ABB MEASUREMENT & ANALYTICS | DATA SHEET

TZIDC-120
Digital Positioner
Compact, well-proven, and flexible

For FOUNDATION Fieldbus®

Communication-ready for FOUNDATION Fieldbus®
- Fieldbus connection acc. to IEC 61158-2
- Power consumption 11.5 mA, 9 to 32 V DC

Easy to commission, user-friendly
- Fully automatic autoadjust
- Setup via integrated operator panel or remote configuration
- Mechanical position indicator

Robust and environmentally ruggedized
- Shock and vibration influence < 1 %
- Aluminum housing, protection class IP 65

Additional temperature range
- −40 to 85 °C (−40 to 185 °F)

Mounting on pneumatic linear actuators or rotary actuators

Low operating cost
- Air consumption < 0.03 kg/h
Contents

1 Description .................................................................................................................................................. 4
   1.1 Pneumatics ............................................................................................................................................... 4
   1.2 Operation .................................................................................................................................................. 4
   1.3 Communication ....................................................................................................................................... 4
   1.4 Modular design ......................................................................................................................................... 4

2 Mounting versions ........................................................................................................................................ 6
   2.1 To linear actuators in accordance with the standard ............................................................................... 6
   2.2 To rotary actuators in accordance with the standard ............................................................................ 6
   2.3 Integral mounting to control valves ......................................................................................................... 6
   2.4 Special actuator-specific mounting .......................................................................................................... 6

3 Operation .................................................................................................................................................... 8
   3.1 General .................................................................................................................................................... 8
   3.2 Operator panel ......................................................................................................................................... 9

4 Communication ........................................................................................................................................... 10
   4.1 General .................................................................................................................................................. 10
   4.2 Configuration .......................................................................................................................................... 10
   4.3 FOUNDATION Fieldbus H1 .................................................................................................................... 10
   4.4 Benefits of FF communication ............................................................................................................ 10
   4.5 FF communication for TZIDC-120 ......................................................................................................... 10

5 Specifications ............................................................................................................................................... 11
   5.1 Communication .................................................................................................................................... 11
   5.2 Designation .......................................................................................................................................... 11
   5.3 Output ................................................................................................................................................... 11
   5.4 Travel .................................................................................................................................................... 11
   5.5 Air supply ............................................................................................................................................ 11
   5.6 Transmission data and influences ......................................................................................................... 12
   5.7 Environmental capabilities ..................................................................................................................... 12
   5.8 Housing .............................................................................................................................................. 12
   5.9 Options ................................................................................................................................................. 13
   5.10 Accessories ....................................................................................................................................... 13

6 Ex relevant specifications ............................................................................................................................. 14
   6.1 ATEX ...................................................................................................................................................... 14
   6.2 IECEx ..................................................................................................................................................... 15
   6.3 FM/CSA ................................................................................................................................................ 16

7 Electrical connections ................................................................................................................................. 20

8 Dimensions ................................................................................................................................................ 22

9 Ordering information .................................................................................................................................. 25
   9.1 Accessories .......................................................................................................................................... 27
1 Description

The TZIDC-120 is an electronically configurable positioner with communication capabilities designed for mounting to pneumatic linear or rotary actuators. It features a small and compact design, a modular construction, and an excellent cost-performance ratio. Fully automatic determination of the control parameters and adaptation to the final control element yield considerable time savings and an optimal control behavior.

1.1 Pneumatics

An I/P module with subsequent pneumatic amplifier is used to control the pneumatic actuator. The well-proven I/P module proportionally converts the permanent electrical positioning signal from the CPU into a pneumatic signal used to adjust a 3/3-way valve. The air flow for pressurizing or depressurizing the actuator is continuously adjusted. As a result, excellent control is achieved. When reaching the set point, the 3/3-way valve is closed in center position to minimize the air consumption. Four different pneumatics versions are available: for single-acting or double-acting actuators, each with “fail-safe” or “fail-freeze” function.

1.1.1 “Fail-safe” function

If the electrical power supply fails, the positioner output 1 is depressurized, and the pneumatic actuator’s return spring moves the valve to the defined safe position. In case of a double-acting actuator the second output 2 is additionally pressurized.

1.1.2 “Fail-freeze” function

If the electrical power supply should fail, the positioner output 1 (and 2, if applicable) is closed and the pneumatic actuator stops (“freezes”) the valve in the current position. If compressed air supply should fail, the positioner depressurizes the actuator.

1.2 Operation

The positioner has a built-in operating panel providing a 2-line LCD and 4 pushbuttons for optimal local configuration, commissioning and operational monitoring. Alternatively, the appropriate configuration program and the available communication option can be used.

1.3 Communication

Communication with the TZIDC-120 positioner occurs via FOUNDATION Fieldbus.

1.4 Modular design

The TZIDC-120 basic model can be enhanced at any time by retrofitting optional equipment. Option modules for analog or digital position feedback can be installed. Additionally, a mechanical position indicator, proximity switches or 24 V microswitches are available for indicating the position independently of the mother board function.
Fig. 1: TZIDC-120 schematic diagram

**Basic model**
1. Bus connector
2. Supply, 1.4 … 6 bar
3. Exhaust
4. I/P module with 3/3-way valve
5. Position sensor (optional up to 270° rotation angle)

**Optional upgrades**
6. Mechanical position indicator
7. Mechanical feedback with proximity switches
8. Mechanical feedback with microswitches 24 V

**Important**
With optional upgrades either the “mechanical feedback with proximity switches” (7) or the “mechanical feedback with microswitches 24 V” (8) can be used.
In both cases, the “mechanical position indicator” (6) must be installed.
2 Mounting versions

2.1 To linear actuators in accordance with the standard

Lateral attachment is in accordance with DIN / IEC 534 (lateral attachment to NAMUR). The required attachment kit is a complete set of attachment material, but does not include the screwed pipe connections and air pipes.

2.2 To rotary actuators in accordance with the standard

This attachment is designed for mounting according to the standard VDI / VDE 3845. The attachment kit consists of a console with mounting screws for mounting on a rotary actuator. The adapter for coupling the positioner feedback shaft to the actuator shaft has to be ordered separately. Screwed pipe connections and air pipes have to be provided on site.

2.3 Integral mounting to control valves

The TZIDC-120 positioner featuring standard pneumatic action is available as an option for integral mounting. The required holes are found at the back of the device. The benefit of this design is that the point for mechanical stroke measurement is protected and that the positioner and actuator are linked internally. No external tubing is required.

2.4 Special actuator-specific mounting

In addition to the mounting methods described above, there are special actuator-specific attachments. Please contact us for details.
Fig. 2: Mounting options

1 Mounting to linear actuators acc. to DIN / IEC 534
2 Mounting to rotary actuators to VDI / VDE 3845
3 Integral mounting to control valves
4 Integral mounting to control valves by using an adapter panel
3 Operation

3.1 General
The intelligent, microprocessor-controlled TZIDC-120 positioner allows you to obtain optimal results. The positioner features high-precision control functions and high operational reliability. The optimal parameters are set automatically during autoadjust. If necessary, corrections can be made manually.

The total range of parameters includes:
- Operating parameters
- Adjustment parameters
- Monitoring parameters

3.1.1 Operating parameters
The following operating parameters can be activated and configured:

Characteristics of operation (travel = f (signal))
Linear, equal percentage 1:25 or 1:50 or 25:1 or 50:1 or freely configurable with 20 reference points.

Tolerance band
When the tolerance band is reached, the position is considered as corrected. From this point on, the position is further slowly re-adjusted until the dead band is reached. The factory setting for this parameter is 0.3 %.

Dead band (sensitivity)
When the dead band is reached, the position is held. The factory setting for this parameter is 0.1 %. The tolerance band and dead zone are automatically calculated as part of the controller’s self-optimization process.

Travel limit
The positioning travel, i.e. the stroke or angle of rotation, can be reduced as required within the full range of 0 ... 100 %, provided that a minimum value of 20 % is observed.

Shut-off function
This function can be selected separately for each end position. When the respective configured limit value is exceeded, the shut-off function causes the actuator to travel immediately to the selected end position.

Travel time prolongation
This function can be used to increase the max. travel time for full travel. This time parameter can be set separately for each direction.

Important
This function can only be used with the pneumatic with the safety function “fail-safe”.

Rules in end position
For both end positions, you can select whether the pneumatic actuator is vented fully or whether the position is controlled.

3.1.2 Adjustment parameters
The TZIDC-120 positioner has a special function for automatic adjustment of the parameters. The function is launched either via the integrated operator’s panel or the user interface.

The following adjustment parameters can be activated and configured:

Parameters for control block
To optimally adjust the actuator position, the control parameters can be set individually for the optimal behavior of the valve.

Range 0 ... 100 %
Configuration of end positions for the valve to be adjusted to start position “0” and end position “100 %”.

Direction of the actuator
Calibration to both possible directions of action:
- Air opens / spring force closes
- Air closes / spring force opens

Display 0 ... 100 %
Adjusting the display (0 ... 100 %) to the direction of action for opening or closing the valve.

3.1.3 Monitoring parameters
Various functions for permanent operational monitoring are implemented in the TZIDC-120 operating program, e.g.:
- Internal positioning time-out
- Sensor monitoring
- Backup monitoring

While automatic commissioning is in progress, the current state is continuously indicated on the integrated LCD. Remaining messages can be retrieved via the user interface.

The fieldbus enables users to implement enhanced monitoring in the control system. A special window displays the most important process variables OFFLINE such as the positioning signal (in %), the position (in %), the control deviation (in %) as well as the status messages.
3.2 Operator panel

The TZIDC-120 positioner’s operator panel with four pushbuttons allows for:
- operational monitoring
- manual control
- configuration
- fully automatic commissioning

The operator panel is protected by a cover which avoids unauthorized access to the operating elements.

3.2.1 Single-button commissioning

Commissioning the TZIDC-120 positioner is especially easy. The standard Autoadjust function for automatic adaptation of the device parameters can be started by simply pressing a single front panel button, and without knowing parameterization details.

Depending on the selected actuator type (linear or rotary), the displayed zero position is automatically adapted:
- for linear actuators counter-clockwise (CTCLOCKW)
- for rotary actuators clockwise (CLOCKW).

Besides this standard function, a customized “Autoadjust” function is available. The function is launched either via the operator’s panel or the configuration program.

3.2.2 Operation

The four pushbuttons enable users to select operating levels, configure the device and store settings. In addition to the known operating functions, a simplified autoadjust can be performed. This enables you to launch the device’s automatic configuration function in a few steps and without detailed knowledge regarding parameters.

When changing the actuator type from linear to rotary, the zero position of the display is automatically updated. This is indicated in the display for valves closing on the right in the closed position 0 %.

3.2.3 Display

The information indicated by the 2-line LCD is permanently updated and adapted during operation, to inform the operator in an optimal way.

During control operation the following TZIDC-120 data can be called up by pressing the pushbuttons briefly:

- **Up button**
  - Cyclic communication:
    - Setpoint (%)
    - Setpoint status
  - Acyclic communication:
    - Status of communication

- **Down button**
  - Operating mode on the bus and bus address

- **Enter**
  - Software Version

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Fig. 3: TZIDC-120 with removed cover, view of the operator panel

Fig. 4: TZIDC-120 operating elements and display
4 Communication

4.1 General
Communication occurs via the fieldbus connection. In conformance with bus convention, device data is read in cyclic operation (operating mode AUT, MAN or RCAS) and data is written in the O/S (out-of-service) mode. Newly set parameters are saved in the non-volatile memory directly after writing to the field device, and become active immediately.

FOUNDATION Fieldbus is an open bus standard that enables users to integrate devices from various manufacturers in a system and supports interoperability.

Communication occurs via an FF system using the fast, superordinate HSE bus (high-speed ethernet) and the slower but intrinsically safe H1 bus. It is layer-oriented and based on the ISO/OSI model (International Standards Organization’s Open System Interconnect).

A device description (DD) provided in file format by the manufacturer contains all the necessary information on the FF device and its functions.

4.2 Configuration
The user interface for the TZIDC-120 positioner is integrated in the control system. This allows you to work with the fieldbus in the commissioning phase, during operation and for service tasks when monitoring the device, setting parameters and uploading data.

4.3 FOUNDATION Fieldbus H1
The FOUNDATION Fieldbus H1 was developed primarily for use in process automation. The transmission method (physical layer) complies with IEC 61158. The power supply for the field devices is provided concurrent with signal transmission via the fieldbus line. FOUNDATION Fieldbus H1 is also well suited for use in explosion-proof installations.

4.4 Benefits of FF communication
- Standardized function blocks and an interoperability test ensure smooth integration of devices from various manufacturers
- Acyclic access to device data (even during operation) for configuration, diagnostics and service
- High system uptimes based on comprehensive device and bus diagnostics as well as default value strategies in the event of an error
- Support for efficient facility management through provision of operating values

4.5 FF communication for TZIDC-120
Using the FOUNDATION Fieldbus in combination with a suitable configuration program installed in the control system, the TZIDC-120 can be easily monitored, configured and queried. Newly set parameters are saved in the non-volatile memory directly upon download to the device, and become active immediately.

Fig. 5: Communication via FOUNDATION Fieldbus
5 Specifications

5.1 Communication

<table>
<thead>
<tr>
<th>Specification</th>
<th>Details</th>
</tr>
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<tbody>
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<td>Foundation fieldbus, version 1.5</td>
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<tr>
<td>Block types</td>
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<td>1 PID block</td>
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<tr>
<td></td>
<td>1 Resource block</td>
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<tr>
<td></td>
<td>1 Transducer block</td>
</tr>
<tr>
<td></td>
<td>1 physical block</td>
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<tr>
<td>Block class</td>
<td>AO block: standard</td>
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<tr>
<td></td>
<td>PID block: enhanced</td>
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<tr>
<td></td>
<td>Resource block: enhanced</td>
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<tr>
<td></td>
<td>Transducer block: custom</td>
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5.2 Designation

<table>
<thead>
<tr>
<th>Device name</th>
<th>ABB TZID-120-TAG</th>
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<tr>
<td>Dev. ID</td>
<td>0003200028-TZIDC-120000000000</td>
</tr>
</tbody>
</table>

5.3 Output

**Range**

- 0 ... 6 bar (0 ... 90 psi)

**Air capacity**

- at 1.4 bar (20 psi) supply pressure: 5.0 kg/h = 3.9 Nm³/h = 2.3 scfm
- at 6 bar (90 psi) supply pressure: 13 kg/h = 10 Nm³/h = 6.0 scfm

**Output function**

For single or double-acting actuators, air is vented from actuator or actuator is blocked in case of (electrical) power failure.

**Shut-off values**

- End Position 0 % = 0 ... 45 %
- End position 100 % = 55 ... 100 %

5.4 Travel

**Rotation angle**

- 25 ... 120° rotary actuators, optionally 270° linear actuators
- 25 ... 60° linear actuators

**Travel time prolongation**

- Setting range: 0 ... 200 seconds, separately for each direction

5.5 Air supply

**Instrument air**

Free of oil, water and dust to DIN/ISO 8573-1. Pollution and oil content according to Class 3 (purity: max. particle size = 5 µm, max. particle density = 5 mg / m³; oil content: max. concentration = 1 mg / m³; pressure dew point: 10 K below operating temperature)

**Supply pressure**

- 1.4 ... 6 bar (20 ... 90 psi)

**Air consumption**

- < 0.03 kg/h / 0.015 scfm (independent of supply pressure)
5.6 Transmission data and influences

Direction of action (output signal or pressure in actuator)

Increasing
- Increasing output signal 0 ... 100 %
- Increasing pressure y1 in the actuator

Decreasing
- Decreasing output signal 0 ... 100 %
- Decreasing pressure y1 in the actuator

Characteristic deviation < 0.5 %
Tolerance band 0.3 ... 10 %, adjustable
Dead band 0.1 ... 5 %, adjustable
Resolution (A/D conversion) > 16000 steps
Sample rate 20 ms
Influence of ambient temperature < 0.5 % for each 10 K
Influence of vibration ≤ ± 1 % to 10 g and 80 Hz

Seismic requirements
Meets requirements of DIN / IEC 68-3-3 Class III for strong and strongest earthquakes.

Influence of mounting orientation
Not measurable.

Meets the requirements of the following directives
- EMC Directive 2004/108/EC as of December 2004
- EC Directive for CE conformity marking

5.7 Environmental capabilities

Ambient temperature
For operation, storage and transport: -40 ... 85 °C (-40 ... 185 °F)

Relative humidity
Operational (with closed housing and air supply switched on): 95 % (annual average), condensation permissible
Transport and storage: 75 % (annual average), non-condensing

5.8 Housing

Material / Degree of protection
Aluminum with ≤ 0.1 % copper, protection class IP 65 (optional IP 66) / NEMA 4X

Surface / Color
Electrostatic dipping varnish with epoxy resin, stove-hardened.
Case varnished black, RAL 9005, matte, housing cover Pantone 420.

Electrical connections
Screw terminals: Max. 1.0 mm² (AWG 17) for options
Max. 2.5 mm² (14 AWG) for bus connector

IMPORTANT (NOTE)
Do not expose the terminals to strain.

Four thread combinations for cable entry and pneumatic connection
- Cable: thread 1/2-14NPT, air pipe: thread 1/4-18 NPT
- Cable: thread M20 x 1,5, air pipe: thread 1/4-18 NPT
- Cable: thread M20 x 1,5, air pipe: thread G 1/4
- Cable: thread G 1/2, air pipe: thread Rc 1/4
(Optional: With cable gland(s) and pipe plugs if necessary)

Weight
1.7 kg (3.75 lb)

Mounting orientation
Any
5.9 Option

Mechanical position indicator
- Indicator disk
- Cover with transparent dome
- Symbol label
- Extension shaft

Digital position feedback with proximity switches
Two proximity switches for independent position signaling. Switching points adjustable between 0 ... 100 %
Current circuits acc. to DIN 19234 / NAMUR
Supply voltage 5 ... 11 V DC
Signal current < 1.2 mA Switching state logical "0"
Signal current > 2.1 mA Switching state logical "1"
(function dependent on software and electronics for actuator)

Direction of action (logical state)

<table>
<thead>
<tr>
<th>Proximity switch</th>
<th>&lt; Lim. 1</th>
<th>&gt; Lim. 1</th>
<th>&lt; Lim. 2</th>
<th>&gt; Lim. 2</th>
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</thead>
<tbody>
<tr>
<td>SJ2-SN (NC)</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
</tr>
</tbody>
</table>

Digital position feedback with 24 V microswitches*
Two microswitches for independent position signaling. Switching points adjustable between 0 ... 100 %.
Voltage max. 24 V AC / DC
Load rating max. 2 A
Contact surface 10 µm Gold (AU)

Mechanical position indicator
Indicator disk in enclosure cover, linked with positioner feedback shaft.

* The "digital feedback" is activated directly from the axis of rotation for the variable pick-off and can only be used with the "mechanical position indicator".

5.10 Accessories

Mounting material
- Attachment kit for linear actuators to DIN / IEC 534 / NAMUR
- Attachment kit for part-turn actuators to VDI / VDE 3845
- Attachment kit for integral mounting to control valves
- Attachment kit for actuator-specific attachment upon request

Pressure gauge block
- Pressure gauges for supply and output pressure
- Pressure gauges with housing ø 28 mm
- Aluminum connection block in black
- Installation material for mounting on positioner

Filter regulator
All metal version in brass, varnished black, bronze filter element (40 µm) and condensate drain.
Max. pre-pressure 16 bar (232 psi), output adjustable to 1.4 ... 6 bar (20 ... 90 psi)

IMPORTANT (NOTE)
These options are also available for retrofitting by Service.
6 Ex relevant specifications

6.1 ATEX

6.1.1 ATEX Ex i

Marking: II 2 G Ex ia IIC T6 resp. T4 Gb
II 3 G Ex ic IIC T6 resp. T4 Gc

Type examination certificate: TÜV 02 ATEX 1834 X

Type: Intrinsically safe equipment

Standards: EN 60079-0:2009
EN 60079-11:2007
EN 60079-27:2008

<table>
<thead>
<tr>
<th>Temperature class</th>
<th>Ambient temperature range</th>
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<tbody>
<tr>
<td>T4</td>
<td>-40 ... 85 °C</td>
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<tr>
<td>T5</td>
<td>-40 ... 55 °C</td>
</tr>
<tr>
<td>T6</td>
<td>-40 ... 40 °C</td>
</tr>
</tbody>
</table>

Electrical data for ia/ib/ic for groups IIB/IIC

With the intrinsically safe Ex i IIC type of protection, only for connection to a certified FISCO power supply unit, a barrier or a power supply unit with linear characteristic curves and the following maximum values:

Signal circuit (terminal +11 / -12 or + / -)
- U = 24 V
- I = 250 mA
- P = 1.2 W
- Characteristic curve: linear
- L < 10 µH
- C < 5 nF

Mechanical digital feedback
For maximum values, see EC type examination certificate number PTB 00 ATEX 2049 X

6.1.2 ATEX Ex n

Marking: II 3 G Ex nA IIC T6 resp. T4 Gc
TU V 02 ATEX 1943 X

Type: "n" type of protection

Device group: II 3 G

Standards: EN 60079-15:2010
EN 60079-0:2009

<table>
<thead>
<tr>
<th>Temperature class</th>
<th>Ta Ambient temperature range</th>
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</thead>
<tbody>
<tr>
<td>T4</td>
<td>-40 ... 85 °C</td>
</tr>
<tr>
<td>T6</td>
<td>-40 ... 50 °C</td>
</tr>
</tbody>
</table>

Electrical data for II 3 G Ex nA IIC T6 or T4 Gc

Signal circuit (terminal +11 / -12)
- U = 9 ... 32 V DC
- I = 11.5 mA

Mechanical digital feedback (terminal Limit1 +51 / -52 or Limit2 +41 / -42)
- U = 5 ... 11 V DC

Special requirements

- Devices may only be connected to circuits in zone 2 if they are suitable for operation in zone 2 potentially explosive atmospheres and for the conditions prevailing at the installation location (manufacturer's declaration or certificate from an inspection authority)

- For the "digital feedback with proximity switches" circuit, external measures must be implemented to prevent the rated voltage from being exceeded by more than 40 % in the event of transient disturbances

- It is only permissible to connect, disconnect and switch live circuits during installation or maintenance, or for the purpose of carrying out repairs. Note: It is considered very unlikely that a potentially explosive atmosphere would be present in zone 2 at the same time that installation or maintenance/repair work was being carried out

- Only non-flammable gases may be used for the pneumatic power supply

- Only use suitable cable entries that meet the requirements of IEC 60079-15
6.2 IECEx

6.2.1 IECEx

Marking: Ex ia IIC T6 or T4 Gb
Ex ib IIC T6 or T4 Gb
Ex ic IIC T6 or T4 Gc
Ex nA IIC T6 or T4 Gc

Certificate no.: IECEx TUN 04.0015X
Issue no.: 5
Type: Intrinsic safety "i" or type of protection "n"

Standards:
IEC 60079-0:2011
IEC 60079-11:2011
IEC 60079-15:2010

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<th>TZIDC-120 Ex nA IIC</th>
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<td>Ambient temperature range</td>
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<tr>
<td>T4</td>
<td>-40 ... 85 °C</td>
<td>-40 ... 85 °C</td>
</tr>
<tr>
<td>T6</td>
<td>-40 ... 50 °C</td>
<td>-40 ... 50 °C</td>
</tr>
</tbody>
</table>

6.2.2 IECEx i

Electrical data for TZIDC-110 for ia/ib/ic with "Ex i IIC T6" or "T4 Gb" marking

With the intrinsically safe Ex i IIC type of protection, only for connection to a certified FISCO power supply unit, a barrier or a power supply unit with linear characteristic curves and the following maximum values:

<table>
<thead>
<tr>
<th>Signal circuit (terminal +11 / -12)</th>
<th>U = 24 V</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>I = 250 mA</td>
</tr>
<tr>
<td></td>
<td>P = 1.2 W</td>
</tr>
<tr>
<td>Characteristic curve: linear</td>
<td></td>
</tr>
</tbody>
</table>

Special requirements

- Devices may only be connected to circuits in zone 2 if they are suitable for operation in zone 2 potentially explosive atmospheres and for the conditions prevailing at the installation location (manufacturer's declaration or certificate from an inspection authority)
- For the "digital feedback with proximity switches" circuit, external measures must be implemented to prevent the rated voltage from being exceeded by more than 40 % in the event of transient disturbances.
- It is only permissible to connect, disconnect and switch live circuits during installation or maintenance, or for the purpose of carrying out repairs. Note: It is considered very unlikely that a potentially explosive atmosphere would be present in zone 2 at the same time that installation or maintenance/repair work was being carried out.
- Only non-flammable gases may be used for the pneumatic power supply
- Only use suitable cable entries that meet the requirements of IEC 60079-15

6.2.3 IECEx n

Electrical data for TZIDC-120 with "Ex nA IIC T6" or "T4 Gc" marking

<table>
<thead>
<tr>
<th>Signal circuit (terminal +11 / -12)</th>
<th>U = 9 ... 32 V DC</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>I = 11.5 mA</td>
</tr>
<tr>
<td>Mechanical digital feedback (terminal Limit1 +51 / -52 or Limit2 +41 / -42)</td>
<td>U = 5 ... 11 V DC</td>
</tr>
</tbody>
</table>

Certificate no.: IECEx TUN 04.0015X
Issue no.: 5
Type: Intrinsic safety "i" or type of protection "n"
6.3 FM/CSA

6.3.1 CSA Certification Record

Certificate: 1649904 (LR 20312)
Class 2258 04
EQUIPMENT – Intrinsically Safe, Entity – For Hazardous Locations
Class I, Div 1, Groups A, B, C and D;
Class II, Div 1, Groups E, F, and G;
Class III, Div 1, Enclosure Type 4X;

Model TZIDC-120, P/N V18347-x042x2xx0x Intelligent Positioner

<table>
<thead>
<tr>
<th>Terminals</th>
<th>Type</th>
<th>Groups</th>
<th>Parameters</th>
<th>Vmax</th>
<th>Imax</th>
<th>Pi</th>
<th>Ci</th>
<th>Li</th>
</tr>
</thead>
<tbody>
<tr>
<td>+11 / -12</td>
<td>Entity A-G</td>
<td>V max = 24 V I max = 250 mA C = 2.8 nF L = 7.2 uH</td>
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<tr>
<td>+11 / -12</td>
<td>FISCO A-G</td>
<td>U max = 30 V I max = 60 mA C = 3.8 nF L = 0 uH</td>
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<td>+11 / -12</td>
<td>FISCO C-G</td>
<td>U max = 16 V I max = 20 mA C = 60 nF L = 100 uH</td>
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</tbody>
</table>

When installed per installation Drawing No 901265

Temperature Code T4
Max. Ambient 85 Deg C

IMPORTANT (NOTE)
- The "x" in P/N denotes minor mechanical variations or optional features.
- Local communication interface LKS shall not be used in hazardous location.
- Each pair of conductors of each intrinsic safety circuit shall be shielded.

6.3.2 FM Approvals

TZIDC-120 Positioner, Model V18347-a042b2cd0e
IS/I,II,III/1/ABCDEFG/T6,T5,T4 Ta = 40 °C, 55 °C, 85 °C-901265
Entity, FISCO

Entity and FISCO Parameters

<table>
<thead>
<tr>
<th>Terminals</th>
<th>Type</th>
<th>Groups</th>
<th>Parameters</th>
<th>Vmax</th>
<th>Imax</th>
<th>Pi</th>
<th>Ci</th>
<th>Li</th>
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NN/I/II/ABCD/T6,T5,T4 Ta = 40 °C, 55 °C, 85 °C
S/II,III/2/EFG//T6,T5,T4 Ta = 40 °C, 55 °C, 85 °C

Equipment Ratings:
TZIDC-120 Positioners
Intrinsically safe, Entity and FISCO, for Class I, II and III, Division 1, Applicable Groups A, B, C, D, E, F, G; nonincendive for Class I, Division 2, Group E, F and G hazardous (classified) indoor and outdoor NEMA 4x locations.

The following temperature code ratings were assigned for the equipment and protection methods described above:
- T6 in ambient temperatures of 40 °C
- T5 in ambient temperatures of 55 °C
- T4 in ambient temperatures of 85 °C
6.3.3 FM Control Document

Electro-Pneumatic Positioner TZIDC-120
for FOUNDATION Fieldbus

Page: 1 of 3

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2003 | Date   | Name          | Title                      | Scale |
-----|--------|---------------|----------------------------|------|
      |        |               | FM/CSA-Control-Document    | /    |

ABB Automation Products

Supersedes Doc. | Part Class |
                | 901265     |
Electro-Pneumatic Positioner TZIDC-120
for FOUNDATION Fieldbus

FISCO rules

The FISCO Concept allows the interconnection of intrinsically safe apparatus to associated apparatus not specifically examined in such combination. The criterion for such interconnection is that the voltage (Vmax), the current (Imax) and the power (P) which intrinsically safe apparatus can receive and remain intrinsically safe, considering faults, must be equal or greater than the voltage (Uo, Voc, Vt), the current (Io, Ioc, It) and the power (Po) which can be provided by the associated apparatus (supply unit). In addition, the maximum unprotected residual capacitance (C1) and inductance (L1) of each apparatus (other than the terminators) connected to the Fieldbus must be less than or equal to 5nF and 10µH respectively.

In each I.S. Fieldbus segment only one active source, normally the associated apparatus, is allowed to provide the necessary power for the Fieldbus system. The allowed voltage (Uo, Voc, Vt) of the associated apparatus used to supply the bus must be limited to the range of 14V d.c. to 24V d.c. All other equipment connected to the bus cable has to be passive, meaning that the apparatus is not allowed to provide energy to the system, except to a leakage current of 50 µA for each connected device. Separately powered equipment needs a galvanic isolation to ensure that the intrinsically safe Fieldbus circuit remains passive.

The cable used to interconnect the devices needs to comply with the following parameters:

- **Loop resistance**: R = 15...150 Ω/km
- **Inductance per unit length**: L′ = 0.4...1 mH/km
- **Capacitance per unit length**: C′ = 80...200 nF/km
- C = C′ line/line + 0.5C″ line/screen, if both lines are floating
  or
  C = C′ line/line + C″ line/screen, if the screen is connected to one line
- **Length of spur cable**: max. 30m
- **Length of trunk cable**: max. 1km
- **Length of splice**: max. 1m

**Terminators**

At each end of the trunk cable an approved line terminator with the following parameters is suitable:

- **Resistance**: R = 90...100 Ω
- **Inductance**: L = 0...2.2 µH

**System evaluation**

The number of passive devices like transmitters, actuators, connected to a single bus segment is not limited due to I.S. Reasons. Furthermore, if the above rules are respected, the inductance and capacitance of the cable need not to be considered and will not impair the intrinsic safety of the installation.
Installation Notes For FISCO and Entity Concepts:

1. The Intrinsic Safety Entity concept allows the interconnection of FM/CSA Approved Intrinsically safe devices with entity parameters not specifically examined in combination as a system when:
   \[ U_0 \text{ or } V_0 \leq V_{\text{max}}, \text{ Io or Isc or I } \leq I_{\text{max}}, \text{ Po } \leq P_i, \text{ Ca or Co } \geq \frac{V_{\text{max}}}{V_{\text{in}}}, \text{ cable.} \]
   For inductance use either \( L_0 \text{ or } L_0 + Z_{\text{in}} \text{ cable} \) or \( L_0 / R_0 \leq (L_0 / R_0 + L_0 / R_0) \) and \( L_0 / R_0 \leq (L_0 / R_0 + L_0 / R_0) \).

2. The Intrinsic Safety FISCO concept allows the interconnecting of FM/CSA Approved Intrinsically safe devices with FISCO parameters not specifically examined in combination as a system when: \( U_0 \text{ or } V_0 \leq V_{\text{max}}, \text{ Io or Isc or I } \leq I_{\text{max}}, \text{ Po } \leq P_i, \text{ Ca or Co } \geq \frac{V_{\text{max}}}{V_{\text{in}}}, \text{ cable.} \)

3. Control equipment connected to the Associated Apparatus must not use or generate more than 250 Vrms or Vdc.

4. Installation should be in accordance with ANSI/ISA RP12.6 (except chapter 5 for FISCO Installations)

5. Installation of Intrinsically Safe System for Hazardous (Classified) Locations (the National Electrical Code® (ANSI/NFPA 70) Sections 504 and 505).

6. The configuration of associated Apparatus must be Factory Mutual Research /Canadian Standards Association Approved under the associated concept.

7. Associated Apparatus manufacturer’s installation drawing must be followed when installing this equipment.

8. No revision to drawing without prior Factory Mutual Research Approval/Canadian Standards Association approval.

9. Special conditions for safe use

   The operation of the local communication interface (LKS) and of the programming interface (XS) is only allowed outside of the Hazardous explosive area.

NONINCENDIVE, CLASS I, DIV. 2, GROUP A, B, C, D, AND FOR CLASS II AND III, DIV. 1&2, GROUP E, G.

HAZARDOUS LOCATION INSTALLATION.

1. Install per National Electrical Code (NEC) using threaded metal conduit. Intrinsic safety barrier required. Max. Supply voltage 30 V. For T-code see table.

2. A dust tight seal must be used at the conduit entry when the positioner is used in a Class II & III Location.

3. WARNING: Explosion Hazard – do not disconnect equipment unless power has been switched off or the area is known to be Non-Hazardous.

   WARNING: Substitution of components may impair suitability for hazardous locations.

<table>
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<tr>
<th>Rev.</th>
<th>Date</th>
<th>Name</th>
<th>File</th>
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ABB Automation Products

Drwg. No. (Part No.) 901265

Supersedes Doc.

Part Code:
7 Electrical connections

Fig. 6: Screw terminals, overview

1 Not assigned
2 Digital position feedback, either proximity switches or 24 V microswitches
3 Same as 4
4 Bus connector
5 Grounding screw
Fig. 7: Pin configuration

A  Basic model
B  Options

1  Fieldbus, bus feed
2  Proximity switches
3  Microswitches

Important
Keep cable shields as short as possible and connect on both sides.
8 Dimensions

All dimensions in mm (inch)

Fig. 8: Top view

Fig. 9: Front and rear views

- A Tap hole M8 (10 mm low)
- B Tap hole M6 (8 mm low)
- C Tap hole M5 x 0.5 (air vents for direct mount)
- D Sensor shaft (larger than scale)
Electro-Pneumatic Positioner TZIDC-120
for FOUNDATION Fieldbus

Fig. 10: side view (from left to right)
A Pneumatic connections, NPT 1/4"-18 or G1/4"

Fig. 11: Mounting drawings
Mounting to linear actuators to DIN / IEC 534
Mounting to rotary actuators to VDI / VDE 3845
*) Dimensions A and B are dependent on the rotary actuator
Fig. 12: Positioner TZIDC-120 with pressure gauge block and filter regulator
### 9 Ordering information

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#### Case / Mounting

- Case made of aluminium, varnished, for mounting to linear actuators acc. DIN/IEC 534 / NAMUR or to rotary actuators acc. VDI/VDE 3845
- Case made of aluminium, varnished, with mechanical position indicator, for mounting to linear actuators acc. DIN/IEC 534 / NAMUR or to rotary actuators acc. VDI/VDE 3845
- Case made of aluminium, varnished, for integral mounting to control valves
- Case made of aluminium, varnished, with mechanical position indicator, for integral mounting to control valves
- Case made of aluminium, varnished, for mounting to rotary actuators acc. VDI/VDE 3845 with extended rotation angle up to 270°
- Case made of aluminium, varnished, with mechanical position indicator, for mounting to rotary actuators acc. VDI/VDE 3845 with extended rotation angle up to 270°

#### Input / Communication Port

- FOUNDATION Fieldbus

#### Explosion Protection

- Without
- ATEX II 2 G Ex ia IIC T6 resp. T4 Gb
- FM / CSA
- ATEX II 3 G Ex na IIC T6 resp. T4 Gc
- IECEx ia IIC T6 resp. T4 Gb
- IECEx Ex na IIC T6 resp. T4 Gc
- GOST Russia - Ex II 2 G ExEx ia II C T6
- GOST Russia - EEx na II T6
- ATEX II 3 G Ex ic IIC T6 resp. T4 Gc
- IECEx ic IIC T6 resp. T4 Gc

#### Output / Safe Position (in case of an electrical power failure)

- Single acting, fail safe
- Single acting, fail freeze
- Double acting, fail safe
- Double acting, fail freeze

#### Connections

- Cable: Thread 1/2-14 NPT, air pipe: Thread 1/4-18 NPT
- Cable: Thread M20 x 1.5, air pipe: Thread 1/4-18 NPT
- Cable: Thread M20 x 1.5, air pipe: Thread G 1/4
- Cable: Thread G 1/2, air pipe: Thread Rc 1/4

#### Option Module for Shutdown Function

- Without

#### Optional Mechanical Kit for Digital Position Feedback

- Without
- Mechanistic Mechanical kit for digital position feedback with proximity switches SJ2-SN (NC or logical 1)
- Mechanical kit for digital position feedback with 24 V AC / DC microswitches (change-over contacts)

Continued on next page

1) Only for model with mechanical position indicator, no IECEx
2) Not for explosion protected version and only for model with mechanical position indicator
Electro-Pneumatic Positioner TZIDC-120
for FOUNDATION Fieldbus

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<tr>
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<td>V18347</td>
<td>X</td>
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Design (Varnish / Coding)
- Standard
- Special version for Chemical Industries

Add. Code

Certificate of Compliance
- Certificate of compliance with the order acc. EN 10204-2.1 (DIN 50049-2.1) with item description
- Test report 2.2 acc. EN 10204 (DIN 50049-2.2)

Inspection Certificate
- Inspection certificate 3.1 acc. EN 10204

Device Identification Label
- Stainless steel 11.5 x 60 mm (0.45 x 2.36 in.)
- Sticker 11 x 25 mm (0.43 x 0.98 in.)

3) Details on request
## Accessories

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<tr>
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<td>EDP300 / TZIDC Form - locking shaft adapter</td>
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