

# Supplement ACS880 drives with ABB motors in explosive atmospheres

## Introduction

This supplement describes the necessary parameter settings for an ACS880 drive type when it is used with an ABB motor for explosive atmospheres (Ex). For other parameter settings, see *ACS880 primary control program firmware manual (3AUA0000085967 [English])*.



## Parameter settings

Use the control panel or the Drive composer PC tool to make the parameter settings.

- Set the following parameters that are common to motors in explosive atmospheres and ACS880 drive combinations:

Parameter no.	Parameter name	Bit	Name	Value	Description
95.15	Special HW settings	0	Ex motor	1 = Yes	Used with Ex motor

Example of the Ex parametrization:

Local  ACS880 1500.0 rpm	Local  ACS880 1500.0 rpm	Local  ACS880 1500.0 rpm
95 HW configuration	95.15 Special HW settings	95.15 Special HW settings
95.04 Control board supply Internal 24V	0  EX motor =No	0  EX motor =Yes
95.08 DC switch monitoring Disable	1 <input type="checkbox"/> ABB Sine filter =No	1 <input type="checkbox"/> ABB Sine filter =No
95.09 Fuse switch control Disable	2 <input type="checkbox"/> High speed mode =No	2 <input type="checkbox"/> High speed mode =No
95.15 Special HW settings 0000 0000 0000 0001		
Back 15:55 Edit	Cancel 15:55 Save	Cancel 15:55 Save

## Motor and VSD rating plates

Standard IEC motor rating plate is used to program parameter group 99 within the ACS880 drive and motor's variable speed drive (VSD) plate is used to set-up limits and protections of the drive.

### 99.04 Motor control mode to DTC

The figure below shows an example of motor rating plate.

ABB Oy, Motors and Generators Vaasa, Finland						
CE		IE2		Ex II 3G		
3~ Motor M3GP 160MLA 6 IMV6/IM1031						
Ex nA II C T3 Gc						
871486-1		2014		No. 3GF14192428		
				Ins.cl. F		IP 55
V	Hz	kW	r/min	A	cos φ	Duty
690 Y	50	7.5	968	9.2	0.78	S1
400 D	50	7.5	968	15.8	0.78	S1
415 D	50	7.5	969	15.3	0.77	S1
IE2-87.7%(100%)-89.2%(75%)-89.6%(50%)						
Prod. code 3GGP163410-ADH066163180						
LCIE 12 ATEX 1008 X / IECEx LCI 09.0012X						
Manual: 3GZF500730-47			Nmax		r/min	
6309/C3			6309/C3		220 kg	
ABB		IEC 60034-1				

99.07 Motor nominal voltage

99.08 Motor nominal frequency

99.10 Motor nominal power

99.09 Motor nominal speed

99.06 Motor nominal current

99.11 Motor nominal cos φ

Carry out the ID run as normal.

The figure below shows an example of the motor's customer specific VSD plate.

ABB						
3~ Motor M3GP 160MLA 6 IMV6/IM1031						
No. 3GF14192428						
<b>CONVERTER SUPPLY</b>						
FC Type ACS880/DTC						
Switc.freq.: 2 kHz						
F.W.P. 400VD 50Hz						
V	Hz	kW	r/min	A	Nm	Duty
400 D	51.3	6.1	1000	14	58.2	59
QUADRATIC TORQUE 0-1500rpm						

**Mandatory:**  
Ensure minimum switching frequency is adhered to by setting: par. 95.15 Bit 0 = 1

**Recommended:**  
Set power limits in par. 30.26 and par. 30.27 at the nominal voltage.

**Recommended:**  
Set current limit in par. 30.17 Current x 01.05 gives some hysteresis for the control.

**Mandatory:**  
Hexagonal field weakening shall be disabled if this function is available.

**Recommended:**  
Set speed limits in par. 30.11 and par.30.12.

**Note:** If standard VSD plate is used, the values need to be converted to motor specific data.

## ACS880 Ex mode derating tables

When Ex mode is activated, dimensioning the drive correctly requires derating the continuous drive output current (motor current). This is very important in order to reach a safe and reliable solution. DriveSize tool calculates this automatically. Derating tables can be found from Drive specific HW manual.