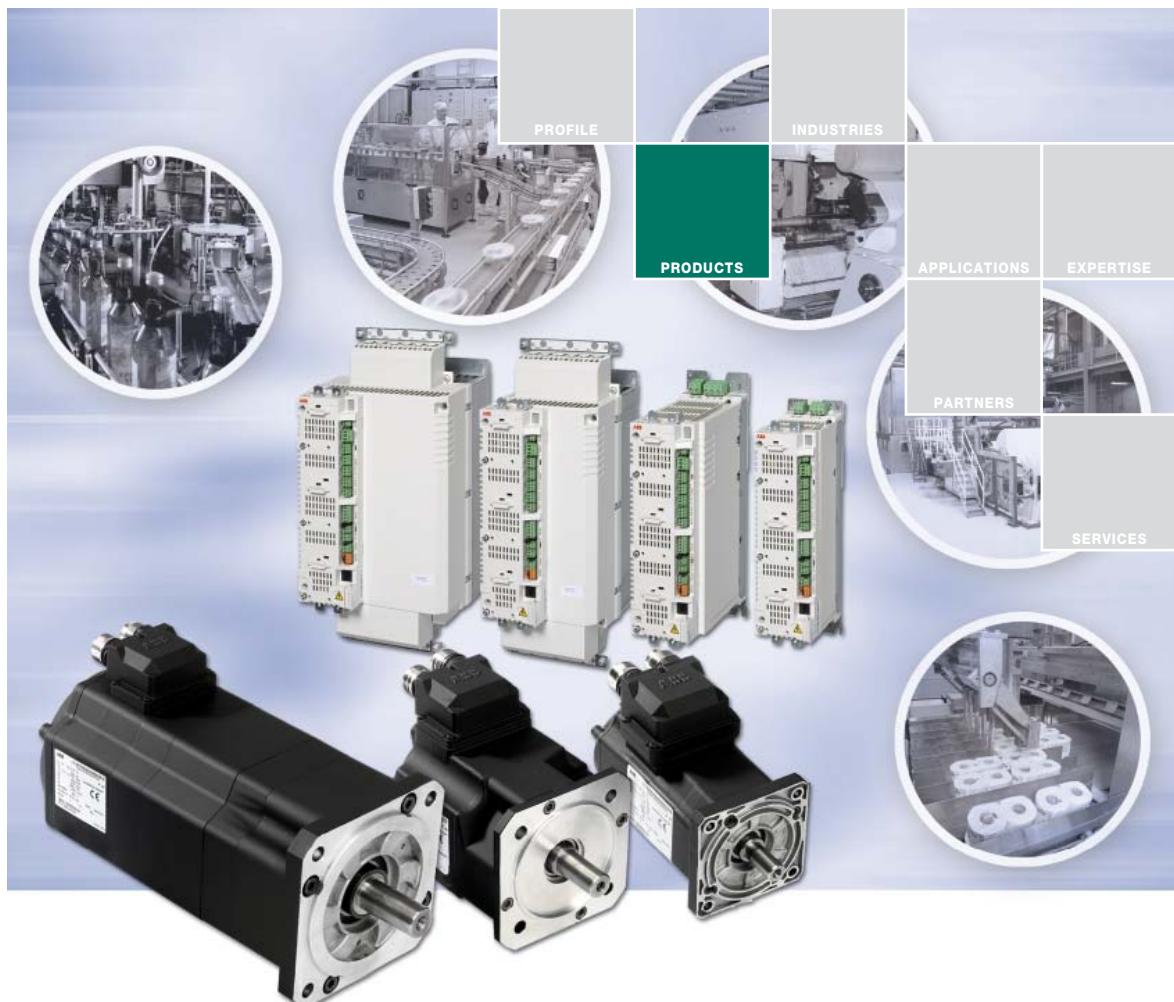


ABB servo motors

9C series

for ABB high performance machinery drives

Technical catalogue



ABB

Contents



ABB servo motors 9C series for ABB high performance machinery drives

ABB servo motors	3
Technical specifications	4
Ordering information.....	6
Dimensions.....	8
Combined motor and drive performance	10
Cables.....	12
Motor speed/torque curves	13
Contact and web information.....	15



Matched drive and motor combination

The 9C series servo motor and the ABB high performance machinery drive ACSM1 provide a compact and powerful package for machine building and other applications requiring high precision.

ABB servo motors

The 9C series of ABB servo motors is ideal for operation with the ABB high performance machinery drives. The motors are manufactured using the most advanced technology:

- Concentrated windings
- Encapsulation of windings with epoxy resin under vacuum
- Special composite magnetic material
- Modular structure
- Smart solution on connections
- Low cogging torque

ABB high performance machinery drives

ABB high performance machinery drives provide speed, torque and motion control for demanding applications. They can control induction, synchronous and asynchronous servo and high torque motors with a variety of feedback devices. The compact hardware and various control arrangements ensure optimum solutions for many different needs.

Feature	Advantage	Benefit
9C series AC synchronous servo motors		
Concentrated windings	Low energy consumption Extremely compact	Reduced running costs Space savings, easy to fit in restricted spaces
Encapsulation of windings with epoxy resin under vacuum	Motor winding partial discharge free up to 3 kV Uniform temperature on the motor windings	High product reliability
Special composite material "Soft Magnetic Composite"	Low losses in high frequency	Higher nominal speed
Modular structure	More variants with standard components	Short delivery time
Flexible connection methods	Connectors easy to turn back to front Easy-to-use plug-in connectors or cost-effective internal connections	Maximum connection flexibility Time savings Cost savings
High stall and rated torque	Excellent torque/dimensions ratio	Efficient space usage
Very low rotor inertia	High dynamic performance	High acceleration in very heavy duty cycle
Most common feedback devices available	Resolver Optical multturn SinCos encoder, Endat 2.1	Cost-effective and very reliable solution in harsh environmental conditions Very high performance
Optional integrated holding brake with high dynamic characteristics	Permanent magnet brake Spring holding brake	Holding brake without any backlash Suitable for dynamic emergency braking
Shaft with keyway - delivery contains half and full key	Full key for belt and pulley transmission or half key for friction coupling transmission	Wide flexibility, one motor for two different applications
Ready-made power and feedback cables	Complete package solution	Guaranteed quality of final installation
Motors delivered from centralized stock	Well organized logistics	Motors available on customer site in a few days

Technical specifications



General specifications

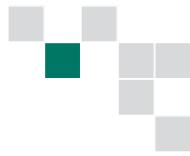
9C series AC synchronous servo motors	
Mounting	IMB5, V1, V3
Cooling	IC-0041 (EN 60034-6)
Motor pole pairs	5
Operating temperature range	0 to 40°C, up to 50 °C (derating of 1% per 1 °C must be applied above 40 °C)
Storage temperature range	-30 to 85 °C
Operating humidity range	85% max w/o condensation
Insulation class	F
Thermal protection	PTC
Compliance	CE, UL pending
Degree of protection	Body: IP65 Shaft: IP54 standard, IP64 with oil seal
Motor feedback	Resolver, one pole pair, size 15. Optical encoder, 1Vpp 512 signal periods per revolution, absolute position, multiturn (Endat) 4096 revolutions. Inductive encoder, 1Vpp 32 signal periods per revolution, absolute position, multiturn (Endat) 4096 revolutions.

Optional holding brake specification

Motor type	Rated voltage	Input power	Input current	Braking torque	Armature release time	Armature pull-in time	Inertia	Weight (Approx.)
	[VDC]	[W]	[A]	[Nm]	[ms]	[ms]	[kgcm ²]	[kg]
9C1	24	6.3	0.26	2.5	50	30	0.102	0.5
9C4	24	19.5	0.81	16	70	30	0.73	1.1
9C5	24	28.0	1.17	30	75	30	1.82	1.8

Note: Release and pull-in time values apply with ABB varistor 5248 122-256 wired into electrical circuit.

Ordering information



9C series type code

9	C	x	x	x	x	0	x	x	0	0	0	x	1	M	0	0
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17

Character	Explanation	Alternatives	Made-to-stock			Made-to-order			Notes
			9C1	9C4	9C5	9C1	9C4	9C5	
1 - 2	Product series	9C	x	x	x	x	x	x	
3	Motor size	1	x			x			
		4		x			x		
		5			x			x	
4	Motor length	1	x	x		x	x		
		2		x	x	x	x	x	
		3	x		x	x	x	x	
		4		x		x	x	x	
		6			x			x	
5 - 6	Rated speed	20						x	2000 r/min
		30	x	x	x	x	x	x	3000 r/min
		40					x		4000 r/min
		60				x			6000 r/min
7	Flange	0	x			x			F100
		0		x			x		F115
		0			x			x	F165
8 - 9	Feedback device	R0	x	x	x	x	x	x	Relresolver size 15
		E0	x	x	x	x	x	x	Optical encoder EQN1325, 1Vpp 512 signal periods, absolute multiturn position
		E1				x	x	x	Inductive encoder EQI1331, 1Vpp 32 signal periods, absolute multiturn position
10	Connector	0	x	x	x	x	x	x	Signal connector 17 pins and power connector 8 pins
		2				x	x	x	Cable glands for signal and power connections
11	Mechanical and vibration tolerances	0	x	x	x	x	x	x	Class "N" DIN 42955 - "N" DIN 45665
12	Shaft details	0	x	x	x	x	x	x	Shaft with keyway - half key fitted, full key included in the shipment
13	Brake	0	x	x	x	x	x	x	No brake
		1	x	x	x	x	x	x	Spring holding brake
14	Thermal switch	1	x	x	x	x	x	x	PTC type
15	DC bus voltage	M	x	x	x	x	x	x	560 V (drive supply 400 V)
16 - 17	Special execution	00	x	x	x	x	x	x	No special execution

Ordering information for stock items



Resolver motor without brake

Motor type code	Product ordering code
9C1.1.30.0.R0.0.0.0.0.1.M.00	68881358
9C1.3.30.0.R0.0.0.0.0.1.M.00	68881366
9C4.1.30.0.R0.0.0.0.0.1.M.00	68881374
9C4.2.30.0.R0.0.0.0.0.1.M.00	68881382
9C4.4.30.0.R0.0.0.0.0.1.M.00	68959951
9C5.2.30.0.R0.0.0.0.0.1.M.00	68881412
9C5.3.30.0.R0.0.0.0.0.1.M.00	68881421
9C5.6.30.0.R0.0.0.0.0.1.M.00	68881439

Resolver motor with brake

Motor type code	Product ordering code
9C1.1.30.0.R0.0.0.0.1.1.M.00	68881528
9C1.3.30.0.R0.0.0.0.1.1.M.00	68881544
9C4.1.30.0.R0.0.0.0.1.1.M.00	68881552
9C4.2.30.0.R0.0.0.0.1.1.M.00	68881561
9C4.4.30.0.R0.0.0.0.1.1.M.00	68959985
9C5.2.30.0.R0.0.0.0.1.1.M.00	68881587
9C5.3.30.0.R0.0.0.0.1.1.M.00	68881595
9C5.6.30.0.R0.0.0.0.1.1.M.00	68881609

Absolute encoder motor without brake

Motor type code	Product ordering code
9C1.1.30.0.E0.0.0.0.0.1.M.00	68881447
9C1.3.30.0.E0.0.0.0.0.1.M.00	68881455
9C4.1.30.0.E0.0.0.0.0.1.M.00	68881463
9C4.2.30.0.E0.0.0.0.0.1.M.00	68881471
9C4.4.30.0.E0.0.0.0.0.1.M.00	68959969
9C5.2.30.0.E0.0.0.0.0.1.M.00	68881498
9C5.3.30.0.E0.0.0.0.0.1.M.00	68881501
9C5.6.30.0.E0.0.0.0.0.1.M.00	68881510

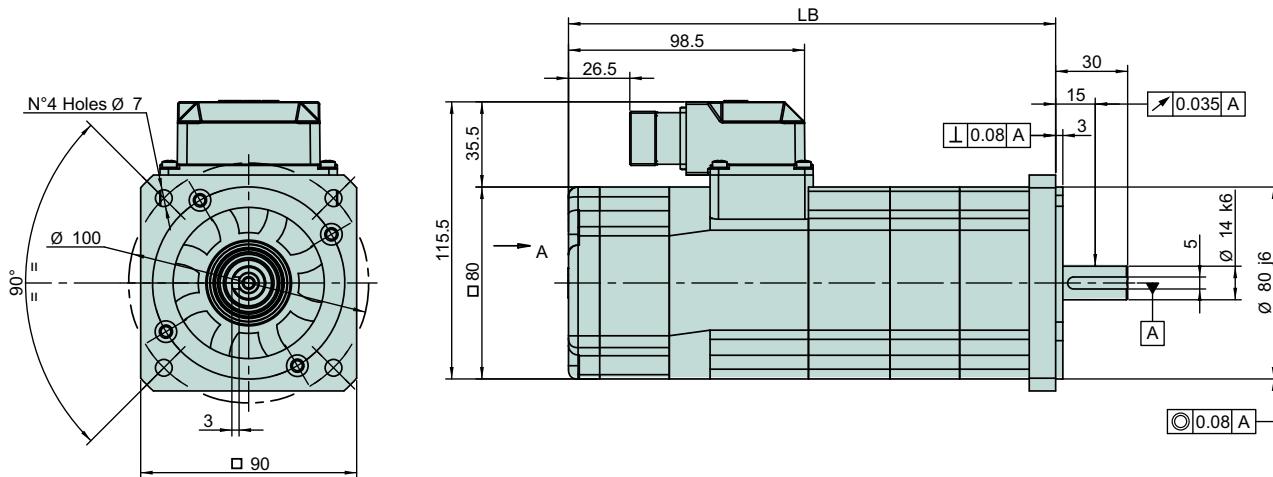
Absolute encoder motor with brake

Motor type code	Product ordering code
9C1.1.30.0.E0.0.0.0.1.1.M.00	68881633
9C1.3.30.0.E0.0.0.0.1.1.M.00	68881650
9C4.1.30.0.E0.0.0.0.1.1.M.00	68881668
9C4.2.30.0.E0.0.0.0.1.1.M.00	68881676
9C4.4.30.0.E0.0.0.0.1.1.M.00	68959993
9C5.2.30.0.E0.0.0.0.1.1.M.00	68881692
9C5.3.30.0.E0.0.0.0.1.1.M.00	68881706
9C5.6.30.0.E0.0.0.0.1.1.M.00	68881714

Dimensions

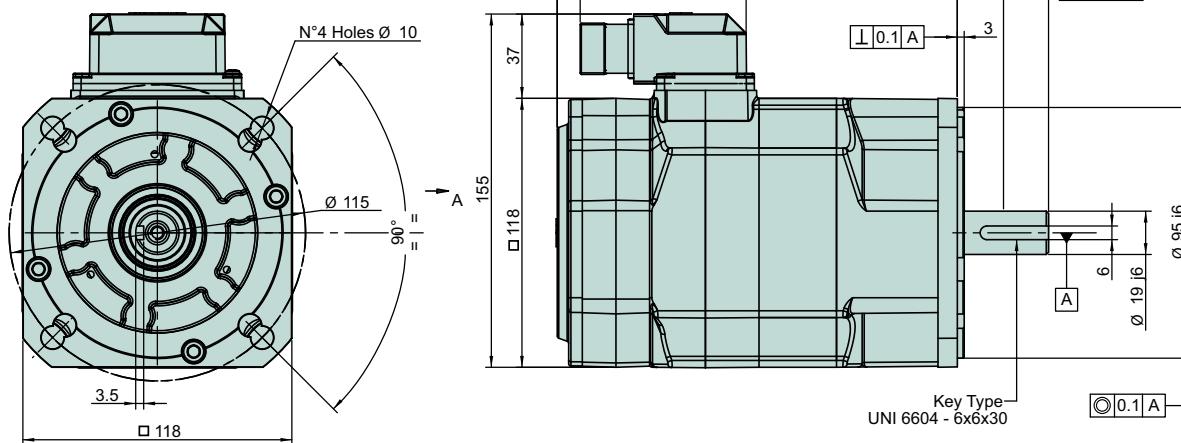


9C1



Motor size	9C1.1	9C1.2	9C1.3	9C1.4
LB with resolver [mm]	142	176	210	244
LB with encoder [mm]	171	205	239	273
LB with brake [mm]	171	205	239	273
LB with brake + encoder [mm]	200	234	268	302

9C4

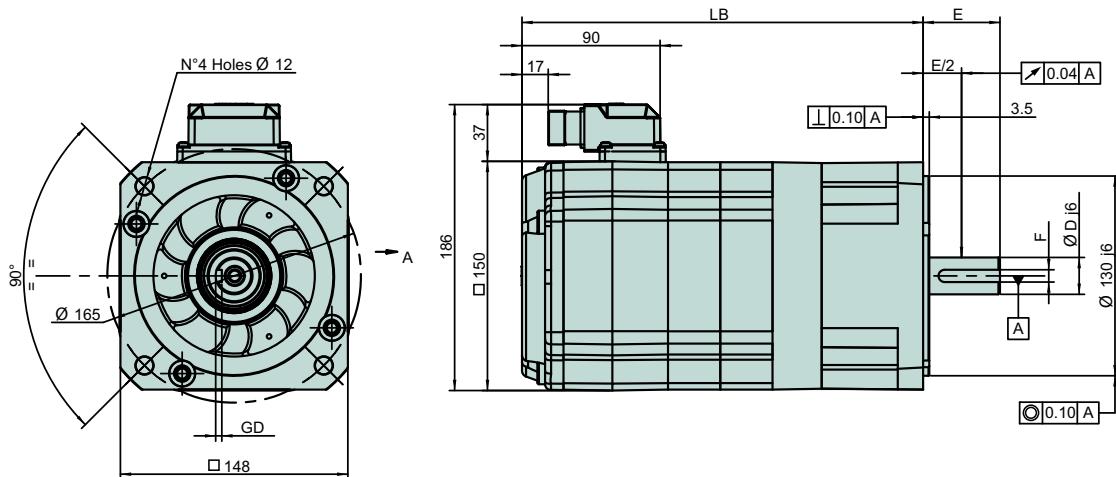


Motor size	9C4.1	9C4.2	9C4.3	9C4.4
LB with resolver [mm]	146	180	214	248
LB with encoder [mm]	175.5	209.5	243.5	277.5
LB with brake [mm]	175.5	209.5	243.5	277.5
LB with brake + encoder [mm]	205	239	273	307

Dimensions



9C5



Motor size	9C5.2	9C5.3	9C5.4	9C5.6
LB with resolver [mm]	261	295	329	397
LB with encoder [mm]	261	295	329	397
D shaft diameter [mm]	24	24	32	32
E shaft length [mm]	50	50	58	58
GD keyway depth [mm]	4	4	5	5
F keyway width [mm]	8	8	10	10
Key type	UNI6604 - 8x7x40		UNI6604 - 10x8x36	

Combined motor and drive performance



Combined motor and drive performance

The following two tables show which ACSM1 drives match which 9C series servo motor. The combined motor and drive performance helps to identify the best combination for your application. The first table lists the made-to-stock models, while the second table lists the made-to-order models of the 9C series of ABB servo motors.

Made-to-stock models

Motor type	T_{rat} ¹⁾ [Nm]	T_{pk} ²⁾ [Nm]	I_{rat} ³⁾ [A]	I_{pk} ⁴⁾ [A]	Drive type	$I_{2cont8k}$ ⁶⁾ cyclic load [A]	I_{2max} ⁷⁾ [A]	Combined T_{rat} ⁸⁾ [Nm]	Combined T_{pk} ⁹⁾ [Nm]
9C1.1.30	1.3	4.1	1.4	4.6	ACSM1-04Ax ⁵⁾ -02A5-4	1.9	5.3	1.3	4.1
9C1.3.30	2.8	9.6	2.5	9.3	ACSM1-04Ax ⁵⁾ -02A5-4	1.9	5.3	2.1	5.5
	2.8	9.6	2.5	9.3	ACSM1-04Ax ⁵⁾ -03A0-4	2.3	6.3	2.5	6.5
9C4.1.30	2.8	9.6	2.5	9.3	ACSM1-04Ax ⁵⁾ -04A0-4	3.0	8.4	2.8	8.7
	2.8	9.6	2.5	9.3	ACSM1-04Ax ⁵⁾ -05A0-4	3.8	10.5	2.8	9.6
9C4.2.30	3.9	12.9	2.8	9.8	ACSM1-04Ax ⁵⁾ -03A0-4	2.3	6.3	3.1	8.3
	3.9	12.9	2.8	9.8	ACSM1-04Ax ⁵⁾ -04A0-4	3.0	8.4	3.9	11.1
9C4.4.30	3.9	12.9	2.8	9.8	ACSM1-04Ax ⁵⁾ -05A0-4	3.8	10.5	3.9	12.9
	6.1	22.5	4.3	16.7	ACSM1-04Ax ⁵⁾ -04A0-4	3.0	8.4	4.3	11.3
9C4.2.30	6.1	22.5	4.3	16.7	ACSM1-04Ax ⁵⁾ -05A0-4	3.8	10.5	5.3	14.1
	6.1	22.5	4.3	16.7	ACSM1-04Ax ⁵⁾ -07A0-4	4.1	14.7	5.9	19.8
9C4.4.30	6.1	22.5	4.3	16.7	ACSM1-04Ax ⁵⁾ -09A5-4	7.1	16.6	6.1	22.4
	7.5	36.0	5.4	27.3	ACSM1-04Ax ⁵⁾ -012A-4	9.0	21.0	7.5	27.7
9C4.4.30	7.5	36.0	5.4	27.3	ACSM1-04Ax ⁵⁾ -016A-4	9.8	28.0	7.5	36.0
	7.5	36.0	5.4	27.3	ACSM1-04Ax ⁵⁾ -024A-4	18.0	42.0	7.5	36.0
9C5.2.30	9.0	36.9	6.9	30.0	ACSM1-04Ax ⁵⁾ -09A5-4	7.1	16.6	9.0	20.4
	9.0	36.9	6.9	30.0	ACSM1-04Ax ⁵⁾ -012A-4	9.0	21.0	9.0	25.8
9C5.2.30	9.0	36.9	6.9	30.0	ACSM1-04Ax ⁵⁾ -016A-4	9.8	28.0	9.0	34.4
	9.0	36.9	6.9	30.0	ACSM1-04Ax ⁵⁾ -024A-4	18.0	42.0	9.0	36.9
9C5.3.30	12.4	55.2	8.6	40.3	ACSM1-04Ax ⁵⁾ -09A5-4	7.1	16.6	10.3	22.7
	12.4	55.2	8.6	40.3	ACSM1-04Ax ⁵⁾ -012A-4	9.0	21.0	12.4	28.8
9C5.3.30	12.4	55.2	8.6	40.3	ACSM1-04Ax ⁵⁾ -016A-4	9.8	28.0	12.4	38.4
	12.4	55.2	8.6	40.3	ACSM1-04Ax ⁵⁾ -024A-4	18.0	42.0	12.4	55.2
9C5.6.30	18.0	90.0	12.1	64.1	ACSM1-04Ax ⁵⁾ -016A-4	9.8	28.0	14.5	39.3
	18.0	90.0	12.1	64.1	ACSM1-04Ax ⁵⁾ -024A-4	18.0	42.0	18.0	59.0
9C5.6.30	18.0	90.0	12.1	64.1	ACSM1-04Ax ⁵⁾ -031A-4	23.3	54.0	18.0	75.8
	18.0	90.0	12.1	64.1	ACSM1-04Ax ⁵⁾ -040A-4	26.3	70.0	18.0	90.0

¹⁾ Rated torque of the motor

²⁾ Intermittent peak torque of the motor

³⁾ Rated current of motor

⁴⁾ Intermittent peak current of the motor

⁵⁾ Control type (torque, speed, motion) of the drive

⁶⁾ Continuous output current of ACSM1 at a switching frequency of 8 kHz at 40 °C (104 °F)

⁷⁾ Maximum short time output current of ACSM1

⁸⁾ Combined rated torque

⁹⁾ Combined intermittent peak torque

Highlights of ACSM1

- For demanding applications
- For synchronous and asynchronous motors
- Wide range of feedback interfaces
- Memory unit for easy drive management
- Safe torque-off function as standard

Note!

The combined motor and drive performance in the table assumes 8 kHz switching frequency with cyclic load. The combined values are subject to ACSM1 supply voltage, ambient temperature and installation altitude de-ratings.



Ready-made motor cables for ACSM1

Cable properties

- Polyurethane (PUR) outer sheath with good flexibility and low adhesion
- Flame retardant and halogen-free
- Resistant to abrasion and oil
- Conformity to the DESINA® -standard
- Motor power cables include brake control leads

Motor power cable

Product code	Conductor diam. [mm ²]	Length [m]	Cable
68822742	1.5	5	(4x1,5+(2x1,0))
68823285	1.5	10	(4x1,5+(2x1,0))
68823307	1.5	15	(4x1,5+(2x1,0))
68823323	1.5	20	(4x1,5+(2x1,0))
68823331	1.5	25	(4x1,5+(2x1,0))
68867029	2.5	5	(4x2,5+(2x1,0))
68867037	2.5	10	(4x2,5+(2x1,0))
68867053	2.5	15	(4x2,5+(2x1,0))
68867061	2.5	20	(4x2,5+(2x1,0))
68867070	2.5	25	(4x2,5+(2x1,0))
68867088	4.0	5	(4x4,0+(2x1,0))
68867096	4.0	10	(4x4,0+(2x1,0))
68867100	4.0	15	(4x4,0+(2x1,0))
68867118	4.0	20	(4x4,0+(2x1,0))
68867126	4.0	25	(4x4,0+(2x1,0))

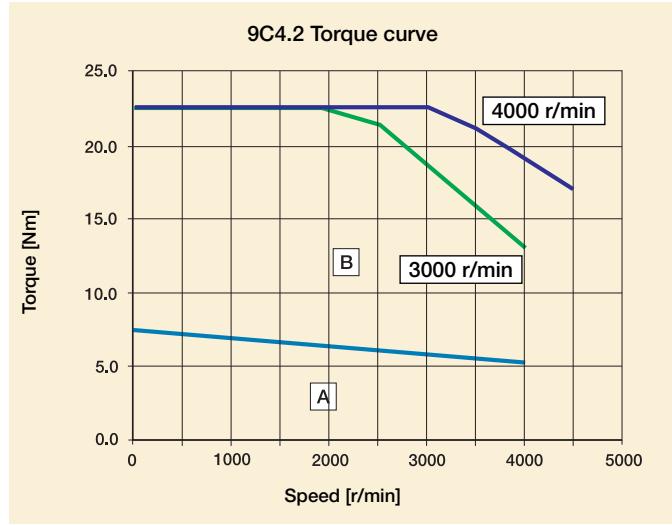
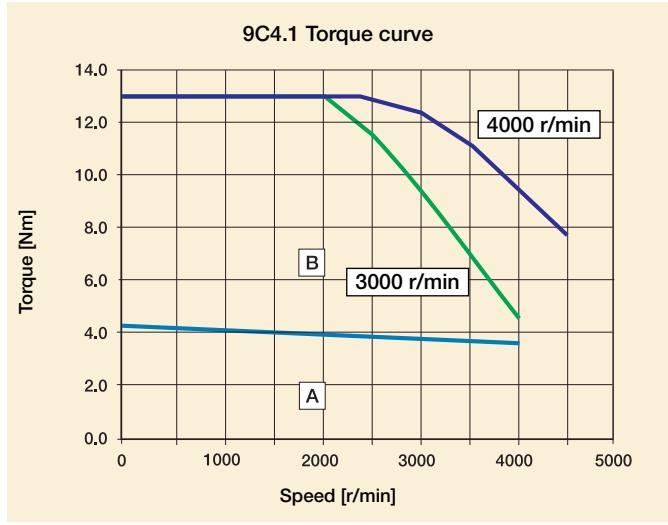
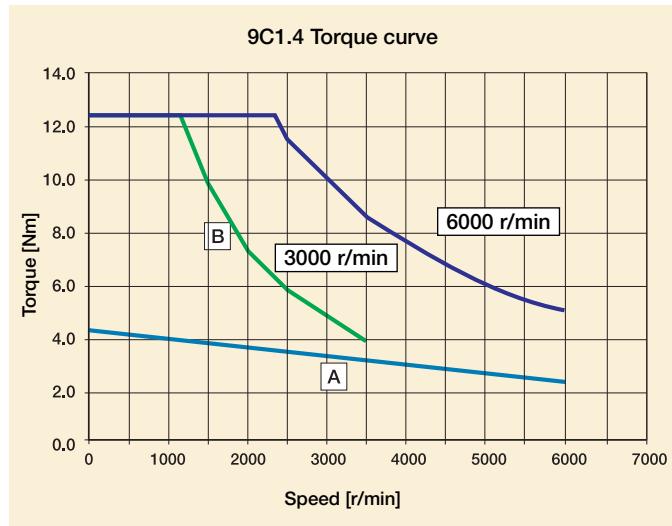
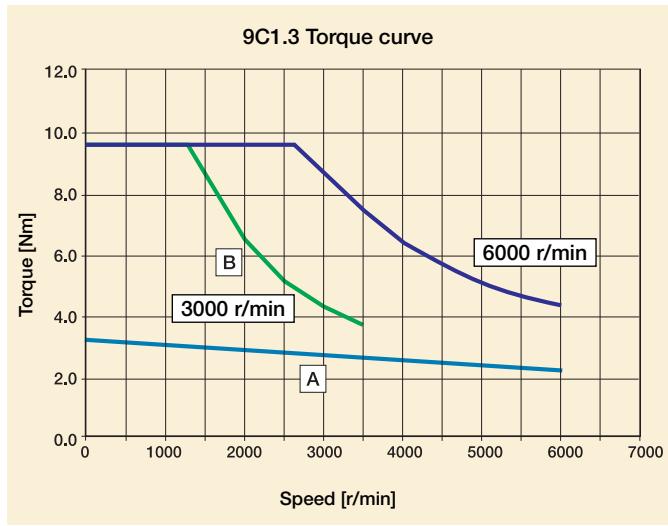
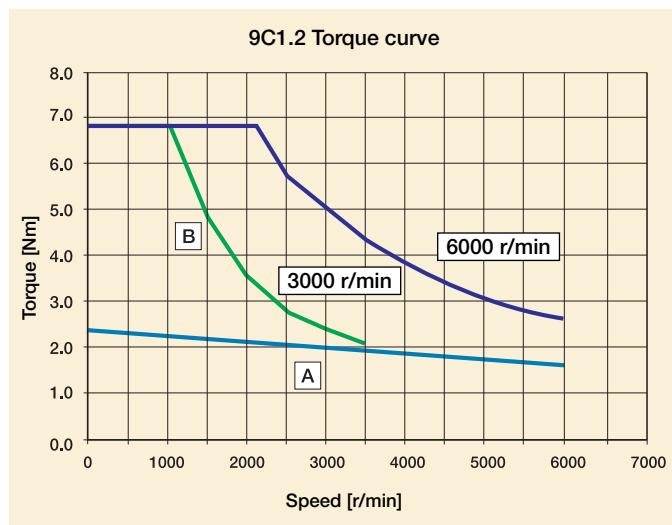
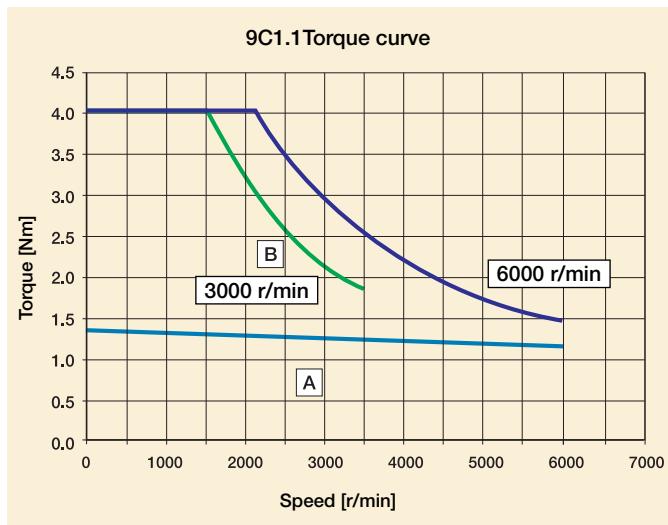
Resolver feedback cable

Product code	Length [m]	Cable
68861721	5	(3x(2x0,14)+(2x0,14))
68861730	10	(3x(2x0,14)+(2x0,14))
68861748	15	(3x(2x0,14)+(2x0,14))
68861756	20	(3x(2x0,14)+(2x0,14))
68861764	25	(3x(2x0,14)+(2x0,14))

Encoder feedback cable

Product code	Length [m]	Cable
68959187	5	(8x2x0,25)
68959209	10	(8x2x0,25)
68959217	15	(8x2x0,25)
68959225	20	(8x2x0,25)
68959233	25	(8x2x0,25)

Motor speed/torque curves

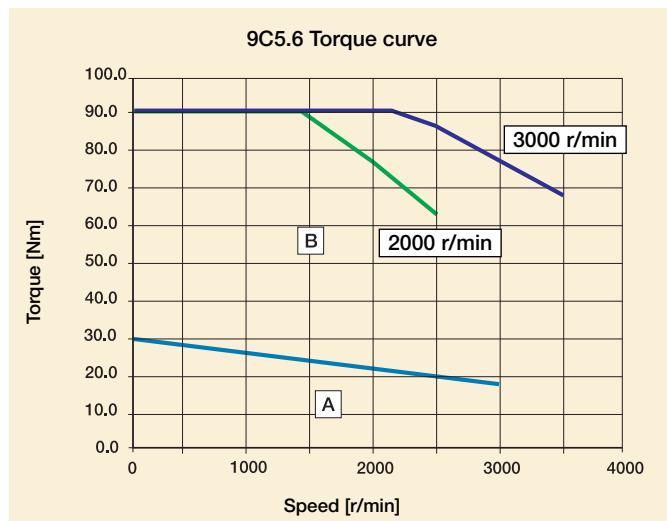
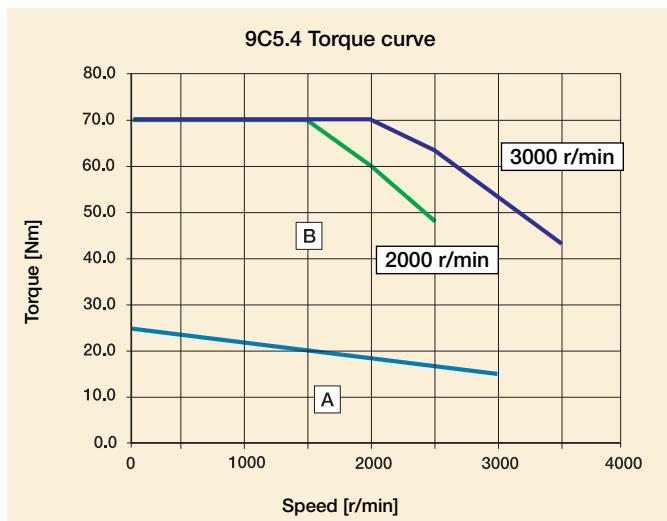
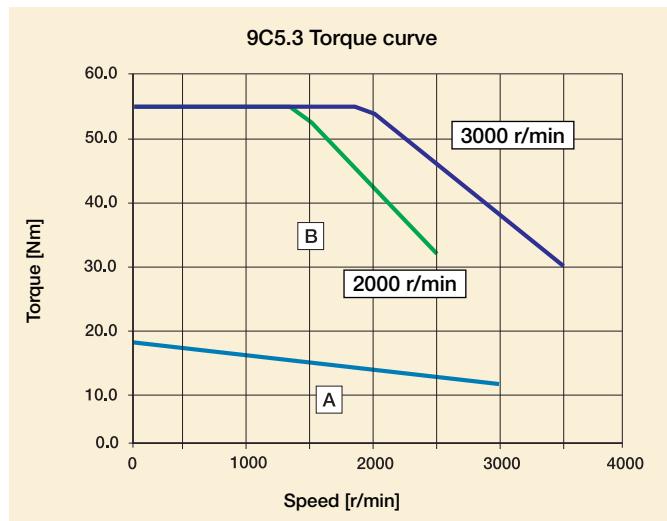
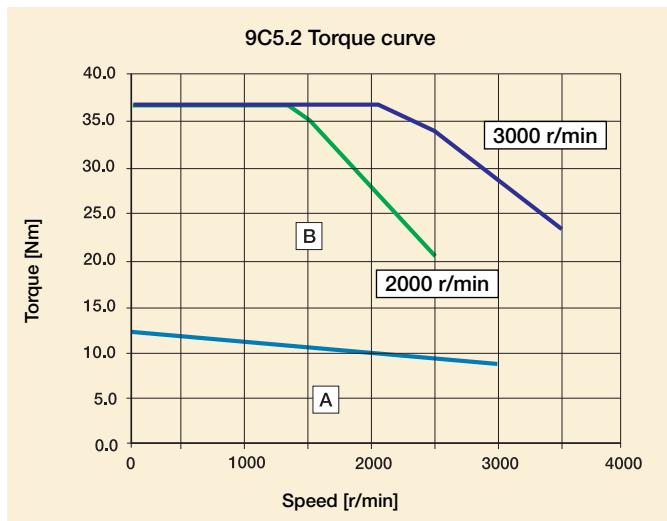
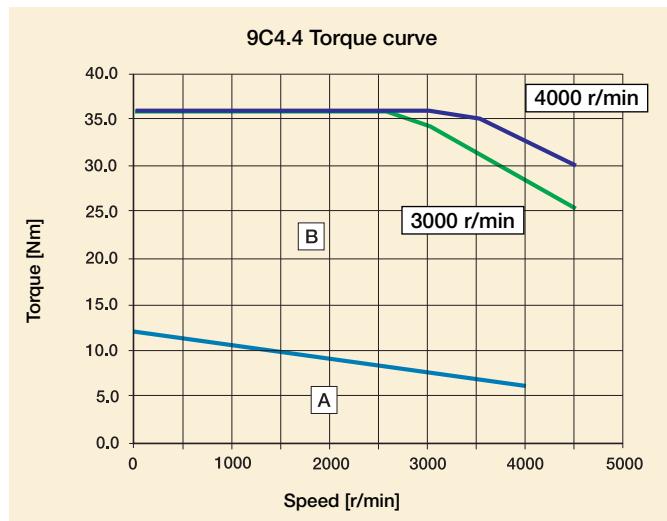
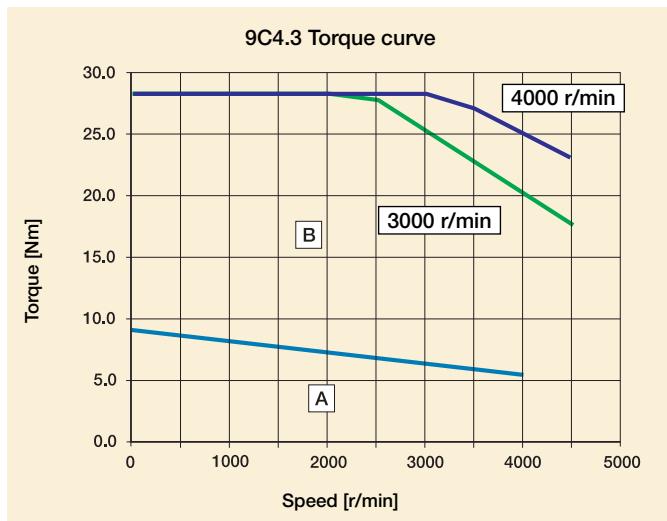


[A] Continuous operation zone
[B] Intermittent operation zone

Note!

All performance data is measured at duty type S1, ambient temperature 40 °C,
mounted on steel flange (dim. 300 x 300 x 20 mm), altitude ≤ 1000 m above sea level.

Motor speed/torque curves



[A] Continuous operation zone

Note!

[B] Intermittent operation zone

All performance data is measured at duty type S1, ambient temperature 40 °C,
mounted on steel flange (dim. 300 x 300 x 20 mm), altitude ≤ 1000 m above sea level.



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