Original instructions

**JSNY9**
Safety interlock switch
Read and understand this document

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1 Introduction

Scope
The purpose of these instructions is to describe the safety interlock switch JSNY9 and to provide the necessary information required for installation and operation.

Audience
This document is intended for authorized installation personnel.

Prerequisites
It is assumed that the reader of this document has knowledge of the following:
- Basic knowledge of ABB/Jokab Safety products.
- Knowledge of safety devices and safety locks.
- Knowledge of machine safety.

Special notes
Pay attention to the following special notes in the document:

⚠️ Warning! An instruction or procedure which, if not carried out correctly, may result in injury to the technician or other personnel.

⚠️ Caution! Danger of damage to the equipment! An instruction or procedure which, if not carried out correctly, may damage the equipment.

NB: Notes are used to provide important or explanatory information.
2 Overview

General description

JSNY9 is a safety interlock switch with a locking function. The switch can only be actuated using a corresponding triple coded actuator and can be mounted in any direction (the switch head can be rotated 4x90 degrees). The actuation direction can be either linear or radial by using a specific actuator. The switch head can also be flipped upwards which allows both horizontal and vertical actuation directions. The holding force is 1500 N.

Additionally, the JSNY9 is tamper-proof (the switch cannot be actuated with screwdrivers, magnets or other tools).

The switch is well suited to lock a door or hatch to prevent access to machines:

- When the machine perform tasks that are not allowed to be stopped during the process, e.g. welding
- When the machine have long stopping time, e.g. paper machines with a long brake process
- To keep unauthorized persons away from a certain area

NB: To reach a high safety level when connected to the machine control system, it is recommended to use an ABB/Jokab Safety safety relay, Pluto safety-PLC or a Vital safety module with a Tina adaptor unit.

⚠️ Warning! In order to maintain the safety level the actuator may only be procured and used as an integral part of the associated safety switch.

Safety regulations

⚠️ Warning! Carefully read through this entire manual before using the device.

The devices shall be installed by a trained electrician following the Safety regulations, standards and the Machine directive.

Failure to comply with instructions, operation that is not in accordance with the use prescribed in these instructions, improper installation or handling of the device can affect the safety of people and the plant.

For installation and prescribed use of the product, the special notes in the instructions must be carefully observed and the technical standards relevant to the application must be considered.

In case of failure to comply with the instructions or standards, especially when tampering with and/or modifying the product, any liability is excluded.
Function description

JSNY9 has 2 pairs (1NC + 1NO) contacts; the first pair change states when the actuator is inserted into the switch, and the second pair change states when the locking mechanism is in its locked position. The locking device is controlled through terminals E1-E2, and locking/unlocking characteristics is depending on the model.

There are two main models of the JSNY9, one with spring interlocking (JSNY9S) and one with solenoid interlocking (JSNY9M).

**Spring interlocking (JSNY9S)**

Spring interlocking (constant current circuit) means that the unit is locked as soon as the actuator is inserted into the switch, and power must be supplied to E1-E2 to unlock the device.

**Solenoid interlocking (JSNY9M)**

Solenoid interlocking (open circuit principle) means that power must be supplied to E1-E2 to lock the unit. This unlocks the door at power failure.
3 Connections

JSNY9 electrical connections

Contacts description:
Normal state when protection is active, i.e. when the actuator is inserted into the switch and the device is locked.

13-14  NO-contact. Closed when actuator is withdrawn.
21-22  NC-contact. Opened when actuator is withdrawn.
E1-E2  Power for locking (M-type) / unlocking (S-type)
31-32  NC-contact. Opened when JSNY9 is unlocked.
43-44  NO-contact. Closed when JSNY9 is unlocked.

By design, locking is not possible unless the actuator is fully inserted into the actuator head. The contacts used to monitor the locking can therefore also be used to monitor the actuator position. The two NC-contacts (positive-opening NC) should be used to achieve the electrical dual-channel connection for the safety function.
Connection examples

Connection example: JSNY9S connected to safety relay RT6, actuator inserted and locked

A) Interlocking safety switch with manual reset and supervising of external relay contacts

* Closing contact unlocks type S, opening contact unlocks type M. Lost motion control or timer should be used if the danger is not removed immediately after shut-off.

B) with automatic reset

Mains contactor / Motor drive

Information PLC

Supervising contactors

Test / Auto reset
System description / Application example

While the machine is running the movable guard is closed. The separate actuator is nested in the head of the safety switch. In this state the safety outputs are closed and unlocking is disabled. In case of e.g. maintenance the operator will need to gear into the machine behind the movable guard. In this case the operator will stop the machine first. The safety switch will keep the actuator locked until the dangerous machine has come to a safe stop. This can be achieved by using a suitable control device, such as a timer or lost motion detector. When the machine is stopped, unlocking is enabled. An unlock command (power supplied or power cut off, depending on type), will unlock the actuator and open the safety circuit. The safety relay will fall, and the machine cannot be started. The movable guard can now be opened. The positive-opening NC contacts should be used in the safety circuit and the auxiliary contacts can be used for signals or as a complement in the safety circuit to the safety relay, to achieve certain functions.

The contacts for monitoring the position of the actuator are operated directly by the actuator in order to register the position of the guard directly. The contacts for monitoring the locking function are directly connected with the locking bolt. A failure of the locking function can be detected by the safety relay. The design of the locking is of such a kind that the locking cannot be activated unless the actuator is completely inserted into the head of the safety switch. Thus the contacts for monitoring the locking function can also be used to monitor the position of the movable guard. The possibility to monitor both contacts (movable guard and locking function) separately leads to a dual channel mode.
4 Installation and maintenance

JSNY9 is easily fitted on the ABB/Jokab Safety Quick-Guard fencing system using special brackets found in the “Accessory”-section below.

The actuation direction can be chosen either linear or curved, using the appropriate actuator.

Actuators and installation

- **Standard actuator**
  - For sliding doors and hinged doors with actuating radius >400 mm.
  - Head position: 0°, 90°, 180°, 270°.
  - NB: Washers for M4 with outer diameter Ø12 mm MUST be used to achieve form-locking!

- **Universal actuator**
  - For hinged doors with actuating radius >150 mm
  - Head position: 0°, 90°, 180°, 270°.
  - NB: Fixing holes Ø 5.5 mm symmetric in position with X- or Z-axis.

**Actuator mounting**

- 2 x M5 DIN 912 or EN ISO 1207
- \( M_{\text{max}} = 4 \, \text{Nm} \)

**Universal actuator pre-adjustment**

- When using the flexible (universal) actuator, proper pre-adjustment of the actuator using the internal hexagon screws are necessary to avoid unnecessary shearing forces on the actuator.

Align the actuator with the machine guard so that opening or closing the machine guard does not apply lateral force to the actuator head. Verify by opening and closing the guards several times.
Actuator head direction

Actuator head rotation

Horizontal directions

Vertical directions
Securing the actuator head

Warning!

To prevent manipulation of the actuator head the pre-fitted torx/slot-head screw should be replaced with the supplied tamper-proof screw.

Exceeding the specified torque of 0.9 Nm or an actuator assembly which causes objectionable forces in the cross plane will result in damage to the actuating parts of the switch gear. This will lead to the loss of the safety function and thus can lead to severe or even fatal accidents to the operator.

Make sure that the head is properly attached to the switch body. A misaligned or loose head can lead to loss of the safety function.

Vibrations and other forces acting on the security screw might cause the screw to loosen over time, which will lead to the loss of the safety function. At regular intervals, make sure the security screw is tightened correctly.
Cable installation

To install a cable gland in the M20 threaded connector:
Release the snap-shut terminal lid with a screwdriver and screw the cable gland into the chosen entry. This will “break-out” the blind hole; remove the plastic disk when detached.

To connect wires to the terminal block:

1) Insert screwdriver (blade width 2.5 mm) in lower opening.
2) Turn 45 degrees according to figure.
3) Insert wire (0.5 – 1.5 mm² cross-section) in upper opening. Release the screwdriver and pull the wire to make sure it is properly connected.

Auxiliary release (JSNY9S only)

1) Loosen the security screw.
2) To unlock, rotate internal hexagon screw 90°.
   The actuator can now be pulled out.
   To return to safe state, rotate the internal hexagon screw backwards.
3) Tighten the security screw and seal with lacquer.

⚠️ Warning!
Auxiliary release shall only be operated during installation or in case of failure of the normal “Power to unlock”. Auxiliary release shall be sealed with lacquer after completed installation of the safety switch.
Installation precautions

- The safety switch may not be used as a mechanical stop!
- Make sure that the head is properly attached to the switch body. A misaligned or loose head can lead to loss of the safety function.
- The device must be mounted on a plane surface.
- Secure the screws against self-loosening.

⚠️ Warning! All the safety functions must be tested before starting up the system.

Maintenance

⚠️ Warning!

It is very important that the security screw holding the actuator head in place is checked regularly for self-loosening, and is retightened correctly if necessary. Do not over-tighten the screw as it will cause damage to the actuating parts of the switch gear.

The safety functions and the mechanics shall be tested regularly, at least once every year to confirm that all the safety functions are working properly (EN 62061:2005).

In order to maintain the safety level, regular inspections for tear and wear, as well as fixing and alignment of switch, actuator, brackets, doors etc should be carried out.

In case of breakdown or damage to the product, contact the nearest ABB/Jokab Safety Service Office or reseller. Do not try to repair the product yourself since it may accidentally cause permanent damage to the product, impairing the safety of the device which in turn could lead to serious injury to personnel.
5 Operation

JSNY9 S-types

Spring to lock
JSNY9 S-types “spring to lock”, i.e. the device is locked as soon as the actuator is inserted into the actuator head. By design, the locking cannot be activated unless the actuator is completely inserted into the actuator head.

Power to release
JSNY9 S-types require "power to release", i.e. the device requires power supplied to E1-E2 in order to unlock the actuator when inserted into the actuator head.

Contact states
The internal contacts (2 pairs of 1 NC + 1 NC, “normal” state when machine is allowed to run) switch states when the actuator is inserted and when the device is locked. The first pair switches states as soon as the actuator is inserted into the actuator head, and the second pair switch states when the device is locked, i.e. when no power is supplied to E1-E2. Since the locking cannot be activated unless the actuator is completely inserted into the actuator head, the contacts used to monitor the locking can also be used to monitor the position of the movable guard.

JSNY9 M-types

Power to lock
JSNY9 M-types require “power to lock”, i.e. the device requires power supplied to E1-E2 in order to lock the device after the actuator has been inserted into the actuator head. By design, the locking cannot be activated unless the actuator is completely inserted into the actuator head.

Spring to release
JSNY9 M-types “spring to release”, i.e. the device unlocks as soon as the power to E1-E2 is cut off.

Contact states
The internal contacts (2 pairs of 1 NC + 1 NC, “normal” state when machine is allowed to run) switch states when the actuator is inserted and when the devices is locked. The first pair switches states as soon as the actuator is inserted into the actuator head, and the second pair switch states when the device is locked, i.e. when power is supplied to E1-E2. Since the locking cannot be activated unless the actuator is completely inserted into the actuator head, the contacts used to monitor the locking can also be used to monitor the position of the movable guard.
## Model overview

<table>
<thead>
<tr>
<th>Type</th>
<th>Article number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>JSNY9S 24 VUC</td>
<td>2TLJ020036R4400</td>
<td>JSNY9 safety switch with spring locking (power to lock), 24 V DC/AC.</td>
</tr>
<tr>
<td>JSNY9M 24 VUC</td>
<td>2TLJ020036R4500</td>
<td>JSNY9 safety switch with solenoid locking (power to unlock), 24 V DC/AC.</td>
</tr>
</tbody>
</table>

### Accessories

Note that all brackets come with nuts and screws for use with ABB/Jokab Safety Quick-Guard fencing system. For further information, contact your local ABB/Jokab Safety sales office.

<table>
<thead>
<tr>
<th>Type</th>
<th>Article number</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spare part</td>
<td>2TLJ020033R0300</td>
<td>Lid packing for JSNY9.</td>
</tr>
<tr>
<td>Spare part</td>
<td>2TLJ020033R0400</td>
<td>Security screw for JSNY9 head. PTS 3x16 one-way screw.</td>
</tr>
<tr>
<td>JSM D4F</td>
<td>2TLJ040033R3000</td>
<td>Brackets for sliding door.</td>
</tr>
<tr>
<td>JSM D4C</td>
<td>2TLJ040033R1600</td>
<td>Brackets for hinged door.</td>
</tr>
<tr>
<td>JSNY8/9N1</td>
<td>2TLJ020032R0400</td>
<td>Standard actuator for JSNY8/9. Fixed, for actuating radius &gt;400 mm.</td>
</tr>
<tr>
<td>JSNY8/9N2</td>
<td>2TLJ020032R0500</td>
<td>Universal actuator for JSNY8/9. Flexible, for actuating radius &gt;150 mm.</td>
</tr>
</tbody>
</table>

![Brackets for hinged door](image1.png)

**JSM D4C**
- Brackets for hinged door
- Article number: 2TLJ040033R1600

![Brackets for sliding door](image2.png)

**JSM D4F**
- Brackets for sliding door
- Article number: 2TLJ040033R3000

![Standard actuator](image3.png)

**JSNY8/9N1**
- Standard actuator
- Article number: 2TLJ020032R0400

![Universal actuator](image4.png)

**JSNY8/9N2**
- Universal actuator
- Article number: 2TLJ020032R0500
# 7 Technical data

## Manufacturer

| Address          | ABB AB / JOKAB SAFETY  
|                 | Varlabergsvägen 11  
|                 | SE-434 39 Kungsbacka  
|                 | Sweden              |

## Electrical characteristics

<table>
<thead>
<tr>
<th>Utilization category</th>
<th>AC15 230 V/2.5 A</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rated impulse withstand voltage ($U_{imp}$)</td>
<td>2.5 kV</td>
</tr>
<tr>
<td>Rated insulation voltage ($U_i$)</td>
<td>250 V</td>
</tr>
<tr>
<td>Rated thermal current ($I_\text{n}$)</td>
<td>5 A</td>
</tr>
<tr>
<td>Total current max (4 contacts)</td>
<td>4 x 2.5 A</td>
</tr>
<tr>
<td>Short circuit protection (fuse)</td>
<td>4 A slow-blow fuse</td>
</tr>
</tbody>
</table>

## Solenoid

<table>
<thead>
<tr>
<th>Duty cycle</th>
<th>100 % ED (at E1:E2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature class</td>
<td>F (155°C)</td>
</tr>
<tr>
<td>Inrush power consumption</td>
<td>12 VA (0.2 s), UC-type</td>
</tr>
<tr>
<td>Permanent power consumption</td>
<td>4.4 VA, UC-type</td>
</tr>
<tr>
<td>Switch operation (permanent)</td>
<td>Max 600/h</td>
</tr>
<tr>
<td>Operating voltage</td>
<td>24 V DC or AC, UC-type</td>
</tr>
<tr>
<td>Switch-on delay</td>
<td>Max 250 ms</td>
</tr>
</tbody>
</table>

## Mechanical data

| Material                  | Enclosure: PA 6 GV (UL94-VO)  
|                          | Cover (lid): PA 6 GV (UL94-VO)  
|                          | Actuating mechanism: PA 6 GV (UL94-VO)/Zn-GD  
|                          | Actuator: Steel/PA/Zn-GD |
| Colour                   | Black, yellow label |
| Ambient temperature      | -25…+70°C          |
| Holding force (max)      | Locked: 1500 N (GS-ET 19, see note below)  
|                          | Unlocked: 27 N     |
| Switching function/contact configuration | Locking: 1 NO + 1 NC  
|                          | Movable guard: 1 NO + 1 NC |
| Mechanical life          | 1 million operations (at max 600 operations/h) |
| Actuating radius (min)   | Standard actuator: $R_{\text{min}} = 400 \text{ mm}$  
|                          | Universal actuator: $R_{\text{min}} = 150 \text{ mm}$ |
| Actuating velocity (max) | $V_{\text{max}} = 0.5 \text{ m/s}$ |
| Size                     | See drawings below |
| Weight                   | Approx 0.3 kg      |
| Mounting                 | 4 x M5 screws ISO1207/DIN 84  
|                          | Max. torque: $M = 2 \text{ Nm ISO4762/DIN 912}$ |
### Mechanical data

<table>
<thead>
<tr>
<th>Description</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cable size (max)</td>
<td>Max 1.5 mm² stranded wire</td>
</tr>
<tr>
<td>Terminals</td>
<td>10 cage clamp elements</td>
</tr>
<tr>
<td>Cable entries</td>
<td>3 x M20x1.5</td>
</tr>
<tr>
<td>Protection class</td>
<td>IP67 according to IEC/EN 60529</td>
</tr>
</tbody>
</table>

**NB:** 1 holding force test cycle according to GS-ET 19:

- a) steady increase of holding force 200 N/s
- b) keep max holding force for 5 s.
- c) safety factor 1.3

### Safety / Harmonized Standards

#### Conformity

- European Machinery Directive 2006/42/EC
- VDE 0660 T100, EN 60947-1, VDE 0660 T200, EN 60947-5-1, GS-ET 19

#### EN ISO 13849-1

- Category 1
- B10c 2,000,000

#### Certificates

- CSA

**NB:** A single JSNY9 can achieve performance level PL c according to EN ISO 13849 if used correctly with an ABB/Jokab Safety safety relay, Pluto safety-PLC or Vital safety module. If two JSNY9-switches are used for the same safety function, a performance level up to PL e can be achieved. Refer to EN ISO 13849 for details on how to achieve this if necessary.
Dimensions

JSNY9 dimensions

Actuator dimensions

JSNY8/9N1
Standard actuator

JSNY8/9N2
Universal actuator

NB: All measurements in millimetres.
8 EC Declaration of conformity

EC Declaration of conformity

We ABB AB
JOKAB Safety
Varlabergsvägen 11
SE-434 39 Kungsbacka
Sweden

declare that the safety components of ABB AB manufacture with type
designations and safety functions as listed below, is in conformity with
the Directive

2006/42/EC

Authorised to compile the technical file
ABB AB
JOKAB Safety
Varlabergsvägen 11
SE-434 39 Kungsbacka
Sweden

Product
Lockable safety interlock switch
JSNY8
JSNY9

Used harmonized standards
EN 60204-1:2009+A1:2009

Jesper Kristensson
PRJ Manager
Kungsbacka 2011-12-06

www.abb.com
www.jokabsafety.com

Original