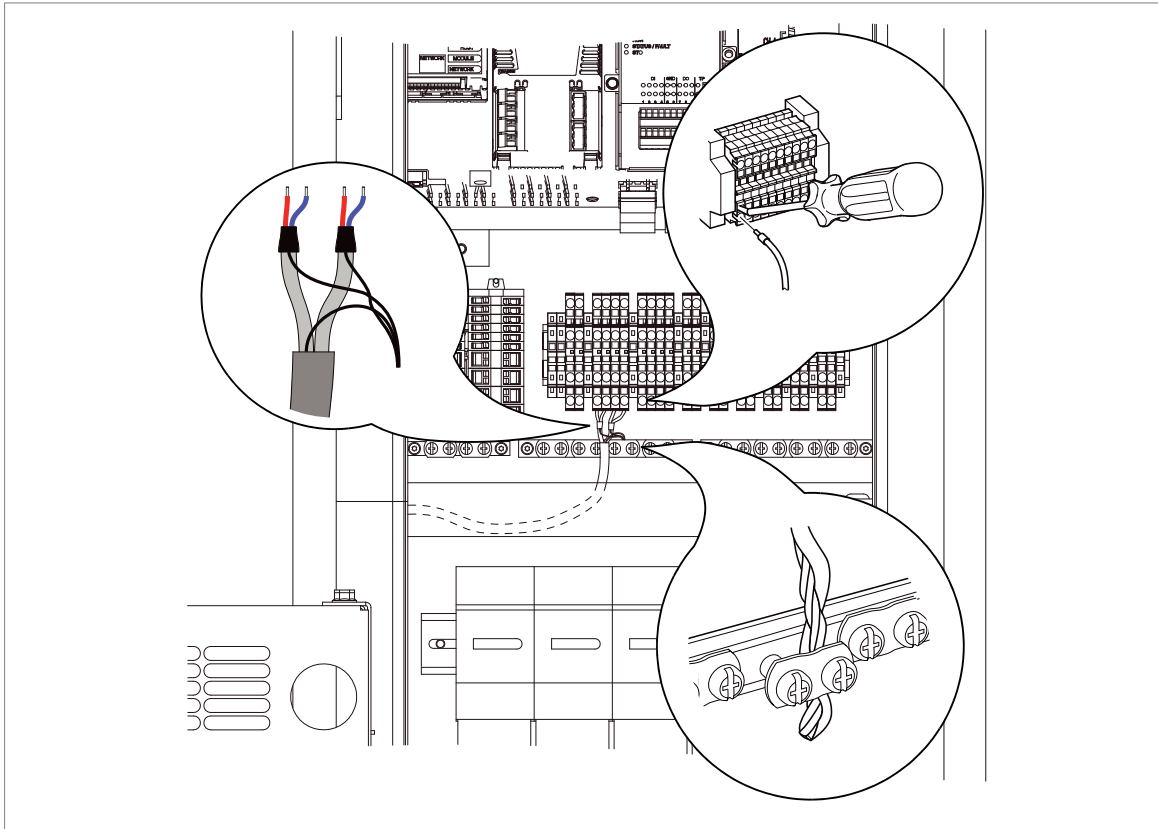
Connect the conductors to the appropriate terminals. Refer to the wiring diagrams delivered with the drive.

Obey these instructions:

- Connect the inner twisted pair shields and all separate grounding wires to the grounding clamps near the terminals.
- Ground the outer shield of the cable with a 360° grounding at the cable entry. Do not make the 360° grounding at the grounding clamps near the terminals.

- Keep any signal wire pairs twisted as close to the terminals as possible. Twisting the wire with its return wire reduces disturbances caused by inductive coupling.
- At the other end of the cable, leave the shields unconnected or ground them indirectly via a high-frequency capacitor with a few nanofarads, eg. 3.3 nF / 630 V. The shield can also be grounded directly at both ends if they are in the same ground line with no significant voltage drop between the end points.

The drawing below represents the grounding of the control cabling when connecting to a terminal block inside the cabinet. The grounding is done in the same way when connecting directly to a component such as the control unit.



Installing option modules

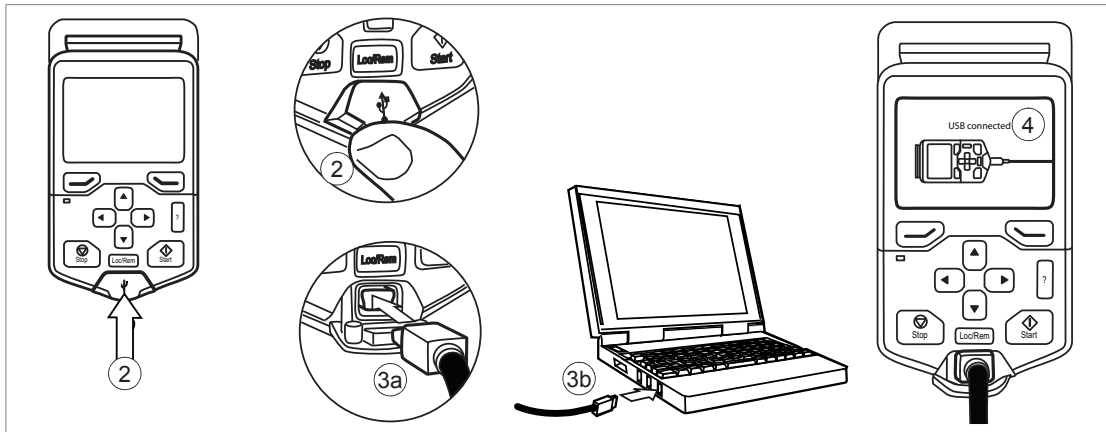
For installation instructions, refer to the option module manual.

Connecting a PC

NOTICE Do not connect a PC directly to the control panel connector of the control unit. It can cause damage.

To connect a control panel to a PC (with, for example, Drive Composer PC tool):

1. Put the control panel into the panel holder or platform.
2. Remove the USB connector cover on the front of the control panel.
3. Connect a USB cable (Type A to Type Mini-B) between the USB connector on the control panel (3a) and a free USB port on the PC (3b).
4. The panel shows when the connection is active.
5. Refer to the documentation of the PC tool for setup instructions.



Alternatively, you can connect an Ethernet cable (for example, Cat 5e) to the Ethernet port behind the control panel. Make sure that the control panel is on a platform or a DIN rail.



6

Control unit (UCU)

Contents of this chapter

This chapter:

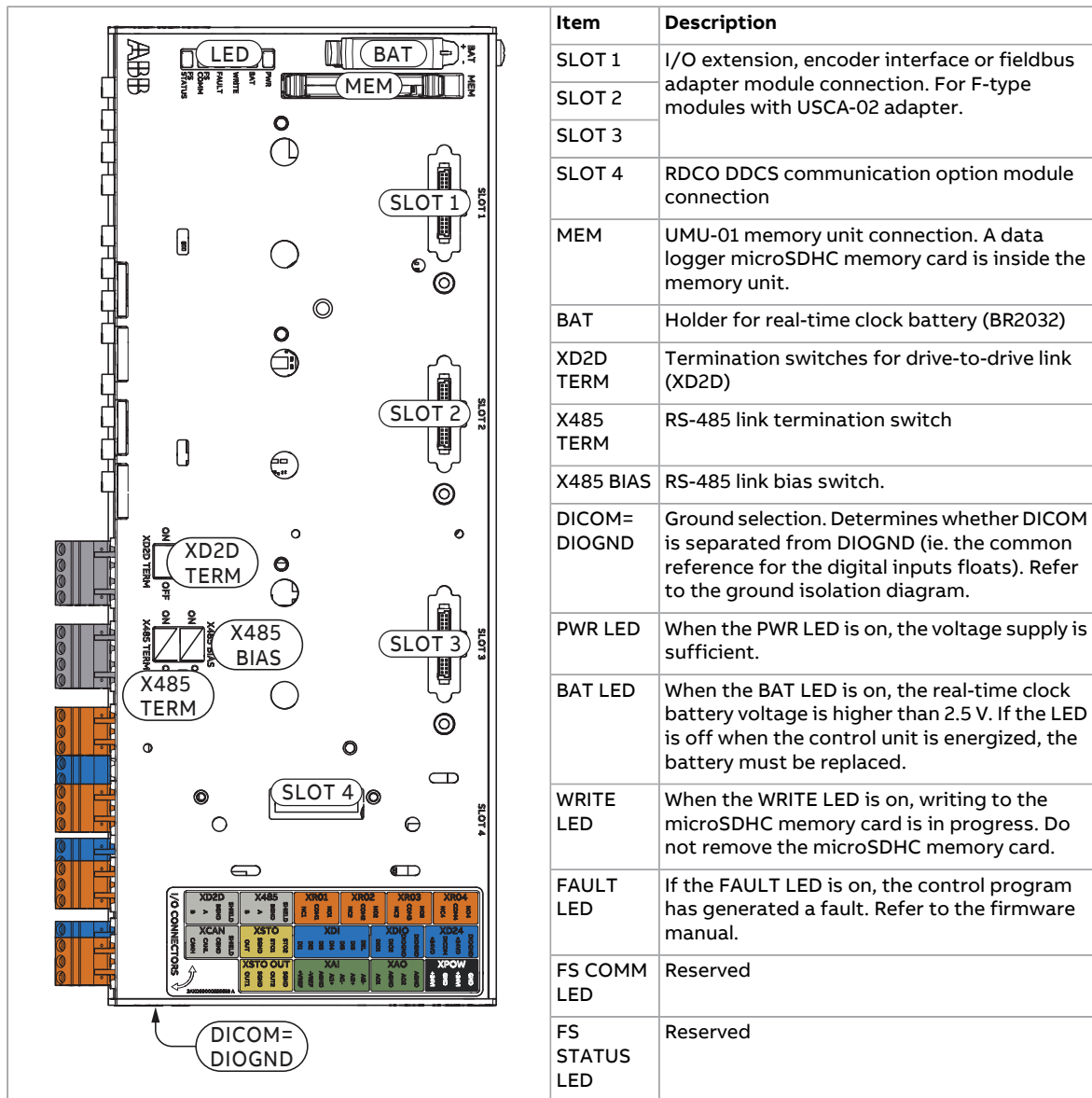
- gives information on the connections of the control unit, and
- contains the specifications of the inputs and outputs of the control unit.

General

The UCU-22...24 control units are used for controlling power modules (drive, inverter, supply, converter, etc) via fiber optic links. UCU-22 has two, UCU-23 has eight and UCU-24 has 14 power module connections. The UCU-22...24 control units have integrated branching unit functionality for collecting and storing real-time data from the power modules to help fault tracing and analysis. The data is stored on a memory card which can be analyzed by ABB service personnel.

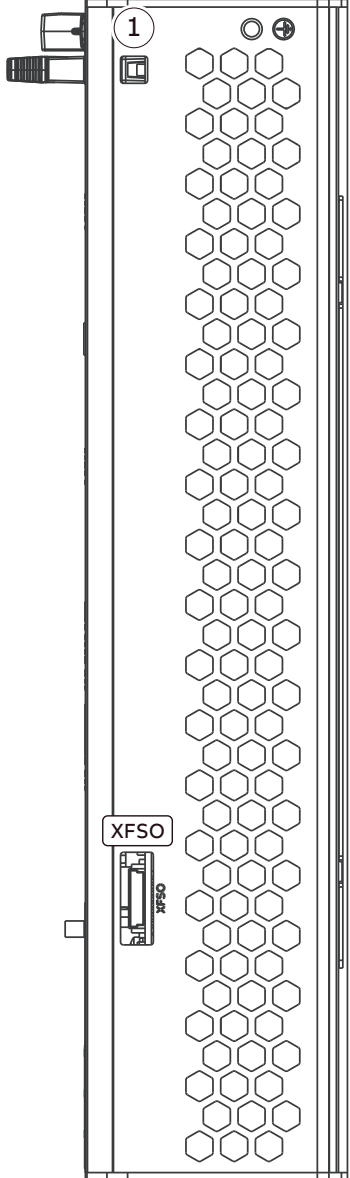
Layout

The figures below show the layout of the UCU-24 control unit.



Item	Description
XAI	Analog input
XAO	Analog output
XCAN	Not in use
XCAN TERM	CAN bus termination switch
XDI	Digital input
XDIO	Digital input/output
XD2D	Drive-to-drive link or Modbus/RTU
XD24	+24 V output (for digital input)
XETH1	Ethernet ports for fieldbus, internal switch
XETH2	
XETH3	Ethernet ports for tool communication, internal switch
XETH4	
XPAN	Control panel connection
XPAN TERM	Panel bus termination switch
XPOW	External power input
XRO1	Relay output RO1
XRO2	Relay output RO2
XRO3	Relay output RO3
XRO4	Relay output RO4, reserved
XSTO	Safe torque off connection (input signals)
XSTO OUT	Safe torque off connection (to inverter modules)
X485	RS-485 link
V1T/V1R ... V14T/V14R	Fiber optic connections (VxT = transmitter, VxR = receiver) <u>UCU-22</u> : V1T/V1R ... V2T/V2R <u>UCU-23</u> : V1T/V1R ... V8T/V8R <u>UCU-24</u> : V1T/V1R ... V14T/V14R

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	Item	Description
	XFSO	Optional connection for FSO safety functions module (supported only in inverter units)
	1	Humidity and temperature measurements

Default control connection diagram of the converter control unit

The table below shows the default I/O connections of the UCU control unit of the DC/DC converter. Under normal circumstances, the factory-made wiring should not be changed.

Terminal			Description	
XD2D			Drive-to-drive link	
1 2 3 4	1	B	Not supported in DC/DC converter units	
	2	A		
	3	BGND		
	4	SHIELD		
ON 1	XD2D TERM		Drive-to-drive link termination switch	
X485			RS485 connection	
5 6 7 8	5	B	CIO-01 module connection	
	6	A		
	7	BGND		
	8	SHIELD		
ON 1	X485 BIAS		X485 bias selection switch	
ON 1	X485 TERM		X485 termination switch	
XCAN			CAN bus	
9 10 11 12	9	CANH	Not supported	
	10	CANL		
	11	CGND		
	12	SHIELD	Control cable shield	
1 ON	XCAN TERM		CANopen termination switch	
XRO1			Relay output 1	
11 12 13	11	NC1	Norm. closed	XRO1: Not in use 250 V AC / 30 V DC, 2 A
	12	COM1	Common	
	13	NO1	Norm. open	
XRO2			Relay output 2	
21 22 23	21	NC2	Norm. closed	XRO2: Fault (-1) ¹⁾ (Energized = no fault) 250 V AC / 30 V DC, 2 A
	22	COM2	Common	
	23	NO2	Norm. open	
XRO3			Relay output 3	
31 32 33	31	NC3	Norm. closed	XRO3: Fan control (DC/DC converter in operation, fan control on) 250 V AC / 30 V DC, 2 A
	32	COM3	Common	
	33	NO3	Norm. open	

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Terminal			Description
XRO4			Relay output 4
	41	NC4	Norm. closed
	42	COM4	Common
	43	NO4	Norm. open
			XRO4: Not supported 250 V AC / 30 V DC, 2 A
XSTO			Safe torque off input connection
	1	OUT	XSTO: STO1 and STO2 are connected to OUT at the factory. To enable start and operation, STO1 and STO2 must be connected to OUT.
	2	SGND	
	3	STO1	
	4	STO2	
XSTO OUT			Safe torque off output connection (to inverter modules)
	5	OUT1	XSTO OUT: Not in use.
	6	SGND	
	7	OUT2	
	8	SGND	
XDI			Digital inputs
	1	DI1	Temp fault ¹⁾ (0 = overtemperature)
	2	DI2	Not in use by default
	3	DI3	Not in use by default
	4	DI4	Not in use by default
	5	DI5	Not in use by default
	6	DI6	Not in use by default
	7	DIIL	Not in use by default. DIIL is connected to XD24:5 at the factory.
XDIO			Digital input/outputs
	1	DIO1	Not in use by default
	2	DIO2	Not in use by default
	3	DIOGND	Digital input/output ground
	4	DIOGND	Digital input/output ground
XD24			Auxiliary voltage output
	5	+24VD	+24 V DC 200 mA ²⁾
	6	DICOM	Digital input ground
	7	+24VD	+24 V DC 200 mA ²⁾
	8	DIOGND	Digital input/output ground
	DICOM=DIOGND		Ground selection switch. Determines whether DICOM is separated from DIOGND (ie, common reference for digital inputs floats). ON: DICOM connected to DIOGND. OFF: DICOM and DIOGND separate.

Terminal			Description
XAI			Analog inputs, reference voltage output
1 2 3 4 5 6 7	1	+VREF	10 V DC, R_L 1...10 kohm
	2	-VREF	-10 V DC, R_L 1...10 kohm
	3	AGND	Ground
	4	AI1+	Not in use by default. 0(2)...10 V, $R_{in} > 200$ kohm ³⁾
	5	AI1-	
	6	AI2+	Not in use by default. 0(4)...20 mA, $R_{in} = 100$ ohm ⁴⁾
	7	AI2-	
XAO			Analog outputs
1 2 3 4	1	AO1	Zero (no signal indicated) ¹⁾ 0...20 mA, $R_L < 500$ ohm (not in use by default)
	2	AGND	
	3	AO2	Zero (no signal indicated) ¹⁾ 0...20 mA, $R_L < 500$ ohm (not in use by default)
	4	AGND	
XPOW			External power input
1 2 3 4	1	+24VI	19...32 V DC, 1.5 ... 2.9 A (depends on the load and supply voltage) External power input. Two supplies can be connected to the control unit for redundancy.
	2	GND	
	3	+24VI	
	4	GND	
XFSO			Safety functions module connection. Not supported in DC/DC converter units.
XETH1			Ethernet ports for fieldbus. Support depends on the firmware. Refer to the firmware manual.
XETH2			
XETH3			Ethernet ports for tool communication. Support depends on the firmware. Refer to the firmware manual.
XETH4			
XPAN			Control panel connection
1 ON	XPAN TERM		Control panel connection termination switch. Used for panel bus configuration.
MEM			Memory unit connection

¹⁾ Default use of the signal in the control program. The use can be changed by a parameter. See also the delivery-specific circuit diagrams.

²⁾ Total load capacity of these outputs is 4.8 W (200 mA at 24 V) minus the power taken by DIO1 and DIO2.

³⁾ Current [0(4)...20 mA, $R_{in} = 100$ ohm] or voltage [0(2)...10 V, $R_{in} > 200$ kohm]. Change of setting requires reboot of control unit.

⁴⁾ Current [0(4)...20 mA, $R_{in} = 100$ ohm] or voltage [0(2)...10 V, $R_{in} > 200$ kohm]. Change of setting requires reboot of control unit.

Additional information on the connections

■ Power supply for the control unit (XPOW)

Power to the control unit is supplied through terminal block XPOW.

Refer to the control unit connector data for the current and voltage ratings of the power supply.

80 Control unit (UCU)

Connect an additional external power supply to the free +24 V and GND terminals of the XPOW terminal block if:

- the control unit must be kept operational during input power breaks, for example, because of continuous fieldbus communication
- immediate restart is necessary after a power break (that is, no control unit power-up delay is permitted).

■ Digital interlock (DIIL)

Digital interlock input (DIIL) terminal is originally intended for interlock signals that stop the drive/unit when necessary.

In the ACS880 primary control program, DIIL terminal is the source for the run enable signal by default. The inverter unit or drive cannot start, or it stops when there is no DIIL signal. In other control programs (and units), the default use of the DIIL terminal varies. Refer to the firmware manual for more information.

Note: This input is **not** SIL or PL classified.

■ Control panel connection (XPAN)

The XPAN connector can be used to connect an assistant control panel or FDPI-02 diagnostics and panel interface unit to the control unit. With FDPI-02, it is possible to connect one control panel to two or more control units in a chain topology, also known as a panel bus. For more information, refer to [FDPI-02 diagnostics and panel interface user's manual \(3AUA0000113618 \[English\]\)](#).

The XPAN TERM switch sets the termination for the panel bus. Must be set to ON if there is no panel bus, or if the control unit is the last one in a panel bus. On intermediate units in a panel bus, set termination to OFF (1).

■ Safe torque off (XSTO, XSTO OUT)

The XSTO input only acts as a true Safe torque off input on the inverter control unit. De-energizing the STO input terminals of other control units (supply, DC/DC converter, or brake unit) stops the unit but does not constitute a SIL/PL classified safety function.

■ MicroSDHC memory card slot

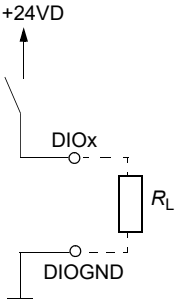
The control unit has an on-board data logger that collects real-time data from the power modules to help fault tracing and analysis. The data is stored onto the microSDHC memory card inserted into the UMU-01 memory unit and can be analyzed by ABB service personnel.

Connector data

The wire size accepted by all screw terminals (for both stranded and solid wire) is 0.5 ... 2.5 mm² (22...12 AWG). Connector pitch is 5 mm.

Maximum tightening torque of the screw terminals is 0.45 N·m (4 lbf·in).

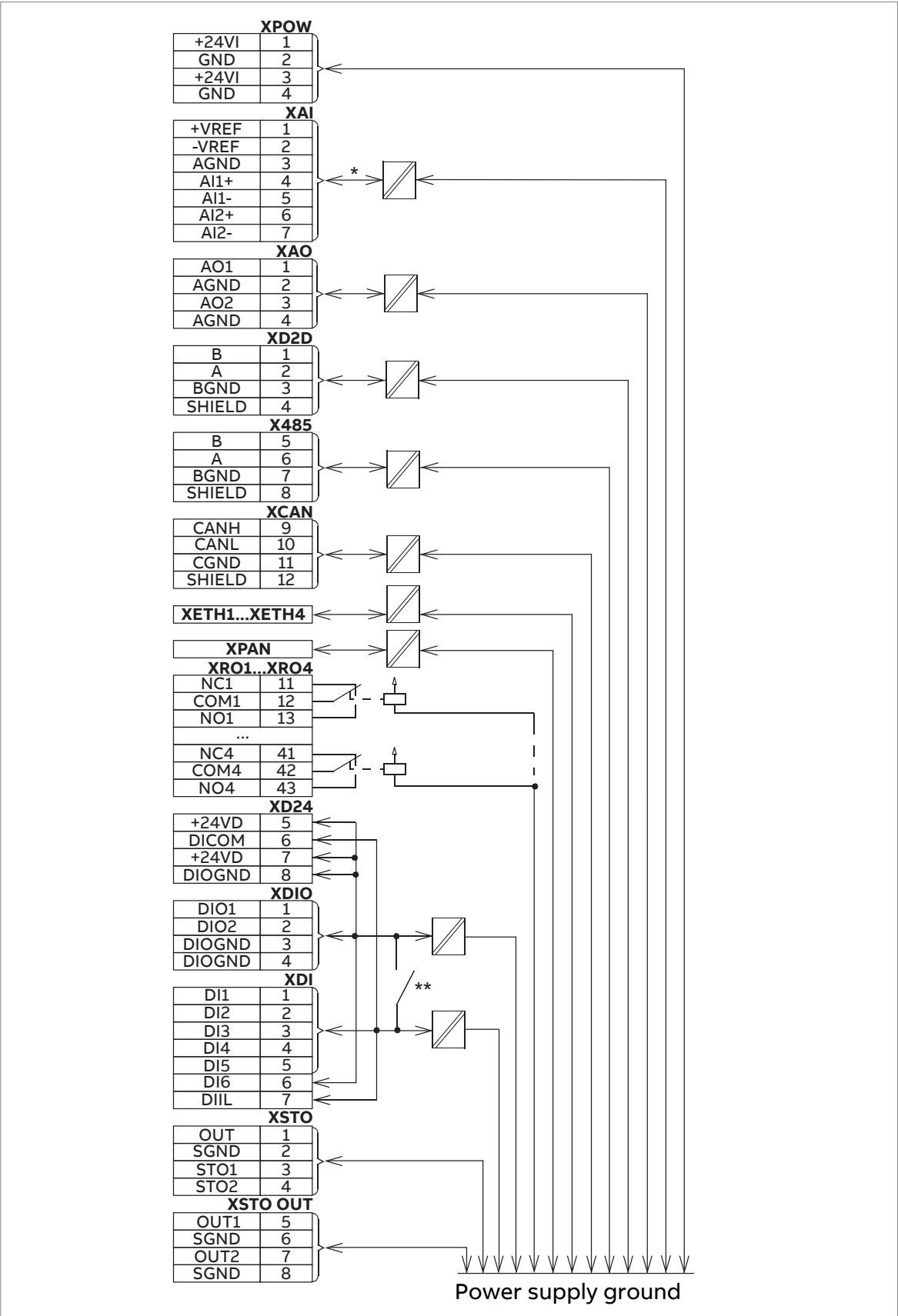
Power supply (XPOW)	19...32 V DC, 1.5 ... 2.9 A (depends on the load and supply voltage) External power input. Two supplies can be connected to the control unit for redundancy.
Relay outputs XRO1...XRO4	250 V AC / 30 V DC, 2 A Protected by varistors

+24 V output (XD24:5 and XD24:7)	Total load capacity of these outputs is 4.8 W (200 mA / 24 V) minus the power taken by DIO1 and DIO2.
Digital inputs DI1...DI6 (XDI:1...XDI:6)	24 V logic levels: "0" < 5 V, "1" > 15 V R_{in}: 2.0 kohm Input type: NPN/PNP (DI1...DI5), PNP (DI6) Hardware filtering: 0.04 ms, digital filtering up to 8 ms I_{max}: 15 mA (DI1...DI5), 5 mA (DI6)
Start interlock input DIIL (XDI:7)	24 V logic levels: "0" < 5 V, "1" > 15 V R_{in}: 2.0 kohm Input type: NPN/PNP Hardware filtering: 0.04 ms, digital filtering up to 8 ms
Digital inputs/outputs DIO1 and DIO2 (XDIO:1 and XDIO:2) Input/output mode selection by parameters. DIO1 can be configured as a frequency input (0...100 kHz with hardware filtering of 4 microseconds) for 24 V level square wave signal (sinusoidal or other wave form cannot be used). In some control programs, DIO2 can be configured as a 24 V level square wave frequency output. Refer to the firmware manual, parameter group 11.	<u>As inputs:</u> 24 V logic levels: "0" < 5 V, "1" > 15 V. R_{in}: 2.0 kohm. Filtering: 1 ms. <u>As outputs:</u> Total output current from +24VD is limited to 200 mA 
Reference voltage for analog inputs +VREF and -VREF (XAI:1 and XAI:2)	10 V $\pm$1% and -10 V $\pm$1%, R_{load} 1...10 kohm Maximum output current: 10 mA
Analog inputs AI1 and AI2 (XAI:4 ... XAI:7). Current/voltage input mode selection by parameters 12.15 AI1 unit selection and 12.25 AI2 unit selection	Current input: -20...20 mA, R_{in} = 100 ohm Voltage input: -10...10 V, R_{in} > 200 kohm Differential inputs, common mode range $\pm$30 V Sampling interval per channel: 0.25 ms Hardware filtering: 0.25 ms Resolution: 11 bit + sign bit Inaccuracy: 1% of full scale range
Analog outputs AO1 and AO2 (XAO)	0...20 mA, R_{load} < 500 ohm Frequency range: 0...500 Hz Resolution: 11 bit + sign bit Inaccuracy: 2% of full scale range
XD2D connector	Physical layer: RS-485 Transmission rate: 8 Mbit/s Cable type: Shielded twisted-pair cable with a twisted pair for data and a wire or another pair for signal ground (nominal impedance 100 ... 165 ohm, for example Belden 9842) Maximum length of link: 50 m (164 ft) Termination by switch
RS-485 connection (X485)	Physical layer: RS-485 Cable type: Shielded twisted-pair cable with a twisted pair for data and a wire or another pair for signal ground (nominal impedance 100 ... 165 ohm, for example Belden 9842) Maximum length of link: 50 m (164 ft) Termination and bias by switch (X485 TERM and X485 BIAS)

82 Control unit (UCU)

CAN connection (XCAN)	Termination by switch (XCAN TERM) This connection is not supported by the ACS880 control programs.
Safe torque off connection (XSTO)	Input voltage range: -3...30 V DC Logic levels: "0" < 5 V, "1" > 17 V. Note: Both circuits must be closed to enable start and operation (STO1 and STO2 must be connected to OUT). This applies to all control units (including drive, inverter, supply, brake, DC/DC converter etc. control units), but SIL/PL classified Safe torque off functionality is only achieved through the XSTO connector of the drive/inverter control unit. Current consumption (continuous) per STO channel: 15 mA. The number of parallel inverter modules does not have an effect on the current consumption. EMC (immunity) according to IEC 61326-3-1 and IEC 61800-5-2
Safe torque off output (XSTO OUT)	To STO connector of inverter module.
Control panel connection (XPAN)	Connector: RJ-45 Cable length < 50 m (164 ft) Termination by switch (XPAN TERM)
Control Ethernet connection with internal switch (XETH1 and XETH2)	Connector: RJ-45 Cable type: minimum requirement CAT5e
Tool Ethernet connection with internal switch (XETH3 and XETH4)	Connector: RJ-45 Cable type: minimum requirement CAT5e
microSDHC memory card slot (microSDHC CARD)	Memory card type: microSDHC (minimum of class 4 speed grade) Supported memory size: 4 GB...32 GB
Battery	Real-time clock battery type: BR2032
The terminals of the control unit fulfill the Protective Extra Low Voltage (PELV) requirements. The PELV requirements of a relay output are not fulfilled if a voltage higher than 48 V is connected to the relay output.	

■ Ground isolation diagram



*The maximum common mode voltage between each AI input and AGND is ± 30 V.

****Ground selector (DICOM=DIOGND) settings**

DICOM=DIOGND: ON

All digital inputs share a common ground (DICOM connected to DIOGND). This is the default setting.

DICOM=DIOGND: OFF

Ground of digital inputs DI1...DI5 and DIIL (DICOM) is isolated from DIO signal ground (DIOGND). Isolation voltage 50 V.

7

Control unit (BCU)

Contents of this chapter

This chapter:

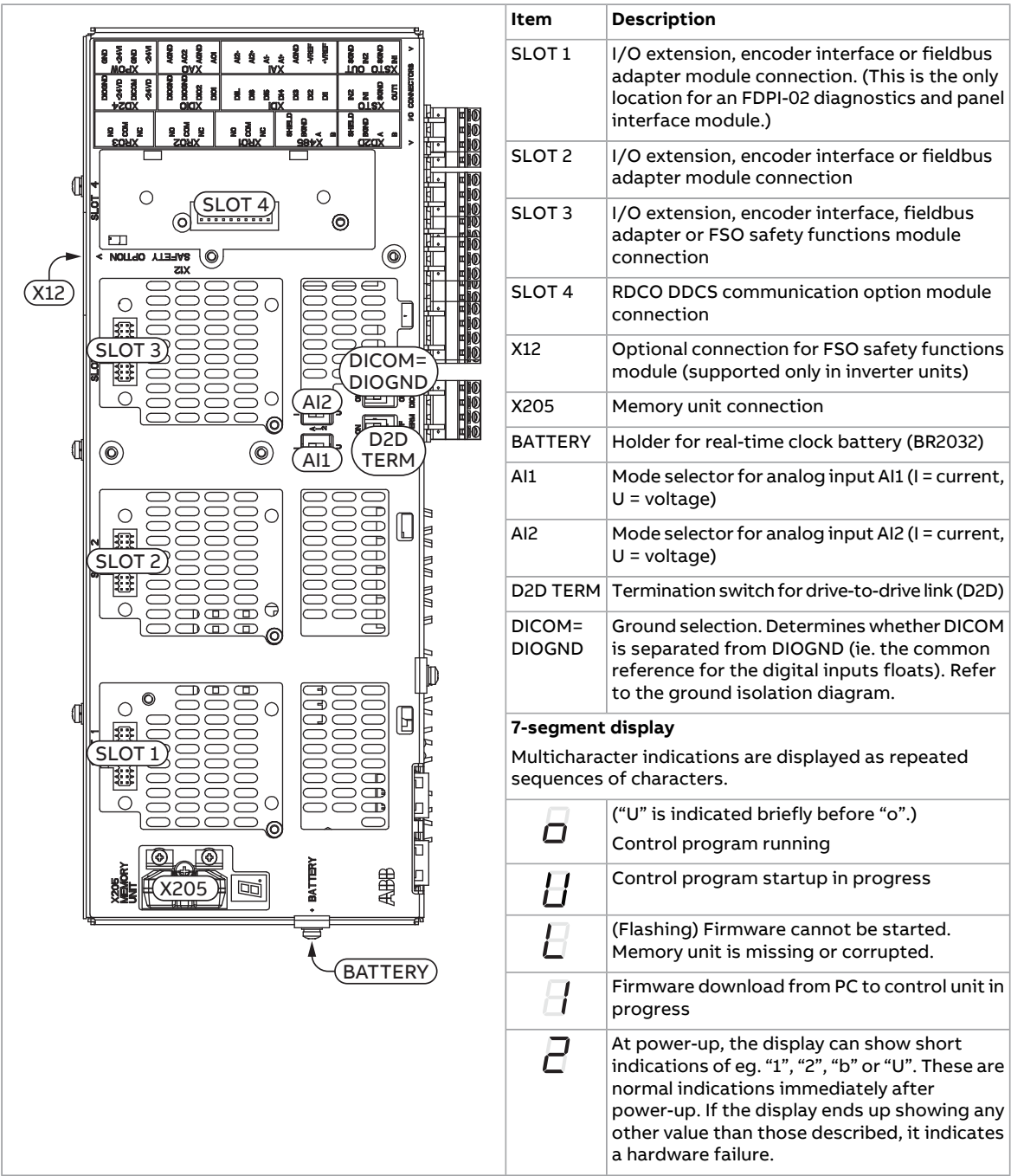
- gives information on the connections of the control unit, and
- contains the specifications of the inputs and outputs of the control unit.

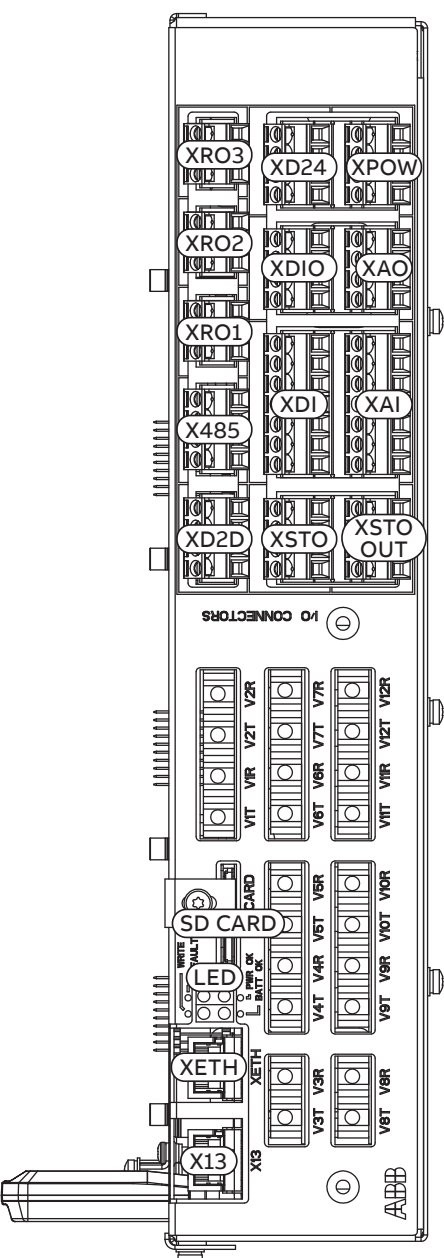
General

The BCU control units are used for controlling power modules (drive, inverter, supply, converter, etc) via fiber optic links. BCU-02 has two, BCU-12 has seven, and BCU-22 has 12 power module connections. The BCU control units have integrated branching unit functionality for collecting and storing real-time data from the power modules to help fault tracing and analysis. The data is stored on a memory card which can be analyzed by ABB service personnel.

Layout

The figures below show an example layout of the BCU control unit.



	Item	Description
	XAI	Analog input
	XAO	Analog output
	XDI	Digital input
	XDIO	Digital input/output
	XD2D	Drive-to-drive link or Modbus/RTU
	XD24	+24 V output (for digital input)
	XETH	Ethernet port (not in use)
	XPOW	External power input
	XRO1	Relay output RO1
	XRO2	Relay output RO2
	XRO3	Relay output RO3
	XSTO	Safe torque off connection (input signals)
	XSTO OUT	Safe torque off connection (to inverter modules)
	X13	Control panel connection (PC connection through control panel)
	X485	Connection to CIO-01
	V1T/V1R ... V12T/V12R	Fiber optic connections (VxT = transmitter, VxR = receiver) BCU-02: V1T/V1R ... V2T/V2R BCU-12: V1T/V1R ... V7T/V7R BCU-22: V1T/V1R ... V12T/V12R
	SD CARD	Data logger memory card
	BATT OK LED	When the BATT OK LED is on, the real-time clock battery voltage is higher than 2.8 V. If the LED is off when the control unit is energized, the battery must be replaced.
	PWR OK LED	When the PWR OK LED is on, the voltage supply is sufficient.
	FAULT LED	If the FAULT LED is on, the control program has generated a fault. Refer to the firmware manual.
	WRITE LED	When the WRITE LED is on, writing to the memory card is in progress. Do not remove the memory card.

Default control connection diagram of the converter control unit

The table below shows the default I/O connections of the BCU control unit of the converter. Under normal circumstances, the factory-made wiring should not be changed.

Terminal			Description	
XD2D			Drive-to-drive link	
1 2 3 4	1	B	Not supported in DC/DC converter units	
	2	A		
	3	BGND		
	4	Shield		
ON OFF	D2D.TERM		Drive-to-drive link termination switch	
X485			RS485 connection	
5 6 7 8	5	B	CIO-01 module connection	
	6	A		
	7	BGND		
	8	Shield		
XRO1, XRO2, XRO3			Relay outputs	
11 12 13 21 22 23 31 32 33	11	NC	Norm. closed	XRO1: Not in use 250 V AC / 30 V DC, 2 A
	12	COM	Common	
	13	NO	Norm. open	
	21	NC	Norm. closed	XRO2: Fault (-1) ¹⁾ (Energized = no fault) 250 V AC / 30 V DC, 2 A
	22	COM	Common	
	23	NO	Norm. open	
	31	NC	Norm. closed	XRO3: Fan control (DC/DC converter running, fan control on) 250 V AC / 30 V DC, 2 A
	32	COM	Common	
	33	NO	Norm. open	
XSTO			Safe torque off input connection	
1 2 3 4	1	OUT	XSTO: IN1 and IN2 are connected to OUT at the factory. To enable start and operation, IN1 and IN2 must be connected to OUT.	
	2	SGND		
	3	IN1		
	4	IN2		
XSTO OUT			Safe torque off output connection (to inverter modules)	
5 6 7 8	5	IN1	XSTO OUT: Not in use	
	6	SGND		
	7	IN2		
	8	SGND		

Terminal			Description
XDI			Digital inputs
1 2 3 4 5 6 7	1	DI1	Temp fault ¹⁾ (0 = overtemperature)
	2	DI2	Not in use by default
	3	DI3	Not in use by default
	4	DI4	Not in use by default
	5	DI5	Not in use by default
	6	DI6	Not in use by default
	7	DIIL	Not in use by default. DIIL is connected to XD24:5 at the factory.
XDIO			Digital input/outputs
1 2 3 4	1	DIO1	Not in use by default
	2	DIO2	Not in use by default
	3	DIOGND	Digital input/output ground
	4	DIOGND	Digital input/output ground
XD24			Auxiliary voltage output
5 6 7 8	5	+24VD	+24 V DC 200 mA ²⁾
	6	DICOM	Digital input ground
	7	+24VD	+24 V DC 200 mA ²⁾
	8	DIOGND	Digital input/output ground
	DICOM=DIOGND		Ground selection switch. Determines whether DICOM is separated from DIOGND (ie, common reference for digital inputs floats). ON: DICOM connected to DIOGND. OFF: DICOM and DIOGND separate.
XAI			Analog inputs, reference voltage output
1 2 3 4 5 6 7	1	+VREF	10 V DC, R_L 1...10 kohm
	2	-VREF	-10 V DC, R_L 1...10 kohm
	3	AGND	Ground
	4	AI1+	Not in use by default. 0(2)...10 V, $R_{in} > 200$ kohm ³⁾
	5	AI1-	
	6	AI2+	Not in use by default. 0(4)...20 mA, $R_{in} = 100$ ohm ⁴⁾
	7	AI2-	
	AI1		AI1 current/voltage selection switch
	AI2		AI2 current/voltage selection switch
XAO			Analog outputs
1 2 3 4	1	AO1	Zero ¹⁾ 0...20 mA, $R_L < 500$ ohm (not in use by default)
	2	AGND	
	3	AO2	Zero ¹⁾ 0...20 mA, $R_L < 500$ ohm (not in use by default)
	4	AGND	
XPOW			External power input
1 2 3 4	1	+24VI	24 V DC ($\pm 10\%$), 2 A External power input. Two supplies can be connected to the control unit for redundancy.
	2	GND	
	3	+24VI	
	4	GND	

Terminal	Description
X12	Safety functions module connection. Not supported in DC/DC converter units.
X13	Control panel connection
X205	Memory unit connection

- ¹⁾ Default use of the signal in the control program. The use can be changed by a parameter. See also the delivery-specific circuit diagrams.
- ²⁾ Total load capacity of these outputs is 4.8 W (200 mA at 24 V) minus the power taken by DIO1 and DIO2.
- ³⁾ Current [0(4)...20 mA, $R_{in} = 100 \text{ ohm}$] or voltage [0(2)...10 V, $R_{in} > 200 \text{ kohm}$] input selected by switch AI1. Change of setting requires reboot of control unit.
- ⁴⁾ Current [0(4)...20 mA, $R_{in} = 100 \text{ ohm}$] or voltage [0(2)...10 V, $R_{in} > 200 \text{ kohm}$] input selected by switch AI2. Change of setting requires reboot of control unit.

Additional information on the connections

■ Power supply for the control unit (XPOW)

Power to the control unit is supplied through terminal block XPOW.

Refer to the control unit connector data for the current and voltage ratings of the power supply.

Connect an additional external power supply to the free +24 V and GND terminals of the XPOW terminal block if:

- the control unit must be kept operational during input power breaks, for example, because of continuous fieldbus communication
- immediate restart is necessary after a power break (that is, no control unit power-up delay is permitted).

■ Digital interlock (DIIL)

Digital interlock input (DIIL) terminal is originally intended for interlock signals that stop the drive/unit when necessary.

In the ACS880 primary control program, DIIL terminal is the source for the run enable signal by default. The inverter unit or drive cannot start, or it stops when there is no DIIL signal. In other control programs (and units), the default use of the DIIL terminal varies. Refer to the firmware manual for more information.

Note: This input is **not** SIL or PL classified.

■ Safe torque off (XSTO, XSTO OUT)

The XSTO input only acts as a true Safe torque off input on the inverter control unit. De-energizing the STO input terminals of other control units (supply, DC/DC converter, or brake unit) stops the unit but does not constitute a SIL/PL classified safety function.

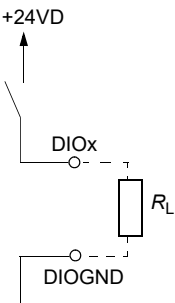
■ SDHC memory card slot

The control unit has an on-board data logger that collects real-time data from the power modules to help fault tracing and analysis. The data is stored onto the SDHC memory card inserted into the SD CARD slot and can be analyzed by ABB service personnel.

Connector data

The wire size accepted by all screw terminals (for both stranded and solid wire) is 0.5 ... 2.5 mm² (22...12 AWG). Connector pitch is 5 mm.

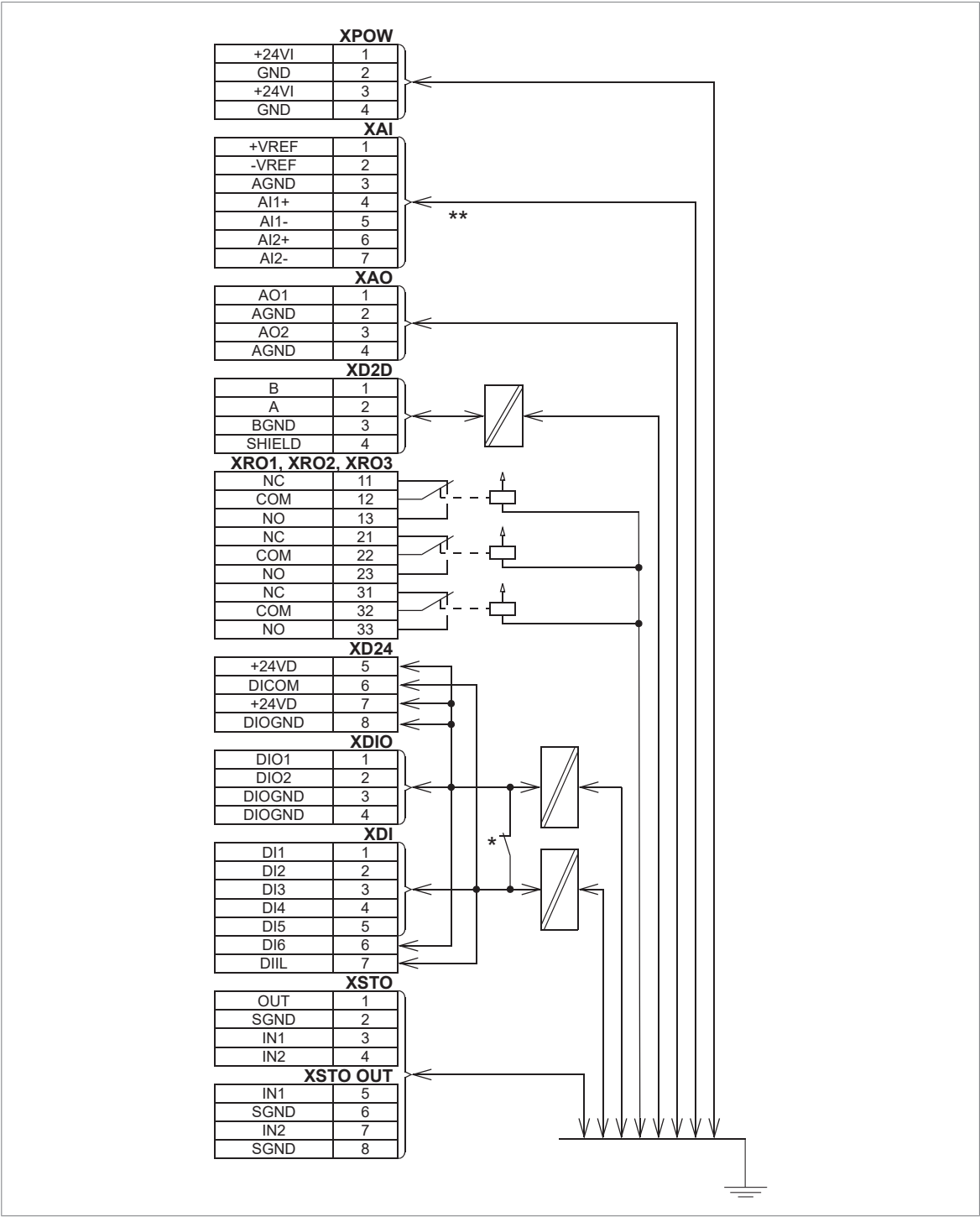
The maximum tightening torque for screw terminals is 0.45 N·m (4 lbf·in).

Power supply (XPOW)	24 V DC ($\pm 10\%$), 2 A External power input. Two supplies can be connected to the BCU control unit for redundancy.
Relay outputs RO1...RO3 (XRO1...XRO3)	250 V AC / 30 V DC, 2 A Protected by varistors
+24 V output (XD24:5 and XD24:7)	Total load capacity of these outputs is 4.8 W (200 mA / 24 V) minus the power taken by DIO1 and DIO2.
Digital inputs DI1...DI6 (XDI:1...XDI:6)	24 V logic levels: "0" < 5 V, "1" > 15 V R_{in} : 2.0 kohm (DI1...DI5) Input type: NPN/PNP (DI1...DI5), PNP (DI6) Hardware filtering: 0.04 ms, digital filtering up to 8 ms I_{max} : 15 mA (DI1...DI5), 5 mA (DI6)
Start interlock input DIIL (XDI:7)	24 V logic levels: "0" < 5 V, "1" > 15 V R_{in} : 2.0 kohm Input type: NPN/PNP Hardware filtering: 0.04 ms, digital filtering up to 8 ms
Digital inputs/outputs DIO1 and DIO2 (XDIO:1 and XDIO:2) Input/output mode selection by parameters. DIO1 can be configured as a frequency input (0...16 kHz with hardware filtering of 4 microseconds) for 24 V level square wave signal (sinusoidal or other wave form cannot be used). In some control programs, DIO2 can be configured as a 24 V level square wave frequency output. Refer to the firmware manual, parameter group 11.	As inputs: 24 V logic levels: "0" < 5 V, "1" > 15 V. R_{in} : 2.0 kohm. Filtering: 1 ms. As outputs: Total output current from +24VD is limited to 200 mA 
Reference voltage for analog inputs +VREF and -VREF (XAI:1 and XAI:2)	10 V $\pm 1\%$ and -10 V $\pm 1\%$, R_{load} 1...10 kohm Maximum output current: 10 mA
Analog inputs AI1 and AI2 (XAI:4 ... XAI:7). Current/voltage input mode selection by switches	Current input: -20...20 mA, R_{in} = 100 ohm Voltage input: -10...10 V, R_{in} > 200 kohm Differential inputs, common mode range ± 30 V Sampling interval per channel: 0.25 ms Hardware filtering: 0.25 ms Resolution: 11 bit + sign bit Inaccuracy: 1% of full scale range
Analog outputs AO1 and AO2 (XAO)	0...20 mA, R_{load} < 500 ohm Frequency range: 0...500 Hz Resolution: 11 bit + sign bit Inaccuracy: 2% of full scale range

92 Control unit (BCU)

XD2D connector	Physical layer: RS-485 Transmission rate: 8 Mbit/s Cable type: Shielded twisted-pair cable with a twisted pair for data and a wire or another pair for signal ground (nominal impedance 100 ... 165 ohm, for example Belden 9842) Maximum length of link: 50 m (164 ft) Termination by switch
RS-485 connection (X485)	Physical layer: RS-485 Cable type: Shielded twisted-pair cable with a twisted pair for data and a wire or another pair for signal ground (nominal impedance 100 ... 165 ohm, for example Belden 9842) Maximum length of link: 50 m (164 ft)
Safe torque off connection (XSTO)	Input voltage range: -3...30 V DC Logic levels: "0" < 5 V, "1" > 17 V. Note: Both circuits must be closed to enable start and operation (IN1 and IN2 must be connected to OUT). This applies to all control units (including drive, inverter, supply, brake, DC/DC converter etc. control units), but SIL/PL classified Safe torque off functionality is only achieved through the XSTO connector of the drive/inverter control unit. Current consumption: 66 mA (continuous) per STO channel per drive/inverter module EMC (immunity) according to IEC 61326-3-1 and IEC 61800-5-2
Safe torque off output (XSTO OUT)	To STO connector of inverter module.
Control panel connection (X13)	Connector: RJ-45 Cable length < 100 m (328 ft)
Ethernet connection (XETH)	Connector: RJ-45 This connection is not supported by the firmware
SDHC memory card slot (SD CARD)	Memory card type: SDHC Maximum memory size: 4 GB
Battery	Real-time clock battery type: BR2032
The terminals of the control unit fulfill the Protective Extra Low Voltage (PELV) requirements. The PELV requirements of a relay output are not fulfilled if a voltage higher than 48 V is connected to the relay output.	

■ BCU ground isolation diagram



***Ground selector (DICOM=DIOGND) settings**

DICOM=DIOGND: ON
All digital inputs share a common ground (DICOM connected to DIOGND). This is the default setting.
DICOM=DIOGND: OFF
Ground of digital inputs DI1...DI5 and DIIL (DICOM) is isolated from DIO signal ground (DIOGND). Isolation voltage 50 V.

******The maximum common mode voltage between each AI input and AGND is +30 V

8

Installation checklist

Contents of this chapter

This chapter contains a checklist for the mechanical and electrical installation of the drive.

Checklist



⚠️WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠️WARNING Do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.

Examine the mechanical and electrical installation of the drive before start-up. Do the tasks in the checklist together with a second person.

Make sure that ...	☒
The ambient operating conditions meet the drive ambient conditions specification and enclosure rating (IP code).	☐
The supply voltage matches the nominal input voltage of the drive. Refer to the type designation label.	☐
The insulation resistance of the input power cable, motor cable, and motor is measured according to local regulations and the manuals of the drive.	☐
The drive cabinet is attached to the floor, and if it is necessary due to vibration etc., also by its top to the wall or roof.	☐

96 Installation checklist

Make sure that ...	☒
<u>If the drive is connected to a network other than a symmetrically grounded TN-S system:</u> You have done all the required modifications (for example, you may need to disconnect the EMC filter or ground-to-phase varistor). Refer to the electrical installation instructions in the supply unit manual.	☐
There is an adequately sized protective earth (ground) conductor(s) between the drive and the switchboard, the conductor is connected to correct terminal, and the terminal is tightened to the correct torque. Grounding is measured according to the regulations.	☐
There is an adequately sized protective earth (ground) conductor between the energy storage and the DC/DC-converter, the conductor is connected to the correct terminal, and the terminal is tightened to the correct torque. Proper grounding is measured according to the regulations.	☐
The energy storage cable is connected to the correct terminals of the DC/DC-converter and energy storage, and the terminals are tightened to the correct torque.	☐
The energy storage is equipped with fuses for protecting the energy storage cable in a cable short-circuit situation.	☐
The energy storage is equipped with a disconnecting device.	☐
The input power cable is connected to the correct terminals, the phase order is correct, and the terminals are tightened to the correct torque.	☐
There is an adequately sized protective earth (ground) conductor between the motor and the drive. The conductor is connected to the correct terminal, and the terminal is tightened to the correct torque. Grounding has also been measured according to the regulations.	☐
The motor cable is connected to the correct terminals, the phase order is correct, and the terminals are tightened to the correct torque.	☐
The motor cable is routed away from other cables.	☐
No power factor compensation capacitors are connected to the motor cable.	☐
<u>If an external brake resistor is connected to the drive:</u> There is an adequately sized protective earth (ground) conductor between the brake resistor and the drive, and the conductor is connected to the correct terminal, and the terminals are tightened to the correct torque. Grounding has also been measured according to the regulations.	☐
<u>If an external brake resistor is connected to the drive:</u> The brake resistor cable is connected to the correct terminals, and the terminals are tightened to the correct torque.	☐
<u>If an external brake resistor is connected to the drive:</u> The brake resistor cable is routed away from other cables.	☐
The control cables are connected to the correct terminals, and the terminals are tightened to the correct torque.	☐
The voltage setting of the auxiliary voltage transformers (if any) is correct. Refer to the electrical installation instructions.	☐
<u>If a drive bypass connection will be used:</u> The direct-on-line contactor of the motor and the drive output contactor are either mechanically and/or electrically interlocked, that is, they cannot be closed at the same time. A thermal overload device must be used for protection when bypassing the drive. Refer to local codes and regulations.	☐
There are no tools, foreign objects, or dust from drilling inside the drive.	☐
The terminal box cover of the motor is in place. Cabinet shrouds are in place and doors are closed.	☐
The motor and the driven equipment are ready for power-up.	☐
The coolant connections between cubicles (if any) and to the cooling circuit are tight.	☐
<u>If the drive is equipped with a cooling unit:</u> Make sure that the mechanical and electrical installation of the cooling unit is completed. Refer to the cooling unit documentation.	☐

9

Start-up

Contents of this chapter

This chapter describes the start-up procedure of the converter unit. The persons who do the start-up procedure must know the energy storage system, the DC/DC-converter control program and the operation principle of the DC/DC-converter.

The default device designations are given in square brackets, for example, [Q11]. The same device designations are also used in the delivery-specific circuit diagrams.

Refer to the delivery-specific circuit diagrams when you do the start-up procedure.

Before you start, connect a control panel to the DC/DC-converter unit. ABB recommends that you also have a PC with a drive commissioning tool (Drive Composer) connected. For information on the use of the control panel, refer to [ACS-AP-I, -S, -W and ACH-AP-H, -W Assistant control panels user's manual \(3AUA0000085685 \[English\]\)](#). For information on the use of the Drive Composer PC tool, refer to [Drive Composer start-up and maintenance PC tool user's manual \(3AUA0000094606 \[English\]\)](#).



Start-up procedure

Tasks	☒
Safety	
 ⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.	☐
Checks/Settings with no voltage connected	
Make sure that it is safe to start the work. Do the steps in section Electrical safety precautions (page 59) .	☐
Make sure that the disconnecter of the supply transformer is locked into the open position and that voltage cannot be connected to the drive accidentally.	☐
Make sure that all external auxiliary circuits are de-energized and disconnected. See the start-up instructions in the supply unit hardware manual.	☐
Make sure that the supply unit is de-energized, and the drive system is isolated from the supply network.	☐
<u>DC/DC-converter with the DC switch-disconnector [Q11] (option +F286):</u> Make sure that the DC switch-disconnector [Q11] and the DC/DC-converter charging switch [Q10] are open and locked.	☐
Make sure that the energy storage disconnecting device (customer or system integrator-installed device) is locked into the open position.	☐
Make sure that the mechanical and electrical installation of the converter unit is completed and inspected. Refer to the installation checklist.	☐
Make sure that the drive is ready for the converter unit power up: • The supply and inverter units have been installed according to the instructions given in their hardware manuals. • The supply unit has been started up according to the instructions given in the applicable supply unit manual. • The inverter units have been started up according to the instructions given in the hardware manual and applicable firmware manual.	☐
If the drive or some of the converter units were stored for more than one year: Reform the electrolytic DC capacitors in the DC bus of the drive. Refer to Capacitor reforming instructions (3BFE64059629 [English]) .	☐
Close the auxiliary voltage circuit breakers of the converter unit [F21, F22]. Close also other circuit breakers of the converter auxiliary circuits: cabinet fans [F115] and BAMU voltage/current measurement [F7] if present and the auxiliary voltage switch of the drive supply unit. Refer to the circuit diagrams delivered with the converter unit.	☐
Starting and checking the cooling system	
Fill up and bleed the internal cooling circuit. Start the cooling unit up. See Filling up and bleeding the internal cooling circuit (page 150) .	☐
Check the cooling system for leaks. Make sure that cooling circuit joints at the shipping split joining cubicles are tight and that all drain valves have been closed.	☐
Make sure that the coolant can flow freely in all cubicles.	☐
Close the cabinet doors.	☐
Connecting voltage to the drive and converter control unit	
Connect main AC voltage to the input terminals of the drive supply unit: Close the disconnecter of the supply transformer.	☐

Tasks	☒
 ⚠ WARNING When you connect voltage to the supply unit, the DC busbars and the converters connected to the DC bus will become energized.  ⚠ WARNING <u>Converter units with a DC switch-disconnector:</u> Some types of converter modules can be energized through a charging circuit even if the DC switch-disconnector is open or the DC fuses are removed. <u>Converter units without a DC switch-disconnector:</u> If the converter unit only has DC fuses without a switch fuse, all the converter units with the DC fuses in position will be energized when the main breaker/contactator closes. To prevent this, remove the fuses from the converter units which are to remain de-energized before you connect the voltage. Do not install or remove DC fuses when the main breaker/contactator of the supply unit is closed (DC busbars are energized). If the drive is equipped with a main switch-disconnector (option +F253): Close the main disconnecting device of the drive system.	☐
Close the auxiliary voltage switch [Q21] of the drive supply unit. The converter control unit will be powered. Do not close the main circuit breaker [Q1] (option +F255) or the main contactor [Q2] (option +F250) of the drive supply unit! You must not energize the drive DC bus at this time.	☐
Setting the parameters	
Set the DC/DC-converter parameters. Refer to chapter Start-up in DC/DC-converter control program firmware manual (3AXD50000024671 [English]).	☐
Charging the DC/DC-converter and connecting voltage to the converter	
Make sure that the energy storage disconnecting device is open.  ⚠ WARNING Always keep the energy storage disconnected from DC/DC-converter until the DC/DC-converter is charged.	☐
Start the supply unit and close the main contactor [Q2] (option +F250) or the main circuit breaker [Q1] (option +F255) of the drive supply unit.	☐
Power up and charge the DC/DC-converter: <u>DC/DC-converter with the DC switch-disconnector [Q11] (option +F286):</u> 1. Close the DC/DC-converter charging switch [Q10.x]. To complete the charging, wait a few seconds until the Charged [P11] light illuminates. The DC/DC-converter disconnected indicator light [P12.x] goes off. 2. After the Charging OK indicator light [P11.x] comes on, close the DC switch-disconnector [Q11]. 3. Open the DC/DC-converter charging switch [Q10.x]. Note: The charging switch must be open before you can start the DC/DC-converter. <u>DC/DC-converter without DC switch-disconnector (without option +F286):</u> 1. Start the supply unit and close the main contactor [Q2] (option +F250) or the main breaker [Q1] (option +F255) of the drive supply unit. The DC/DC-converter is energized and gets charged.	☐
Connecting the energy storage to the DC/DC-converter	
Set parameter 120.12 Run enable 1 to Off. This makes sure that the DC/DC-converter does not start automatically or unexpectedly after you connect the energy storage.	☐
Set the control panel to local control mode with the Loc/Rem key.	☐
Make sure that the energy storage voltage is less than the drive DC bus voltage.	☐
 ⚠ WARNING Do not close the energy storage disconnecting device if the DC/DC-converter is not connected to the drive DC bus or not ready to use. Close the energy storage disconnecting device. The load disconnected indicator [P13.x] goes off.	☐
Close the energy storage protective circuit breaker (customer or system integrator-installed device).	☐



100 Start-up

Tasks	☒
Testing the DC/DC-converter operation	
Set parameter 120.12 Run enable 1 to On.	☐
Set parameter 122.01 User Power ref to 0 A.	☐
Set current limits to low values, for example, 130.119 Minimum current to -50 A. 130.120 Maximum current to 50 A.	☐
Push the Start key on the control panel to start the converter. After start, increase slowly the value of parameter 122.01 User Power ref.	☐
Check the following signals: 102.01 DC voltage 102.02 ES voltage used 102.08 Total current 102.11 Modulation index % 130.101 DDC limit word 1.	☐
Press the Stop key on the control panel to stop the converter.	☐



10

Maintenance

Contents of this chapter

This chapter contains maintenance instructions and information on status indications.

Maintenance intervals

The tables show the maintenance tasks that can be done by the end user. For the ABB Service offering, contact your local ABB Service representative (new.abb.com/contact-centers).

■ Description of symbols

Action	Description
I	Inspection (visual inspection and maintenance action if needed)
P	Performance of on/off-site work (commissioning, tests, measurements or other work)
R	Replacement

■ Recommended maintenance intervals after start-up

Recommended annual actions by the user	
Connections and environment	
Quality of supply voltage	P
Spare parts	
Spare parts	I
DC circuit capacitors reforming, spare modules and spare capacitors	P
Inspections by user	
Tightness of terminals	I
Dustiness, corrosion and temperature	I
Cooling liquid pipe connections	I
Coolant antifreeze concentration	P
Other	
ABB-SACE Air circuit breaker maintenance	I
ABB Contactors maintenance	I

Recommended every 2nd year actions by the user	
Inspection of expansion tank air pressure	P
External circuit of main heat exchanger (temperature/flow/pressure)	I

Item	Years from start-up						
	3	6	9	12	15	18	21
Coolant							
Coolant draining and refill		R		R		R	
Liquid cooling circuit							
ABB cooling unit	Refer to ACS880-1007LC liquid cooling unit user's manual (3AXD50000129607 [English])						
Cabinet fans							
Cooling fans, 230 VAC 50/60 Hz			R			R	
Cooling fans, 24 VDC		R		R		R	
CIO module for fan control (230 VAC and 24 VDC)			R			R	
Cooling fans, 115 VAC 50/60 Hz		R		R		R	
CIO module for fan control (115 VAC) ¹⁾		I/R		R		I/R	
Internal cooling fan for circuit boards							
R7i module fan 24 VDC			R			R	
Aging							
UCU control unit battery (Real-time clock)			R			R	
BCU control unit battery (Real-time clock)		R		R		R	

Item	Years from start-up						
	3	6	9	12	15	18	21
Control panel battery (Real-time clock)			R			R	
Cabinet auxiliary power supplies ²⁾				R			
Buffer module 24 VDC +F276 Ride through function		R		R		R	

1) Replace CIO module or reset fan counters. Refer to [CIO-01 I/O module for distributed I/O bus control user's manual \(3AXD50000126880 \[English\]\)](#).

2) Check amount of auxiliary power supplies and buffer modules from cabinet or manufactured bill of materials.

Note:

- The maintenance and component replacement intervals are valid when the equipment operates within the specified ratings and ambient conditions. ABB recommends annual drive inspections.
- Long-term operation near the specified maximum ratings or ambient conditions may require shorter maintenance intervals for certain components. Contact your local ABB Service representative for additional maintenance recommendations.

Maintenance timers and counters

The control program has maintenance timers and counters that can be configured to generate a warning when a pre-defined limit is reached. Each timer/counter can be set to monitor any parameter. This feature is especially useful as a service reminder. For more information, refer to the firmware manual.

Cabinet

■ Cleaning the interior of the cabinet



⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

NOTICE Use an antistatic wrist strap and a vacuum cleaner with an antistatic hose and nozzle. A normal vacuum cleaner creates static discharges which can cause damage to circuit boards.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cabinet door.
3. Clean the interior of the cabinet. Use a vacuum cleaner and a soft brush.
4. Clean the air inlets of the fans and air outlets of the modules (top).
5. Clean the air inlet gratings (if any) on the door.
6. Close the door.

■ Cleaning the exterior



▲WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Clean the exterior. Use:
 - vacuum cleaner with an antistatic hose and nozzle
 - soft brush
 - dry or damp (not wet) cleaning cloth. Moisten with clean water, or mild detergent (pH 5...9 for metal, pH 5...7 for plastic).

NOTICE Do not use too much water, a hose, or steam to clean the drive. Moisture can go into the drive and cause damage.

Disconnecting the DC/DC-converter

■ Disconnecting the DC/DC-converter from the energy storage



▲WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

This procedure tells you how to disconnect the DC/DC-converter from the energy storage.

1. Set the control panel to local mode with the **Loc/Rem** key.
2. Push the **Stop** key on the control panel.
3. Set parameter 120.19 Enable start signal to value Off. This prevents an accidental start of the unit.
4. Open the energy storage protective circuit breaker.
5. Open the energy storage disconnecting device. Lock out and tag out.

Note: The load disconnected indicator light [P13.x] is on when the energy storage disconnecting device is open.

6. If it is necessary to disconnect the DC/DC-converter from the drive system, and the converter has a DC switch-disconnector [Q11], continue with step 2 of the procedure in section [Disconnecting the DC/DC-converter from the drive system with the DC switch-disconnector \(page 105\)](#).

■ Disconnecting the DC/DC-converter from the drive system with the DC switch-disconnector



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

This procedure tells you how to disconnect the DC/DC-converter from the energy storage and the drive system with the optional DC switch-disconnector (option +F286).

1. Do the steps in section [Disconnecting the DC/DC-converter from the energy storage \(page 104\)](#).
2. Drives with DC switch-disconnector [Q11]: Open the DC switch-disconnector [Q11] (option +F286). Lock out and tag out.

Note: The DC/DC-converter disconnected indicator light [P12.x] is on when the DC switch-disconnector [Q11] is open.

3. If it is necessary to do work inside the DC/DC-converter unit, stop the drive system and isolate it from the main and auxiliary power supplies. Do the steps in section [Electrical safety precautions \(page 59\)](#).

Connecting the DC/DC-converter



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

This procedure tells you how to connect the DC/DC-converter to the energy storage and the drive system.

1. Make sure that the work is completed and there are no tools inside the drive.
2. Close the cabinet doors.
3. Connect the DC/DC-converter and energy storage. Refer to these instructions in chapter [Start-up](#):
 - [Connecting voltage to the drive and converter control unit \(page 98\)](#)
 - [Charging the DC/DC-converter and connecting voltage to the converter \(page 99\)](#)
 - [Connecting the energy storage to the DC/DC-converter \(page 99\)](#).
4. Set the control panel to local mode with the **Loc/Rem** key.
5. Set parameter 120.19 Enable start signal to value On.
6. Push the **Start** key on the control panel.

Fuses

■ Checking and replacing the fuses – frame R7i

Replacing a converter fuse



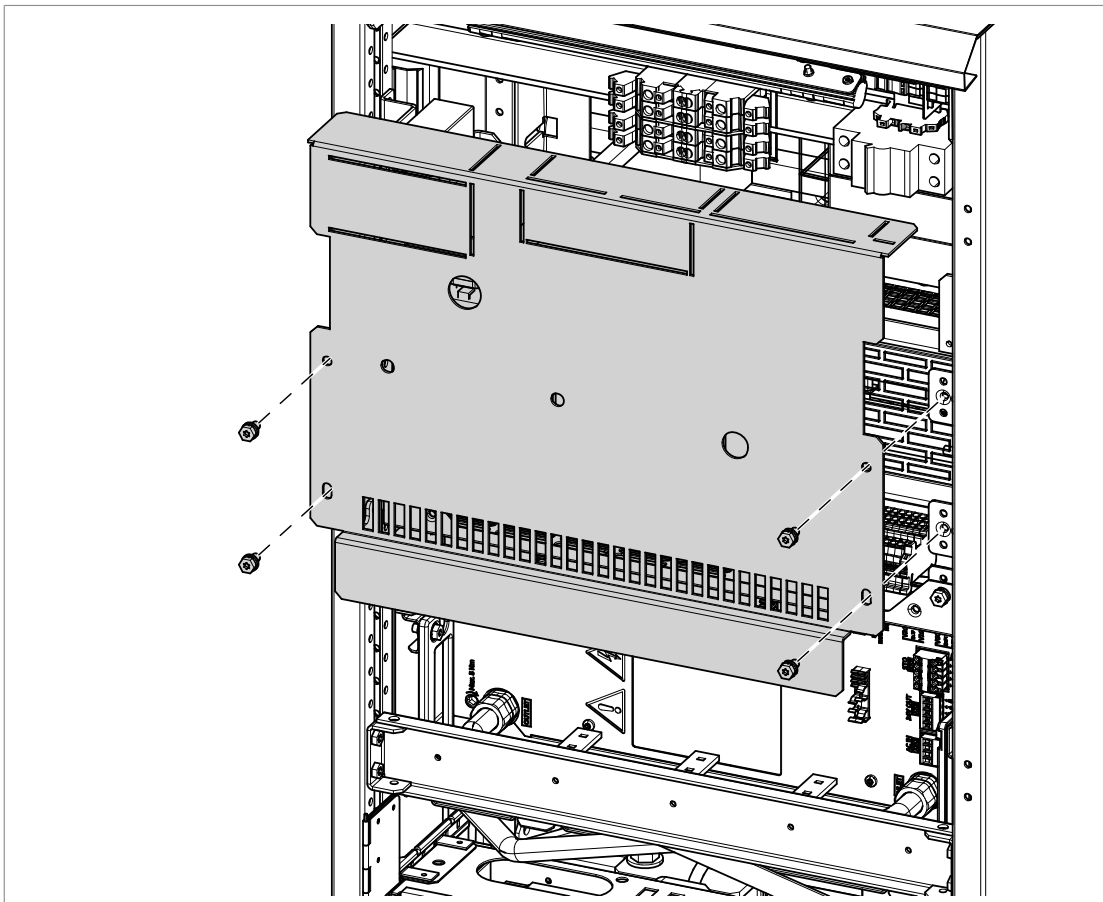
⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



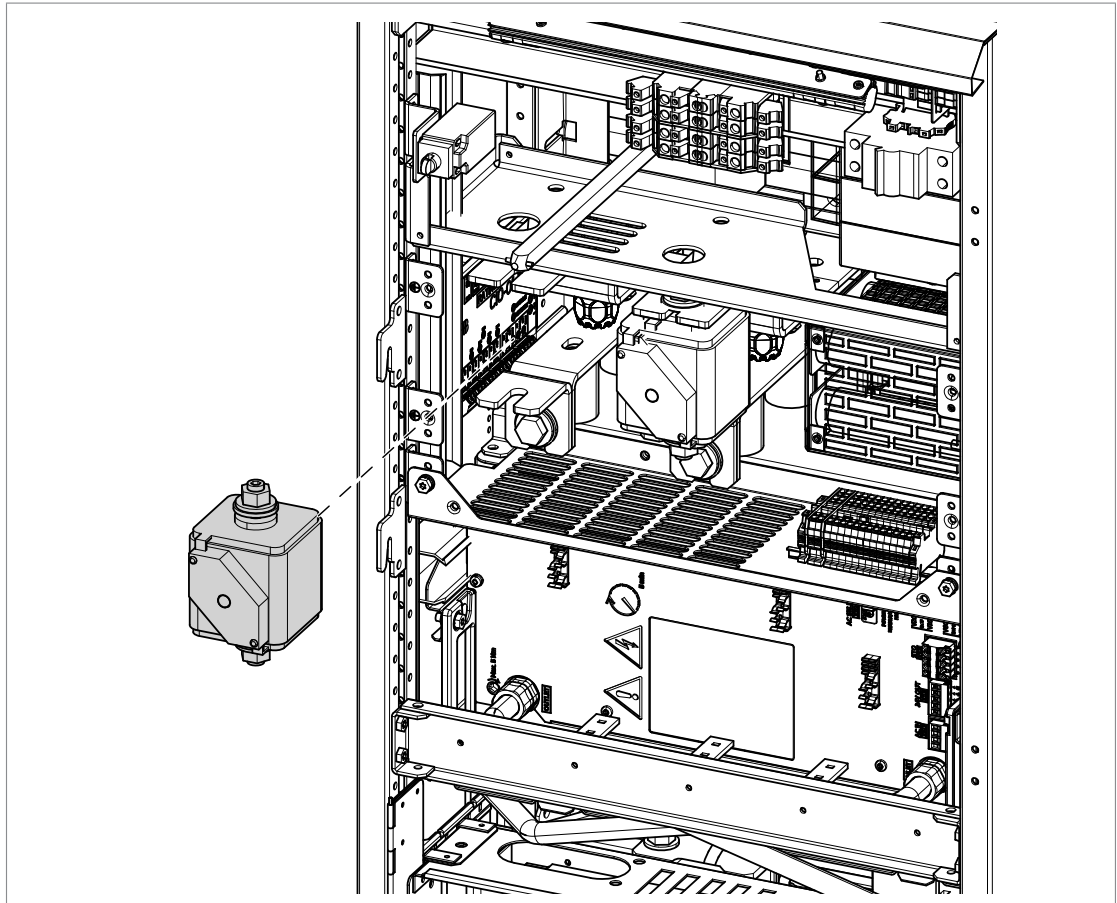
⚠ WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

Replace a blown fuse with a new one of the same type as follows. For tables of recommended fuses, see the technical data.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the converter fuse cover.



4. Loosen the two nuts on the studs attached to the fuse. Slide the fuse block out.



5. Remove the studs, nuts and washers from the fuse and install them to the new fuse. Make sure that you install the washers in the original order.
6. Torque the nuts as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
7. Install the converter fuse cover.

Replacing an output fuse



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

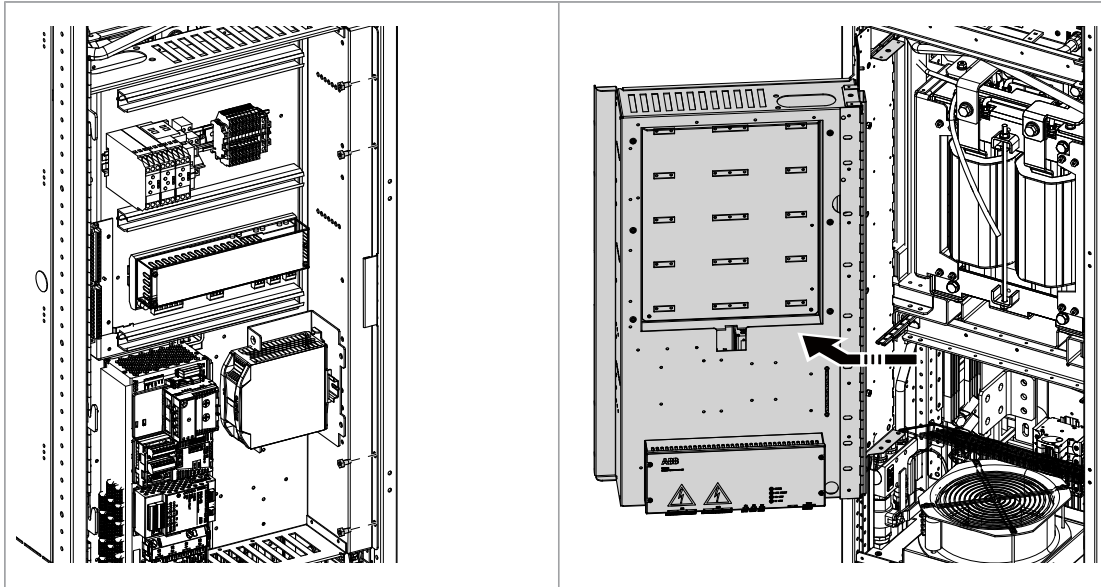


⚠WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

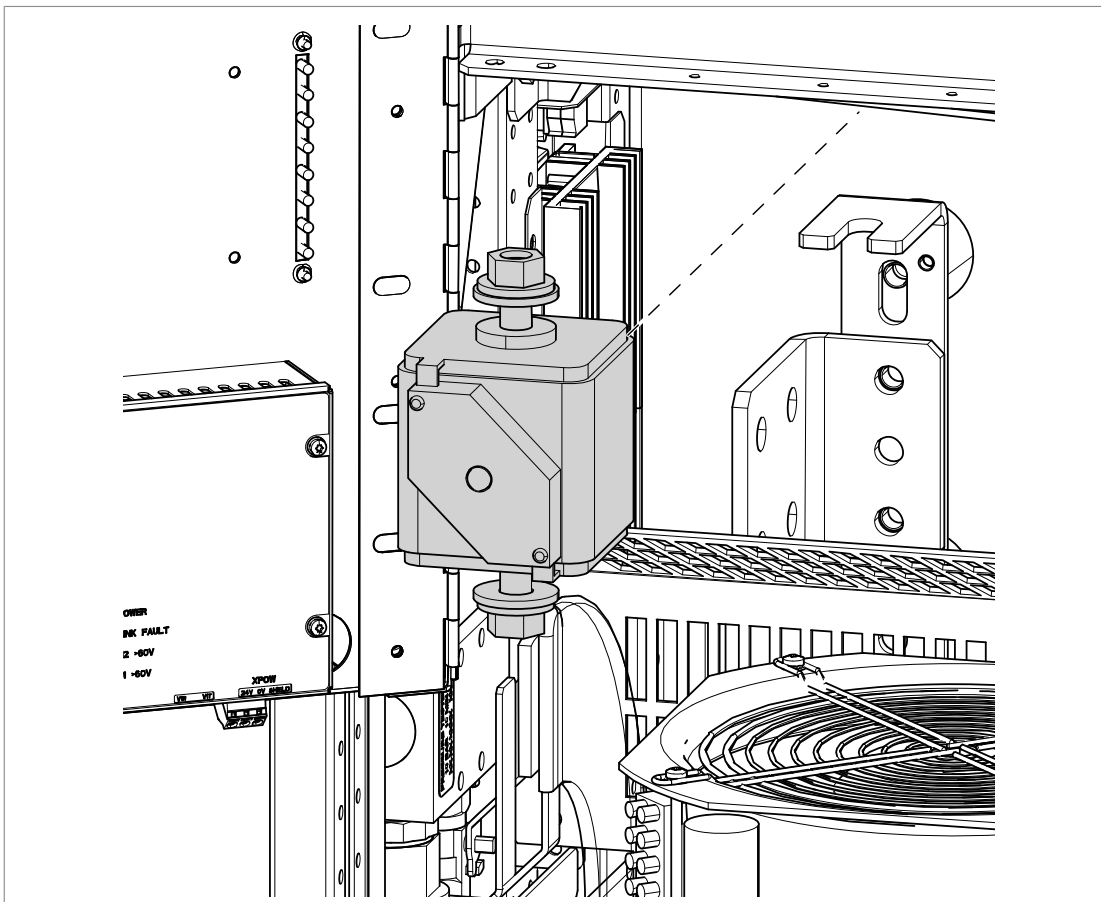
Replace a blown fuse with a new one of the same type as follows. For tables of recommended fuses, see the technical data.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.

3. Remove the screws that hold the swing-out frame closed. Then open the frame.



4. Loosen the two nuts on the studs attached to the fuse. Slide the fuse block out.



5. Remove the studs, nuts and washers from the fuse and install them to the new fuse. Make sure that you install the washers in the original order.

6. Torque the nuts as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
7. Close the swing-out frame and install the screws.

■ Checking and replacing the fuses – frame 2×R7i in one cubicle

Replacing a converter fuse (without DC switch-disconnector)



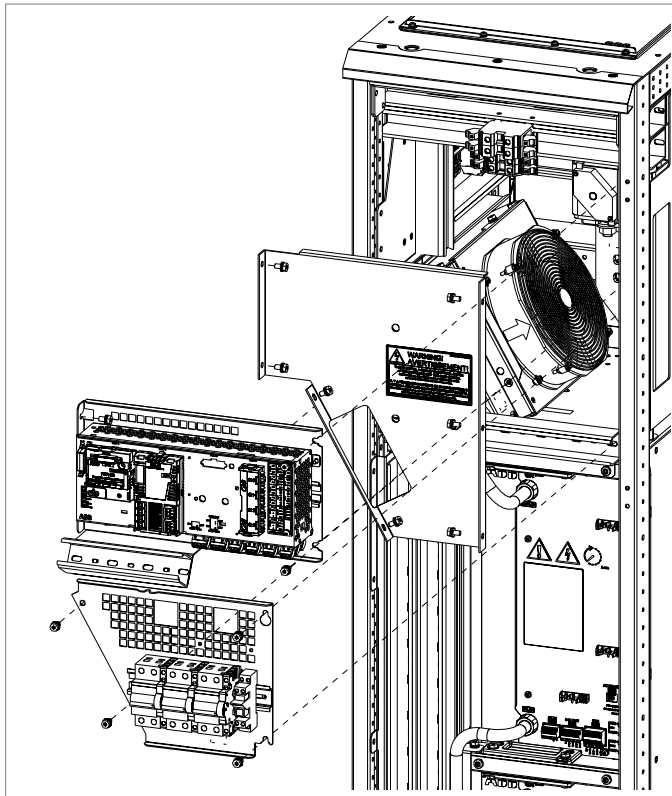
▲WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



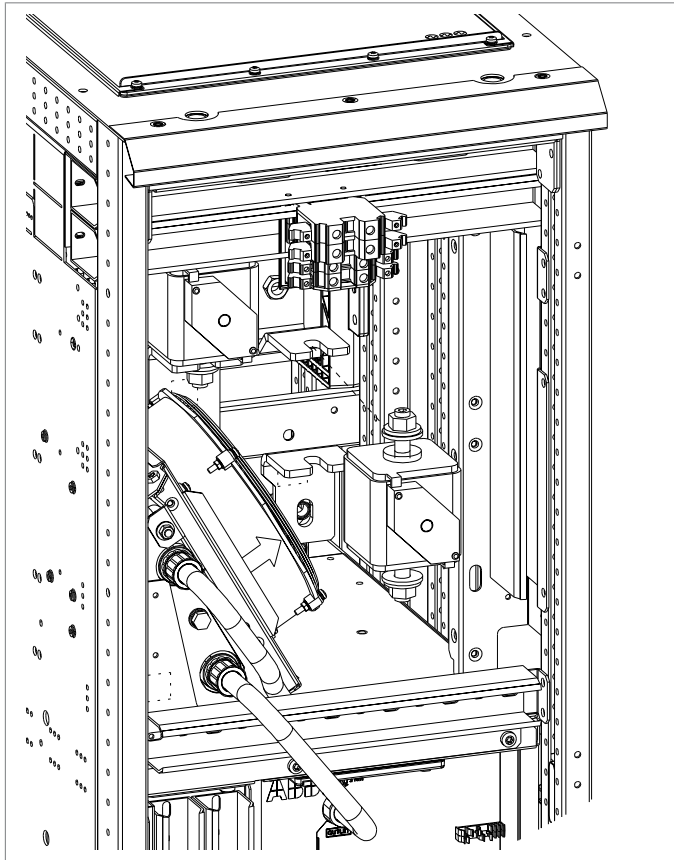
▲WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

There are two converter fuses at the top of the cubicle.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the control board plate.
4. Remove the inner shroud.



5. Loosen the two nuts on the studs attached to the fuse. Slide the fuse block out.



6. Remove the studs, nuts and washers from the fuse and install them to the new fuse. Make sure that you install the washers in the original order.
7. Insert the new fuse into its slot.
8. Torque the nuts as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
9. Install the inner shroud.
10. Install the control board plate.

Replacing a converter fuse (with DC switch-disconnector)



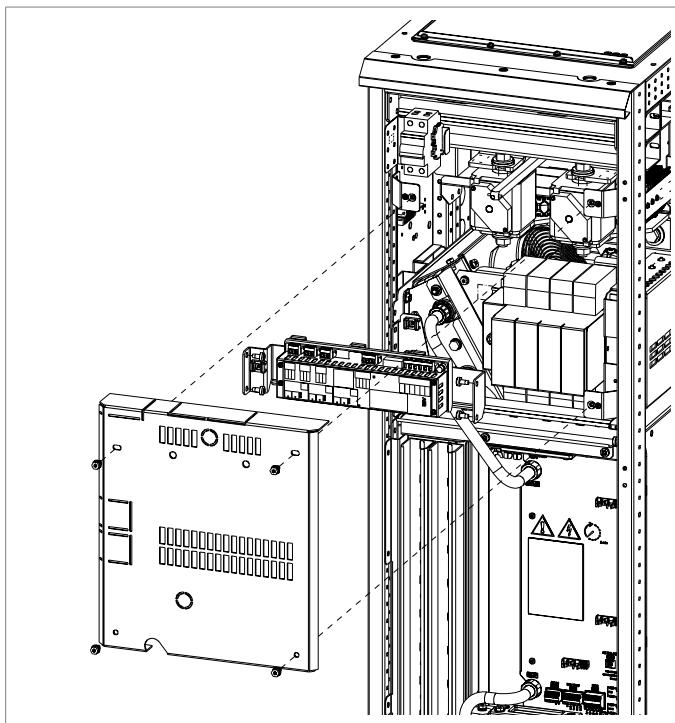
⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



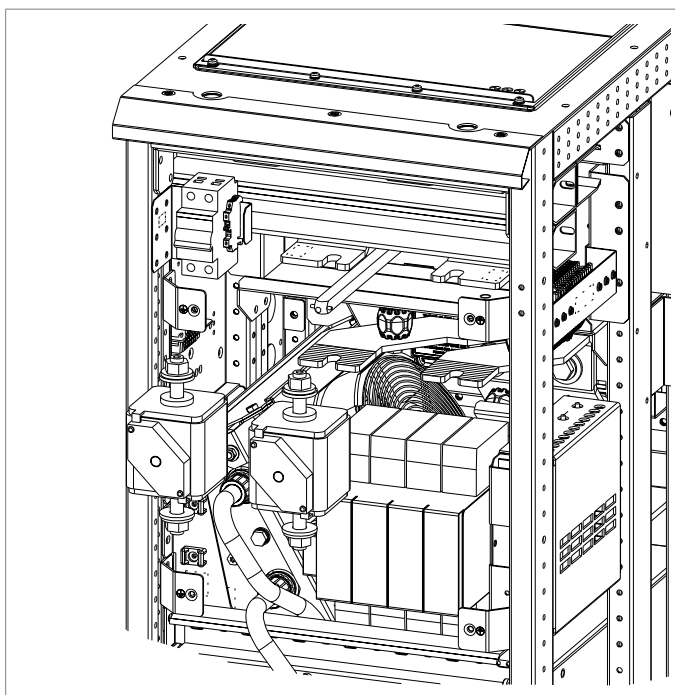
⚠ WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

There are two converter fuses at the top of the cubicle.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the shroud.
4. Remove the charging control board.



5. Loosen the two nuts on the studs attached to the fuse. Slide the fuse block out.



6. Remove the studs, nuts and washers from the fuse and install them to the new fuse. Make sure that you install the washers in the original order.
-

7. Insert the new fuse into its slot.
8. Torque the nuts as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
9. Install the charging control board.
10. Install the shroud.

Replacing an output fuse



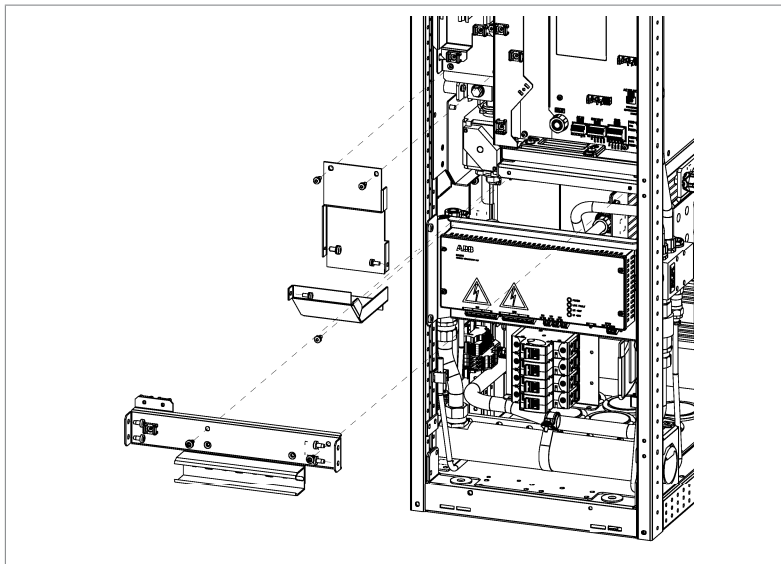
⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠ WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

There is one output fuse at the bottom of the cubicle.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the module frame support beam.
4. Remove the fuse covers.



5. Close the inlet and outlet valves of the cubicle.
6. Put the drain hoses into a container. Open the drain valves. This will drain all the equipment in the cubicle.
7. After the coolant is drained, disconnect the three coolant pipes at the bottom of the cubicle.
8. Loosen the two nuts on the studs attached to the fuse. Slide the fuse block out.

9. Remove the studs, nuts and washers from the fuse and install them to the new fuse. Make sure that you install the washers in the original order.
10. Insert the new fuse into its slot.
11. Torque the nuts as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
12. Connect the coolant pipes. Tighten to 20 N·m (14.75 lbf·ft).
13. Fill up the cooling system. For instructions, see section [Filling up and bleeding the internal cooling circuit \(page 150\)](#).
14. Install the fuse covers.
15. Install the module frame support beam.

■ Checking and replacing the fuses – frame R8i



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

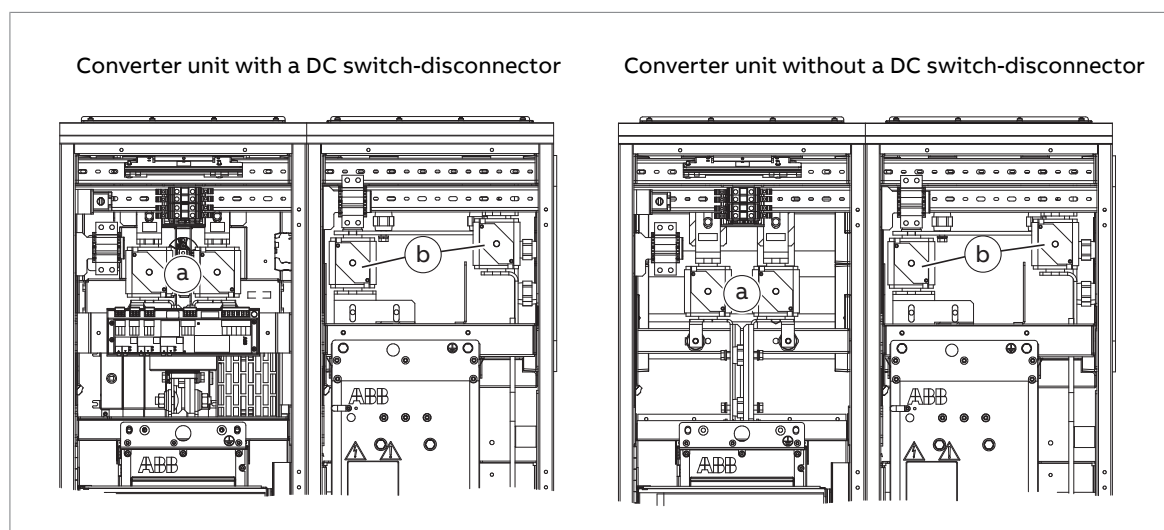


⚠WARNING Do not remove or install a fuse when the drive DC bus is energized. If you do, serious injury or death, or damage to the equipment can occur.

The DC/DC-converter unit has two sets of fuses: output fuses on the energy storage side and fuses on the DC bus side.

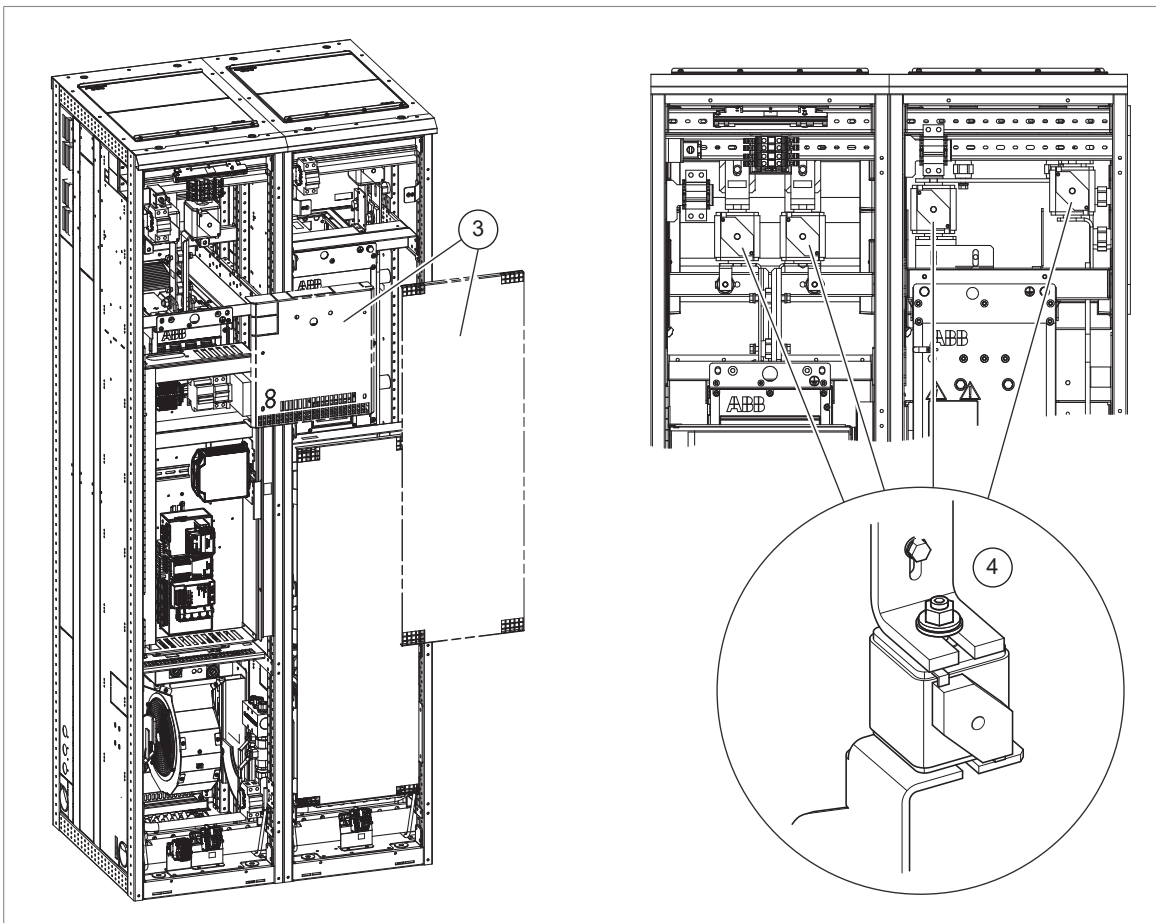
For the location of the fuses, see the figures:

- The converter fuses [F11.x] on the drive DC bus side are marked with **a** in the figure.
- The output fuses [F13.x] on the energy storage side are marked with **b** in the figure.



Replace a blown fuse with a new one of the same type as follows. For tables of recommended fuses, see the technical data.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the screws of the shroud in the upper part of the cubicle. Remove the shrouds.
4. Loosen the nuts of the headless screws of the fuses so that you can slide out the fuse blocks. Make note of the order of the washers on the screws.
5. Remove the screws, nuts and washers from the old fuses and attach them to the new fuses. Make sure to keep the washers in the original order.
6. Insert the new fuses into their slots in the cubicle.
7. Tighten the nuts to torque as follows:
 - Bussmann fuses: 50 N·m (37 lbf·ft)
 - Other: Refer to the fuse manufacturer's instructions.
8. Install the shrouds.



Fans

The lifespan of the cooling fans of the drive depends on running time, ambient temperature and dust concentration. Refer to the firmware manual for the actual signal which indicates the running time of the cooling fan. Reset the running time signal after fan replacement. If the maintenance interval requires it, change the CIO-01 module. Refer also to [CIO-01 I/O module and distributed I/O bus user's manual \(3AXD50000126880 \[English\]\)](#).

Replacement fans are available from ABB. Do not use other than ABB-specified spare parts.

■ Frame R7i cabinet fan replacement

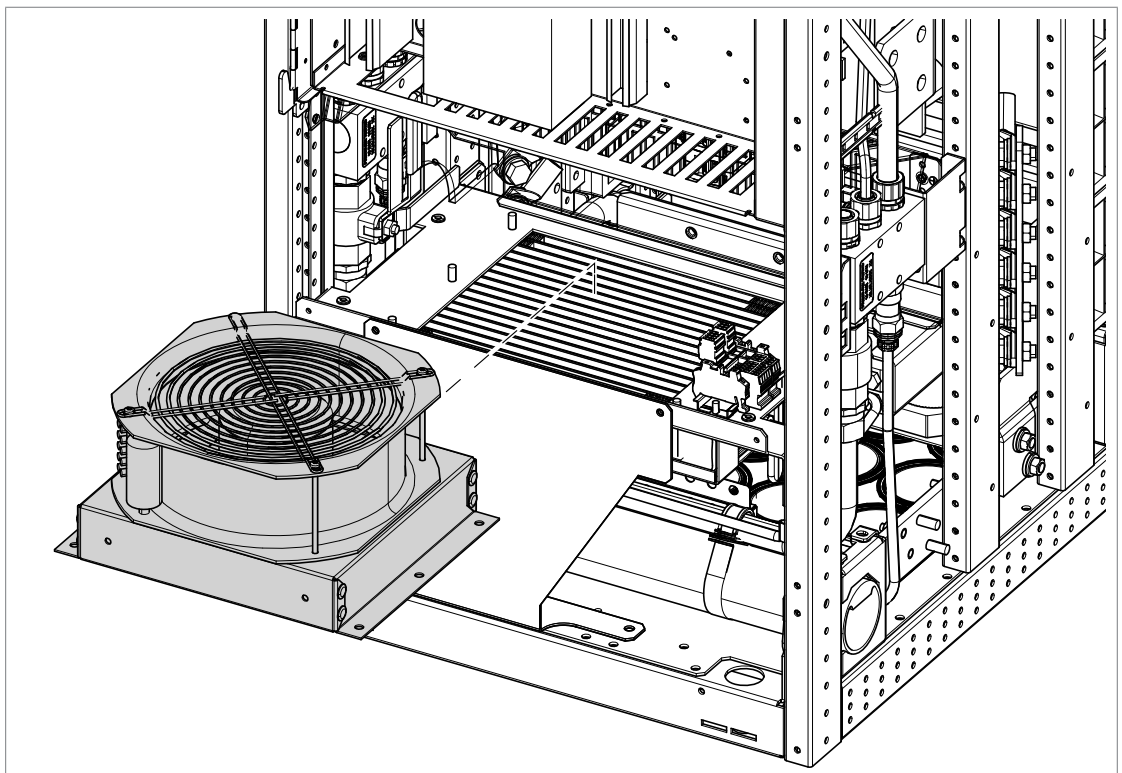


⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

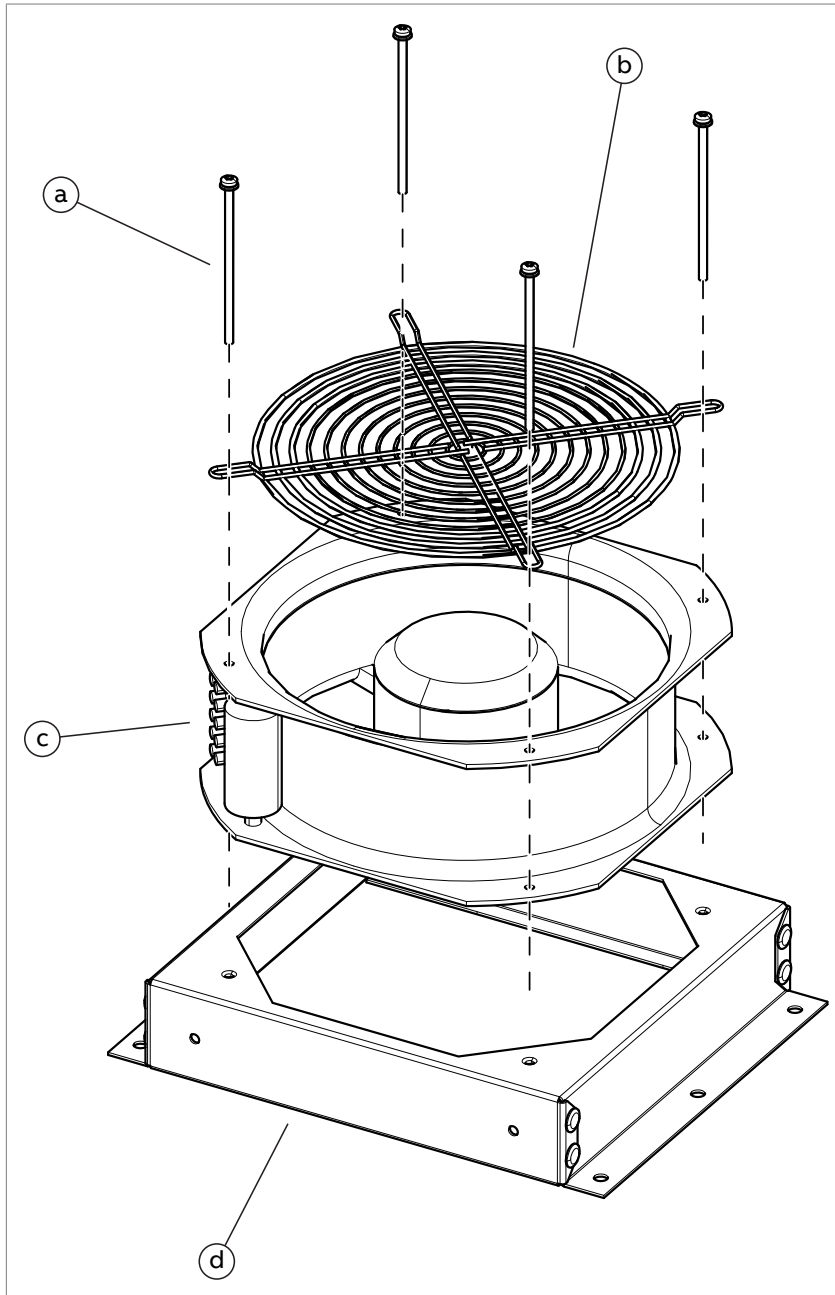


⚠CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Disconnect the fan wiring.
4. Remove the six screws that attach the fan assembly to the heat exchanger. Then remove the fan assembly from the cabinet.



5. Remove the screws (a) that hold the finger guard (b) and fan (c) to the fan mounting plate (d).



6. Assemble the fan assembly with a new fan. The airflow direction of the fan must be up.
7. Install the fan assembly into the cubicle
8. Connect the fan wiring.

■ Frame R7i – internal module fan replacement



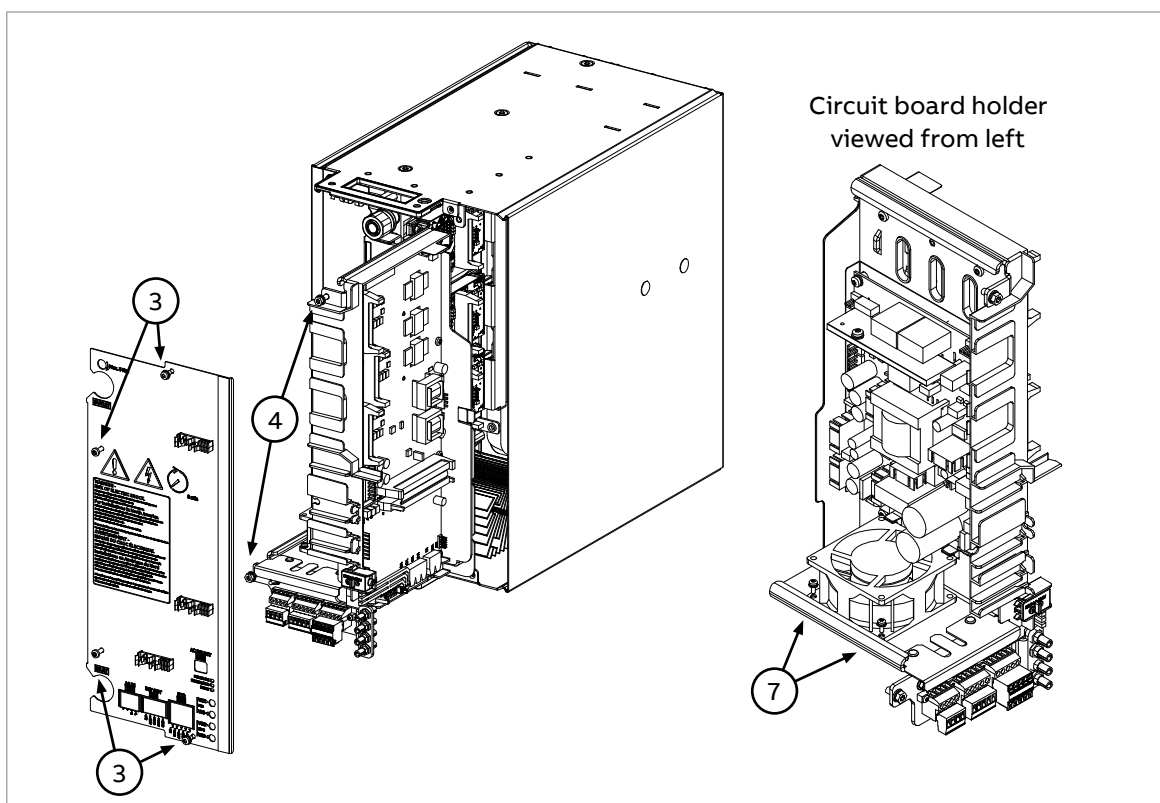
⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.

NOTICE Use an antistatic wrist strap when you handle printed circuit boards. Do not touch the boards unnecessarily. The boards are sensitive to electrostatic discharge.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Detach and move aside the wiring in front of the module.
3. Remove the four screws that hold the faceplate of the module. Remove the faceplate.
4. Remove the two screws that attach the circuit board holder to the module frame.
5. Carefully pull the circuit board holder outward until you have access to the cooling fan at the bottom of the holder. Detach the wiring coming to the circuit boards if necessary.
6. Disconnect the wiring of the fan.
7. Remove the two screws that hold the fan. Remove the fan.
8. Install a new fan in reverse order to the above. Note that the direction of airflow is up.



■ Frame 2×R7i in one cubicle fan replacement

Top fan replacement (without DC switch-disconnector)

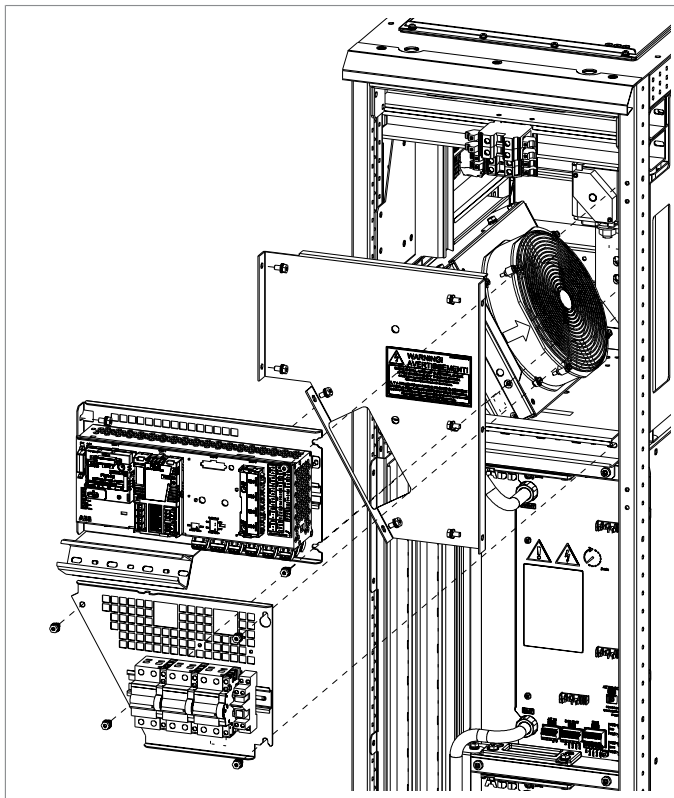


⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



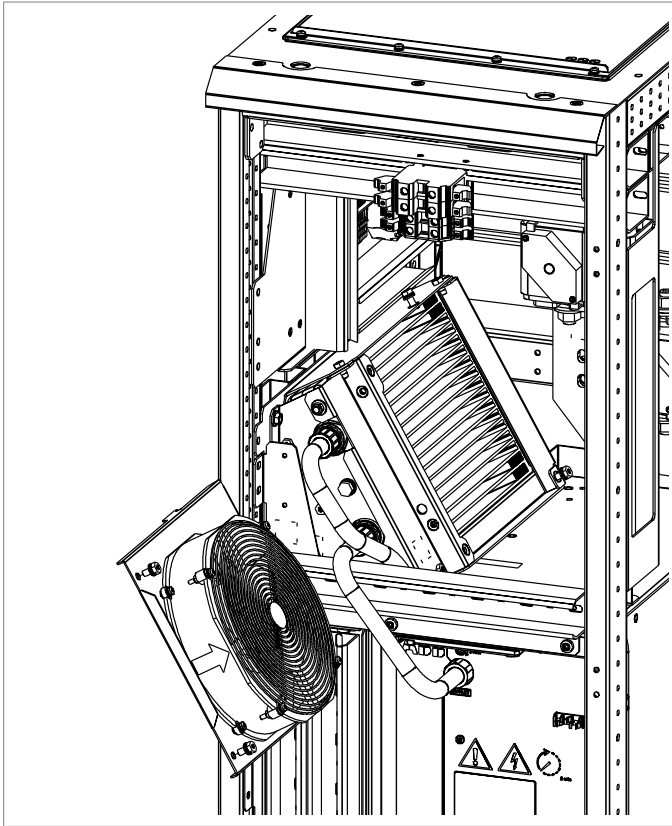
⚠ CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Remove the control board plate.
3. Remove the inner shroud.



4. Disconnect the fan wiring.

5. Remove the two front screws that hold the fan. Loosen the other two screws. Pull the fan outwards to separate it from the housing.

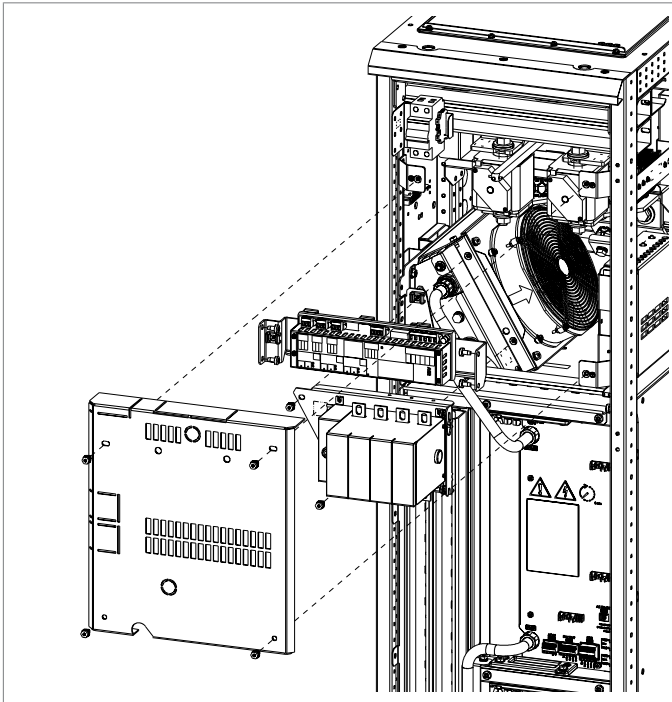


6. To install a new fan, reverse the instructions. Note the direction of airflow.

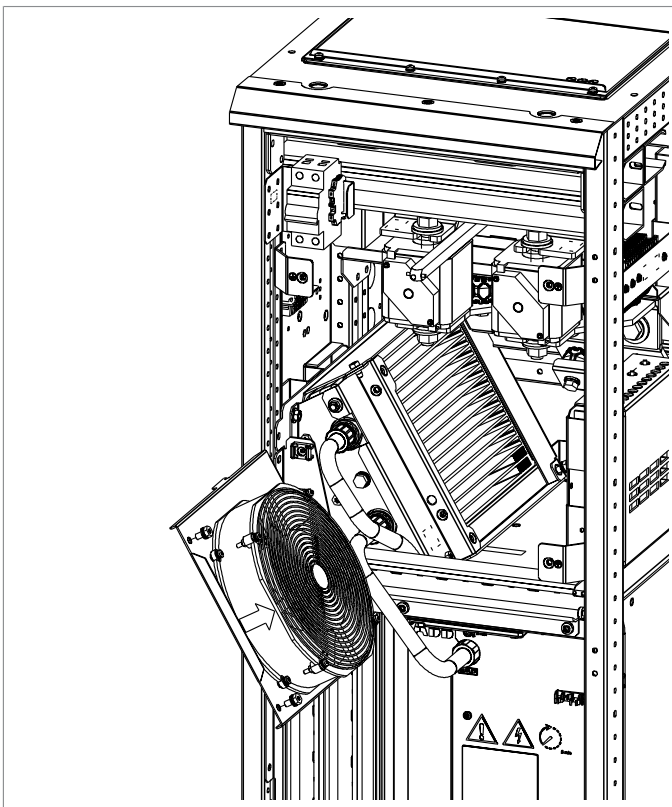
Top fan replacement (with DC switch-disconnector)

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
 2. Remove the shroud.
 3. Remove the charging control board.
-

4. Remove the charging switch plate.



5. Disconnect the fan wiring.
6. Remove the two front screws that hold the fan. Loosen the other two screws. Pull the fan outwards to separate it from the housing.



7. To install a new fan, reverse the instructions. Note the direction of airflow.
-

Bottom fan replacement

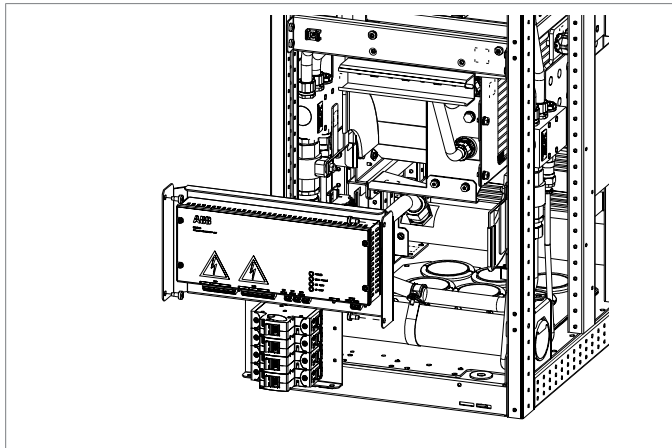


⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

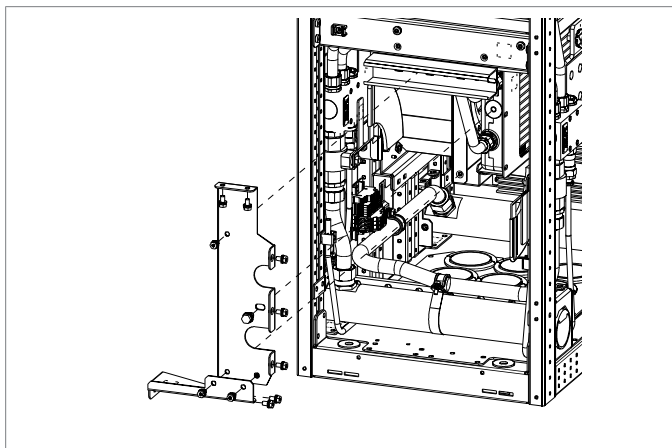


⚠ CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.

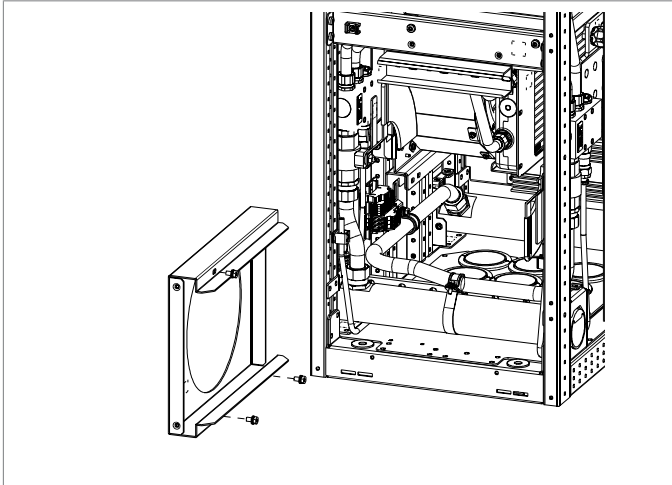
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Remove the BAMU measurement unit.



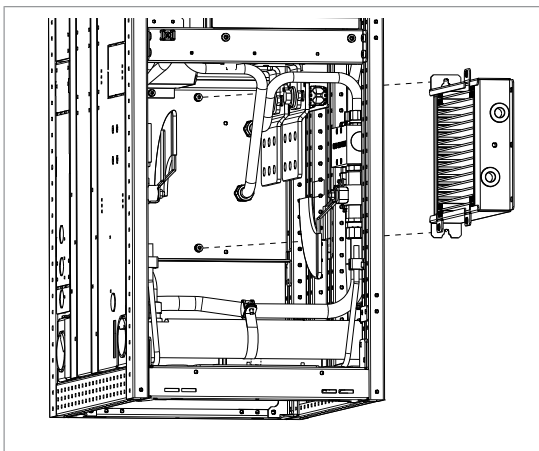
3. Remove the heat exchanger plates.



4. Remove the air guide.

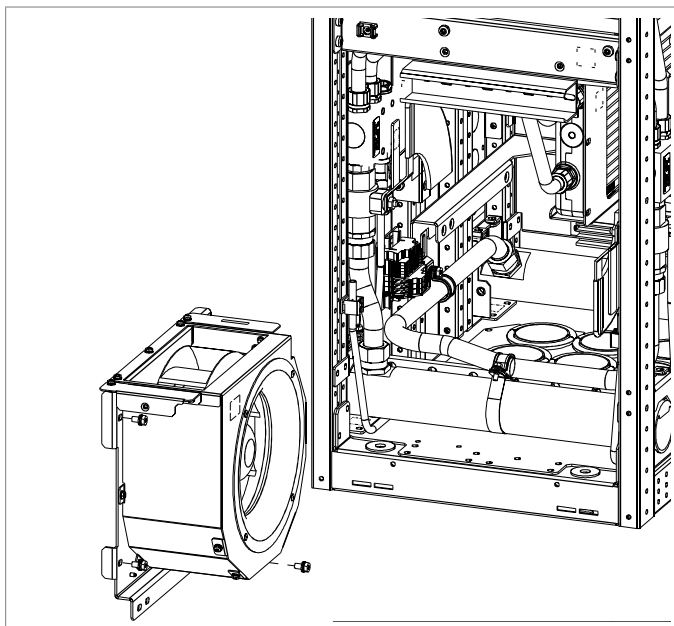


5. If more space is necessary:
- A. Close the inlet and outlet valves of the cubicle.
 - B. Put the drain hoses into a container. Open the drain valves. This will drain all the equipment in the cubicle.
 - C. After the coolant is drained, disconnect the coolant pipes from the heat exchanger.
 - D. Loosen the two screws that hold the heat exchanger support.
 - E. Carefully pull out the heat exchanger.



6. Disconnect the fan wiring.

7. Remove the screws that hold the fan. Pull the fan outwards to separate it from the housing.



8. To install a new fan, reverse the instructions. Note the direction of airflow.

■ Frame R8i fan replacement

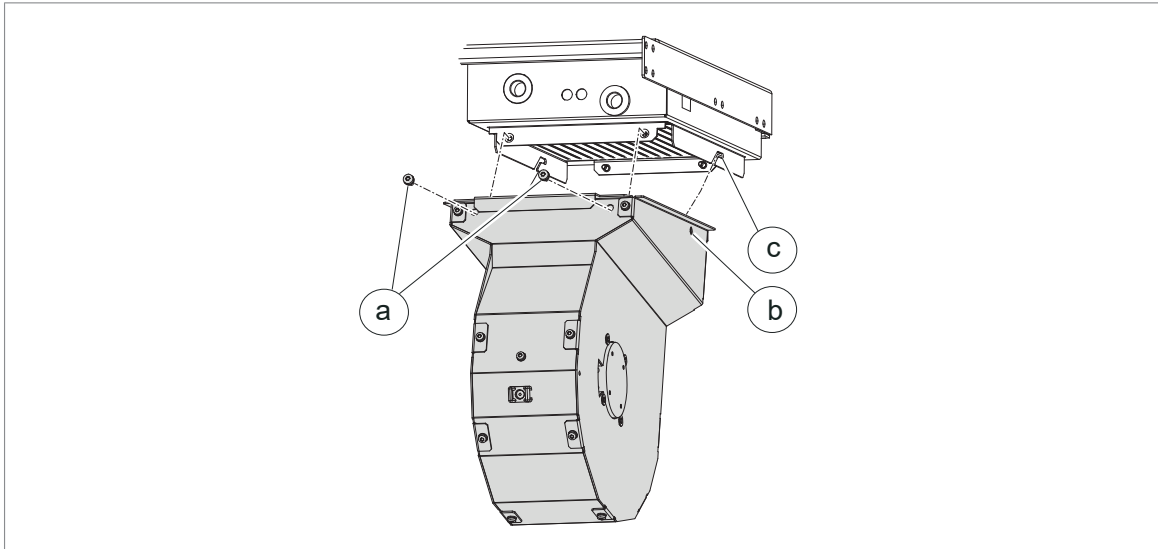


⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠ CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.

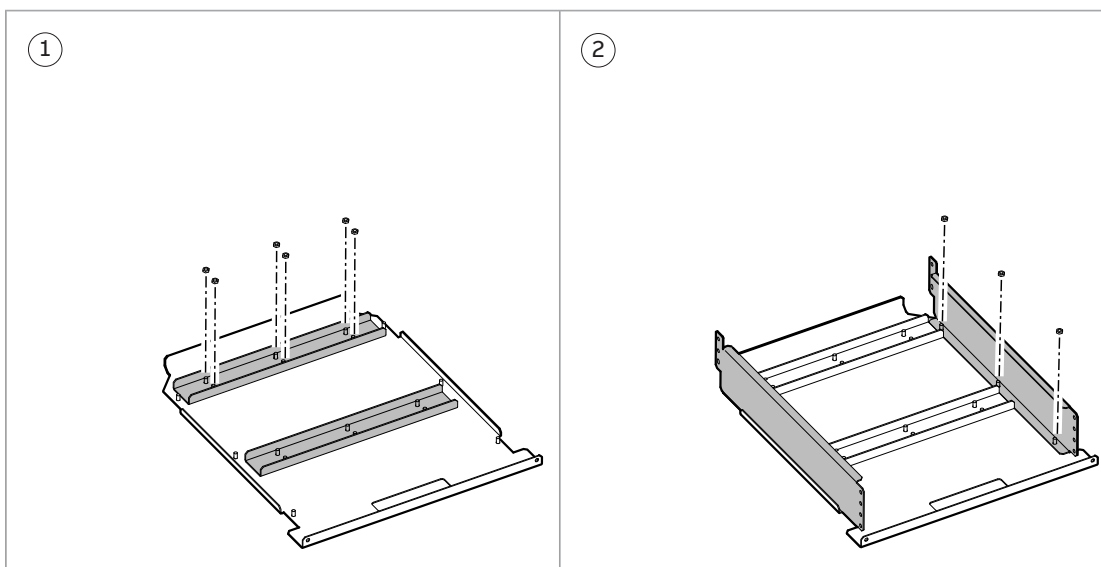
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the door.
3. Remove any shrouding in front of the cooling fan (option +C121).
4. Disconnect the fan wiring. Remove the CIO module.
5. Remove the two retaining screws (a).
6. Pull the fan outwards to separate it from the heat exchanger housing.
7. Install new fan in reverse order. Align the guide pins (b) at the rear of the fan cowling with the slots (c) in the module bottom guide, then install the retaining screws (a).



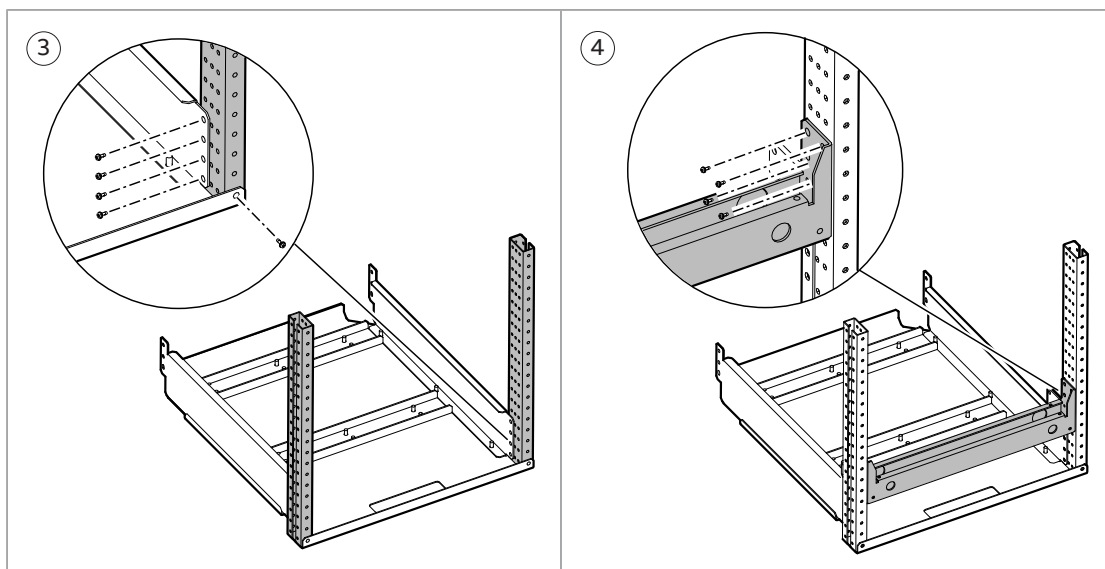
Assembling the service platform

The service platform is included in the cabinet delivery. Use the platform when you remove or install power modules of a liquid-cooled drive. Use the platform with module sizes R7i, R8i, and D8T. Measure the required height of the platform ahead to assemble the platform correctly.

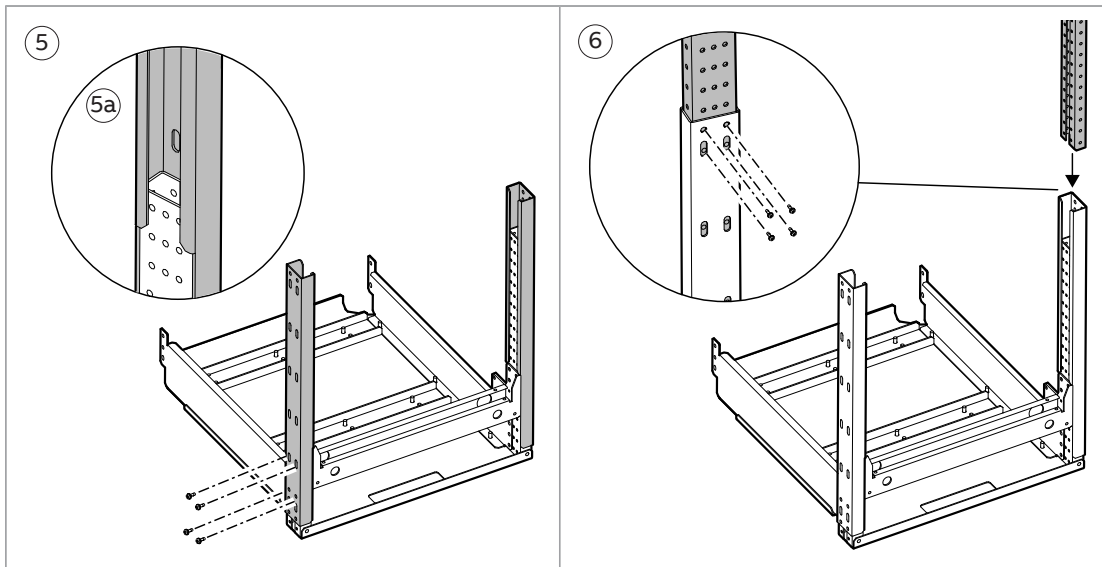
1. Choose a slide plate according to the width of the frame. Attach the two horizontal supports to the slide plate (6 × counter nuts for each horizontal support for 500 mm wide and 10 × counter nuts for 700 mm wide slide plate). Tighten to 5 N·m / 44.3 lbf·in.
2. Attach the two side supports to the slide plate (3 × counter nuts for each side support, torque: 5 N·m / 44.3 lbf·in).



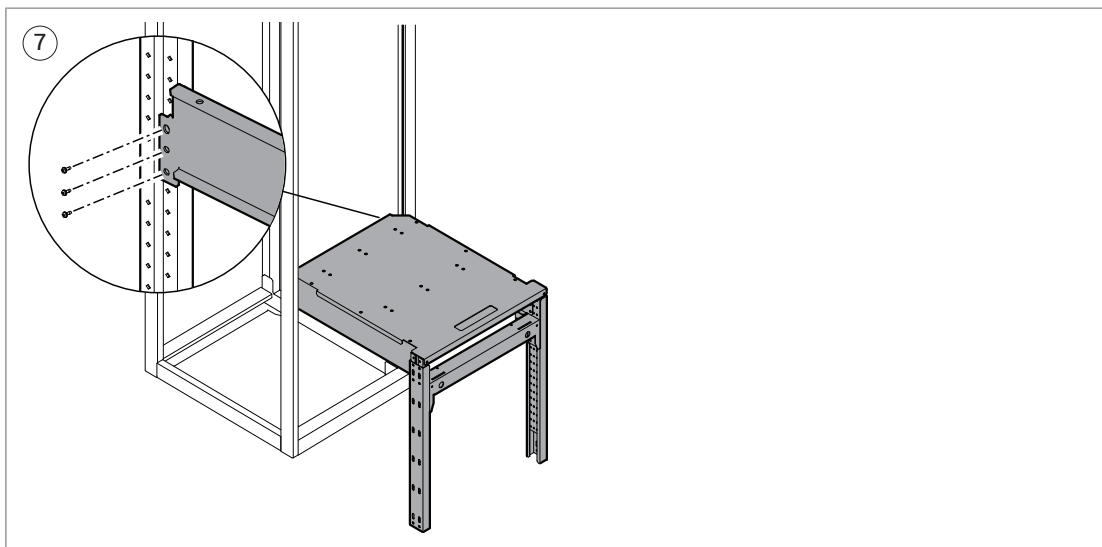
3. Attach the support legs to the side supports (5 × M6 self-tapping screws for each leg, torque: 5 N·m / 44.3 lbf·in).
4. Attach a horizontal support beam between the support legs (8 × M6 self-tapping screws). Make sure that the guide pins are correctly inserted in the holes of the support leg. Tighten the screws to torque (5 N·m / 44.3 lbf·in).



5. Slide braces over the support legs. Adjust the height of the support leg + brace according to the total height required for the service platform. Attach the braces to the legs (4 × M6 self-tapping screws for each brace, torque: 5 N·m / 44.3 lbf·in). Important: The brace must go long enough over the support leg. Refer to detail 5a.
6. If the total height of the support legs + braces is less than the total height required, attach additional support legs to the braces. Attach the additional legs on the braces (4 × M6 self-tapping screws for each additional leg, torque: 5 N·m / 44.3 lbf·in). When using additional support legs, attach an additional support beam between the support legs at a suitable height.



7. Attach the assembled service platform to the frame from the side supports (6 × M6 self-tapping screws, torque: 5 N·m / 44.3 lbf·in).



Converter module

■ Frame R7i and 2×R7i in two cubicles converter module



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠WARNING If screws or other items fall inside the drive or module, find and remove them. Unwanted items inside the drive can cause a short-circuit or arc blast when the drive is energized.



⚠CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.



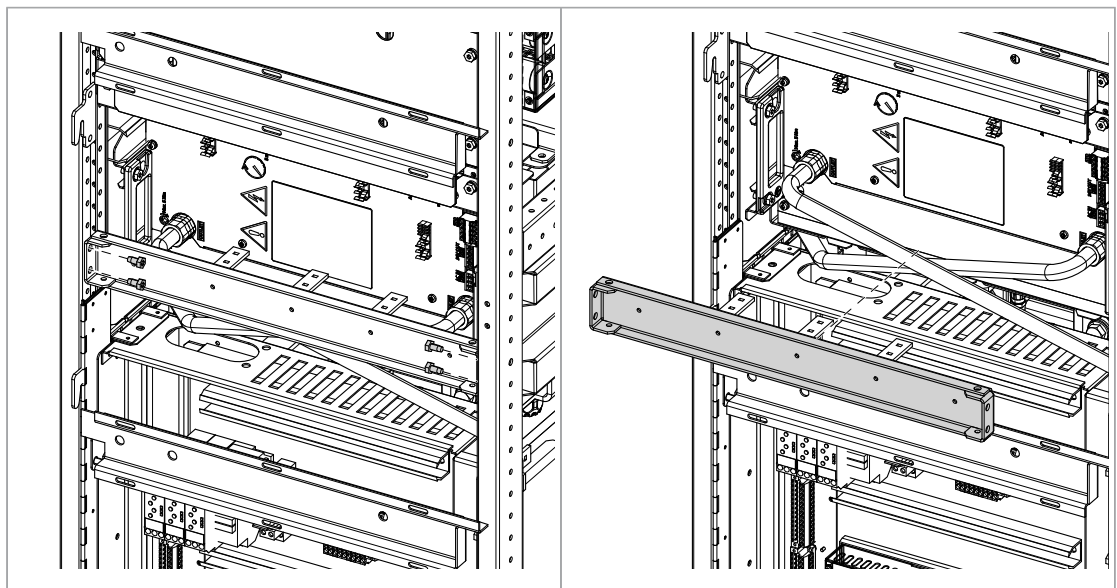
⚠CAUTION Stop the pumps and drain the coolant before you do work on the liquid cooling system. There is high-pressure hot coolant (6 bar, max. 50 °C) in the cooling circuit when it is in operation.

Note: You can replace a module that does not have option +E205 with a module that has option +E205 (for example, if you have a spare part module with option +E205). For DC/DC-converter units with parallel-connected R7i modules, the modules must **not** have option +E205.

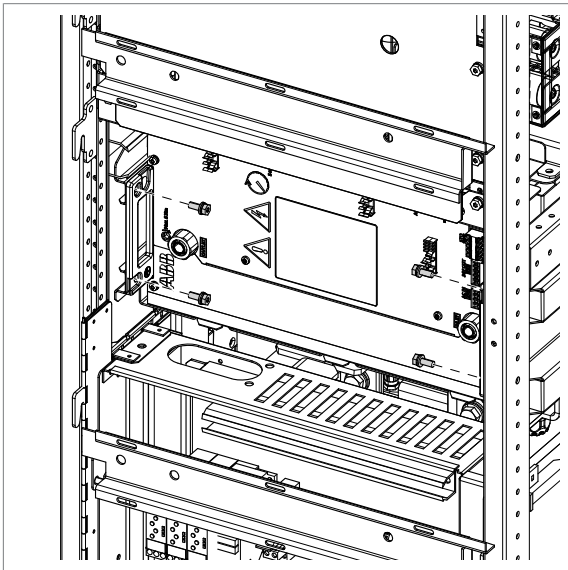
Removing the module

Remove the module as follows:

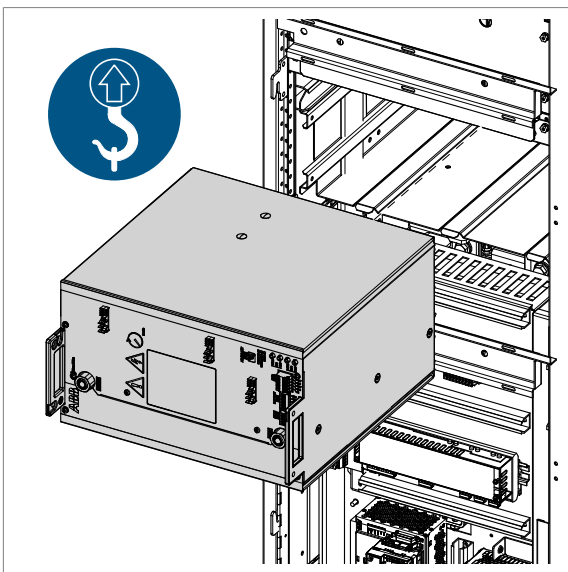
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Remove the support beam in front of the module.



4. Disconnect the power and control cables from the module.
5. Close the inlet and outlet valves of the cubicle.
6. Put the drain hoses into a container. Open the drain valves. This will drain all the equipment in the cubicle.
7. After the coolant is drained, disconnect the coolant pipes from the module.
8. Assemble and install the service platform included in the delivery. Instructions are included in the platform kit.
9. Position the service platform in front of the cabinet and below the module.
10. Attach a lifting device to the module. Tighten the lifting slings.
11. Remove the screws that attach the module to the cabinet frame.



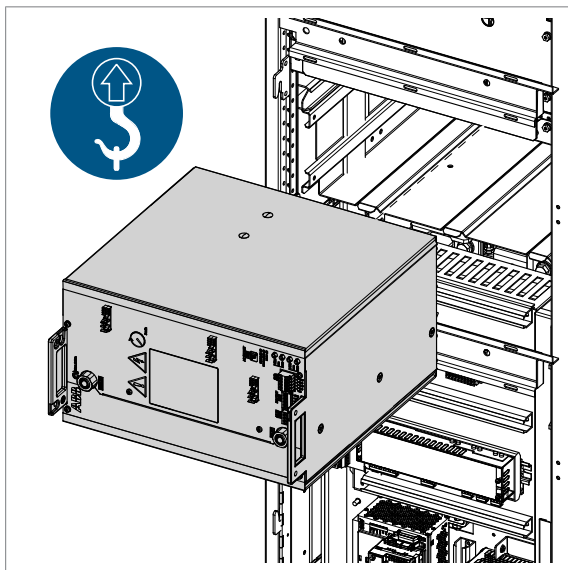
12. Pull out the module carefully and position it on the service platform. Keep constant tension on the lifting slings.



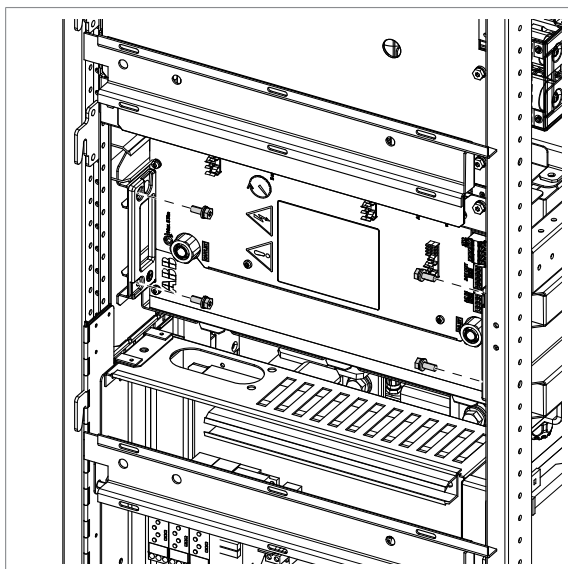
Installing the module

Install the module as follows:

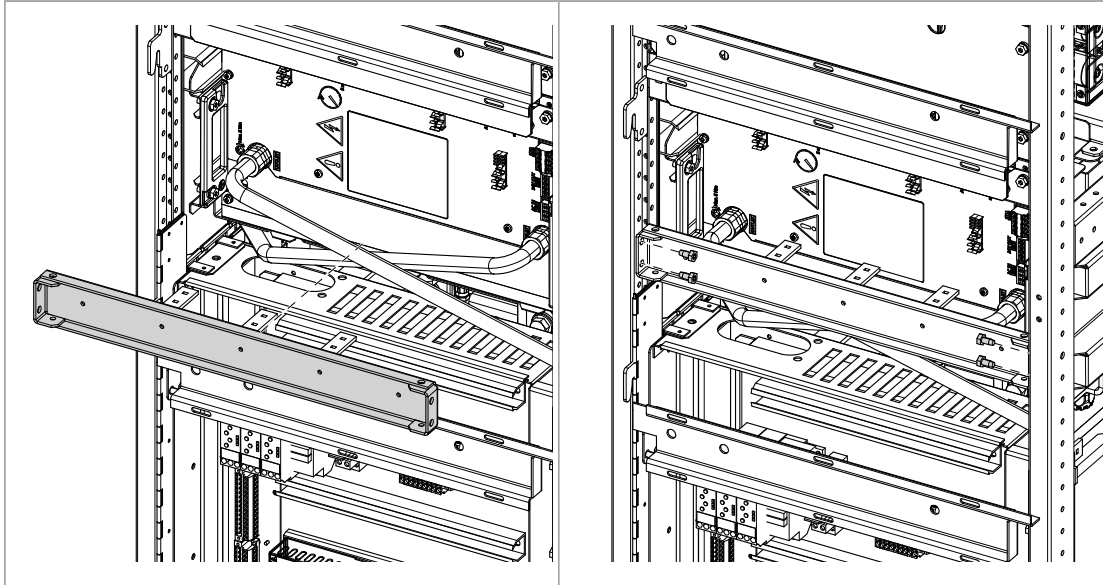
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Make sure that the service platform is attached to the cabinet.
3. Attach a lifting device to the module and lift it onto the service platform. Keep constant tension on the lifting slings.
4. Push the module carefully into its bay.



5. Install the module retaining screws and torque them to 5 N·m (3.6 lbf·ft).



6. Connect the coolant pipes to the module. Tighten to 20 N·m (14.75 lbf·ft).
 7. Connect the power and control cables to the module.
 8. Fill up the cooling system. For instructions, see section [Filling up and bleeding the internal cooling circuit \(page 150\)](#).
 9. Install the support beam in front of the module.
-



10. Close the cubicle door.

■ Frame 2×R7i in one cubicle converter module



⚠WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠WARNING If screws or other items fall inside the drive or module, find and remove them. Unwanted items inside the drive can cause a short-circuit or arc blast when the drive is energized.



⚠CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.



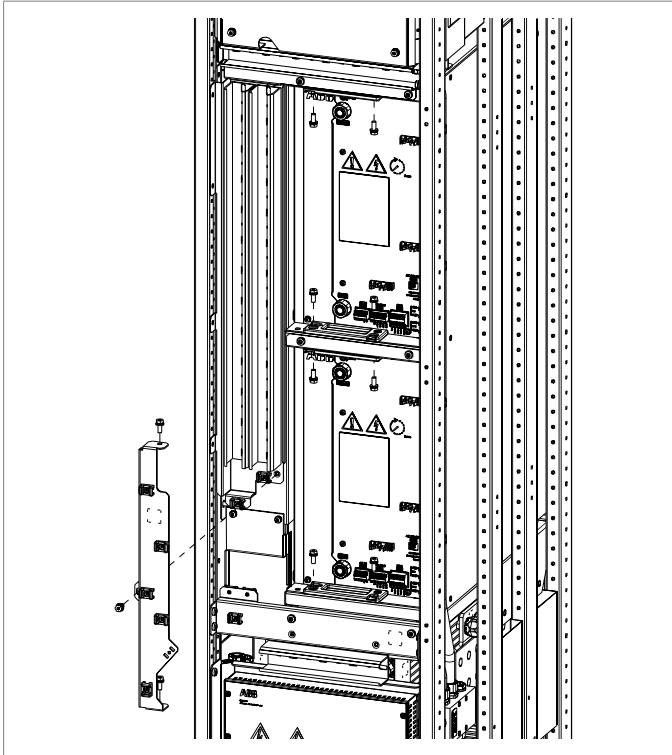
⚠CAUTION Stop the pumps and drain the coolant before you do work on the liquid cooling system. There is high-pressure hot coolant (6 bar, max. 50 °C) in the cooling circuit when it is in operation.

Removing the module

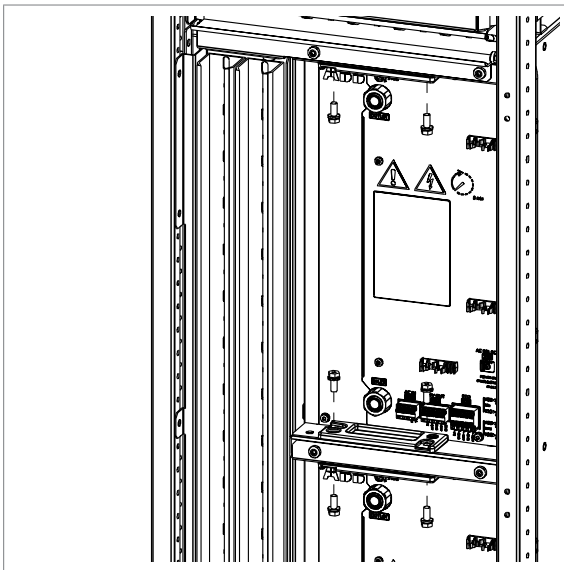
Remove the module as follows:

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Open the cubicle door.
3. Disconnect the power and control cables from the module.
4. Close the inlet and outlet valves of the cubicle.
5. Put the drain hoses into a container. Open the drain valves. This will drain all the equipment in the cubicle.

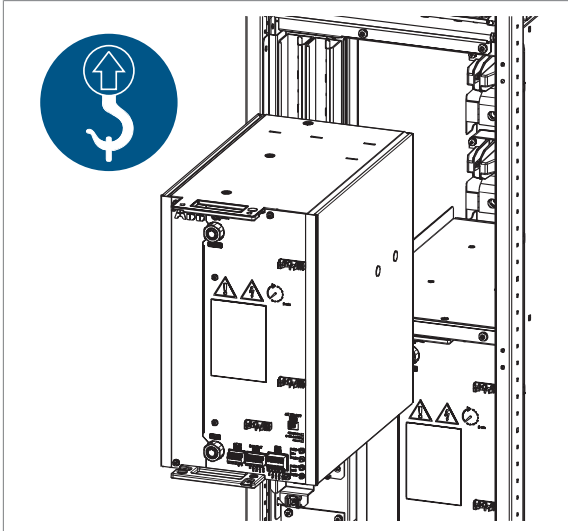
6. After the coolant is drained, disconnect the coolant pipes from the module.
7. Remove the pipe support plate.



8. Assemble and install the service platform included in the delivery. Instructions are included in the platform kit.
9. Attach a lifting device to the module. Tighten the lifting slings.
10. Remove the screws that attach the module to the cabinet frame.



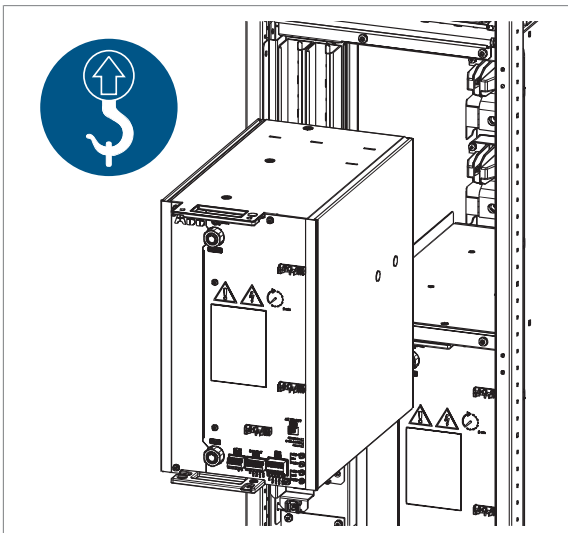
11. Pull out the module and position it carefully on the platform. Keep constant tension on the lifting slings.



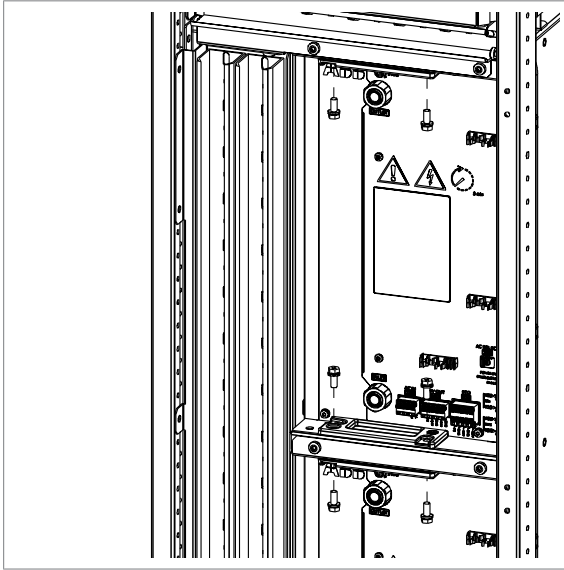
Installing the module

Install the module as follows:

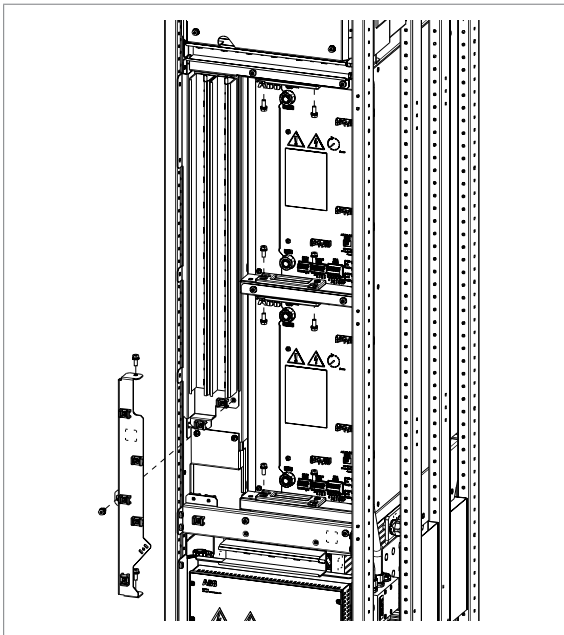
1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Make sure that the service platform is attached to the cabinet.
3. Attach a lifting device to the module and lift it onto the service platform. Keep constant tension on the lifting slings.
4. Push the module carefully into its bay.



5. Install the module retaining screws and torque them to 5 N·m (3.6 lbf·ft).



6. Install the pipe support plate.



7. Connect the coolant pipes to the module. Tighten to 20 N·m (14.75 lbf·ft).
 8. Connect the power and control cables to the module.
 9. Fill up the cooling system. For instructions, see section [Filling up and bleeding the internal cooling circuit \(page 150\)](#).
 10. Close the cubicle door.
-

■ Frame R8i converter module

Replacing an R8i converter module



⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.



⚠ WARNING If screws or other items fall inside the drive or module, find and remove them. Unwanted items inside the drive can cause a short-circuit or arc blast when the drive is energized.



⚠ WARNING The module is heavy. Reserve two persons, hoist and a suitable platform for the replacement procedure. Keep the module fastened to the hoist to prevent the module from falling. For information on a lifting device available from ABB, refer to [Converter module lifting device for drive cabinets hardware manual \(3AXD50000210268 \[English\]\)](#).



⚠ CAUTION Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.



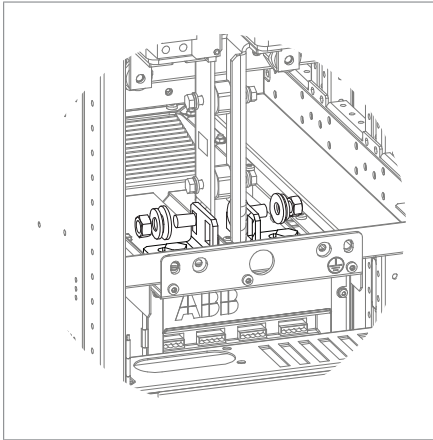
⚠ CAUTION Stop the pumps and drain the coolant before you do work on the liquid cooling system. There is high-pressure hot coolant (6 bar, max. 50 °C) in the cooling circuit when it is in operation.

NOTICE Make sure that the replacement module has exactly the same type code as the old module.

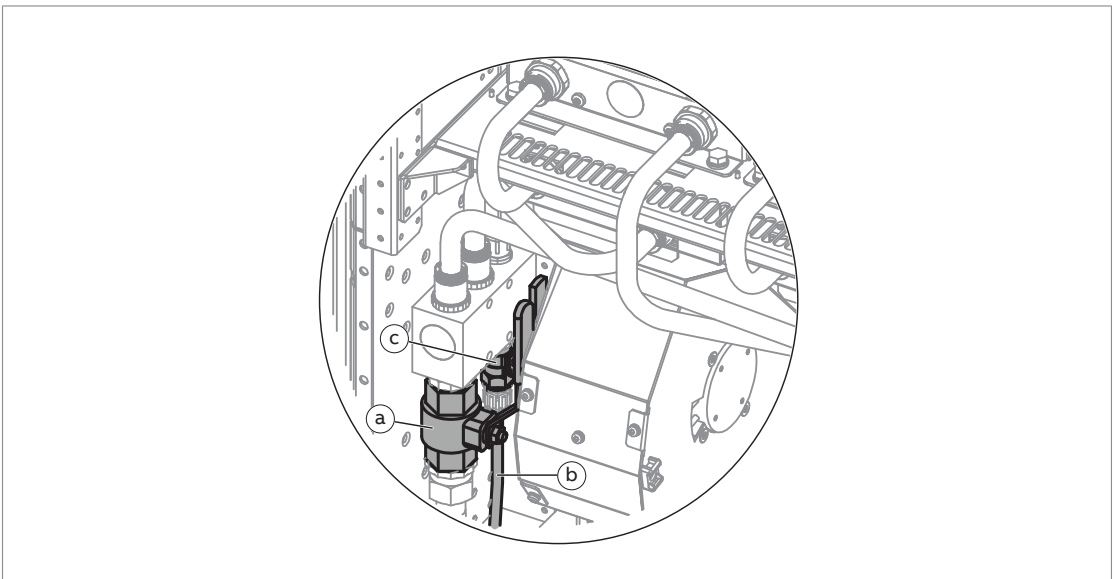
Removing the module

1. Stop the drive and do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Assemble the service platform delivered with the drive. Refer to section [Assembling the service platform](#). Attach the service platform to the cabinet only before you are ready to pull out the module out of the cabinet.
3. Install the converter module lifting device by ABB, or make sure that you have another winch in use. For information on a lifting device available from ABB, refer to [Converter module lifting device for drive cabinets hardware manual \(3AXD50000210268 \[English\]\)](#).
4. Remove the shrouding in front of the module.
5. Remove the fastening screws (a) of the swing-out frame and open it (b).
6. Disconnect the wires from the module and move them aside. Use cable ties to keep the wires out of the way.

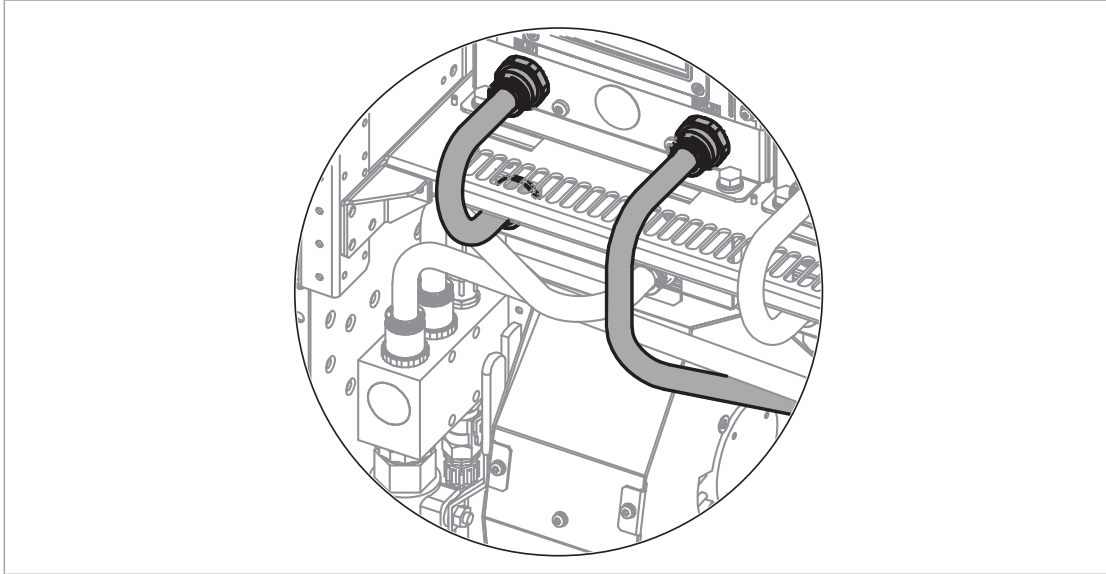
7. Remove the L-shaped DC busbars at the top of the module. Make note of the orientation of the screws as well as the order of the washers.



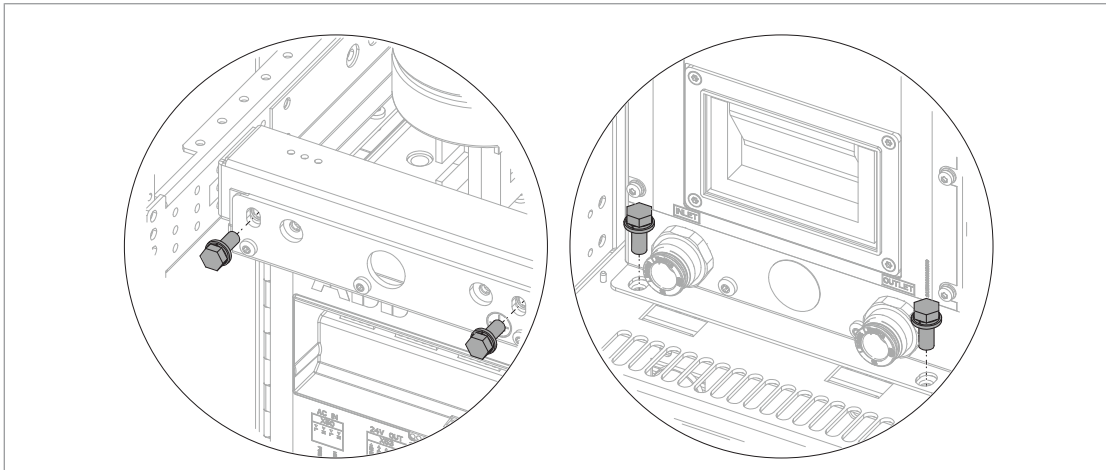
8. Close the inlet valve (a) (located on the left-hand side of the cubicle) and outlet valve (located on the right-hand side of the cubicle). Lead the drain hoses (b, on both sides of the cubicle) into a suitable container. Open the drain valves (c, on both sides of the cubicle). This will drain all modules in the cubicle.



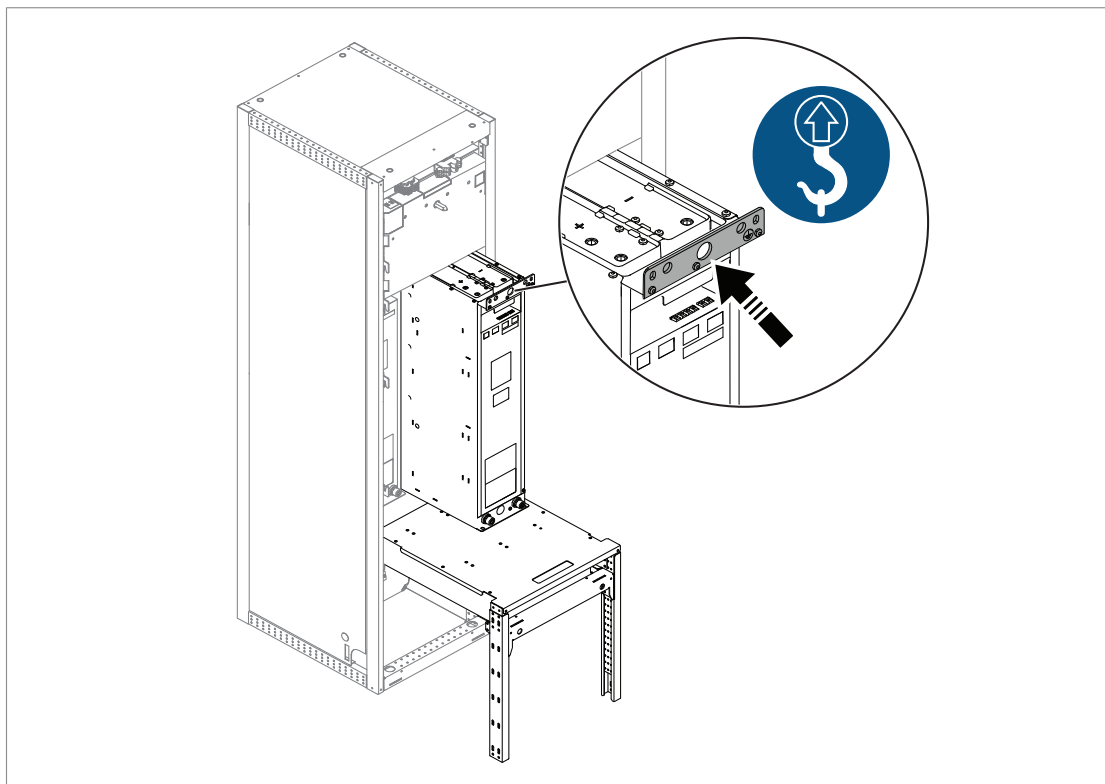
9. After the module has drained, disconnect the piping from the module.



10. Remove the module retaining screws at the top and the bottom of the module.



11. Pull the module carefully out onto the service platform. Attach the module secured to a hoist or equivalent to prevent the module from falling. For information on using the lifting device, refer to [Converter module lifting device for drive cabinets hardware manual \(3AXD50000210268 \[English\]\)](#).



Installing the module

1. Assemble the service platform delivered with the drive, if it is not yet assembled. Refer to section [Assembling the service platform \(page 124\)](#).
2. Install the converter module lifting device by ABB, or make sure that you have another winch in use. For information on a lifting device available from ABB, refer to [Converter module lifting device for drive cabinets hardware manual \(3AXD50000210268 \[English\]\)](#).
3. Attach the lifting device to the spare module to be installed, and lift it onto the service platform.
4. Push the module carefully into its bay.
5. Fasten the retaining screws at the top and the bottom of the module.
6. Install the DC busbars at the top of the module. Tighten the fastening bolts to 70 N·m (51.6 lbf·ft).
7. Connect the coolant pipes to the module. Tighten to the specified torque. R8i module coolant connections: 15 N·m (11.1 lbf·ft). Other connections: 20 N·m (14.75 lbf·ft).
8. Connect the control wiring to the module.
9. Fill up the cooling system. For instructions, see section [Filling up and bleeding the internal cooling circuit](#).
10. Remove the service platform and lifting device, if they were assembled earlier.
11. Close the swing-out frame (if present). Install all shrouds removed earlier.

Capacitors

The intermediate DC circuit of the drive contains several electrolytic capacitors. The operating time, load, and surrounding air temperature have an effect on the operating life of these capacitors. A lower ambient temperature can increase the operating life of capacitors.

Capacitor failure can cause damage to the unit, an input cable fuse failure, or a fault trip. If you think that any capacitors in the drive have failed, contact ABB.

■ Reforming the capacitors

Reform the capacitors if the drive was not powered for a year or more (is in storage or is unused). Read the manufacturing date from the type designation label. For the instructions, refer to [Capacitor reforming instructions \(3BFE64059629 \[English\]\)](#).

Control panel

Refer to [ACS-AP-I, -S, -W Assistant control panels user's manual \(3AUA0000085685 \[English\]\)](#).

UCU control unit

Refer to [UCU-22, UCU-23 and UCU-24 control units hardware manual \(3AXD50000817726 \[English\]\)](#).

BCU control unit

Refer to [BCU-02, BCU-12 and BCU-22 control units hardware manual \(3AUA0000113605 \[English\]\)](#).

LEDs and other status indicators

This section gives information on how to read the status indications of the DC/DC-converter.

The control panel on the cabinet door shows the warnings and faults given by the control program. You can also use the Drive Composer PC tool to view the warnings and faults. For more information, refer to the firmware manual and the Drive Composer PC tool manual.

■ Control panel and panel platform/holder LEDs

The ACS-AP-... control panel has a status LED. The control panel mounting platform or holder has two status LEDs. For status LED indications, refer to the following table.

Location	LED	Indication
Control panel	Continuous green	The unit operates normally.
	Flickering green	Data is transferred between the PC and the unit through the USB connection of the control panel.
	Flashing green	There is an active warning in the unit.
	Continuous red	There is an active fault in the unit.
	Flashing red	There is a fault that requires the stopping and restarting of the drive/converter/inverter.
	Flashing blue (ACS-AP-W only)	The Bluetooth interface is enabled, in discoverable mode, and ready for pairing.
	Flickering blue (ACS-AP-W only)	Data is transferred through the Bluetooth interface of the control panel.
Control panel mounting platform or holder (with the control panel removed)	Red	There is an active fault in the unit.
	Green	Power supply for the control unit is OK.

■ Converter module LEDs

The converter module LEDs are given in section [Converter module hardware \(page 30\)](#)

■ Converter unit LEDs

The converter unit cabinet has 1...3 door lamps. The indications are given in this table.

LED	Color	Indication (When the LED is on)
Charging OK indicator	Green	The DC bus of the converter modules is charged. The unit is ready for connection to the common DC bus.
DC/DC-converter disconnected	White	The DC/DC-converter unit is disconnected from the main DC bus. Note: Auxiliary voltages must be disconnected separately.
Load disconnected indicator (white)	White	The disconnecter of the energy storage is open.

Note: When the white lamps are on, DC/DC-converter is disconnected from the DC bus and the energy storage.

Liquid pipe connector installation instructions

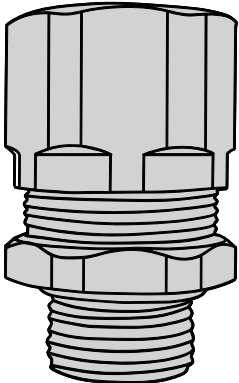
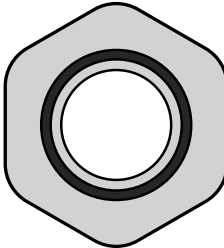
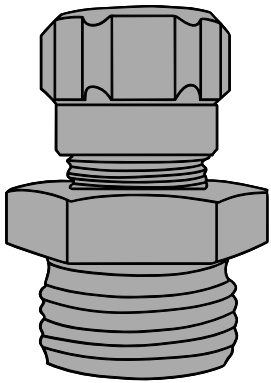
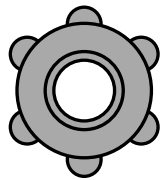
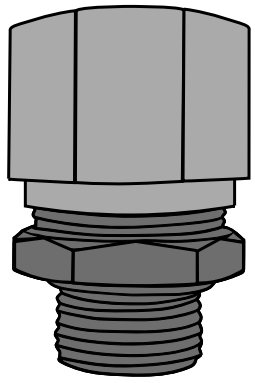
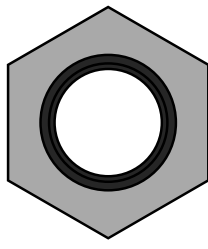


⚠ WARNING Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do electrical installation, commissioning or maintenance work.

These instructions apply to the liquid pipe connectors that are used in ABB drives and converters. There are three types of pipe connectors: type A, type B and type C. Refer

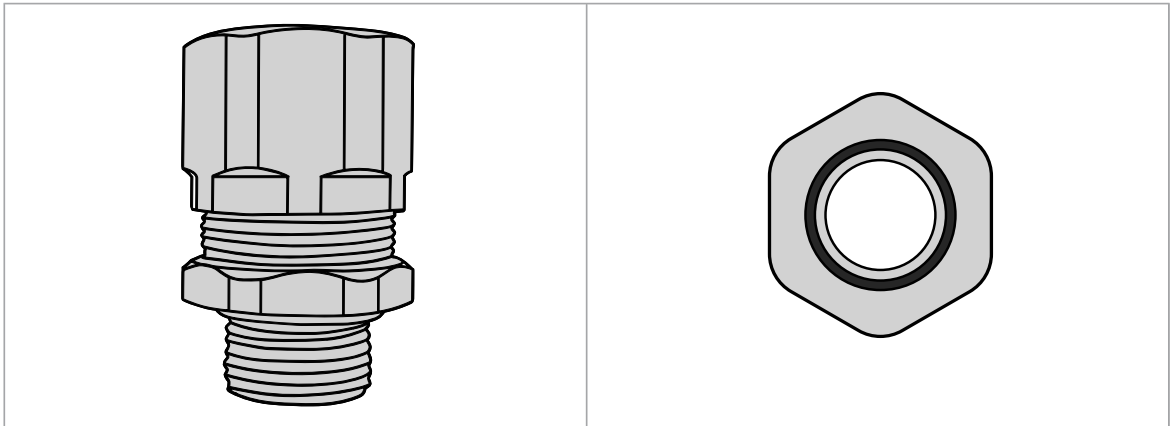
to the figures that follow. When you install a pipe connector, identify the connector type first. Obey the type-specific instructions carefully.

■ **Pipe connector types**

Type A pipe connector Thread size: G 3/8"	
	
Type B pipe connector Thread size: G 1/4" or G 3/8"	
	
Type C pipe connector Thread size: G 3/4"	
	

■ Type A pipe connector

This section is applicable to type A pipe connectors.

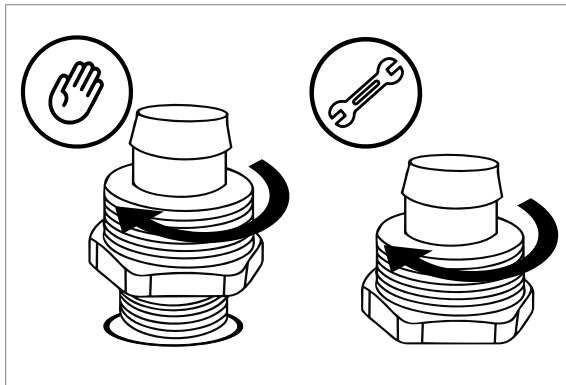


Reserve these tools and materials at hand:

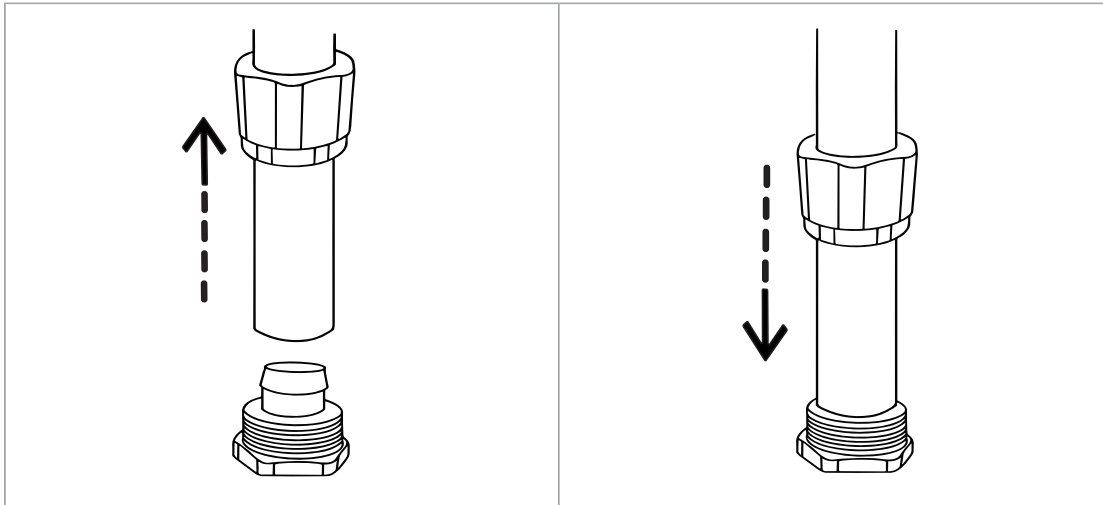
- O-ring lubricant compatible with EPDM and polyurethane materials
- torque wrench.

Installation procedure:

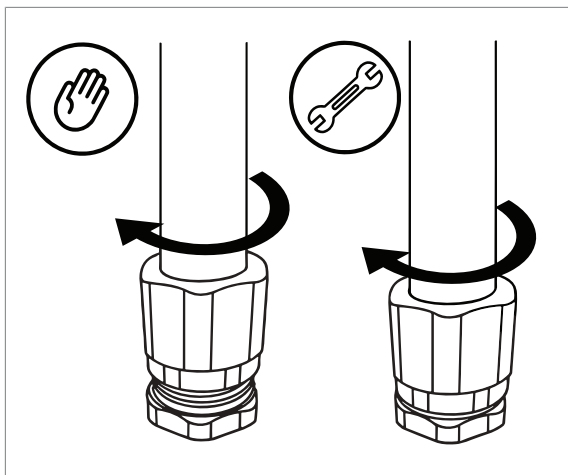
1. Do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Make sure that the pipe connector has an O-ring.
3. Lubricate the O-ring.
4. Put the pipe connector base carefully onto the threads and start to turn it in by hand. Tighten the pipe connector base to 30 N·m (22.1 lbf·ft).



5. Push the locking ring onto the pipe. Then push the pipe onto the pipe connector base and pull down the locking ring. Make sure that the pipe is perpendicular to the pipe connector base.

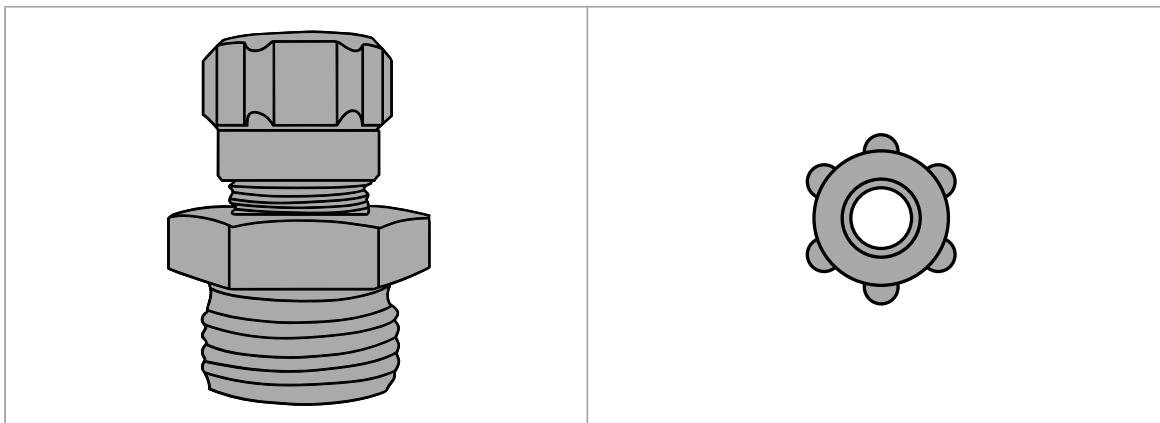


6. Start to turn the locking ring by hand. Tighten the locking ring with a torque wrench to 20 N·m (14.8 lbf·ft).



■ Type B pipe connector

This section is applicable to type B pipe connectors.

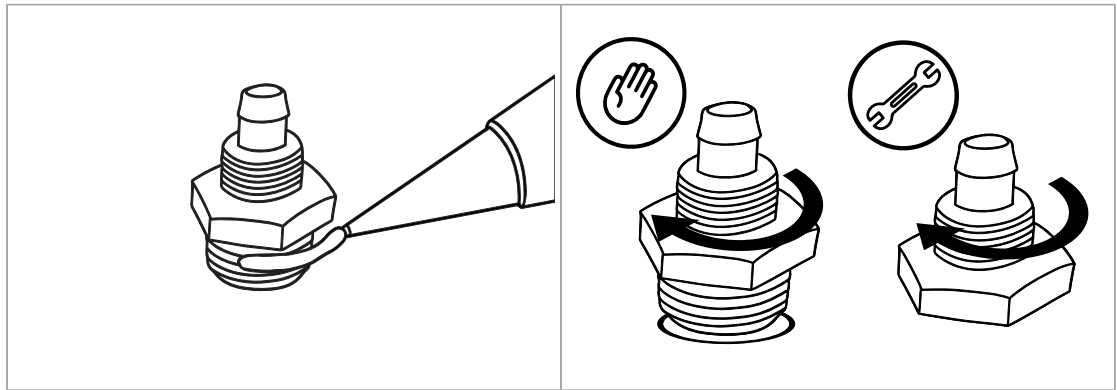


Reserve these materials and tools at hand:

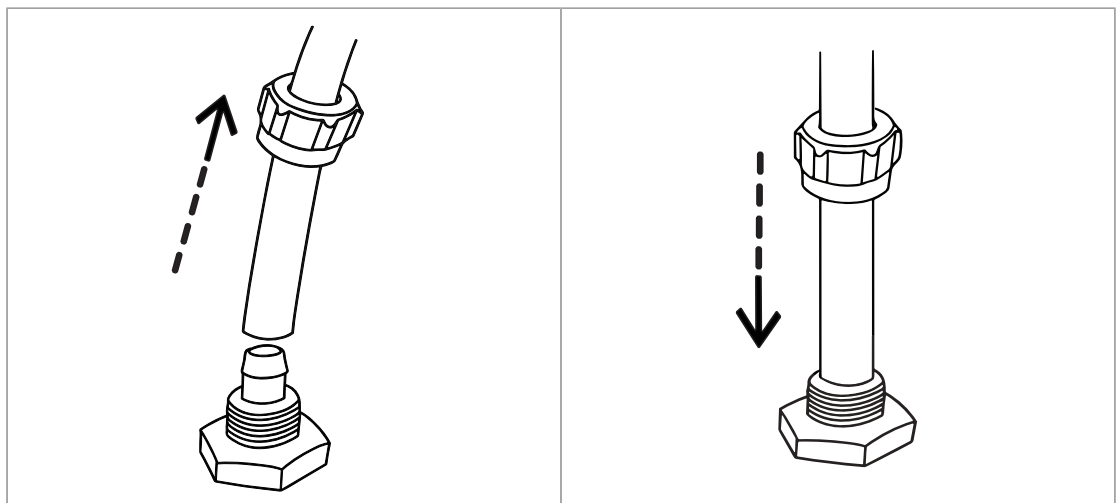
- Loctite® 2700 threadlocker. If Loctite 2700 is not available, use an equivalent threadlocker.
- torque wrench
- adjustable pliers.

Installation procedure:

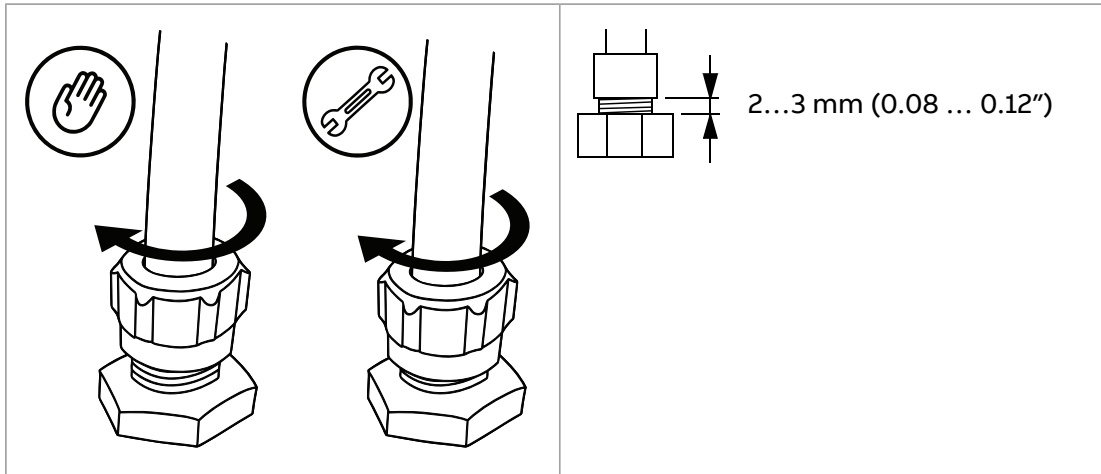
1. Do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. If the pipe connector has an O-ring, remove and discard the O-ring.
3. Apply threadlocker to the threads of the pipe connector base. Always add the threadlocker onto the outer thread. This prevents the threadlocker from entering the cooling circuit.
4. Put the pipe connector base carefully onto the threads and start to turn it in by hand. Tighten the pipe connector base to 20 N·m (14.8 lbf·ft). Wipe out extra threadlocker.



5. Push the locking ring onto the pipe. Push the pipe onto the pipe connector base and pull down the locking ring. Make sure that the pipe is perpendicular to the pipe connector base.



6. Start to turn the locking ring by hand. Tighten the locking ring with adjustable pliers. Leave 2...3 mm thread visible.

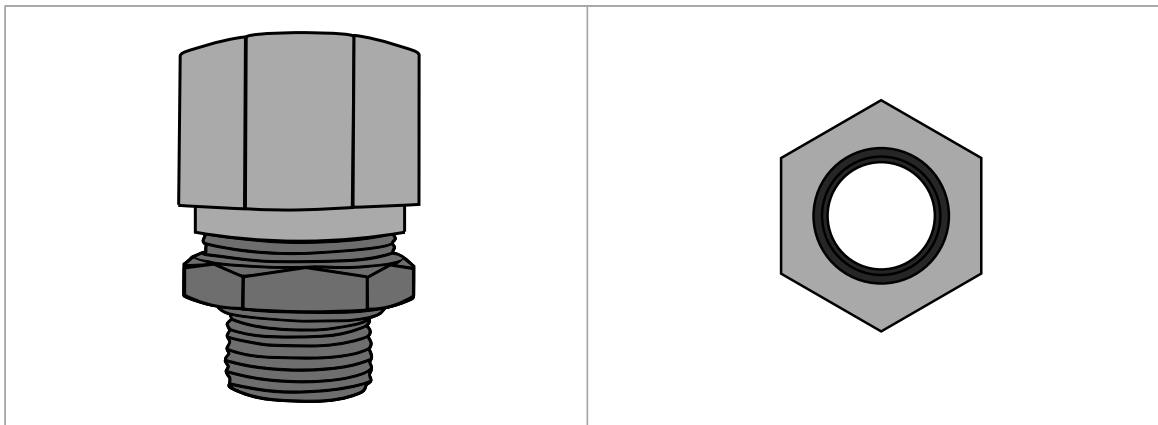


NOTICE Do not tighten the locking ring of the pipe connector too much. It can cause damage to the pipe.

7. Let the threadlocker dry completely before you fill the cooling circuit. The drying time for Loctite 2700 is 24 hours at room temperature.

■ Type C pipe connector

This section is applicable to type C pipe connectors.



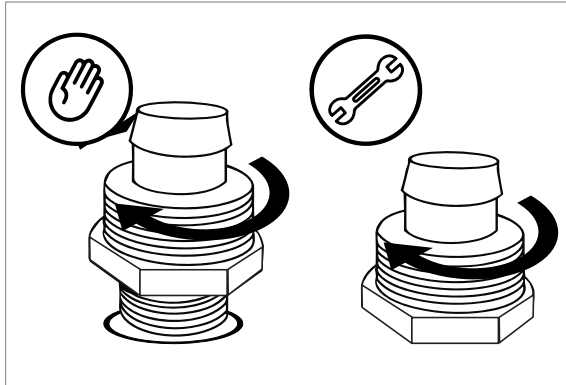
Reserve these tools and materials at hand:

- O-ring lubricant compatible with EPDM and polyurethane materials
- torque wrench.

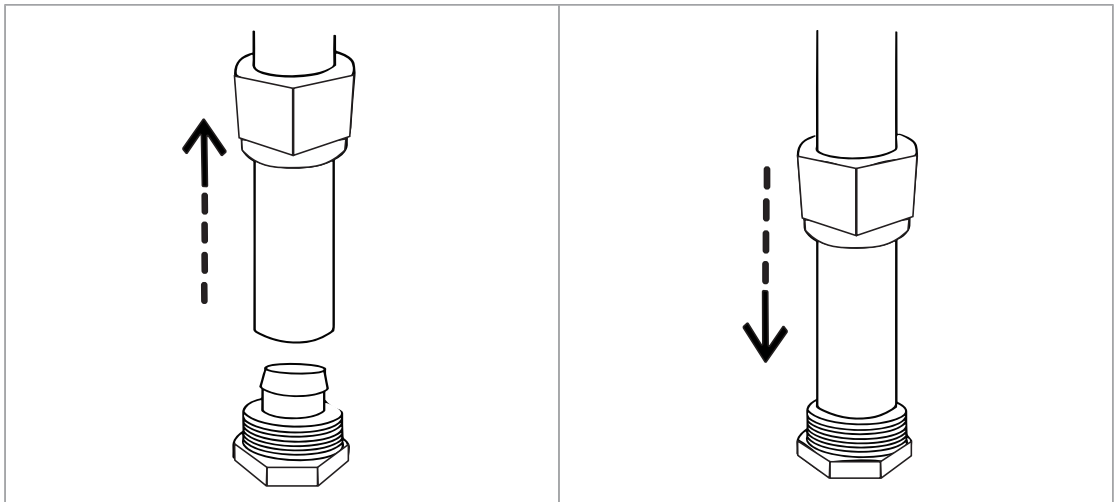
Installation procedure:

1. Do the steps in [Electrical safety precautions \(page 59\)](#) before you start the work.
2. Make sure that the pipe connector has an O-ring.
3. Lubricate the O-ring.

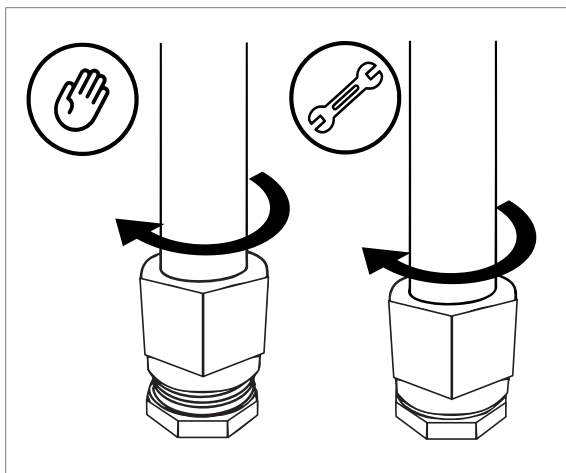
4. Put the pipe connector base carefully onto the threads and start to turn it in by hand. Tighten the pipe connector base to 60 N·m (44.2 lbf·ft).



5. Push the locking ring onto the pipe. Then push the pipe onto the pipe connector base and pull down the locking ring. Make sure that the pipe is perpendicular to the pipe connector base.



6. Start to turn the locking ring by hand. Tighten the locking ring with a wrench.



NOTICE Do not tighten the locking ring of the pipe connector too much. It can cause damage to the pipe.

11

Internal cooling circuit

Contents of this chapter

The cooling system of a liquid-cooled drive consists of two circuits: the internal cooling circuit and the external cooling circuit. The internal cooling circuit covers the heat-generating electrical components of the drive and transfers the heat to the cooling unit. In the cooling unit, the heat is transferred to the external cooling circuit which is usually part of a larger external cooling system. This chapter deals with the internal cooling circuit.

Applicability

The information in this chapter is applicable to cabinet-built ACS880 liquid-cooled drives. Except where otherwise indicated, the information is also applicable to drives built out of ACS880 liquid-cooled multidrives modules.

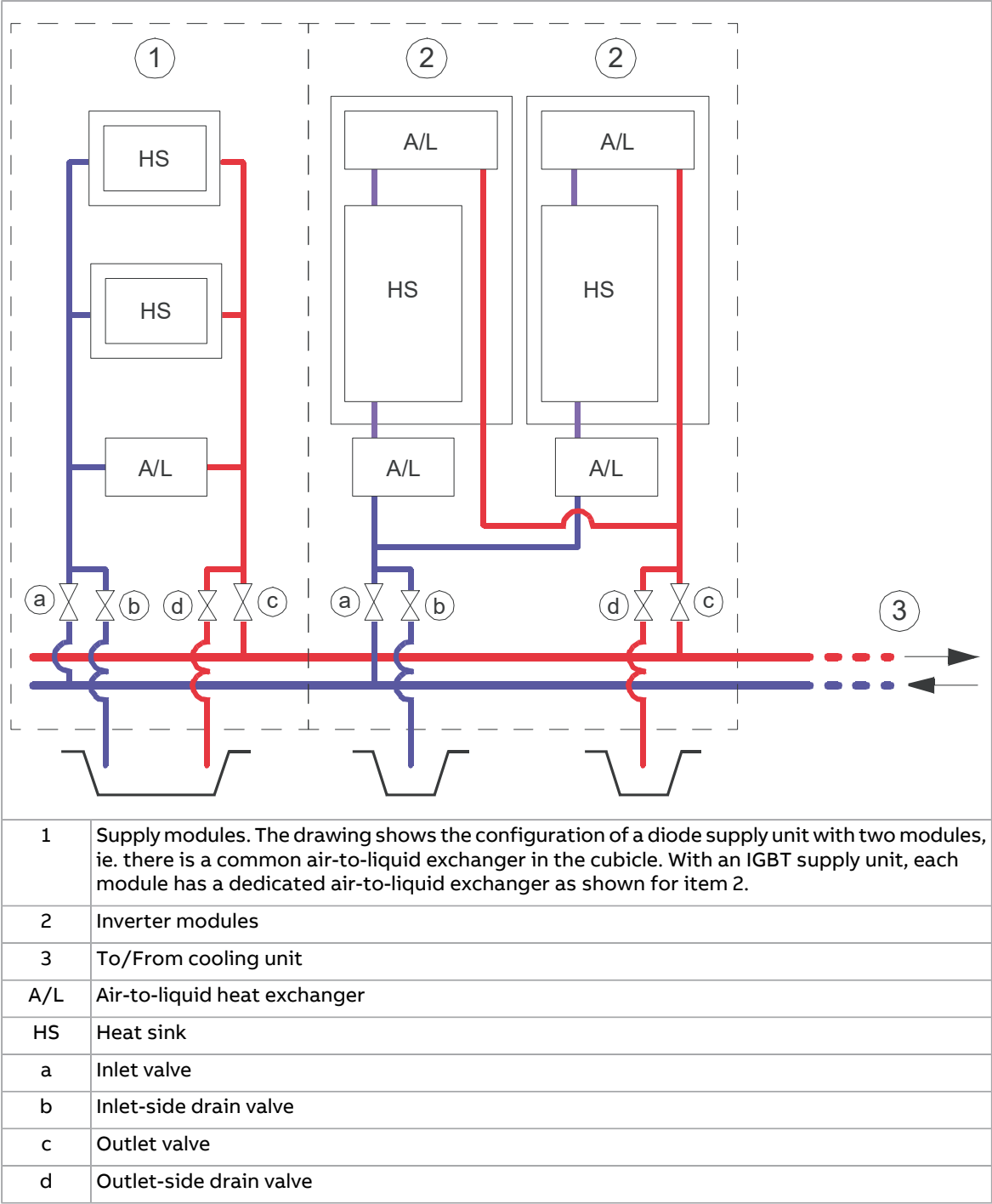
Internal cooling system

Each cubicle has an inlet and an outlet manifold, fitted with a stop valve and a drain valve. The stop valves can be closed to isolate all modules in the cubicle from the main cooling circuit.

In cabinet line-ups built by ABB, valves are color-coded:

- Blue – Open during operation
- Red – Closed during operation

The following diagram shows the coolant pipe connections in a drive system consisting of a supply unit and an inverter unit. Other units, such as brake units, DC/DC converter units have similar cooling arrangements. Other cubicles containing components that require cooling may also contain heat exchangers.



The coolant used with ACS880 liquid-cooled drive systems is Antifrogen® L 25% or 50% mixture. See [Coolant specification \(page 151\)](#).

Connection to a cooling unit

■ Connection to an ACS880-1007LC cooling unit

Refer to [ACS880-1007LC cooling unit user's manual \(3AXD50000129607 \[English\]\)](#).

■ Connection to a custom cooling unit

General requirements

Equip the system with an expansion tank to damp pressure rise due to volume changes when the temperature varies. Equip the system with a pump that provides a nominal flow and pressure. Keep the pressure within the limits specified in [Technical data for the internal cooling circuit \(page 151\)](#). Install a pressure regulator to make sure that the maximum permissible operating pressure is not exceeded.

Install a bleed valve at the highest point of the cooling circuit, and a drain valve at the lowest point.

The materials that can be used are listed in [Cooling circuit materials \(page 154\)](#).

Coolant temperature control

The temperature of the coolant in the internal cooling circuit must be kept within the limits specified in [Technical data for the internal cooling circuit \(page 151\)](#). Note that the minimum temperature is dependent on ambient temperature and relative humidity.

Filling up and bleeding the internal cooling circuit

Both the drive and coolant must be at room temperature before filling up the cooling circuit.

NOTICE Make sure that the maximum permissible operating pressure is not exceeded. When necessary, regulate the pressure to appropriate level by draining excess coolant out of the system.

NOTICE Bleeding of the cooling circuit is very important and must be done carefully. Air bubbles in the cooling circuit can decrease or completely stop coolant flow and cause overheating. Let the air out of the cooling system while filling in coolant, and after maintenance work (for example, after a power module replacement).

■ Drive line-ups with an ACS880-1007LC cooling unit

Obey the filling up and bleeding instructions in [ACS880-1007LC cooling unit user's manual \(3AXD50000129607 \[English\]\)](#).

■ Drive line-ups with a custom cooling unit

Note:

- In filling up the system, the drain valves in the line-up are used only to vent the air from the circuit so that it can be displaced by the coolant. The actual bleeding of the circuit must be done via an external bleed valve installed at the highest point of the cooling circuit. The most practical location for the valve is usually near or at the cooling unit.
 - Observe the instructions given by the manufacturer of the cooling unit. Pay special attention to filling up and bleeding the pumps properly as they may be damaged if operated when dry.
 - Draining coolant into the sewer system is not allowed.
1. Open the bleed valve at the cooling unit.
 2. Open the inlet valve and the outlet-side drain valve of one cubicle. Keep the outlet valve and the inlet-side drain valve closed.
 3. Attach a hose to the outlet-side drain valve and lead it into a suitable container.
 4. Fill the circuit with coolant. For the coolant specification, refer to section [Coolant specification \(page 151\)](#).
To minimize foaming, do not exceed the filling flow rate of 5 l/min (1.3 US gallon/min).
 5. As the piping and modules in the cubicle fills up, coolant starts to flow from the hose. Let some coolant flow out, then close the drain valve.
 6. Close the inlet valve.
 7. Repeat steps 2...6 for all cubicles in the line-up.
 8. Open the inlet and outlet valves in all cubicles. Let any air remaining in the system out through the bleed valve at the cooling unit.
 9. Close the bleed valve at the cooling unit.
 10. Continue to fill in coolant until a base pressure of approximately 250 kPa is achieved.
-

11. Open the bleed valve of the pump to let out any air.
12. Re-check the pressure and add coolant if necessary.
13. Start the coolant pump. Let any air remaining in the system out through the bleed valve at the cooling unit.
14. After one to two minutes, stop the pump or block the coolant flow with a valve.
15. Re-check the pressure and add coolant if necessary.
16. Repeat steps 13...15 a few times until all air is let out of the cooling circuit. Listen for a humming sound and/or feel the piping for vibration to find out if there is still air left in the circuit.

Draining the internal cooling circuit

The modules in each cubicle can be drained through the drain valves without draining the whole internal cooling circuit.



CAUTION Stop the pumps and drain the coolant before you do work on the liquid cooling system. There is high-pressure hot coolant (6 bar, max. 50 °C) in the cooling circuit when it is in operation.

1. Attach hoses to each drain valve in the cubicle to be drained. Lead the hoses into a suitable container. Make sure the ends of the hoses are not immersed in coolant at any point so that air can displace the coolant in the system.
2. Open the drain valves. Wait until all coolant has drained.
Note: Draining coolant into the sewer system is not allowed.
3. If required, dry the piping with compressed oil-free air of less than 6 bar.
4. If the drive is to be stored in temperatures below 0 °C (32 °F),
 - dry the cooling circuit with air,
 - fill the cooling circuit with coolant specified under [Coolant specification \(page 151\)](#).
 - drain the cooling circuit again.

Maintenance intervals of the internal cooling circuit

The coolant replacement interval is specified in the maintenance table. If it is necessary to examine the quality of Antifrogen® L coolant between the replacement intervals, you can send a sample to Clariant through the sample submission process. See 'Antifrogen analysis service' at www.clariant.com. To start the sample submission process, you must buy a voucher. You can buy vouchers from Antifrogen® L distributors or through your local ABB representative.

Technical data for the internal cooling circuit

■ Coolant specification

Coolant type

Antifrogen® L (by Clariant International Ltd, www.clariant.com) 25% or 50% mixture, available from Clariant distributors and ABB Service representatives.

Do not dilute the coolant. It is ready to use.

Antifrogen® L 25% mixture is usable in storage temperatures down to -16 °C (3.2 °F).
Antifrogen® L 50% mixture is usable in storage temperatures down to -40 °C (-40 °F).

Note that operation below 0 °C (32 °F) is not permitted regardless of the freezing point of the coolant.

NOTICE The warranty does not cover damage that occurs from the use of incorrect coolant.

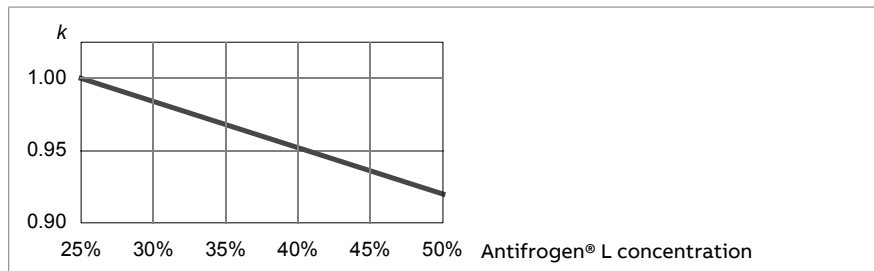
■ Temperature limits

Ambient temperature: See the technical data of the drive/unit.

Freeze protection: The freezing point of the coolant is determined by the concentration of heat transfer fluid in the mixture.

The higher the concentration of heat transfer fluid, the higher the viscosity of the coolant. This results in a higher pressure loss in the system. See [Pressure limits \(page 153\)](#).

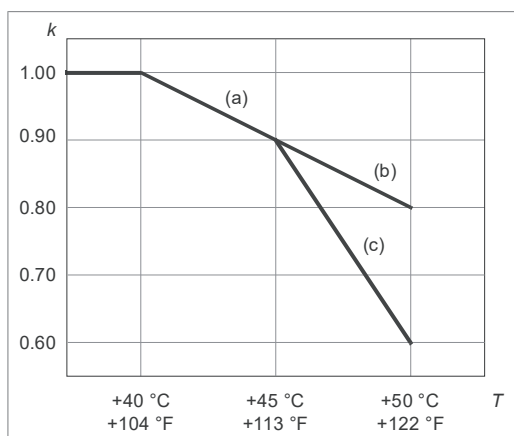
The nominal current ratings of drive system modules apply to an Antifrogen® L / water solution of 25/75% (volume). With the Antifrogen® L concentration between 25% and 50%, the drive output current must be derated by 1/3 percentage point per 1 p.p. increase in Antifrogen® L concentration. The drawing below shows the derating factor (k) in relation to Antifrogen® L concentration.



Incoming coolant temperature:

- 0...40 °C (32...104 °F): no drive output current derating required
- 40...45 °C (104...113 °F): drive output current must be derated by 2 percentage points per 1 °C (1.8 °F) temperature increase, as shown by curve (a).
- 45...50 °C (113...122 °F):
 - If components with a maximum operating temperature of 55 °C (131 °F) are installed in the same space as the drive modules, drive output current must be derated by 6 percentage points per 1 °C (1.8 °F) temperature increase, as shown by curve (c).
 - If there are no components with a maximum operating temperature of 55 °C (131 °F) installed in the same space as the drive modules, drive output current must be derated by 2 percentage points per 1 °C (1.8 °F) temperature increase, as shown by curve (b).

The drawing below shows the derating factor (k) in relation to coolant temperature.



Condensation is not permitted. The minimum coolant temperature to avoid condensation (at an atmospheric pressure of 1 bar) is shown below as a function of relative humidity (RH) and ambient temperature (T_{air}).

T_{air} (°C)	Min. T_{coolant} (°C)				
	RH = 95%	RH = 80%	RH = 65%	RH = 50%	RH = 40%
5	4.3	1.9	-0.9	-4.5	-7.4
10	9.2	6.7	3.7	-0.1	-3.0
15	14.2	11.5	8.4	4.6	1.5
20	19.2	16.5	13.2	9.4	6.0
25	24.1	21.4	17.9	13.8	10.5
30	29.1	26.2	22.7	18.4	15.0
35	34.1	31.1	27.4	23.0	19.4
40	39.0	35.9	32.2	27.6	23.8
45	44.0	40.8	36.8	32.1	28.2
50	49.0	45.6	41.6	36.7	32.8
55	53.9	50.4	46.3	42.2	37.1
	= Not permitted as standard but the coolant temperature must be 0 °C (32 °F) or more.				
Example:	At an air temperature of 45 °C and relative humidity of 65% the coolant temperature must not be less than +36.8 °C				

Maximum temperature rise: Depends on heat losses and mass flow. Typically 10 °C (18 °F) with nominal losses and flow.

■ Pressure limits

Note: The pressure limits for ACS880-1007 cooling units manufactured before week 24 of 2020 are given in ACS880-1007LC user's manual, revision C.

Base pressure: 250 kPa (recommended); 300 kPa (maximum). "Base pressure" denotes the pressure of the system compared with the atmospheric pressure when the cooling circuit is filled with coolant.

Air counterpressure in expansion tank (with ACS880-1007LC cooling unit): 80 kPa

Design pressure (PS): 600 kPa

Nominal pressure difference: 120 kPa with Antifrogen® L 25% coolant solution, 140 kPa with Antifrogen® L 50% coolant solution. This has to be taken into account when dimensioning the liquid cooling circuit.

Maximum pressure difference: 160 kPa

■ Coolant flow rate limits

The maximum coolant flow rate for all drive equipment is $1.3 \times$ nominal. See the technical data chapter for nominal values.

■ Cooling circuit materials

Materials used in the internal cooling circuit are listed below.

- stainless steel AISI 316L (UNS 31603)
- heavy gauge aluminum
- plastic materials such as PA, PEX and PTFE

Note: PVC hoses are not suitable for use with antifreeze.

- rubber gasketing NBR (nitrile rubber).

NOTICE If you connect external piping to the internal cooling circuit, use only materials that are specified above. Other materials can cause galvanic corrosion. If the external piping contains other materials, use a cooling unit with a heat exchanger (for example, ACS880-1007LC) to keep the external piping separate from the internal cooling circuit.

12

Technical data

Contents of this chapter

This chapter contains the technical data for the DC/DC converter units.

Ratings

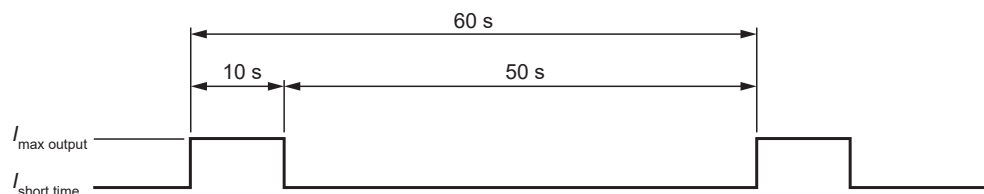
ACS880-1607LC-...	Frame	No-overload use								
		I_1 (input)	I_2 (output)	$P_{\text{cont-max}}$	$P_{\text{cont-max}}$	$I_{\text{max out-put}}$	S_n	I_{p2p}	I_{rms}	$f_{\text{SW out}}$
		A (DC)	A (DC)	kW	hp	A (DC)	kVA	A	A	Hz
$U_n = 500 \text{ V}$										
0150A-5	R7i	147	150	95	128	188	95	9	3	12000
0250A-5	R7i	244	250	159	213	313	159	9	3	12000
0350A-5	R7i	341	350	223	299	438	223	9	3	12000
0450A-5	R7i	439	450	286	384	563	286	9	3	12000
0550A-5	R7i	536	550	350	469	688	350	9	3	12000
0700A-5	2×R7i	682	700	446	597	875	446	5	1	24000
0701A-5	2×R7i	684	700	446	597	875	446	55	16	24000
0900A-5	2×R7i	876	900	572	768	1125	572	5	1	24000
0901A-5	2×R7i	880	900	572	768	1125	572	55	16	24000
1100A-5	2×R7i	1071	1100	700	939	1375	700	5	1	24000
1101A-5	2×R7i	1071	1100	700	939	1375	700	55	16	24000
$U_n = 690 \text{ V}$										
0150A-7	R7i	147	150	132	177	188	132	13	4	12000
0200A-7	R7i	196	200	176	236	250	176	13	4	12000
0300A-7	R7i	293	300	263	353	375	263	13	4	12000

ACS880-1607LC-...	Frame	No-overload use								
		I_1 (input)	I_2 (output)	$P_{\text{cont-max}}$	$P_{\text{cont-max}}$	$I_{\text{max out-put}}$	S_n	I_{p2p}	I_{rms}	$f_{\text{SW out}}$
		A (DC)	A (DC)	kW	hp	A (DC)	kVA	A	A	Hz
0399A-7	R7i	390	400	351	471	500	351	13	4	12000
0599A-7	2×R7i	585	600	527	707	750	527	6	2	24000
0601A-7	2×R7i	588	600	527	707	750	527	75	22	24000
0799A-7	2×R7i	780	800	703	942	1000	703	6	2	24000
0801A-7	2×R7i	783	800	703	942	1000	703	75	22	24000
0400A-7	R8i	391	400	351	471	500	351	38	11	12000
0500A-7	R8i	490	500	439	589	625	439	38	11	12000
0600A-7	R8i	590	600	527	707	750	527	56	16	12000
0700A-7	R8i	690	700	615	824	875	615	56	16	12000
0800A-7	R8i	790	800	703	942	1000	703	56	16	12000
0900A-7	R8i	880	900	790	1060	1125	790	56	16	12000
1000A-7	2×R8i	980	1000	878	1178	1250	878	19	5	24000
1200A-7	2×R8i	1180	1200	1054	1413	1500	1054	28	8	24000
1400A-7	2×R8i	1370	1400	1230	1649	1750	1230	28	8	24000
1600A-7	2×R8i	1570	1600	1405	1884	2000	1405	28	8	24000
1800A-7	2×R8i	1760	1800	1581	2120	2250	1581	28	8	24000

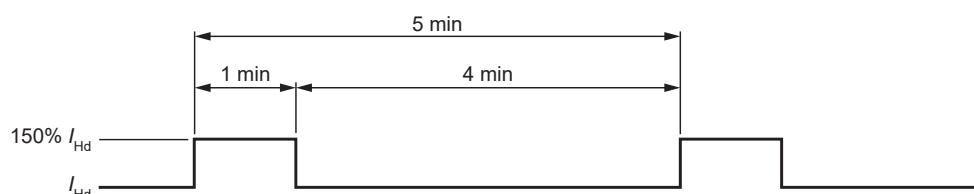
ACS880-1607LC-...	Frame	Short time overload use		Heavy overload use	
		$I_{\text{short time}}$	$P_{\text{short time}}$	I_{Hd}	P_{Hd}
		A	kW	A	kW
$U_n = 500 \text{ V}$					
0150A-5	R7i	94	60	113	72
0250A-5	R7i	156	99	189	120
0350A-5	R7i	219	139	265	168
0450A-5	R7i	281	179	340	216
0550A-5	R7i	344	219	416	265
0700A-5	2×R7i	437	278	529	337
0701A-5	2×R7i	437	278	529	337
0900A-5	2×R7i	562	358	680	433
0901A-5	2×R7i	562	358	680	433
1100A-5	2×R7i	687	437	831	529
1101A-5	2×R7i	687	437	831	529
$U_n = 690 \text{ V}$					
0150A-7	R7i	94	82	113	100
0200A-7	R7i	125	110	151	133
0300A-7	R7i	187	165	227	199
0399A-7	R7i	250	219	302	266
0599A-7	2×R7i	375	329	453	398
0601A-7	2×R7i	375	329	453	398

ACS880-1607LC-...	Frame	Short time overload use		Heavy overload use	
		$I_{\text{short time}}$	$P_{\text{short time}}$	I_{Hd}	P_{Hd}
		A	kW	A	kW
0799A-7	2×R7i	500	439	605	531
0801A-7	2×R7i	500	439	605	531
0400A-7	R8i	250	219	302	266
0500A-7	R8i	312	274	378	332
0600A-7	R8i	375	329	453	398
0700A-7	R8i	437	384	529	465
0800A-7	R8i	500	439	605	531
0900A-7	R8i	562	494	680	597
1000A-7	2×R8i	625	549	756	664
1200A-7	2×R8i	750	658	907	797
1400A-7	2×R8i	874	768	1058	929
1600A-7	2×R8i	999	878	1209	1062
1800A-7	2×R8i	1124	987	1360	1195

U_n	Nominal supply voltage of the drive
I_1	Maximum continuous DC input current from DC bus
I_2	Maximum continuous output current to/from energy storage
P_{contmax}	Maximum continuous output power to/from energy storage
$I_{\text{max output}}$	Maximum output current to/from energy storage. Available for 10 seconds at start, otherwise as long as permitted by drive temperature.
S_n	Nominal apparent power
I_{p2p}	Peak-to-peak value of output current ripple measured after the filter
I_{rms}	rms value of output current ripple measured after the filter
$f_{\text{sw out}}$	Switching frequency at output terminals (energy storage connection) measured after the filter
$I_{\text{short time}}$	Continuous output current allowing 10 s of $I_{\text{max output}}$ every 60 s



$P_{\text{short time}}$	Continuous output power allowing 10 s of $I_{\text{max output}}$ every 60 s
I_{Hd}	Continuous output current allowing 150% I_{Hd} for 1 min every 5 min

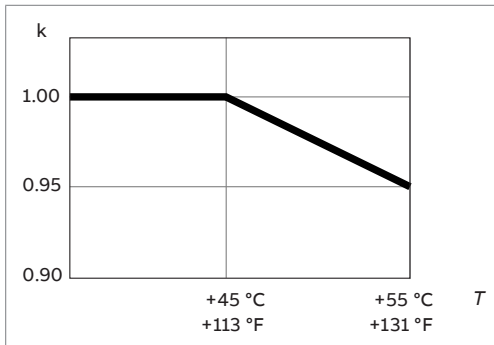


P_{Hd}	Continuous output power allowing 150% I_{Hd} for 1 min every 5 min
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Derating

■ Surrounding air temperature derating

In the temperature range +45...55 °C (+113...131 °F), the rated output current is derated by 0.5 percentage points for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



■ Altitude derating

At altitudes more than 1000 m (3281 ft) above sea level, the output current derating is 1 percentage point for every added 100 m (328 ft). For example, the derating factor for 1500 m (4921 ft) is 0.95. The maximum permitted installation altitude is given in the technical data.

For a more accurate derating, use the DriveSize PC tool.

For coolant derating, refer to section [Temperature limits \(page 152\)](#).

Type equivalence table

Converter unit type	Basic module type			Filter element or module type	
ACS880-1607LC-...	ACS880-104LC-...	Frame size	Qty	Type	Qty
$U_n = 500 \text{ V}$					
0150A-5	0120A-5	R7i	1	BDCL-13LC-7	1
0250A-5	0140A-5	R7i	1	BDCL-13LC-7	1
0350A-5	0200A-5	R7i	1	BDCL-13LC-7	1
0450A-5	0240A-5	R7i	1	BDCL-13LC-7	1
0550A-5	0460A-5	R7i	1	BDCL-13LC-7	1
0700A-5	0200A-5	R7i	2	BDCL-13LC-7	2
0701A-5	0200A-5	R7i	2	BDCL-12	6
0900A-5	0240A-5	R7i	2	BDCL-13LC-7	2
0901A-5	0240A-5	R7i	2	BDCL-12	6
1100A-5	0460A-5	R7i	2	BDCL-13LC-7	2
1101A-5	0460A-5	R7i	2	BDCL-12	6
$U_n = 690 \text{ V}$					
0150A-7	0100A-7	R7i	1	BDCL-13LC-7	1
0200A-7	0140A-7	R7i	1	BDCL-13LC-7	1
0300A-7	0220A-7	R7i	1	BDCL-13LC-7	1

Converter unit type	Basic module type			Filter element or module type	
ACS880-1607LC-...	ACS880-104LC-...	Frame size	Qty	Type	Qty
0399A-7	0389A-7	R7i	1	BDCL-13LC-7	1
0599A-7	0220A-7	R7i	2	BDCL-13LC-7	2
0601A-7	0220A-7	R7i	2	BDCL-12	6
0799A-7	0389A-7	R7i	2	BDCL-13LC-7	2
0801A-7	0220A-7	R7i	2	BDCL-12	6
0400A-7	0480A-7	R8i	1	BDCL-14LC-7	1
0500A-7	0530A-7	R8i	1	BDCL-14LC-7	1
0600A-7	0600A-7	R8i	1	BDCL-15LC-7	1
0700A-7	0670A-7	R8i	1	BDCL-15LC-7	1
0800A-7	0750A-7	R8i	1	BDCL-15LC-7	1
0900A-7	0850A-7	R8i	1	BDCL-15LC-7	1
1000A-7	0530A-7	R8i	2	BDCL-14LC-7	2
1200A-7	0600A-7	R8i	2	BDCL-15LC-7	2
1400A-7	0670A-7	R8i	2	BDCL-15LC-7	2
1600A-7	0750A-7	R8i	2	BDCL-15LC-7	2
1800A-7	0850A-7	R8i	2	BDCL-15LC-7	2

Fuses

■ DC fuses

These fuses are used on the DC bus side and on the energy storage side.

ACS880-1607LC-....	Rating	Size	Type	Ordering code	Qty
	A		Bussmann		
U _n = 500 V					
0150A-5	250	1	170M4390	3AUA00000114933	2
0250A-5	400	1	170M4393	3AUA0000076327	2
0350A-5	550	3	170M6543	3AXD50000698752	2
0450A-5	700	3	170M6545	68735980	2
0550A-5	900	3	170M6547	63919381	2
0700A-5	550	3	170M6543	3AXD50000698752	2
0701A-5	1100	3	170M6549	68736021	2
0900A-5	700	3	170M6545	68735980	2
0901A-5	1400	3	170M6501	3AUA0000086673	2
1100A-5	900	3	170M6547	63919381	2
1101A-5	1400	3	170M6501	3AUA0000086673	2
U _n = 690 V					
0150A-7	250	1	170M4390	3AUA00000114933	2
0200A-7	315	1	170M4391	3AXD50000010196	2
0300A-7	500	3	170M6542	3AXD50000021111	2
0399A-7	630	3	170M6544	63903167	2

ACS880-1607LC-...	Rating	Size	Type	Ordering code	Qty
	A		Bussmann		
0400A-7	630	3	170M6544	63903167	2
0500A-7	800	3	170M6546	63919128	2
0599A-7	500	3	170M6542	3AXD50000021111	2
0600A-7	1000	3	170M6548	63916749	2
0601A-7	1000	3	170M6548	63916749	2
0700A-7	1100	3	170M6549	68736021	2
0799A-7	630	3	170M6544	63903167	2
0800A-7	1250	3	170M6500	63919462	2
0801A-7	1100	3	170M6549	68736021	2
0900A-7	1400	3	170M6501	3AUA0000086673	2
1000A-7	800	3	170M6546	63919128	4
1200A-7	1000	3	170M6548	63916749	4
1400A-7	1100	3	170M6549	68736021	4
1600A-7	1250	3	170M6500	63919462	4
1800A-7	1400	3	170M6501	3AUA0000086673	4

Note: All listed fuses are UL Recognized.

■ BAMU unit fuses

The BAMU voltage/current measurement unit (option +G442) typically has one of these protection devices:

- a miniature circuit breaker of type S804S-UCB10 (IEC), or
- two fuses of type 1021 CP URB 27X60/32 (UL)

For the actual type of protection, refer to the documentation delivered with the drive.

Filter data

Filter element or module type	Nominal inductance / phase	DC resistance / phase
	μH	mohm
BDCL-12	135	7
BDCL-13LC	1610	8
BDCL-14LC	540	7
BDCL-15LC	360	7

Dimensions and weights

ACS880-1607LC-...	Frame	Height ¹⁾	Width	Depth	Weight
		mm	mm	mm	kg
U _n = 500 V					
0150A-5	R7i	2010	500	644	400
0250A-5	R7i	2010	500	644	400

ACS880-1607LC-...	Frame	Height ¹⁾	Width	Depth	Weight
		mm	mm	mm	kg
0350A-5	R7i	2010	500	644	400
0450A-5	R7i	2010	500	644	400
0550A-5	R7i	2010	500	644	400
0700A-5	2×R7i	2010	1000	644	800
0701A-5	2×R7i	2010	400	644	400
0900A-5	2×R7i	2010	1000	644	800
0901A-5	2×R7i	2010	400	644	400
1100A-5	2×R7i	2010	1000	644	800
1101A-5	2×R7i	2010	400	644	400
$U_n = 690 \text{ V}$					
0150A-7	R7i	2010	500	644	400
0200A-7	R7i	2010	500	644	400
0300A-7	R7i	2010	500	644	400
0399A-7	R7i	2010	500	644	400
0599A-7	2×R7i	2010	1000	644	800
0601A-7	2×R7i	2010	400	644	400
0799A-7	2×R7i	2010	1000	644	800
0801A-7	2×R7i	2010	400	644	400
0400A-7	R8i	2010	800	644	680
0500A-7	R8i	2010	800	644	680
0600A-7	R8i	2010	800	644	710
0700A-7	R8i	2010	800	644	710
0800A-7	R8i	2010	800	644	710
0900A-7	R8i	2010	800	644	710
1000A-7	2×R8i	2010	1600	644	1425
1200A-7	2×R8i	2010	1600	644	1425
1400A-7	2×R8i	2010	1600	644	1425
1600A-7	2×R8i	2010	1600	644	1425
1800A-7	2×R8i	2010	1600	644	1425

¹⁾ The top power cable entry (option +H351) increases height (+50 mm) and width (+300 mm)

Free space requirements

The values are as required by cooling, maintenance and operation of the pressure relief (if in use). Also obey the general mechanical installation instructions.

Front		Sides		Above	
mm	in	mm	in	mm	in
1000	39	0	0	250	9.85

Losses, cooling data and noise

■ Losses and noise (frame R7i)

Reported noise values are maximum measured values with a reference converter configuration in hemi-anechoic room in accordance with standard ISO 3746:2010.

The noise level depends on the size and structure of the cabinet, actual load, installation method, and surrounding conditions.

ACS880-1607LC-...	Frame	Losses ¹⁾			Noise		Efficiency ²⁾
		P_{loss} (con- verter)	P_{loss} (filter)	P_{loss} total	L_{WA} ³⁾	L_{pA} ⁴⁾	
		kW	kW	kW	dBA	dBA	%
$U_n = 500\text{ V}$							
0150A-5	R7i	0.6	0.5	1.1	81	64	99.1
0250A-5	R7i	1.0	0.6	1.6	84	67	99.1
0350A-5	R7i	1.3	0.8	2.1	87	69	99.1
0450A-5	R7i	1.7	1.1	2.8	89	72	99.0
0550A-5	R7i	2.0	1.5	3.5	91	74	99.1
0700A-5	2×R7i	2.5	1.6	4.1	90	72	99.1
0701A-5	2×R7i	2.8	3.1	5.9	92	74	99.1
0900A-5	2×R7i	3.2	2.2	5.4	92	75	99.0
0901A-5	2×R7i	3.1	4.4	7.5	94	77	99.1
1100A-5	2×R7i	3.8	2.9	6.7	94	77	99.0
1101A-5	2×R7i	4.0	5.7	9	96	79	99.1
$U_n = 690\text{ V}$							
0150A-7	R7i	1.2	0.7	1.8	83	66	98.9
0200A-7	R7i	1.5	0.8	2.3	85	68	98.9
0300A-7	R7i	2.0	1.0	3.0	88	71	98.9
0399A-7	R7i	2.7	1.2	3.9	91	74	98.9
0599A-7	2×R7i	3.9	1.9	5.7	91	74	99.0
0601A-7	2×R7i	4.9	3.5	8.4	93	76	98.9
0799A-7	2×R7i	5.3	2.4	7.6	94	77	98.9
0801A-7	2×R7i	5.6	4.6	10.2	96	79	99.1

¹⁾ These losses are not calculated according to the ecodesign standard IEC 61800-9-2. The values represent the operating point at which the maximum losses occur.

²⁾ The efficiency is not calculated according to the ecodesign standard IEC 61800-9-2. Efficiency at nominal current and nominal power (U_{DC} typical and U_{ES} at 90% of U_{DC}).

³⁾ L_{WA} represents the calculated sound power level.

⁴⁾ L_{pA} represents the calculated surface time-averaged sound pressure level using right parallelepiped measurement surface with 1 m (3.3 ft) measurement distance.

■ Losses and noise (frame R8i)

Reported noise values are estimated values with a reference converter configuration measured in hemi-anechoic room in accordance with standard ISO 9614-2:1996.

The noise level depends on the size and structure of the cabinet, actual load, installation method, and surrounding conditions.

ACS880-1607LC-...	Frame	Losses ¹⁾			Noise		Efficiency ²⁾
		P_{loss} (con- verter)	P_{loss} (filter)	P_{loss} total	L_{WA} ³⁾	L_{pA} ⁴⁾	
		kW	kW	kW	dBA	dBA	%
$U_n = 690 \text{ V}$							
0400A-7	R8i	3.3	0.9	4.2	82	64	98.8
0500A-7	R8i	4.1	1.2	5.3	82	64	98.8
0600A-7	R8i	4.7	1.5	6.2	82	64	98.8
0700A-7	R8i	5.5	1.8	7.3	82	64	98.8
0800A-7	R8i	6.4	2.1	8.5	82	64	98.8
0900A-7	R8i	7.2	2.5	9.7	82	64	98.8
1000A-7	2×R8i	8.9	2.3	11.2	84	66	98.7
1200A-7	2×R8i	10.6	3.0	13.6	84	66	98.7
1400A-7	2×R8i	12.7	3.6	16.3	84	66	98.7
1600A-7	2×R8i	14.8	4.2	19.0	84	66	98.6
1800A-7	2×R8i	17.1	4.9	22.0	84	66	98.6

¹⁾ These losses are not calculated according to the ecodesign standard IEC 61800-9-2. The values represent the operating point at which the maximum losses occur.

²⁾ The efficiency is not calculated according to the ecodesign standard IEC 61800-9-2. Efficiency at nominal current and nominal power (U_{DC} typical and U_{ES} at 90% of U_{DC}).

³⁾ L_{WA} represents the calculated sound power level.

⁴⁾ Estimated sound pressure level at 1 m (3.3 ft) distance from the cabinet.

■ Cooling data (frame R7i)

ACS880-1607LC-...	Frame	Coolant volume				Coolant flow rate			Pressure loss
		Power mod-ule(s)	Filter	Cabinet	Total	Power mod-ule(s)	Filter(s)	Total	kPa
		l	l	l	l	l/min	l/min	l/min	
U _n = 500 V									
0150A-5	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0250A-5	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0350A-5	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0450A-5	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0550A-5	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0700A-5	2×R7i	0.4	1.6	4.4	6.4	26	4	30	120
0701A-5	2×R7i	0.4	-	3.7	4.1	29	0	29	120
0900A-5	2×R7i	0.4	1.6	4.4	6.4	26	4	30	120
0901A-5	2×R7i	0.4	-	3.7	4.1	29	0	29	120
1100A-5	2×R7i	0.4	1.6	4.4	6.4	26	4	30	120
1101A-5	2×R7i	0.4	-	3.7	6.4	29	0	29	120
U _n = 690 V									
0150A-7	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0200A-7	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0300A-7	R7i	0.2	0.8	2.2	3.2	13	2	15	120

ACS880-1607LC-...	Frame	Coolant volume				Coolant flow rate			Pressure loss
		Power mod- ule(s)	Filter	Cabinet	Total	Power mod- ule(s)	Filter(s)	Total	kPa
		l	l	l	l	l/min	l/min	l/min	
0399A-7	R7i	0.2	0.8	2.2	3.2	13	2	15	120
0599A-7	2×R7i	0.4	1.6	4.4	6.4	26	4	30	120
0601A-7	2×R7i	0.4	-	3.7	4.1	29	0	29	120
0799A-7	2×R7i	0.4	1.6	4.4	6.4	26	4	30	120
0801A-7	2×R7i	0.4	-	3.7	4.1	29	0	29	120

■ Cooling data (frame R8i)

ACS880-1607LC-...	Frame	Coolant volume				Coolant flow rate			Pressure loss
		Power module(s)	Power module cabinet	Filter cabinet	Total	Power module(s)	Filter(s)	Total	kPa
		l	l	l	l	l/min	l/min	l/min	
U _n = 690 V									
0400A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
0500A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
0600A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
0700A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
0800A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
0900A-7	R8i	1.9	2.6	2.6	7.1	16	20	36	120
1000A-7	2×R8i	3.8	5.2	5.2	14.2	32	40	72	120
1200A-7	2×R8i	3.8	5.2	5.2	14.2	32	40	72	120
1400A-7	2×R8i	3.8	5.2	5.2	14.2	32	40	72	120
1600A-7	2×R8i	3.8	5.2	5.2	14.2	32	40	72	120
1800A-7	2×R8i	3.8	5.2	5.2	14.2	32	40	72	120

Tightening torques

Unless a tightening torque is specified in the text, these torques can be used.

■ Electrical connections

Size	Torque	Strength class
M3	0.5 N·m (4.4 lbf·in)	4.6...8.8
M4	1 N·m (9 lbf·in)	4.6...8.8
M5	4 N·m (35 lbf·in)	8.8
M6	9 N·m (6.6 lbf·ft)	8.8
M8	22 N·m (16 lbf·ft)	8.8
M10	42 N·m (31 lbf·ft)	8.8
M12	70 N·m (52 lbf·ft)	8.8

Size	Torque	Strength class
M16	120 N·m (90 lbf·ft)	8.8

■ Mechanical connections

Size	Max. torque	Strength class
M5	6 N·m (53 lbf·in)	8.8
M6	10 N·m (7.4 lbf·ft)	8.8
M8	24 N·m (17.7 lbf·ft)	8.8

■ Insulation supports

Size	Max. torque	Strength class
M6	5 N·m (44 lbf·in)	8.8
M8	9 N·m (6.6 lbf·ft)	8.8
M10	18 N·m (13.3 lbf·ft)	8.8
M12	31 N·m (23 lbf·ft)	8.8

■ Cable lugs

Size	Max. torque	Strength class
M8	15 N·m (11 lbf·ft)	8.8 (A2-70 or A4-70)
M10	32 N·m (23.5 lbf·ft)	8.8
M12	50 N·m (37 lbf·ft)	8.8

Input power (DC bus) connection

Voltage (U_1)	ACS880-1607LC-xxxxx-5 = 566...707 V DC. This is indicated in the type designation label as typical input voltage levels 566 / 679 / 707 V DC. ACS880-1607LC-xxxxx-7 = 742...976 V DC. This is indicated in the type designation label as typical input voltage levels 742 / 849 / 976 V DC (849 V DC for UL/CSA).
element or module	<u>BDCL-12</u> : M10. Torque: 42 N·m (31 lbf·ft). <u>BDCL-13LC</u> : M12. Torque: 70 N·m (52 lbf·ft). <u>BDCL-14LC</u> and <u>BDCL-15LC</u> : M10. Torque: 42 N·m (31 lbf·ft). Maximum intrusion into module 20 mm (0.8 in).

Output power (energy storage) connection

Voltage (U_2)	ACS880-1607LC-xxxxx-5 = Maximum output voltage 50 V...95% of U_{DC} (Drive DC voltage in the DC bus). This is indicated in the type designation label as typical output voltage range 50...509 / 611 / 636 V DC. ACS880-1607LC-xxxxx-7 = Maximum output voltage 50 V...95% of U_{DC} (Drive DC voltage in the DC bus). This is indicated in the type designation label as typical output voltage range 50...668 / 764 / 878 V DC (764 V DC for UL/CSA). Recommended output voltage 150 V...80% of U_{DC} .
Current	See the ratings data.

Output terminals, cabinet	See the dimension drawings.
Maximum energy storage cable length	100 m (328 ft)

Typical power cable sizes

The tables below give the current carrying capacity (I_{Lmax}) and typical size for copper and aluminum cables with PVC or XLPE insulation. A correction factor $K = 0.70$ is used. Time const. is the temperature time constant of the cable.

The cable sizing is based on a maximum of 9 cables installed side by side on a ladder-type cable tray, with three trays on top of each other (with 30 cm of space between the trays), and an ambient temperature of 30 °C (IEC 60364-5-52).

Conductor cross-section (copper)		PVC insulation Conductor temperature 70°		XLPE insulation Conductor temperature 90°		Typical dimensions of copper cable	
mm ²	AWG / kcmil	I_{Lmax} (A)	Time const. (s)	I_{Lmax} (A)	Time const. (s)	Size	ø [mm]
1.5	16	13	85	16	67	3 × 1.5 + 1.5	13
2.5	12	18	121	23	88	3 × 2.5 + 2.5	14
4	12	24	175	30	133	3 × 4 + 4	16
6	10	30	251	38	186	3 × 6 + 6	18
10	8	42	359	53	268	3 × 10 + 10	21
16	6	56	514	70	391	3 × 16 + 16	23
25	4	71	791	89	598	3 × 25 + 16	24
35	1	88	1000	110	760	3 × 35 + 16	26
50	1/0	107	1308	134	990	3 × 50 + 25	29
70	2/0	137	1613	171	1230	3 × 70 + 35	32
95	4/0	167	2046	209	1551	3 × 95 + 50	38
120	250	193	2441	241	1859	3 × 120 + 70	41
150	300	223	2820	279	2139	3 × 150 + 70	44
185	400	255	3329	319	2525	3 × 185 + 95	50
240	500	301	4073	376	3099	3 × 240 + 120	55
300	600	348	4779	435	3636	3 × 300 + 150	58

Conductor cross-section (aluminum)		PVC insulation Conductor temperature 70°		XLPE insulation Conductor temperature 90°		Typical dimensions of aluminum cable	
mm ²	AWG / kcmil	I_{Lmax} (A)	Time const. (s)	I_{Lmax} (A)	Time const. (s)	Size	ø [mm]
35	1	67	736	84	669	3 × 35 + 10 Cu	26
50	1/0	82	959	102	874	3 × 50 + 15 Cu	29
70	2/0	105	1182	131	1079	3 × 70 + 21 Cu	32
95	4/0	128	1492	159	1376	3 × 95 + 29 Cu	38
120	250	148	1776	184	1637	3 × 120 + 41 Cu	41

Conductor cross-section (aluminum)		PVC insulation Conductor temperature 70°		XLPE insulation Conductor temperature 90°		Typical dimensions of aluminum cable	
mm ²	AWG / kcmil	I _{Lmax} (A)	Time const. (s)	I _{Lmax} (A)	Time const. (s)	Size	ø [mm]
150	300	171	2042	213	1881	3 × 150 + 41 Cu	44
185	400	196	2422	243	2237	3 × 185 + 57 Cu	49
240	500	231	2967	286	2740	3 × 240 + 72 Cu	54
300	600	267	3478	330	3229	3 × 300 + 88 Cu	58

■ Frame 2×R7i in one cubicle

The tables below give the typical size for copper cables with PVC or XLPE insulation. The recommended maximum cross-sectional area for a cable is 150 mm².

3-conductor shielded cable	PVC insulation Conductor temperature 70°	XLPE insulation Conductor temperature 90°
Converter unit type	Conductor cross-section (copper)	Conductor cross-section (copper)
ACS880-1607LC-0701A-5	4 × (3 × 150 + 70)	3 × (3 × 150 + 70)
ACS880-1607LC-0901A-5	5 × (3 × 150 + 70)	4 × (3 × 150 + 70)
ACS880-1607LC-1101A-5	6 × (3 × 150 + 70)	5 × (3 × 150 + 70)
ACS880-1607LC-0601A-7	4 × (3 × 120 + 70)	3 × (3 × 120 + 70)
ACS880-1607LC-0801A-7	5 × (3 × 150 + 70)	4 × (3 × 120 + 70)

4-conductor shielded cable	PVC insulation Conductor temperature 70°	XLPE insulation Conductor temperature 90°
Converter unit type	Conductor cross-section (copper)	Conductor cross-section (copper)
ACS880-1607LC-0701A-5	3 × (4 × 95 + 50)	3 × (4 × 70 + 35)
ACS880-1607LC-0901A-5	3 × (4 × 120 + 70)	3 × (4 × 95 + 50)
ACS880-1607LC-1101A-5	3 × (4 × 150 + 70)	3 × (4 × 120 + 70)
ACS880-1607LC-0601A-7	3 × (4 × 70 + 35)	2 × (4 × 95 + 50)
ACS880-1607LC-0801A-7	3 × (4 × 95 + 50)	3 × (4 × 70 + 35)

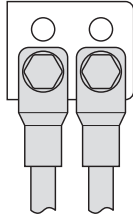
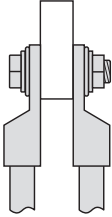
Terminal and cable entry data for the power cables

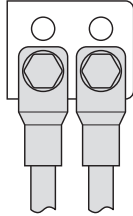
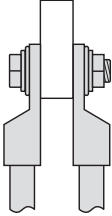
The locations and sizes of the cable entries are shown in the dimension drawings delivered with the drive, and the dimension drawing examples in this manual.

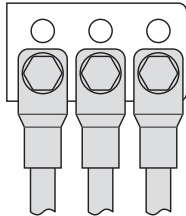
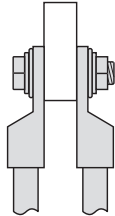
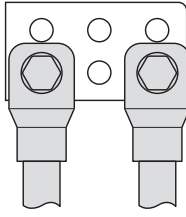
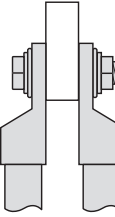
Busbar terminal material: Tin-plated copper.

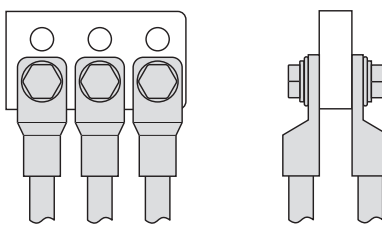
■ Connection capability

Before you select DC cable sizes, check the DC/DC-converter unit construction from the project-specific dimension drawings and use the tables below to determine the connection capability.

Maximum number of conductors for each DC/DC-converter module, n×R7i		
Conductor cross-section (mm²)	Copper compression cable lugs (DIN 46235)	Connection method (example)
50	4	 
70	4	
95	4	
120	4	
150	4	

Maximum number of conductors for each DC/DC-converter module, n×R7i		
Conductor cross-section (mm²)	Aluminum compression cable lugs (DIN 46329)	Connection method (example)
50	4	 
70	4	
95	4	
120	4	
150	4	

Maximum number of conductors for each DC/DC-converter module, n×R8i		
Conductor cross-section (mm²)	Copper compression cable lugs (DIN 46235)	Connection method (example)
50	6	 
70	6	
95	6	
120	6	 
150	4	

Maximum number of conductors for each DC/DC-converter module, n×R8i		
Conductor cross-section (mm ²)	Aluminum compression cable lugs (DIN 46329)	Connection method (example)
50	6	
70	6	
95	6	
120	6	
150	6	

Control accuracy – Current and voltage control performance data

Current control dynamic response	Step response time: typically 10 ms, maximum < 100 ms depending on operating conditions and load step
Current control accuracy (static)	Current error < 1% of the drive nominal current rating For the DC current ripple, refer to the ratings data.
Energy storage voltage control accuracy (static)	Voltage error < 1% of the drive nominal voltage (converter with the optional BAMU voltage/current measurement unit, option +G442) Note: If the converter does not include the BAMU voltage/current measurement unit, the voltage measurement accuracy depends on the customer's measurement device.

Coolant connections

Tube fitting, quick coupler for 16/13 mm polyamide (PA) pipe.

Protection classes

Degrees of protection (IEC/EN 60529)	IP42 (standard), IP54 (option +B055)
Enclosure types (UL50)	UL Type 1 (standard), UL Type 12 (option +B055). For indoor use only.
Arcing class (IEC TR 61641)	B – ASSEMBLY providing personnel and ASSEMBLY protection under arcing conditions. Tested at the following voltage with an arcing current of 65 kA for 300 milliseconds: • 400 V units (indicated by "-4" in drive type): 420 V • 500 V units (indicated by "-5" in drive type): 550 V • 690 V units (indicated by "-7" in drive type): 760 V
Overvoltage category (IEC/EN 60664-1)	III, except for auxiliary power connections (fan, control, heating, lighting, cooling unit pump etc.) which are category II.
Protective class (IEC/EN 61800-5-1)	I

Energy efficiency data (ecodesign)

Energy efficiency data is not provided for the drive/unit. Multidrive and multidrive modules are not in the scope of the EU ecodesign requirements (Regulation EU/2019/1781) or the UK ecodesign requirements (Regulation SI 2021 No. 745).

Ambient conditions

Environmental limits for the drive are given below. The drive is to be used in a heated, indoor, controlled environment.

	Operation installed for stationary use	Storage in the protective pack- age	Transportation in the protective pack- age
Installation site altitude	0...2000 m (0...6562 ft) above sea level. For alti- tudes over 2000 m, con- tact ABB. Output derated above 1000 m (3281 ft).	-	-
Air temperature	0 ... +45 °C (+32 ... +113 °F), no con- densation allowed. Out- put derated in the range +45 ... +55 °C (+113 ... +131 °F).	-40 ... +70 °C (-40 ... +158 °F)	-40 ... +70 °C (-40 ... +158 °F)
Relative humidity	Max. 95%	Max. 95%	Max. 95%
	No condensation allowed. Maximum allowed relative humidity is 60% in the presence of corrosive gases.		
Contamination	IEC/EN 60721-3-3:2002 Chemical gases: Class 3C2 Solid particles: Class 3S2. No conductive dust al- lowed.	IEC 60721-3-1:1997 Chemical gases: Class 1C2 Solid particles: Class 1S3 (packing must support this, otherwise 1S2)	IEC 60721-3-2:1997 Chemical gases: Class 2C2 Solid particles: Class 2S2
Pollution degree IEC/EN 60664-1	2		
Vibration IEC/EN 61800-5-1 IEC 60068-2-6:2007, EN 60068-2-6:2008	10...57 Hz: max. 0.075 mm amplitude 57...150 Hz: 1 g Units with marine con- struction (option +C121): Max. 1 mm (0.04 in) (5 ... 13.2 Hz), max. 0.7 g (13.2 ... 100 Hz) sinusoid- al	10...57 Hz: max. 0.075 mm amplitude 57...150 Hz: 1 g	2...9 Hz: max. 3.5 mm amplitude 9...200 Hz: 10 m/s ² (32.8 ft/s ²)
Shock IEC 60068-2-27:2008, EN 60068-2-27:2009	Not allowed	With packing max. 100 m/s ² (328 ft/s ²) 11 ms	With packing max. 100 m/s ² (328 ft/s ²) 11 ms

Colors

RAL 7035, RAL 9017.

Materials

■ Drive

Refer to [ACS880 cabinet-installed drives Recycling instructions and environmental information \(3AXD50000153909 \[English\]\)](#).

■ Packaging of drive

- Plywood¹⁾
- Wood
- PET (strapping)
- PE (VCI film)
- Metal (fixing clamps, screws)
- VCI emitter capsules
- Clay desiccant.

¹⁾ Seaworthy package only

■ Packaging of options

- Cardboard
- Kraft paper
- PP (straps)
- PE (film, bubble wrap)
- Plywood, wood (only for heavy components)

The materials vary by item type, size, and shape. The typical package is a cardboard box with paper filling or bubble wrap. ESD-safe packaging is used for printed circuit boards and similar items.

■ Manuals

Printed product manuals are made of recyclable paper.

Disposal

The main parts of the product can be recycled to preserve natural resources and energy. Product parts and materials should be dismantled and separated.

In general, all metals, such as steel, aluminum, copper, and its alloys, and precious metals can be recycled. Plastics, rubber, cardboard, and other packaging materials can be used in energy recovery.

Printed circuit boards and DC capacitors require selective treatment according to IEC 62635 guidelines.

To aid recycling, most plastic parts are marked with an appropriate identification code. Components that contain Substances of Very High Concern (SVHCs) are listed in the European Chemicals Agency SCIP database. SCIP is the database for information on Substances of Concern in articles as such or in complex objects (products) established under the Waste Framework Directive (2008/98/EC). For more information, contact your local ABB distributor or consult the European Chemicals Agency SCIP database to determine which SVHCs are used in the product and where the components are located.

Contact your local ABB distributor for more information on environmental aspects. End-of-life treatment must obey international and national regulations.

For more information on ABB end-of-life services, refer to new.abb.com/service/end-of-life-services.

Applicable standards

Refer to [ACS880 liquid-cooled multidrives modules electrical planning \(3AXD50000048634 \[English\]\)](#).

Markings

Refer to [ACS880 liquid-cooled multidrives modules electrical planning \(3AXD50000048634 \[English\]\)](#).

Disclaimers

■ Generic disclaimer

The manufacturer shall have no obligation with respect to any product which (i) has been improperly repaired or altered; (ii) has been subjected to misuse, negligence or accident; (iii) has been used in a manner contrary to the manufacturer's instructions; or (iv) has failed as a result of ordinary wear and tear.

■ Cyber security disclaimer

This product is designed to be connected to and to communicate information and data via a network interface. It is the Customer's sole responsibility to provide and continuously ensure a secure connection between the product and the Customer network or any other network (as the case may be). The Customer shall establish and maintain any appropriate measures (such as but not limited to the installation of firewalls, application of authentication measures, encryption of data, installation of anti-virus programs, etc.) to protect the product, the network, its system and the interface against any kind of security breaches, unauthorized access, interference, intrusion, leakage and/or theft of data or information.

ABB and its affiliates are not liable for damages and/or losses related to such security breaches, any unauthorized access, interference, intrusion, leakage and/or theft of data or information.

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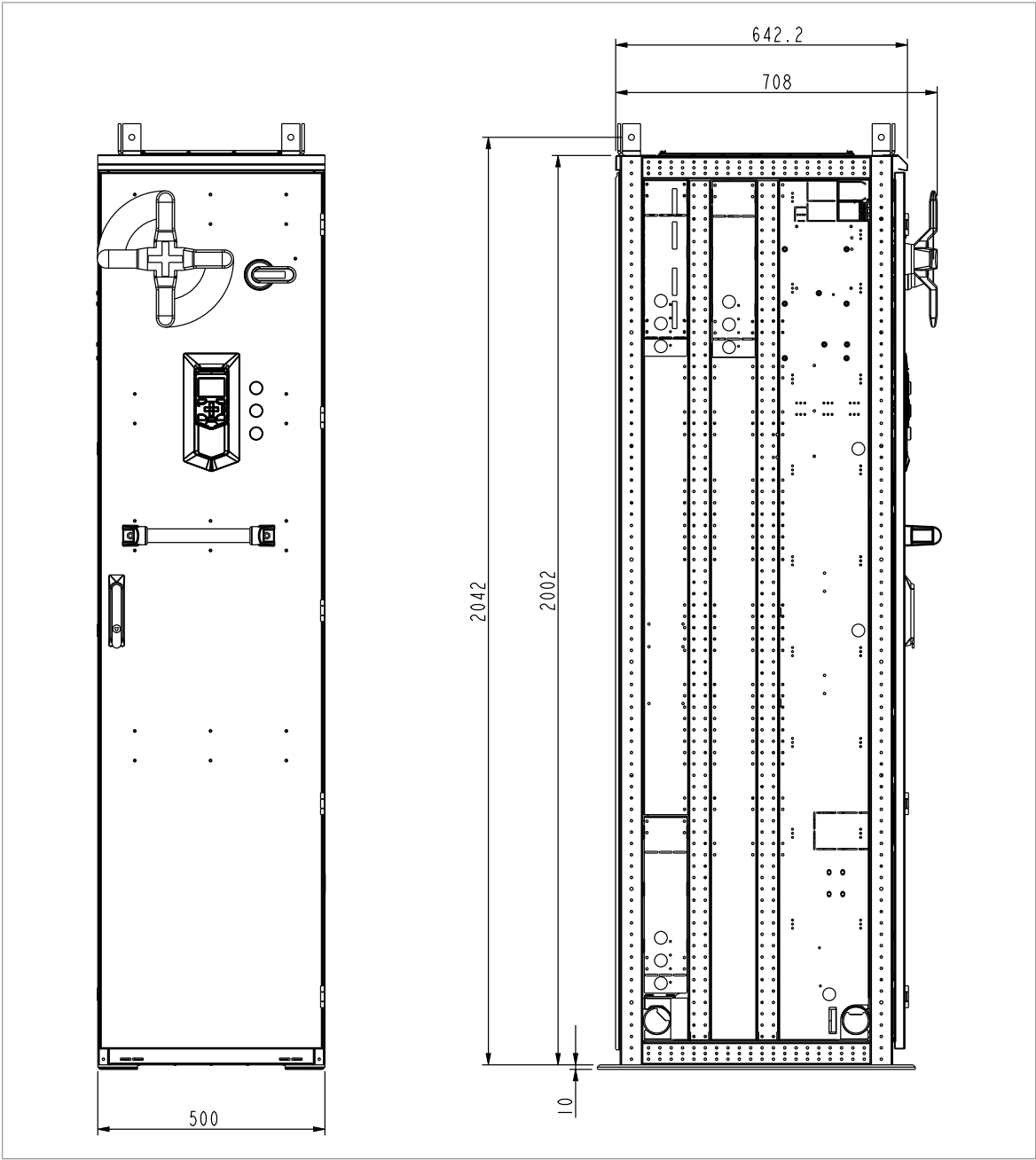
Dimension drawings

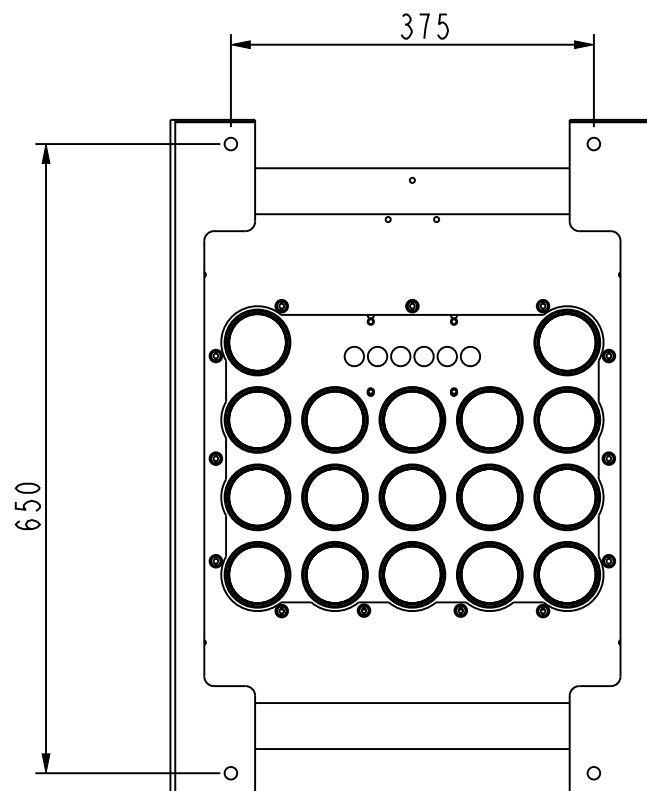
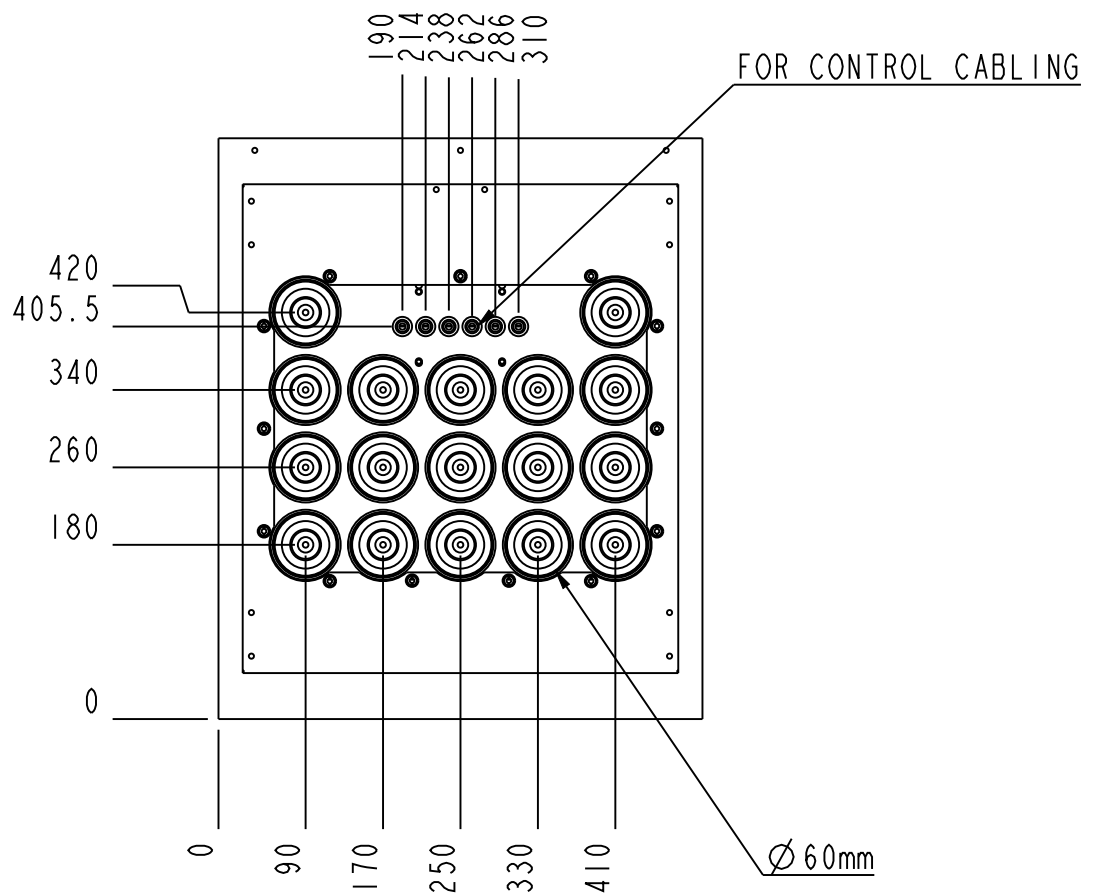
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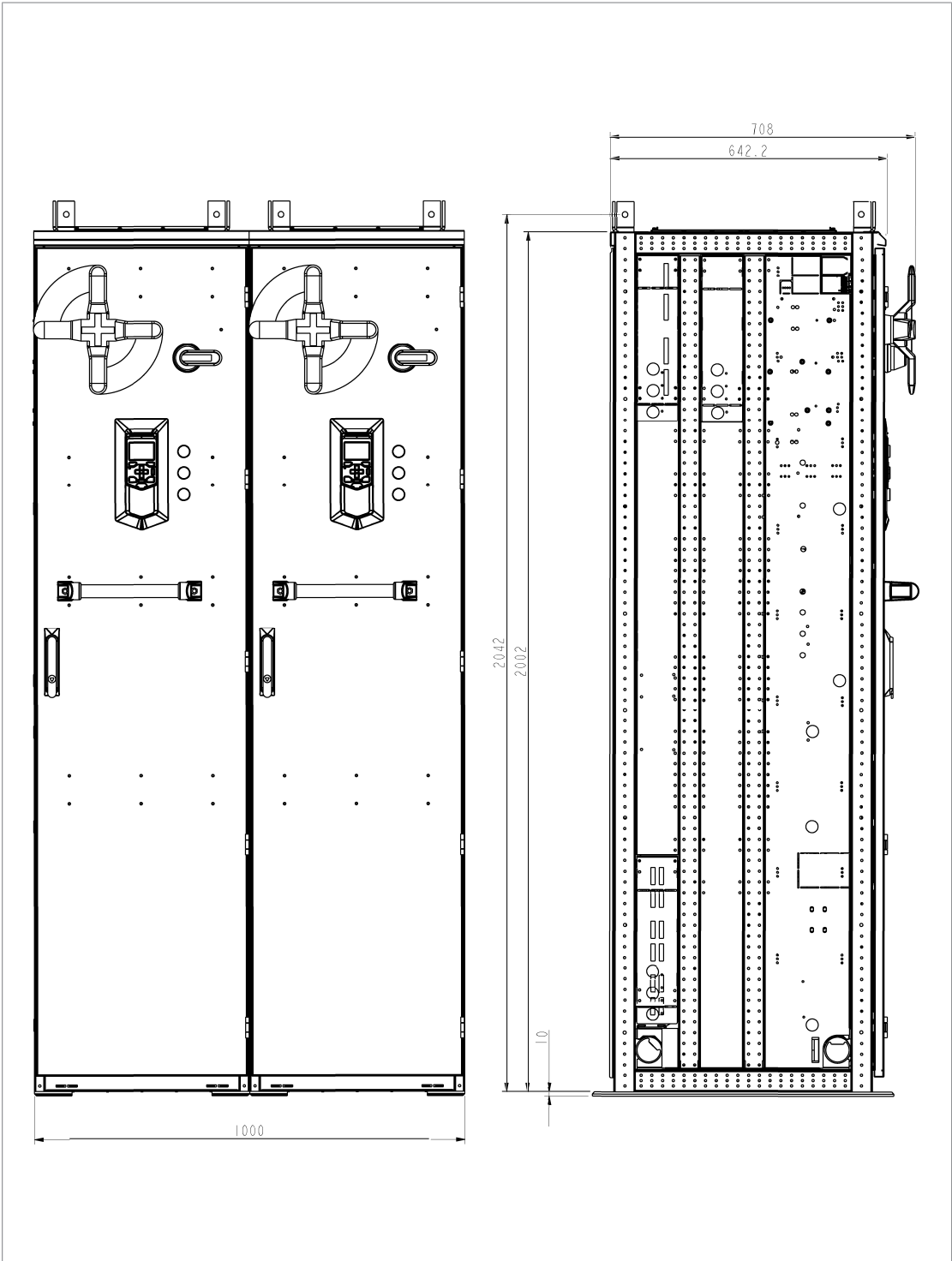
- Dimension drawings of DC/DC converter unit
- Location and size of output terminals for energy storage cables

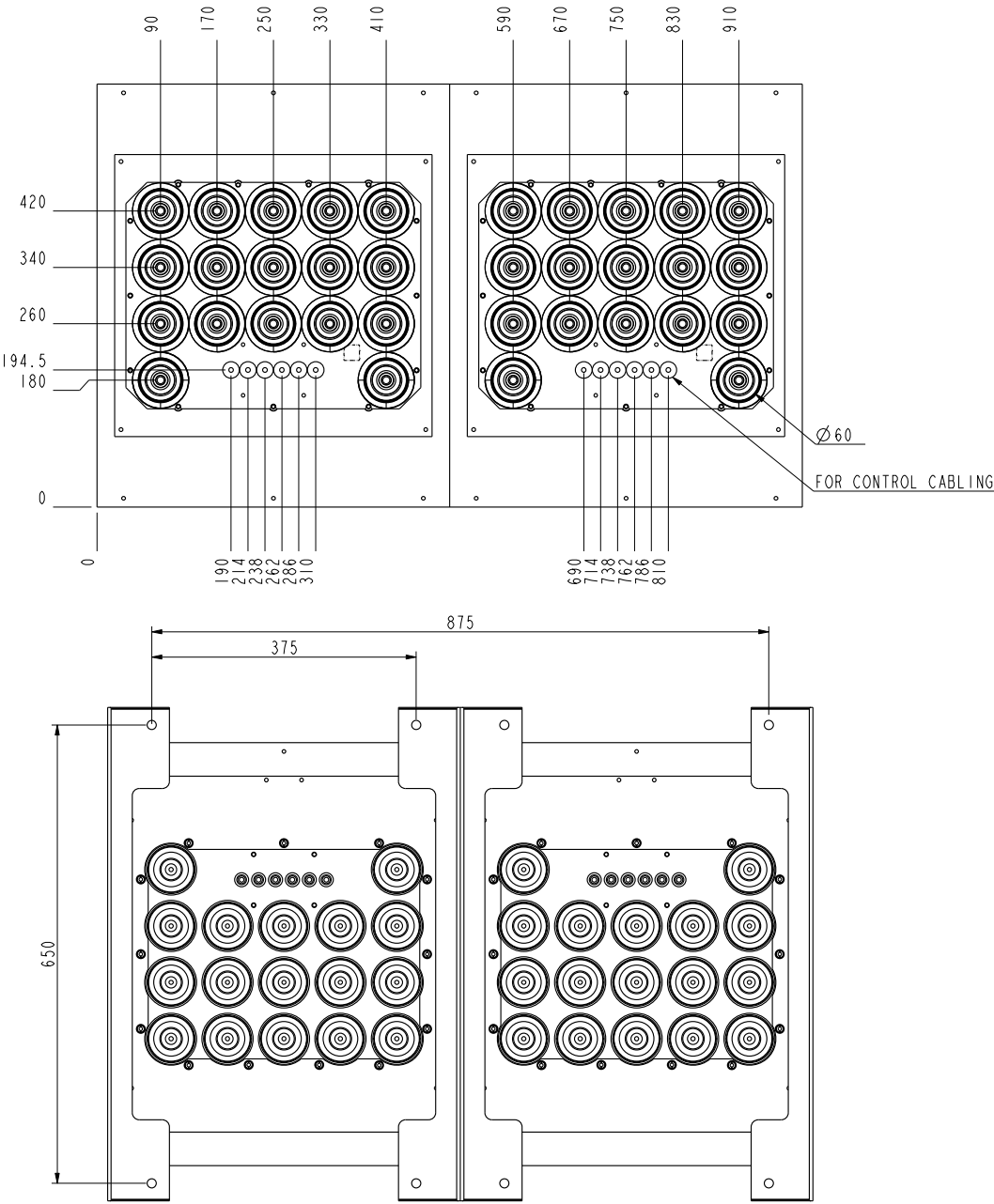
DC/DC-converter unit with 1×R7i converter module



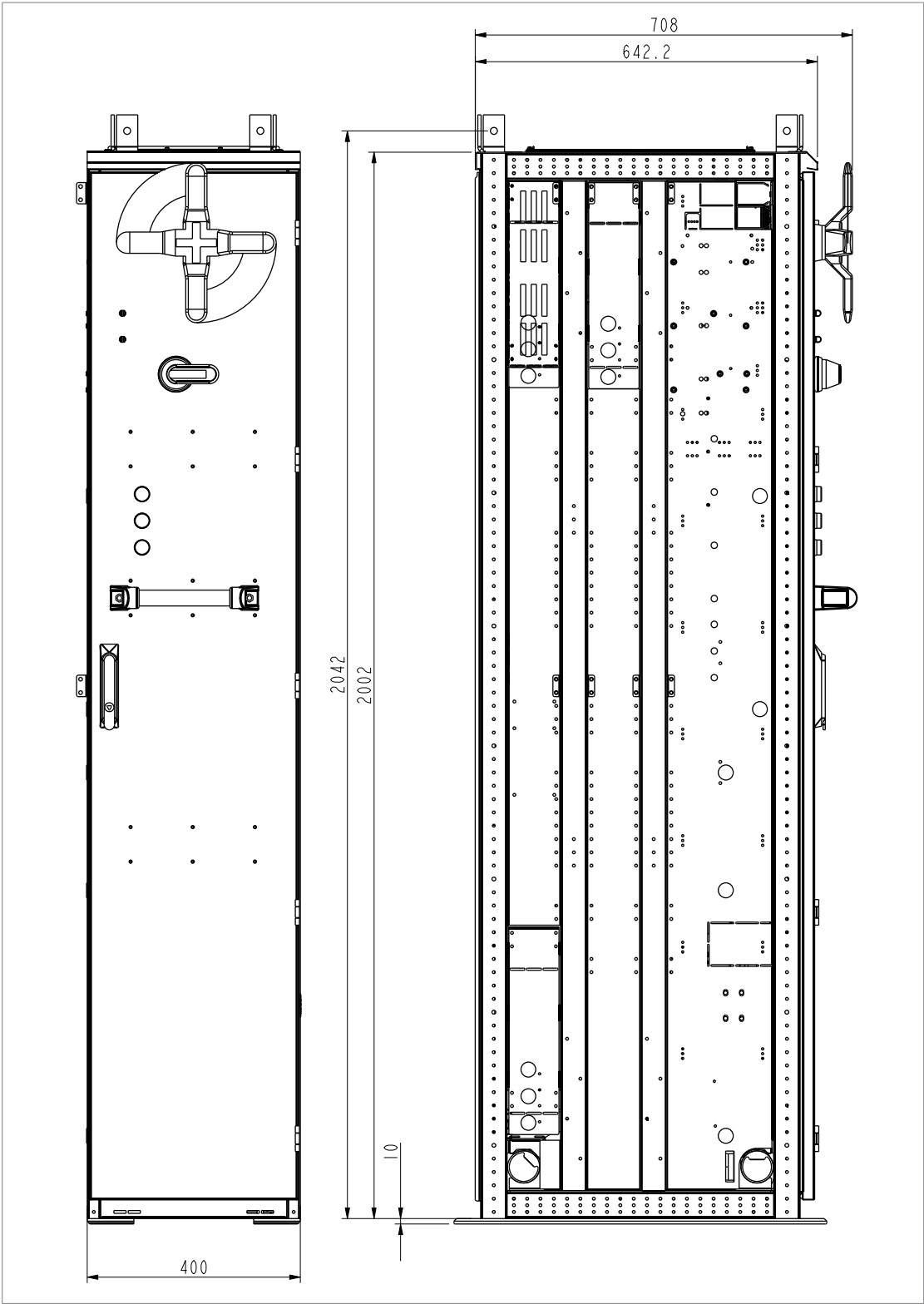


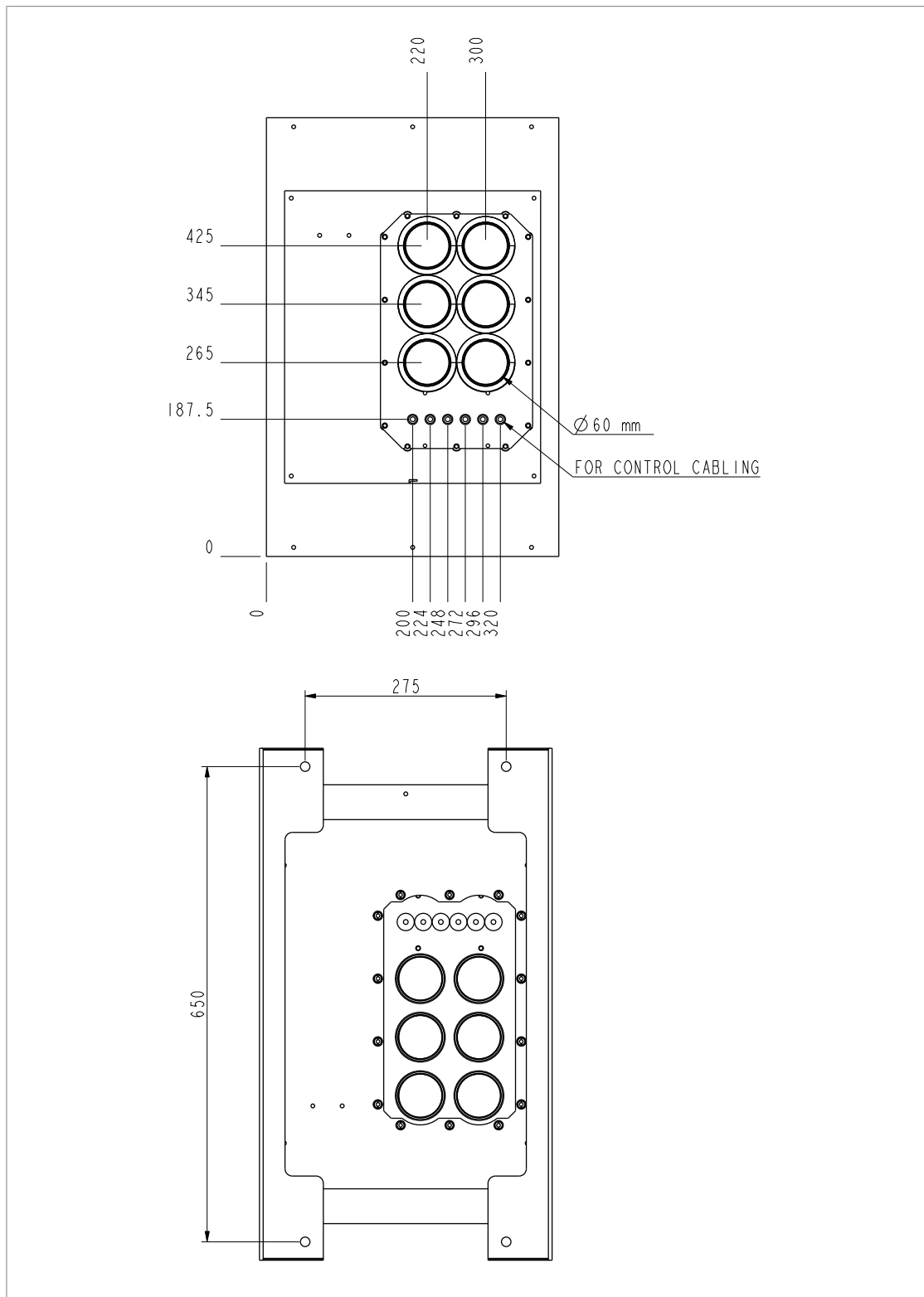
DC/DC-converter unit with 2×R7i in two cubicles converter module



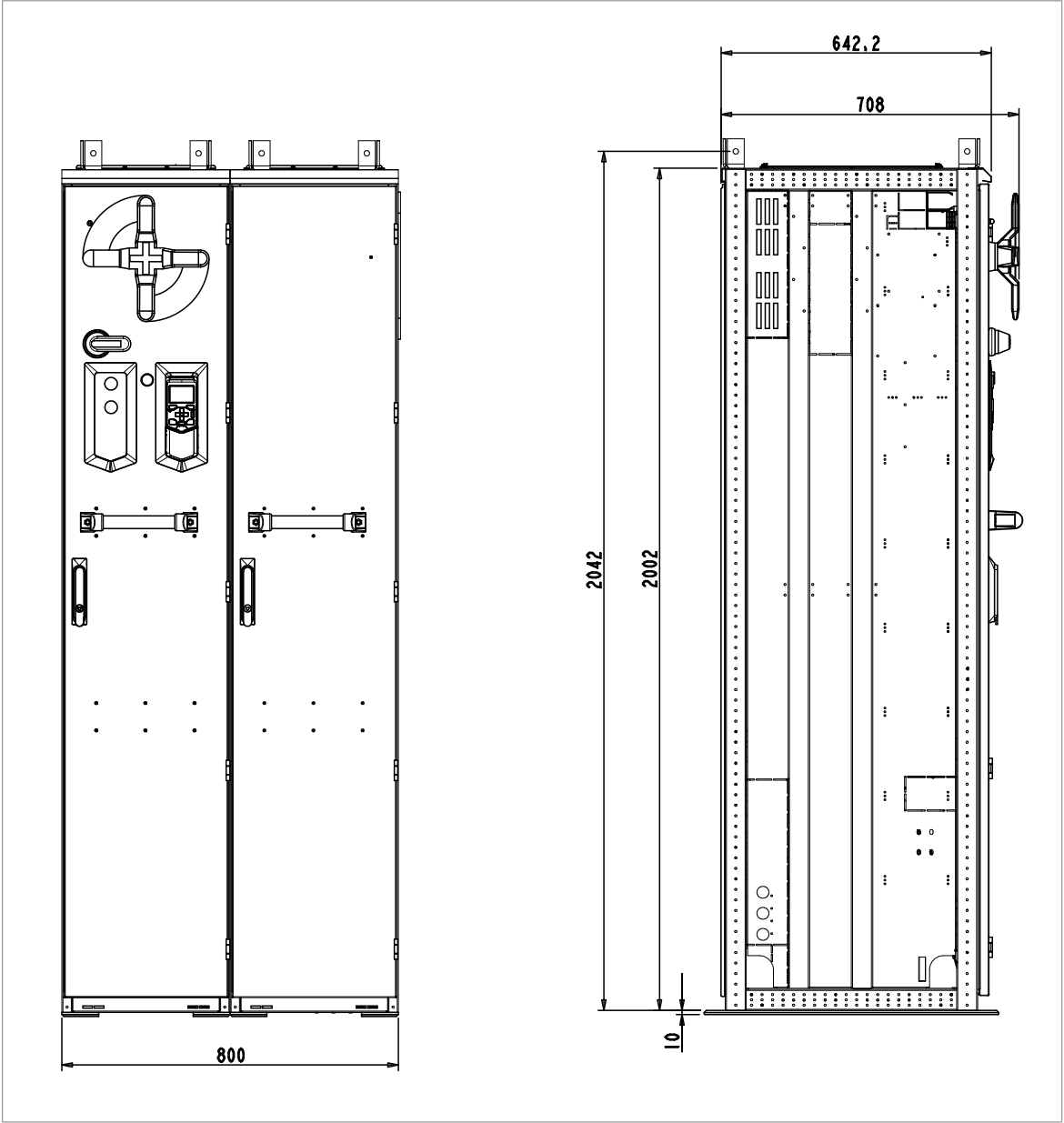


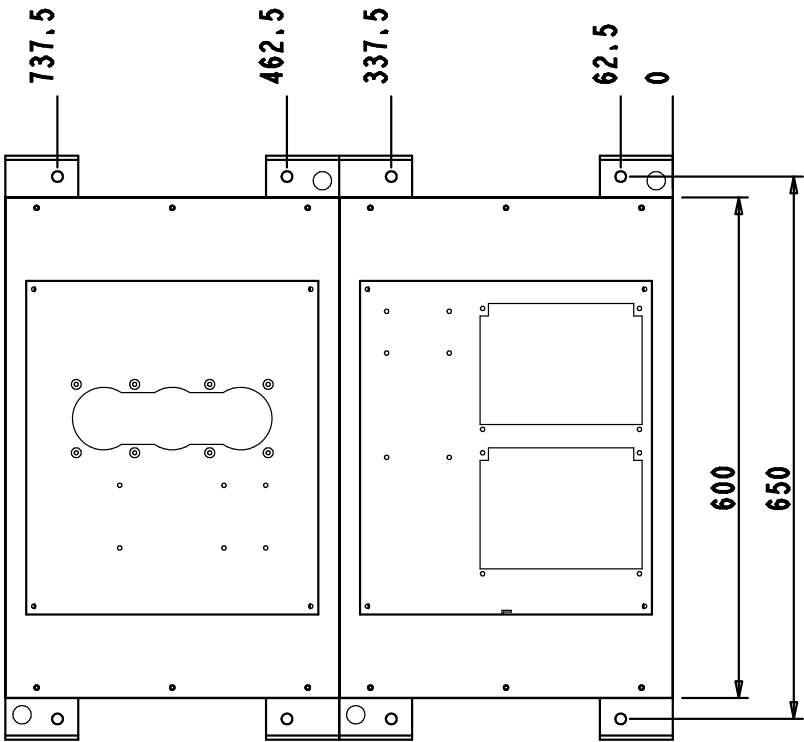
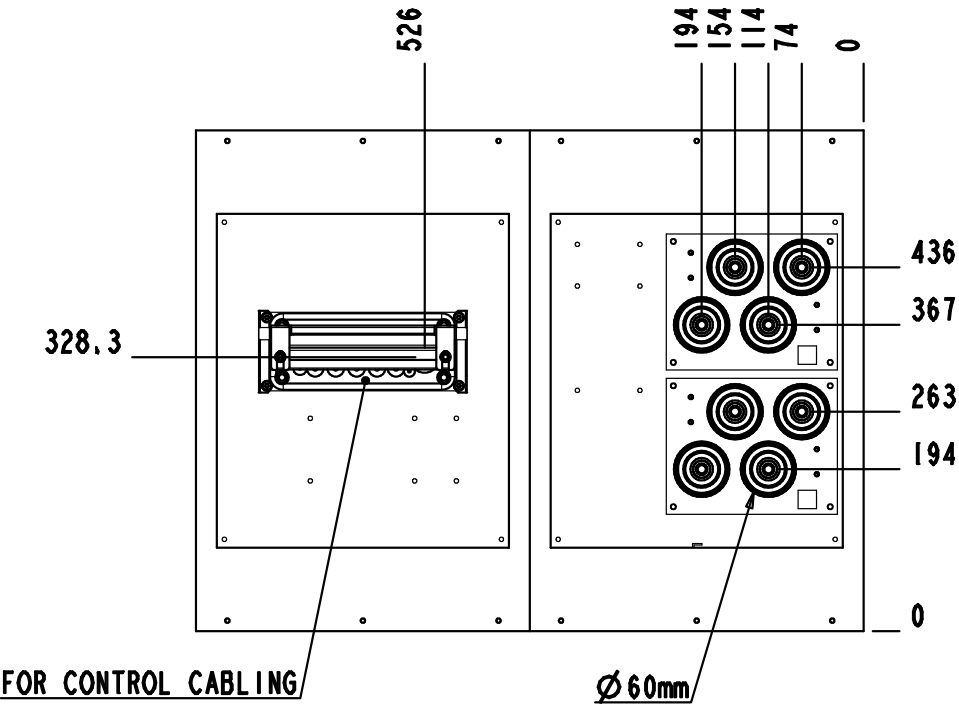
DC/DC-converter unit with 2×R7i in one cubicle converter module



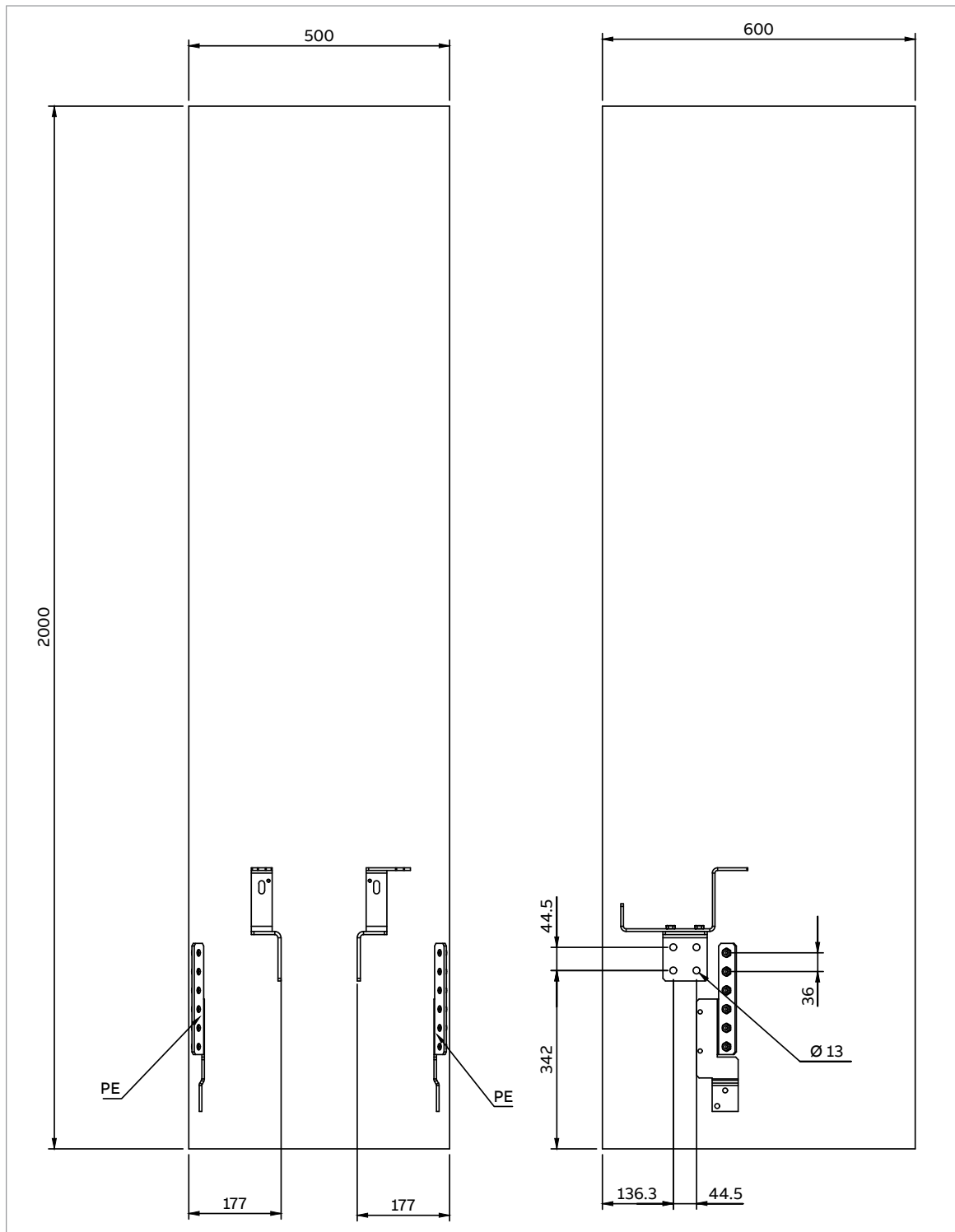


DC/DC-converter unit with 1×R8i converter module

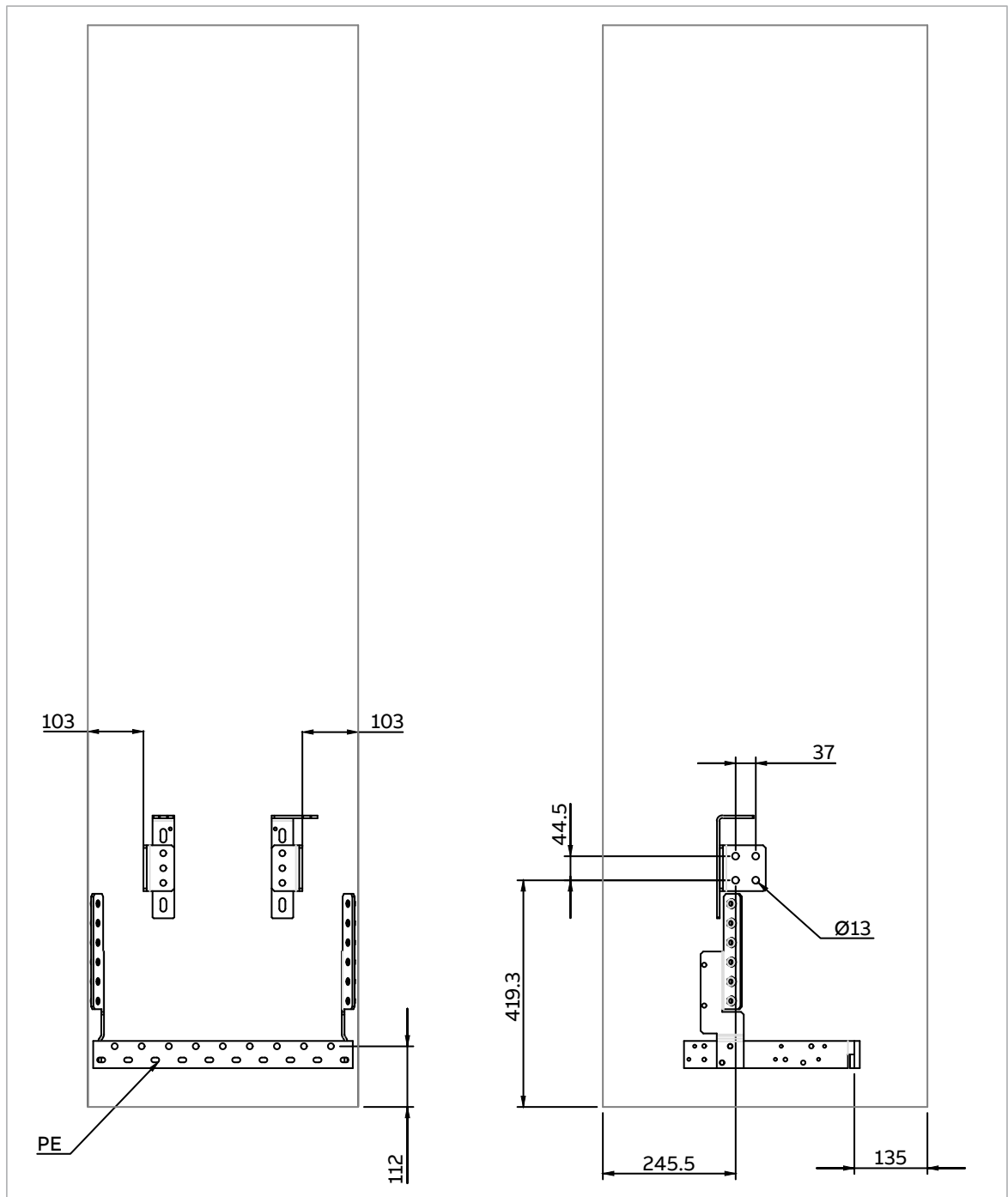




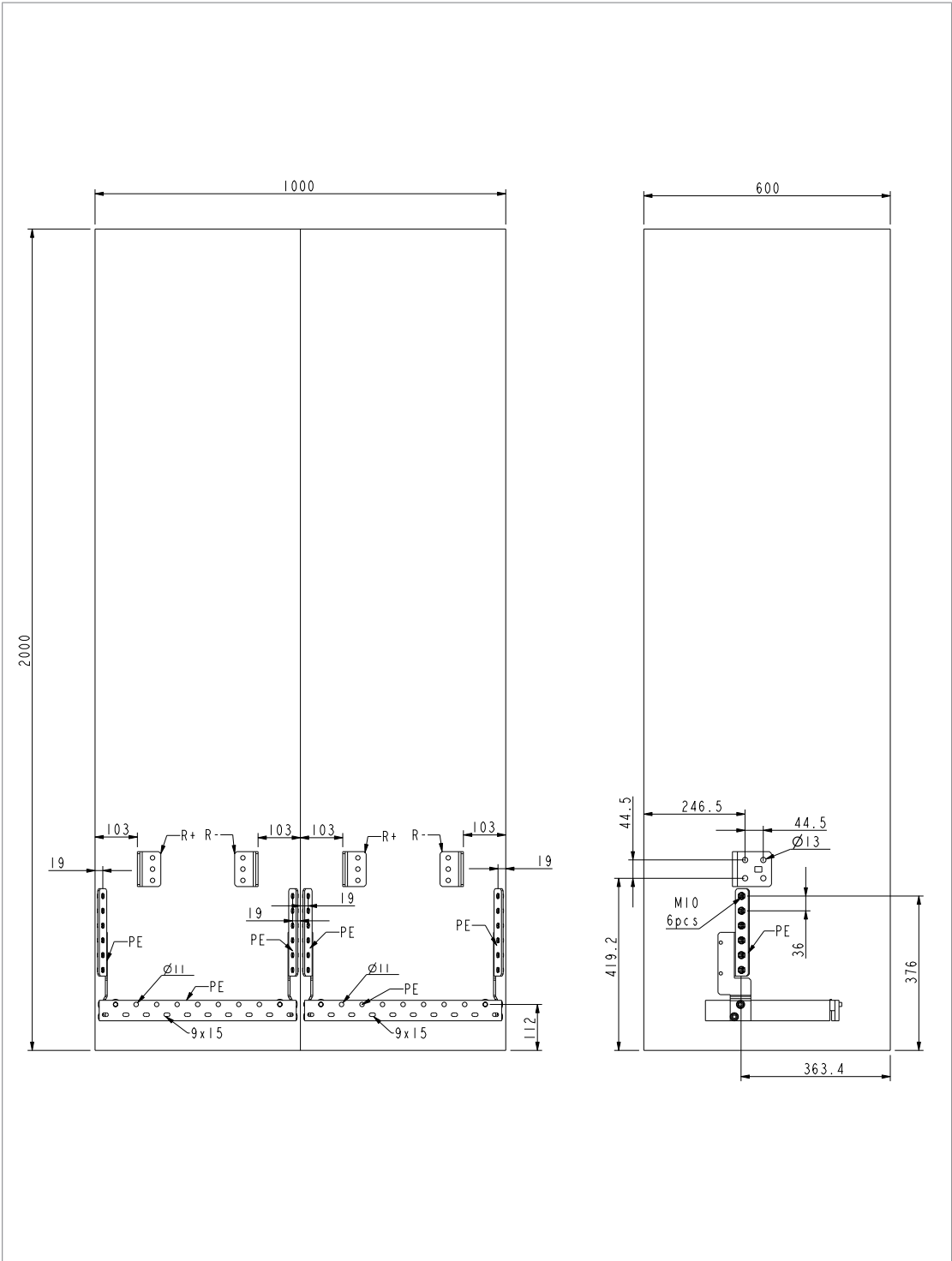
Location and size of energy storage connection terminals (frame R7i with top cable entry)



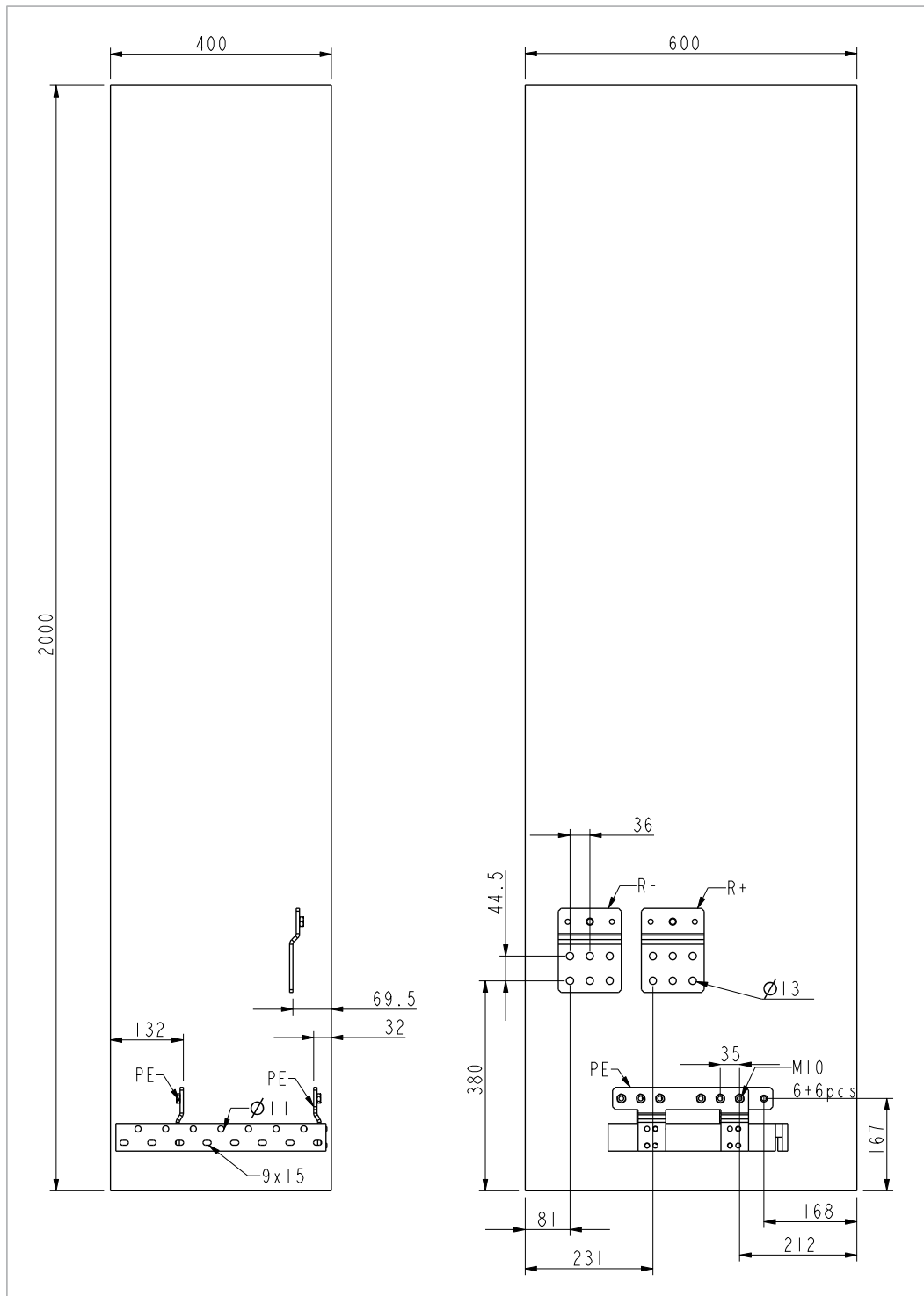
Location and size of energy storage connection terminals (frame R7i with bottom cable entry)



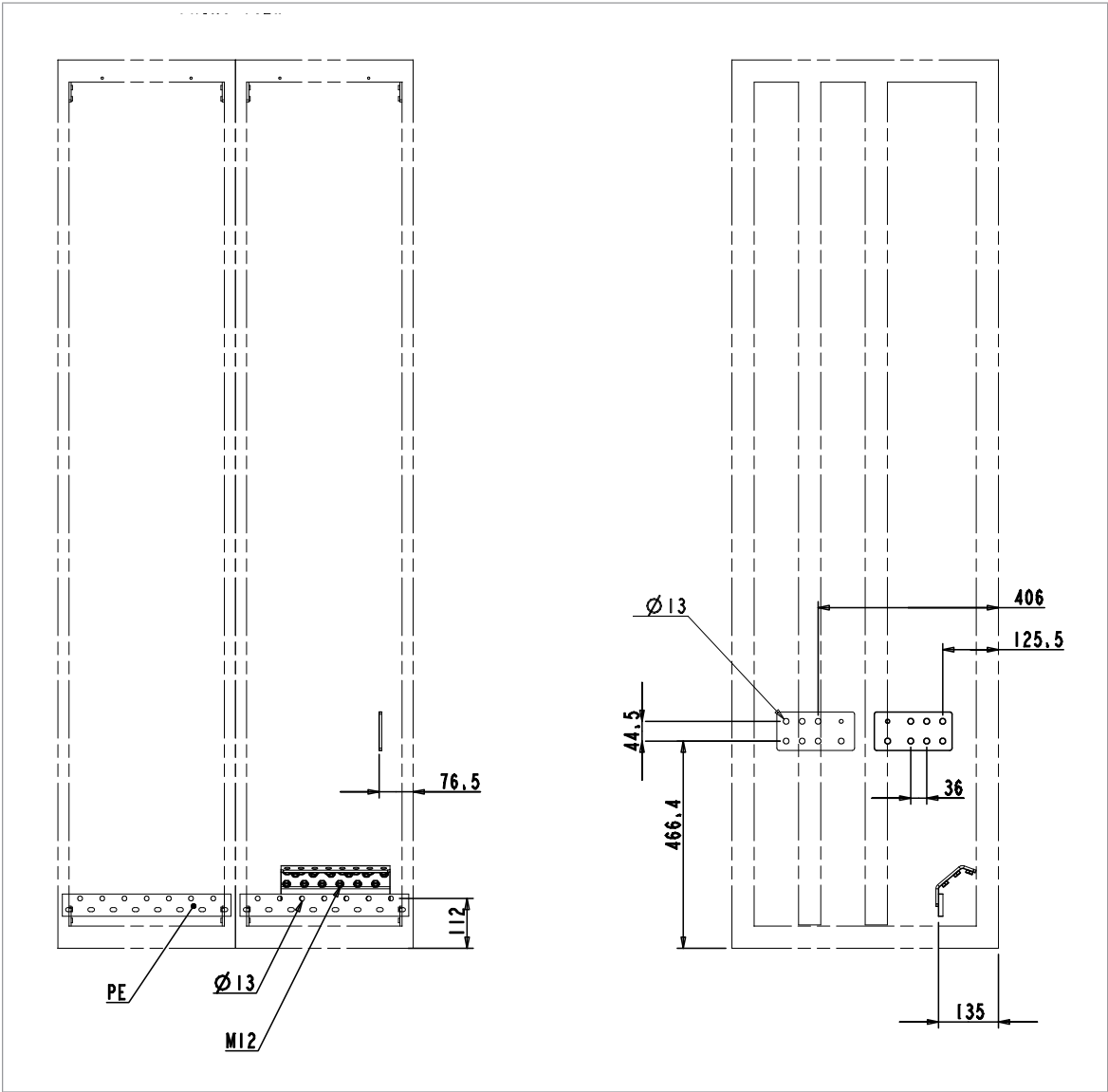
**Location and size of energy storage connection terminals
(frame 2×R7i in two cubicles)**



Location and size of energy storage connection terminals (frame 2×R7i in one cubicle)



Location and size of energy storage connection terminals
(frame R8i)



Further information

Product and service inquiries

Address any inquiries about the product to your local ABB representative, quoting the type designation and serial number of the unit in question. A listing of ABB sales, support and service contacts can be found by navigating to new.abb.com/contact-centers.

Product training

For information on ABB product training, navigate to new.abb.com/service/training.

Providing feedback on ABB manuals

Your comments on our manuals are welcome. Navigate to forms.abb.com/form-26567.

Document library on the Internet

You can find manuals and other product documents in PDF format on the Internet at www.abb.com/drives/documents.



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