# IRBT DELMIA V5 Track Guide to modify



# Guide to modify IRBT DELMIA V5 Track

All IRBT Tracks are delivered with max length but with this guide will help you to modify the track to any track length.

Exampel:

You downloaded the IRBT6004\_Double\_20m but need a IRBT6004\_Double\_7m.

The Change will be done in 4 steps.

- Renaming of ASSEMBLYS
- Modify Geometry
- Change Parameters (Upper Limits and Home Position, Direction)
- Test Kinematic

#### Renaming of ASSEMBLYS OPEN IRBT6004\_Double\_20m\_REV1\_DELMIAV5\_S.CATPRODUCT

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#### File->SAVE



#### SELECT IRBT\_TrackMotion\_Double\_19m



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Change name to IRBT\_TrackMotion\_Standard\_7m



Select IRBT\_6004\_Double\_19m\_CARRIER1



SAVE AS IRBT6004\_Double\_7m\_Carrier1.CATProduct

Change name to IRBT6004\_Double\_7m\_Carrier1

Select IRBT\_6004\_Double\_19m\_CARRIER2

SAVE AS IRBT6004\_Double\_7m\_Carrier2.CATProduct

Change name to IRBT6004\_Double\_7m\_Carrier2

Now the it should look like this.



File->SAVE All Select top node and save all



File->Close

Modify Geometry OPEN Assembly IRBT\_TrackMotion\_Double\_7m.CatProduct

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Delete the last 12 Mid sections





# Move the right Section -12000mm

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Change Parameters File->Open IRBT6004\_Double\_7m\_REV1\_DELMIAV5\_S.CATProduct

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# Select IRBT6004\_Double\_7m\_Carrier2 and OPEN In New Window



#### Double click Mechanism.1



# Change Position to 12000mm and Close



Double Click Command.1 and Reset to Zero



Double Click Prismatic.1 and reduce Upper Limit by 12m to 6.3m

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#### Click OK

File->Save



#### Close window

Go back to IRBT6004\_Double\_7m



Select IRBT6004\_Double\_7m\_Carrier1 and OPEN In New Window





Double Click Prismatic.1 and reduce Upper Limit by 12m to 6.3m

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Click OK

File->Save and Close Window

# **Test the Kinematic**

Select Work Bench, Device Building

Select Command Jog Device



### Select Carrier1



Jog and see if it works



#### It's going in wrong direction !

#### Fix direction, Open Carrier1 in New Window



#### Double click on Command.1



### Click on the blue arrow



### Click OK and save

Close Window and go back and test again.



Now It works

Set the joint values to zero.

Do the same test for carrier 2

Double click Top node

File->Save ALL





Finished.

# How to use components in delmia

Exempel: IRB4400 on a IRBT4004 with a 250 mm raiser. placement should be Inline • Create root product

- Insert Track, Robot and raiser
- Place and Attach components
- Use Coordinate systems defined in

#### MOUNTINGFRAMES

