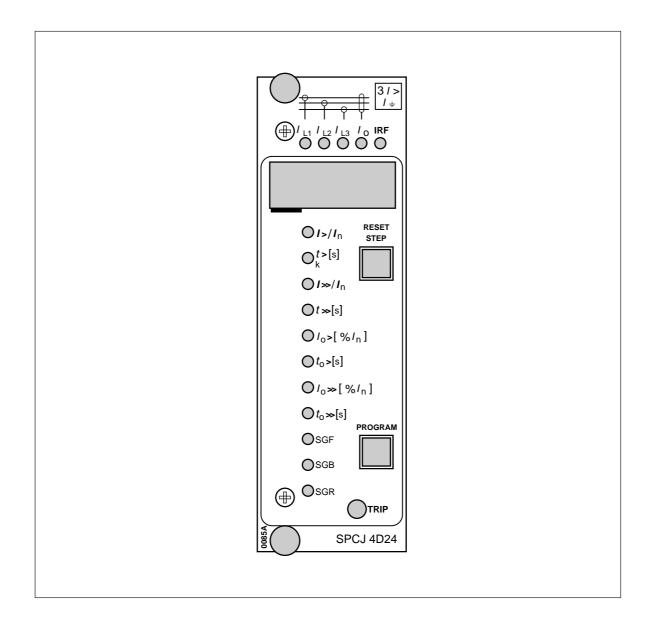
# SPCJ 4D24 Combined overcurrent and earth-fault relay module

User's manual and Technical description





#### 1MRS 750121-MUM EN

Issued 1995-09-14 Modified 2002-05-15 Version B (replaces 34 SPCJ 9 EN1) Checked MK Approved OL

# SPCJ 4D24 Combined overcurrent and earth-fault relay module

Data subject to change without notice

Contents	Features Description of function Block diagram Front panel Operation indicators Settings Programming switches Measured data Recorded information Main menus and submenus of settings and regis		
	Time/current characteristics <i>(modified 2002-05)</i> Technical data Serial communication parameters Fault codes		
Features	A low-set overcurrent stage I> with a definite time and six inverse time modes of operation	Digital display of measured and set values and sets of data recorded at the moment when faults occur	
	A high-set overcurrent stage I>> with a setting range of $0.540 \times I_n$ . The operation of the high- set overcurrent stage can be set out of function	All settings may be keyed in using the push- buttons of the front panel or they may be set using a personal computer	
	A low-set neutral overcurrent stage $I_0$ > with a setting range of 1.025.0 % $I_n$ and definite time mode of operation		
	A high-set neutral overcurrent stage $I_0$ >> with a setting range of 2.0200 % $I_n$ . The opera-	outputs are blocked.	

tion of the high-set neutral over current stage

can be set out of function

Overcurrent unit

The overcurrent unit of the combined overcurrent and earth-fault module SPCJ 4D24 is designed for single-phase, two-phase or threephase operation. It contains two overcurrent stages, i.e. a low-set overcurrent stage I> and a high-set overcurrent stage I>>.

The low-set or high-set current stage starts if the current on one of the phases exceeds the setting value of the stage concerned. When starting, the concerned stage provides a starting signal SS1 or TS1 and simultaneously the digital display on the front panel indicates starting. If the overcurrent situation lasts long enough to exceed the set operating time, the stage that started calls for a C.B. tripping by providing a tripping signal TS2. At the same time the operation indicator goes on with red light. The red operation indicator remains on although the stage resets. The indicator is reset with the RE-SET push-button. By proper configuration of the output relay switchgroups an additional auxiliary trip signal TS1 can be generated.

The maximum continuous current carrying capacity of the energizing inputs is  $4 \ge I_n$ , which must be observed when relay settings are calculated.

The operation of the low-set overcurrent stage I> or the high-set overcurrent stage I>> can be blocked by bringing a blocking signal BS to the unit. The blocking configuration is set by means of switchgroup SGB.

The operation of the low-set overcurrent stage can be based on a definite time or an inverse time characteristic. The mode of operation is programmed with SGF1/1...3. At definite time mode of operation the operating time t> is directly set in seconds within the setting range, 0.05...300 s. When using inverse time mode of operation (I.D.M.T.) four internationally standardized and two special type time/current characteristics are available. The programming switches SGF1/1...3 are also used for selecting the desired operation characteristic.

The operating time t>> of the high-set overcurrent stage is set separately within the range 0.04...300 s. The operation of the two overcurrent stages is provided with a latching facility (switch SGB/6) keeping the tripping output energized, although the signal which caused the operation disappears. The stages are reset by simultaneous pressing of the push-buttons RESET and PRO-GRAM, see section "Programming switches".

The setting value  $I >>/I_n$  of the high-set overcurrent stage may be subject to automatic doubling when connecting the protected object to the network, i.e. in a starting situation. Thus the setting value of the high-set overcurrent stage may be lower than the connection inrush current. The automatic doubling function is selected with switch SGF1/5. The starting situation is defined as a situation where the phase currents rise from a value below 0.12 x I> to a value exceeding 1.5 x I> in less than 60 ms. The starting situation comes to an end when the currents fall below 1.25 x I>.

The setting range of the high-set overcurrent stage is  $0.5...40 \times I_n$ . When selecting a setting in the lower end of the range, the module will contain two almost identical operation stages. In this case the overcurrent unit of the SPCJ 4D24 module may be used for e.g. two-stage load shedding purposes.

The operation of the high-set overcurrent stage may be set out of operation by means of switch SGF2/5. When the high-set unit is set out of operation the display shows a "- - -" readout, indicating that the operating value is infinite.

#### Note!

At inverse time characteristic the effective setting range of the low-set overcurrent stage is  $0.5...2.5 \times I_n$ , although start current settings within the range  $2.5...5.0 \times I_n$  can be set on the relay. At inverse time characteristic any start current setting above  $2.5 \times I_n$  of the low-set stage will be regarded as being equal to  $2.5 \times I_n$ .

#### Note!

The operation of the low-set stage based on inverse time characteristic will be blocked by starting of the high-set stage. Then the operate time of the overcurrent unit is determined by the set operate time of the high-set stage at heavy fault currents.

Earth-fault unit	The non-directional earth-fault unit of the module SPCJ 4D24 is a single-pole neutral current or residual current overcurrent unit. It contains two neutral overcurrent stages, i.e. a low-set overcurrent stage I <sub>0</sub> > and a high-set overcurrent stage I <sub>0</sub> >>. The low-set or high-set overcurrent stage starts if the current to be measured exceeds the setting value of the stage concerned. When starting, the stage provides a starting signal SS1 or TS1 and simultaneously the operation indicator on the front panel indicates starting. If the earth-fault situation lasts long enough to exceed the set operating time, the stage that started calls for a C.B. tripping by providing a tripping signal TS2. At the same time the red operation indicator of the tripping stage goes on. The operation indicator remains on although the stage resets. The indicator is reset with the RE-SET push-button. The neutral current measured by the earth-fault unit is filtered in a low-pass filter which effectively reduces the amount of harmonics in the measured signal. For example the third harmonics is reduced even more. The operation of the low-set overcurrent stage I <sub>0</sub> > or the high-set stage I <sub>0</sub> >> can be blocked by applying a blocking signal BS onto the stage. The blockings are programmed by means of switchgroup SGB on the front of the plug-in module.	The operation of the low-set neutral current stage I <sub>0</sub> > is based on a definite time character- istic. The operating time t <sub>0</sub> > can be set within the setting range 0.05300 s. The operating time t <sub>0</sub> >> of the high-set current stage is set separately within the range 0.05 300 s. The operation of the two neutral overcurrent stages is provided with a latching facility (switch SGB/7) keeping the tripping output energized, although the signal which caused the operation disappears. The stages are reset by simultane- ous pressing of the push-buttons RESET and PROGRAM, see section "Programming switches". The operation of the high-set earth-fault stage may be inhibited when connecting the pro- tected object to the network, i.e. when the low- set stage of the overcurrent unit is started. Thus it is possible to avoid malfunction due to vir- tual earth-fault currents caused by current trans- former anomalies in connection with the con- nection inrush current. The automatic inhibit- ing function is selected with switch SGF1/6. The operation of the high-set earth-fault stage I <sub>0</sub> >> may be totally blocked by means of switch SGF2/6. When the high-set stage is set out of operation, the display shows a "" readout, indicating that the setting value is infinite.
Circuit breaker failure protection	The unit is also provided with a circuit breaker failure protection (CBFP), which gives a trip signal via TS1 within a set time 0.11 s after the normal trip signal TS2, if the fault has not been cleared within that time. The output con- tact of the circuit breaker failure protection is normally used for tripping an upstream circuit breaker. The CBFP can also be used to estab-	lish a redundant trip system by using dual trip coils on the circuit breaker and wiring one of them to TS2 and the other one to TS1. The circuit breaker failure protection is selected by means of switch SGF1/4. The setting of the time delay can be made using submenu position five in register A.
Remote settings	All the main setting values may be provided with alternative setting values that can be called up by remote control. The switching between main and remote settings is normally made by utiliz- ing the serial communication link. If the serial	communication is not used, the control input signal BS can be programmed to perform the switching too. Finally manual switching be- tween setting banks can be made using submenu position four in register A.

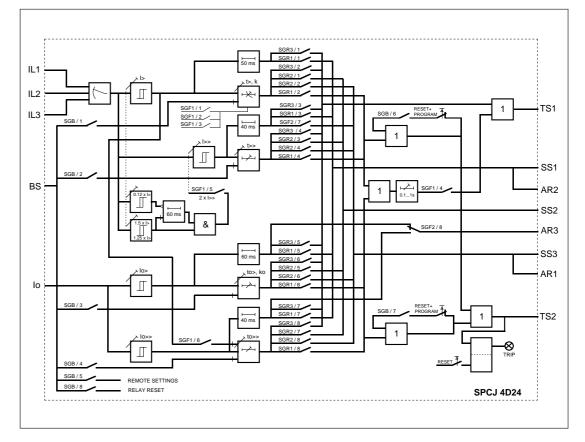


Fig. 1. Block diagram for overcurrent and earth-fault module SPCJ 4D24

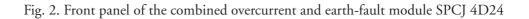
$I_{L1}, I_{L2}, I_{L3}$	Measured phase currents
I <sub>0</sub>	Measured neutral current
BS1	External blocking or resetting signal
SGF	Programming switchgroup SGF on the front panel
SGB	Programming switchgroup SGB on the front panel
SGR13	Programming switchgroups SGR on the front panel
TS1	Starting signal1 or auxiliary tripping signal depending on programming
	of switchgroup SGR3
SS1	Start signal for stages selected with switchgroup SGR1
SS2	Trip signal 1 for stages selected with switchgroup SGR2
SS3	Trip signal 2 for stages selected with switchgroup SGR2
TS2	Tripping signal from stages selected with switchgroup SGR1
AR1, AR2, AR3	Starting signals to autoreclose unit
TRIP	Red indicator for tripping

Note!

All input and output signals of the module are not necessarily wired to the terminals of every relay assembly using this module. The signals in modules

wired to the terminals are shown in the diagram illustrating the flow of signals between the plugin modules of the relay assembly.

31> Current measurement indicators for phases L1, L2, L3 and I<sub>0</sub> RESET Indicator for starting value setting of stage I>  $O_{I>/I_n}$ STEP Indicator for setting of operating time t> or  $O_{k}^{t>[s]}$ time multiplier k of stage I> Indicator for starting value setting of stage I>>  $OI \gg /I_n$ Indicator for operating time setting of stage I>>  $Ot \gg [s]$ Indicator for starting value setting of stage  $I_0$ >  $O_{l_0>[\% l_n]}$ Indicator for setting of operating time  $t_0$ >  $Ot_0>[s]$ Indicator for starting value setting of stage  $I_0 >>$  $O_{I_0 \gg} [\% I_n]$ Indicator for operating time setting of stage  $I_0 >>$  $Ot_0 \gg [s]$ PROGRAM Indicator for switchgroup SGF1..2 checksum OSGF OSGB Indicator for switchgroup SGB checksum Indicator for switchgroup SGR1...3 checksum OSGR  $\oplus$ )TRIP SPCJ 4D24 31> Simplified device symbol ( ↓ 1 / 12 / 13 / 0 IRF Self-supervision alarm indicator Display RESET  $OI>/I_n$ STEP  $O_k^{t>[s]}$ Reset and display step push-button  $OI \gg /I_n$  $Ot \gg [s]$  $O_{I_0>}[\% I_n]$  $O_{t_0>[s]}$  $O_{l_0 \gg} [\% l_n]$  $Ot_0 \gg [s]$ PROGRAM OSGF Programming push-button OSGB OSGR (⊕) Trip indicator TRIP) Type designation of plug-in module SPCJ 4D24



Each overcurrent stage has its own starting indicator and operation indicator shown as a figure in the digital display. Further all stages share a common red LED indicator named "TRIP", which indicates that the module has delivered a tripping signal.

The operation indicator in the display remains illuminated when the current stage resets, thus indicating which protection stage was operating. The operation indicator is reset with the RESET push-button. The function of the plugin module is not affected by an activated operation indicator. If a starting of a stage is short enough not to cause a trip, the starting indication is normally self-reset when the stage is reset. By means of switches SGF2/1...4 if needed, the starting indicators can be programmed for manual resetting. The following table shows the starting and tripping indicators and their meanings.

Indication	Explanation	
1 2 3 4 5 6 7 8 9	I> START I> TRIP I>> START I>> TRIP I <sub>0</sub> > START I <sub>0</sub> > TRIP I <sub>0</sub> >> START I <sub>0</sub> >> TRIP CBFP	<ul> <li>The low-set stage I&gt; of the overcurrent unit has started</li> <li>The low-set stage I&gt; of the overcurrent unit has tripped</li> <li>The high-set stage I&gt;&gt; of the overcurrent unit has started</li> <li>The high-set stage I&gt;&gt; of the overcurrent unit has tripped</li> <li>The low-set stage I<sub>0</sub>&gt; of the earth-fault unit has started</li> <li>The low-set stage I<sub>0</sub>&gt; of the earth-fault unit has tripped</li> <li>The high-set stage I<sub>0</sub>&gt;&gt; of the earth-fault unit has started</li> <li>The high-set stage I<sub>0</sub>&gt;&gt; of the earth-fault unit has started</li> <li>The high-set stage I<sub>0</sub>&gt;&gt; of the earth-fault unit has started</li> <li>The high-set stage I<sub>0</sub>&gt;&gt; of the earth-fault unit has started</li> <li>The high-set stage I<sub>0</sub>&gt;&gt; of the earth-fault unit has started</li> </ul>

When one of the protection stages of the module performs a tripping, the indicators for the measured values of the module indicate the faulty phase, i.e. in which phase(s) the current has exceeded the setting value of the stage (so called phase fault indication). If for instance, the operation indicator of the I> stage is switched goes on and the indicators I<sub>L1</sub> and I<sub>L2</sub> are illuminated, the operation was caused by overcurrent in phases L1 and L2. When pressing the push-button RESET, the phase fault indication disappears. The self-supervision alarm indicator IRF indicates that the self-supervision system has detected a permanent fault. The indicator is lit with red light shortly after the fault has been detected. At the same time the plug-in module delivers a signal to the self-supervision system output relay of the protection assembly. Additionally, in most fault cases, a fault code showing the nature of the fault appears on the display of the module. The fault code, consisting of a red figure one and a green code number, persists until the STEP/RESET button is pressed. When a fault occurs, the fault code should be recorded and stated when ordering service. The setting values are shown by the right-most three digits of the display. An indicator close to the setting value symbol shows when illuminated which setting value is indicated on the display.

I>/I <sub>n</sub>	The operating current of the I> stage as a multiple of the rated current of the protection. Setting range 0.55.0 x $I_n$ at definite time characteristic and 0.52.5 x $I_n$ at inverse time characteristic.
t> k	The operating time of the I> stage, expressed in seconds, when in the definite time mode of operation (SGF1/1-2-3 = 0-0-0). The setting range is $0.05300$ s. At inverse definite minimum time mode of operation the time multiplier k setting range is $0.051.00$ .
I>>/I <sub>n</sub>	The starting current of the I>> stage as a multiple of the rated current of the protection. Setting range $0.540.0 \times I_n$ . Additionally, the setting "infinite" (displayed as n) can be selected, with switch SGF2/5, which makes the stage I>> inoperative.
t>>	The operating time of the I>> stage, expressed in seconds. The setting range is $0.04300 \text{ s}$
$I_0 > /I_n$	The starting current of the $\rm I_0>$ stage as a per cent of the rated current of the protection. Setting range 1.025.0 % $\rm I_n.$
t <sub>0</sub> >	The operating time of the $\rm I_0>$ stage, expressed in seconds. The setting range is 0.05300 s
I <sub>0</sub> >>/I <sub>n</sub>	The starting current of the I <sub>0</sub> >> stage as a percent of the rated current of the protec- tion. Setting range 2.0200% I <sub>n</sub> . Additionally, the setting "infinite" set by switch SGF2/6 (displayed as n) can be selected with switch SGF2/6 which makes the stage I <sub>0</sub> >> inoperative.
t <sub>0</sub> >>	The operating time of the $\rm I_0>>$ stage, expressed in seconds. The setting range is 0.05300 s

Further, the checksums of the programming switchgroups SGF1,SGB and SGR1 are indicated on the display when the indicators adjacent to the switchgroup symbols on the front panel are illuminated. The checksums for groups SGF2, SGR2 and SGR3 are found in the submenus of the corresponding first switchgroup. See further clause "Main menus and submenus of settings and registers". An example of calculating the checksum is given in the general description of the D-type SPC relay modules.

# Programming switches

Additional functions required by individual applications are selected by means of the switchgroups SGF, SGB and SGR indicated on the front panel. The numbering of the switches, 1...8, and the switch positions 0 and 1 are indicated when setting the switchgroups. In normal service only the checksums are shown. The switchgroups SGF2, SGR2 and SGR3 are found in the submenus of the switchgroups SGF and SGR.

Functional switch-		- ·				
group SGF1	Switch	Function				
	SGF1/1Switches SGF1/13 are used for selecting the operation characteristic of set overcurrent stage I>, i.e. definite time mode of operation or inverse d minimum time (I.D.M.T.) mode of operation. At inverse definite minim mode of operation the switches are, further, used for selecting the cur characteristic of the module.					
		SGF1/1         SGF1/2         SGF1/3         Mode of operation         Characteristics				
		$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				
	SGF1/4	Selection of the circuit breaker failure protection.				
		When SGF1/4 =1 the trip signal TS2 will start a timer which will produce a $0.11$ s delayed trip signal via TS1, if the fault has not been cleared before. With switch SGF1/4 = 0 only the normal trip signal TS2 is activated.				
	SGF1/5	Selection of automatic doubling of the setting value of the high-set overcurrent stage when the protected object is energized.				
		When SGF1/5 = 0, no doubling of the setting value I>> is obtained. When SGF1/5 = 1, the setting value of the I>> stage doubles automatically. This makes it possible to give the high-set current stage a setting value below the connection inrush current level.				
	SGF1/6	High-set stage of the earth-fault protection inhibited by starting of the low-set stage of the overcurrent unit				
		When SGF1/6 = 0, the operation of the high-set earth-fault protection is operating under all phase current conditions When SGF1/6 =1, the earth-fault protection is inhibited if the low-set stage of the overcurrent unit has started				
	SGF1/7	Reserved for future use				
	SGF1/8	Reserved for future use				

# Functional switchgroup SGF2

Switch	Function
SGF2/1 SGF2/2 SGF2/3 SGF2/4	Switches SGF2/14 are used for selecting the mode of operation of the starting indicators of the different stages. When the switches are in position 0 the starting signals are all automatically reset when the fault is cleared. In order to get a hand reset starting indication for a stage, the corresponding switch is brought into position 1:
	SGF2/1 = 1 equals manual resetting of the starting indication of stage I> SGF2/2 = 1 equals manual resetting of the starting indication of stage I>> SGF2/3 = 1 equals manual resetting of the starting indication of stage $I_0$ > SGF2/4 = 1 equals manual resetting of the starting indication of stage $I_0$ >>
SGF2/5	The high-set instantaneous operation of the stage I>> can be set out of operation by means of this switch.
	When SGF2/5 = 0 the high-set stage I>> is operative When SGF2/5 = 1 the high-set stage I>> is blocked and the display shows ""
SGF2/6	The high-set instantaneous operation of the stage $I_0$ >> can be completely set out of operation by means of this switch.
	When SGF2/6 = 0 the high-set stage $I_0>>$ is operative When SGF2/6 = 1 the high-set stage $I_0>>$ is blocked and the display shows ""
SGF2/7	The starting signal of the high-set overcurrent stage I>> brought to the auto-reclose signal output AR1
	When SGF2/7 = 1, the starting signal of I>> is controlling AR1. Note! The output is equal to SS3, which means that in this case an other signal must not be connected to same output! When SGF2/7 =0, the starting output of I>> is not affecting the output AR1 or SS3. Thus the signal output SS3 is available for other purposes.
SGF2/8	The starting signal from stage $I_0$ >- or stage $I_0$ >>- brought to auto-reclose signal output AR3
	When SGF2/8 = 0 the starting signal from stage $I_0$ > is controlling AR3 When SGF2/8 = 1 the starting signal from stage $I_0$ >> is controlling AR3

Blocking or control input switchgroup	Switch	Function
SĞB	SGB/14	Switches SGB/14 are used when the external control signal BS is to be used for blocking one or more of the current stages of the module. When all the switches are in position 0 no stage is blocked.
		When SGB/1 = 1, the stage I> is blocked by the input signal BS When SGB/2 = 1, the stage I>> is blocked by the input signal BS When SGB/3 = 1, the stage I <sub>0</sub> > is blocked by the input signal BS When SGB/4 = 1, the stage I <sub>0</sub> >> is blocked by the input signal BS
	SGB/5	This switch enables switching over from the main settings to the second settings and vice versa even without serial communication, using the external control in- put signal BS.
		When SGB/5 = 0, the settings are not to be remotely controlled or they are con- trolled via the serial communication only When SGB/5 = 1, the settings are remotely controlled or via the external input. Main values of the settings are used when there is no control voltage on the input and the second settings are enforced when a control voltage is connected to the control input.
		Note! Whenever main and second settings are used, care should be taken that the switch SGB/5 has the same position both in the main and second setting bank. Other- wise a conflict situation might occur when switching setting banks by contact or via serial communication.
	SGB/6	Selection of a latching feature for the tripping signal TS2 for overcurrent faults.
		When SGB/6 = 0, the tripping signal returns to its initial state (= the output relay drops off), when the measuring signal causing the operation falls below the starting level. When SGB/6 = 1, the tripping signal remains on (= the output relay operated), although the measuring signal falls below the starting level. Then the starting signals have to be reset by pressing the push-buttons RESET and PROGRAM simultaneously. <sup>1</sup>
	SGB/7	Selection of a latching feature for the trip signal TS2 for earth faults.
		When SGB/7 = 0, the tripping signal returns to its initial state (= the output relay drops off), when the measuring signal causing the operation falls below the starting level.
		When SGB/7 = 1, the tripping signal remains on (= the output relay operated), although the measuring signal falls below the starting level. Then the starting signals have to be reset by pressing the push-buttons RESET and PROGRAM simultaneously. <sup>1)</sup>
	SGB/8	Remote resetting of a latched output relay.
		When the output relay with SGB/6 or SGB/7 has been selected to be latching, a remote relay reset can be performed using the control input signal BS when SGB/8 =1. When delivered from factor all switches SGB are set at zero, i.e. the checksum SGB is 0.
	1)	

<sup>1)</sup> From the program version 042D and later versions an additional feature has been incorporated into the relay module SPCJ 4D24. When the latching function is used the latched output can be reset by pushing the PROGRAM button alone, in which case the stored information of the module is not erased.

Output relay matrix switchgroups SGR1, SGR2 and SGR3

SGR1	The switches of switchgroup SGR1 are used to select the protective stages to be brought to the starting signal output SS1 and the tripping signal output TS2.
SGR2	The switches of switchgroup SGR2 are used for configuring the tripping signals of the different protective stages. There are two outputs, SS2 and SS3, to which the signals can be linked.
SGR3	The switches of switchgroup SGR3 are used for configurating the starting and trip- ping signals to the starting or auxiliary tripping output TS1. Note! If the circuit breaker failure protection has been selected in with switch SGF1/4, it will also utilize the TS1 output.

Switch	Function	Factory setting	Checksum value
SGR1/1	When SGR1/1 = 1, the starting signal of stage I> is linked to SS1	1	1
SGR1/2	When SGR1/2 = 1, the tripping signal of stage I> is linked to TS2	1	2
SGR1/3	When SGR1/3 = 1, the starting signal of stage I>> is linked to SS1	0	4
SGR1/4	When SGR1/4 = 1, the tripping signal of stage I>> is linked to TS2	1	8
SGR1/5	When SGR1/5 = 1, the starting signal of stage $I_0$ is linked to SS1	0	16
SGR1/6 SGR1/7	When SGR1/6 = 1, the tripping signal of stage $I_0$ > is linked to TS2	1	32
SGR1/8	When SGR1/7 = 1, the staring signal of stage $I_0>>$ is linked to SS1 When SGR1/8 = 1, the tripping signal of stage $I_0>>$ is	0	64
561(170	linked to TS2	1	128
	Checksum for factory setting of SGR1		171

SGR2/1	When SGR2/1 = 1, the tripping signal from stage I> is		
	linked to SS2	1	1
SGR2/2	When $SGR2/2 = 1$ , the tripping signal from stage I> is	0	2
SGR2/3	linked to SS3 When SGR2/3 = 1, the tripping signal from stage I>> is	0	2
00102/3	linked to SS2	1	4
SGR2/4	When SGR2/4 = 1, the tripping signal from stage I>> is		
CCD2/5	linked to SS3	0	8
SGR2/5	When SGR2/5 = 1, the tripping signal from stage $I_0$ is linked to SS2	0	16
SGR2/6	When SGR2/6 = 1, the tripping signal from stage $I_0$ is	0	10
	linked to SS3	1	32
SGR2/7	When SGR2/7 = 1, the tripping signal from stage $I_0 >>$ is	0	Ch
SGR2/8	linked to SS2 When SGR2/8 = 1, the tripping signal from stage $I_0 >>$ is	0	64
00102,0	linked to SS3	1	128
	Checksum for factory setting of SGR2		165
			~ - /

Switch	Function	Factory setting	Checksum value
SGR3/1	When SGR3/1 = 1, the starting signal of stage I> is linked to TS1	0	1
SGR3/2	When SGR3/2 = 1, the tripping signal of stage I> is linked to TS1	0	2
SGR3/3	When SGR3/3 = 1, the starting signal of stage I>> is linked to TS1	0	4
SGR3/4	When SGR3/4 = 1, the tripping signal of stage I>> is linked to TS1	0	8
SGR3/5	When SGR3/5 = 1, the starting signal of stage $I_0$ is linked to TS1	0	16
SGR3/6	When SGR3/6 = 1, the tripping signal of stage $I_0$ > is linked to TS1	0	32
SGR3/7 SGR3/8	When SGR3/7 = 1, the starting signal of stage $I_0 >>$ is linked to TS1	0	64
3GK3/0	When SGR3/8 = 1, the tripping signal of stage $I_0 >>$ is linked to TS1	0	128
	Checksum for factory setting of SGR3		0

### Measured data

The measured values are displayed by the three right-most digits of the display. The currently LED indicator on the front panel.

Indicator	Measured data
I <sub>L1</sub>	Line current on phase L1 as a multiple of the rated current $I_n (063 \times I_n)$
I <sub>L2</sub>	Line current on phase L2 as a multiple of the rated current $I_n (063 \times I_n)$
I <sub>L3</sub>	Line current on phase L3 as a multiple of the rated current $I_n (063 \times I_n)$
I <sub>0</sub>	Neutral current as a per cent of the rated current $I_n \; (0 \dots 210\% \; I_n)$

# Recorded information

The left-most red digit displays the register address and the other three digits the recorded information. A symbol "//" in the text indicates that the following item is found in a submenu.

Register/ STEP	Recorded information
1	Phase current $I_{L1}$ measured as a multiple of the rated current of the overcurrent protection. If the overcurrent stage starts or performs a tripping, the current value at the moment of tripping is stored in a memory stack. A new tripping moves the old value up one place in the stack and adds a new value to the stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost.
2	Phase current $I_{L2}$ measured as a multiple of the rated current of the overcurrent protection. If the overcurrent stage starts or performs a tripping, the current value at the moment of tripping is stored in a memory stack. A new tripping moves the old value up one place in the stack and adds a new value to the stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost.
3	Phase current $I_{L3}$ measured as a multiple of the rated current of the overcurrent protection. If the overcurrent stage starts or performs a tripping, the current value at the moment of tripping is stored in a memory stack. A new tripping moves the old value up one place in the stack and adds a new value to the stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost.
4	Maximum demand current value for a period of 15 minutes expressed in multiples of the relay rated current In and based on the highest phase current. // Highest maximum demand value found since latest full relay reset.
5	Duration of the latest starting situation of stage I> as a percentage of the set oper- ating time t> or at I.D.M.T. mode of operation the calculated operation time. A new starting resets the counter, which then starts counting from zero and moves the old value up in the memory stack. At a maximum five values are memorized - if a sixth starting occurs the oldest value will be lost. When the concerned stage has tripped, the counter reading is 100. // Number of startings of the low-set overcur- rent stage I>, n (I>) = 0255.
6	Duration of the latest starting situation of stage I>> as a percentage of the set operating time t>>. A new starting resets the counter, which then starts counting from zero and moves the old value up in the memory stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost. When the concerned stage has tripped, the counter reading is 100. // Number of startings of the high-set overcurrent stage I>>, n (I>>) = 0255.
7	Neutral overcurrent $I_0$ measured as a per cent of the rated current of the earth-fault protection. If the earth-fault stage starts or performs a tripping, the current value at the moment of tripping is stored in a memory stack. A new tripping moves the old value up one place in the stack and adds a new value to the stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost.

Register/ STEP	Recorded information
8	Duration of the latest starting situation of stage $I_0$ > as a percentage of the set operating time $t_0$ >. A new starting resets the counter, which then starts counting from zero and moves the old value up in the memory stack. At a maximum five values are memorized - if a sixth starting occurs the oldest value will be lost. When the concerned stage has tripped, the counter reading is 100. // Number of startings of the low-set neutral overcurrent stage $I_0$ >, n ( $I_0$ >) = 0255.
9	Duration of the latest starting situation of stage $I_0>>$ as a percentage of the set operating time $t_0>>$ . A new starting resets the counter, which then starts counting from zero and moves the old value up in the memory stack. At a maximum five values are memorized - if a sixth starting occurs, the oldest value will be lost. When the concerned stage has tripped, the counter reading is 100. // Number of startings of the high-set neutral overcurrent stage $I_0>>$ , n ( $I_0>>$ ) = 0255.
0	Display of blocking signals and other external control signals.
	The right-most digit indicates the state of the blocking input of the unit. The following states may be indicated: 0 = no blocking signal
	1 = the blocking or control signal BS is active.
	The effect of the signal on the unit is determined by the setting of switchgroup SGB
	From this register "0" it is possible to move on to the TEST mode, where the starting and tripping signals of the module are activated one by one. For further details see the description "General characteristics of D-type SPC relay units".
A	The address code of the measuring relay module, required by the serial communi- cation system. The address code is set at zero unless the serial communication system is used.
	The submenus of this register comprise the selection of the data transfer rate of the serial communication, a bus traffic monitor indicating the operating state of the serial communication system, a password required for the remote control of the settings and a status information for the main/second setting bank, and finally the setting of time delay for the circuit breaker failure protection.
	If the module is connected to a system including a control data communicator and if the communication system is operating, the counter reading of the bus traffic monitor will be zero. Otherwise the numbers 0255 are continuously rolling in the counter. The password given in the setting mode of the next submenu step must always be entered via the serial communication before settings can be re- motely altered. With the setting selector status in the fourth submenu either the main setting bank or the second setting bank can be made active.
-	Display dark. By pressing the STEP push-button the beginning of the display sequence is re-entered.

The registers 1...9 are set to zero by pressing the push-buttons RESET and PROGRAM simultaneously. The registers are also cleared if the auxiliary power supply of the module is interrupted. The address code of the plug-in module, the data transfer rate of the serial communication, the password and the status of the main/second setting bank switch are not erased by a voltage failure. The instructions for setting the address and the data transfer rate are described in the "General characteristics of D-type SPC relay units".

## Main menus and submenus of settings and registers

MAIN MENU	SUBMENUS
<b></b>	STEP 0.5 s PROGRAM 1 s
Normal status, display off	
Current on phase L1	
Current on phase L2	
Current on phase L3	
Neutral current lo	REV. STEP 0.5 s SUBMENUS FWD. STEP 1 s
Actual starting value I>	I I I I I I Value for I> I I I Value for I> I I Value for I> I I Value for I> I I I I I I I I I I I I I
Actual operating time t> or multiplier k for stage l>	A the setting the setting to the
Actual starting value I»	▲ ↓ ↓ Main setting ↓ ▲ ↓ ↓ Second setting ↓ ↓
Actual operating time t» of stage I»	▲ ↓ ↓ Main setting ↓ ↓ value for t» ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓
Actual starting value lo>	▲ ► 21 Main setting value for lo>
Actual operating time to> or multiplier ko	→ Xi Main setting Viv value for to> or ko
A Actual starting value lo»	A Second setting A Second S
N Actual operating time to»	→
Actual setting of functional switchgroup SGF1	→ 1 Main setting of SGF1checksum ↓ → 21 SGF2checksum ↓
Actual setting of blocking switchgroup SGB	A I SGB checksum SGB checksum SGB checksum SGB checksum A → C SGB checksum SGB checksum
Actual setting of relay switchgroup SGR1	→ 11 Main setting of SGR1checksum
1 Latest memorized, event (n) value of phase L1	Event (n-1)
Latest memorized, event (n)     value of phase L2	Event (n-1)
Latest memorized, event (n)     value of phase L3	Event (n-1)
Maximum demand current     value for 15 minutes	Highest maximum
5 Duration of event (n) starting of stage l>	L L Duration of event (n-1) L L Starting of stage  > L Starting of stage  > L Starting of stage  > L L Starting of stage  > L L Starting of stage  > L St
6 Duration of event (n) starting of stage I»	► The starting of stage I > The starting of
7 Latest memorized, event (n) value of neutral current lo	Image: Second
Duration of event (n)     starting of stage lo>	Line Starting of stage lo>     Line Starting of stage lo>     Line Starting of stage lo>
9 Duration of event (n) starting of stage lo»	→ ↓ Duration of event (n-1) ↓ ↓ Duration of event (n-2) ↓ ↓ Starting of stage lo»
Status of external relay     blocking / control signal	
A Relay unit identification address for communication	Communication rate ↓ ↓ Communication rate ↓ ↓ Loss of bus traffic time ↓ ↓ Loss of bus traffic time

The measures required for entering a submenu or a setting mode and how to perform the setting and use the TEST mode are described in detail in the manual "General characteristics of the D-type relay modules". A short form guide to the operations is shown below.

Desired step or programming operation	Push-button	Action	
Forward step in main or submenu	STEP	Press for more than 0.5 s	
Rapid scan forward in main menu	STEP	Keep depressed	
Reverse step in main or submenu	STEP	Press less than about 0.5 s	
Entering to submenu from main menu	PROGRAM	Press for 1 s (Active on release)	
Entering or leaving setting mode	PROGRAM	Press for 5 s	
Increasing a value in setting mode	STEP		
Moving the cursor in setting mode	PROGRAM	Press for about 1 s	
Storing a value in setting mode	STEP&PROGRAM	Press simultaneously	
Resetting of memorized values and latched output relays	STEP&PROGRAM		
Resetting of latched output relays	PROGRAM	Note! Display must be off	
Note! All parameters which can be set in a setting mode are indicated with the symbol $\clubsuit$ .			

#### ► 3- Second setting of IN SGF1 checksum

	→ 3/ Main setting of	Second setting of SGR1 checksum	Second setting of SGR2 checksum	►
1	→ 3/ Event (n-3) 21 value of phase L1	► ► Event (n-4)		
2	Event (n-3)	► ► Event (n-4) ► T value of phase L2		
3	→ 3 Event (n-3) 1 value of phase L3	► 24 Event (n-4) value of phase L3		
5	→ Starting of stage l>	→ 24 Duration of event (n-4) 1 Starting of stage l>	► Starts since latest reset	<u>_</u>
6	→ 32 Duration of event (n-3)	→ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	► Starts since latest reset	
7	Event (n-3)	► ► Event (n-4) Value of current lo		
			> I ( Number of low oot corth	

8	Duration of event (n-3)	► ∠4 Duration of event (n-4) ✓ IN starting of stage lo>	→ 5/ Number of low-set earth- fault starts since latest reset
9	Duration of event (n-3) starting of stage lo»	Duration of event (n-4)	► 5 fault starts since latest reset

(1) altering softings	or the total ction
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Time/current characteristics (modified 2002-05)	The operation of the low-set overcurrent stage I> of the module is based on either definite time or inverse time characteristics. The mode of operation is selected with switches 13 of switchgroup SGF1 (see page 9). When selecting an IDMT mode of operation,	the operating time of t tion of the current; the shorter the operating t of six different time/cur according to the BS 14; cial types called the RI istic	e higher the ime.The un rent charact 2 standard	current, the nit comprises eristics - four and two spe-
BS-type characteristics	There are four standard curves, extremely, very, normal and long- time inverse. The relation- ship between current and time complies with	The degree of inversit values of the constants		nined by the
	the standards BS 142.1966 and IEC 60255-3 and may generally be expressed as:	Degree of inversity of the characteristic	α	β
	$t [s] = \frac{k \times \beta}{(I/I)^{\alpha} - 1}$	Normal inverse Very inverse Extremely inverse Long-time inverse	0.02 1.0 2.0 1.0	0.14 13.5 80.0 120.0
	where t = operating time in seconds			

According to the standard BS 142.1966 the normal current range is defined as 2...20 times the setting current. Additionally the relay must start at the latest when the current exceeds a value of 1.3 times the setting, when the time/ current characteristic is normal inverse, very inverse or extremely inverse. When the characteristic is long-time inverse, the normal range in accordance with the standard is 2...7 times the setting and the relay is to start when the current exceeds 1.1 times the setting.

The following requirements with regard to operating time tolerances are specified in the standard (E denotes accuracy in per cent, - = not specified):

I/I>	Normal inv.	Very inv.	Extremely inv.	Long-time inv.
2 5 7 10	2.22 E 1.13 E - 1.01 E	2.34 E 1.26 E 1.01 E	2.44 E 1.48 E 1.02 E	2.34 E 1.26 E 1.00 E
20	1.00 E	1.00 E	1.00 E	-

In the defined normal current ranges, the inverse-time stage of the overcurrent and earthfault unit SPCJ 4D24 complies with the tolerances of class 5 at all degrees of inversity.

k = time multiplier

I> = set current value

The unit includes four BS 142-specified char-

acteristics with different degrees of inversity.

I = current value

The time/current characteristics specified in the BS-standards are illustrated in Fig. 3, 4, 5 and 6.

#### Note.

The actual operate time of the relay, presented in the graphs in Fig. 3...6, includes an additional filter and detection time plus the operate time of the trip output relay. When the operate time of the relay is calculated using the mathematical expression above, these additional times of about 30 ms in total have to be added to the time received.

RI-type characteristic	The RI-type characteristic is a special charac- teristic used mainly for time grading with exist- ing mechanical relays. The characteristic is based on the following mathematical expression:	where t = operating time in seconds k = time multiplier I = phase current I> = set starting current
	t [s] = k / (0.339 - 0.236 x I> / I)	The graph of the characteristic is shown in Fig.7.
RXIDG-type characteristic	The RXIDG-type characteristic is a special characteristic used mainly for earth-fault pro- tection where a high degree of selectivity is needed also for high-resistance faults. With this characteristic, the protection need not to be di- rectional and the scheme can operate without a pilot communication. The time / current characteristic can be ex- pressed as: $t [s] = 5.8 - 1.35 x \log (I / (k \times I))$ where $t = operating in seconds$ k = time multiplier I = phase current I > = set starting current	Note! If the setting is higher than 2.5 x I <sub>n</sub> , the maximum continuous carry (3 x I <sub>n</sub> ) and the level- ling out of the IDMT-curves at high current levels must be noted. Note! The high-current end of any inverse time char- acteristic is determined by the high-set stage which, when started, inhibits the low-set stage operation. The trip time is thus equal to the set t>> for any current higher than I>>. In order to get a trip signal, the stage I>> must of course be linked to a trip output relay.
	The graph of the characteristic is shown in Fig.8.	

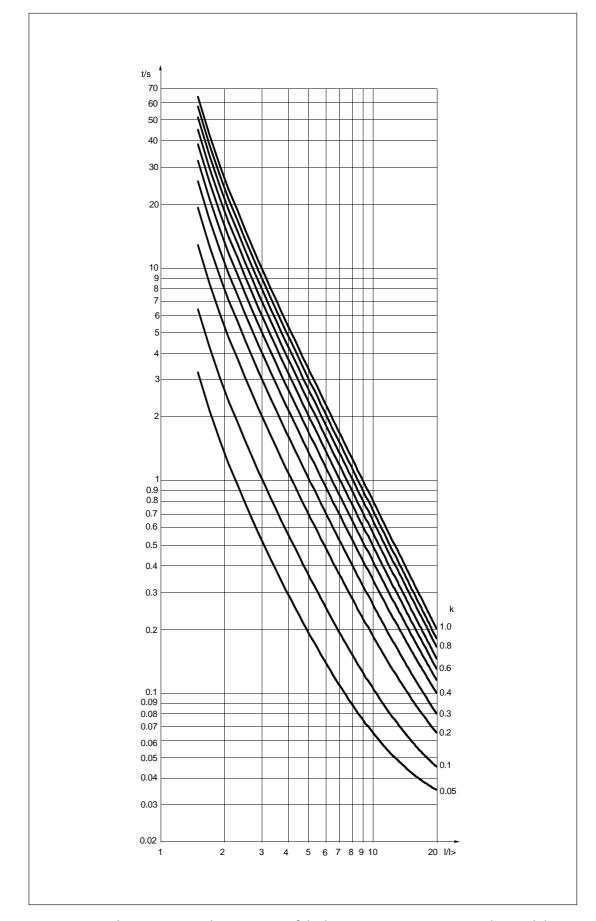


Fig. 3. Extremely inverse-time characteristics of the low-set overcurrent unit in relay module SPCJ  $4\mathrm{D}24$ 

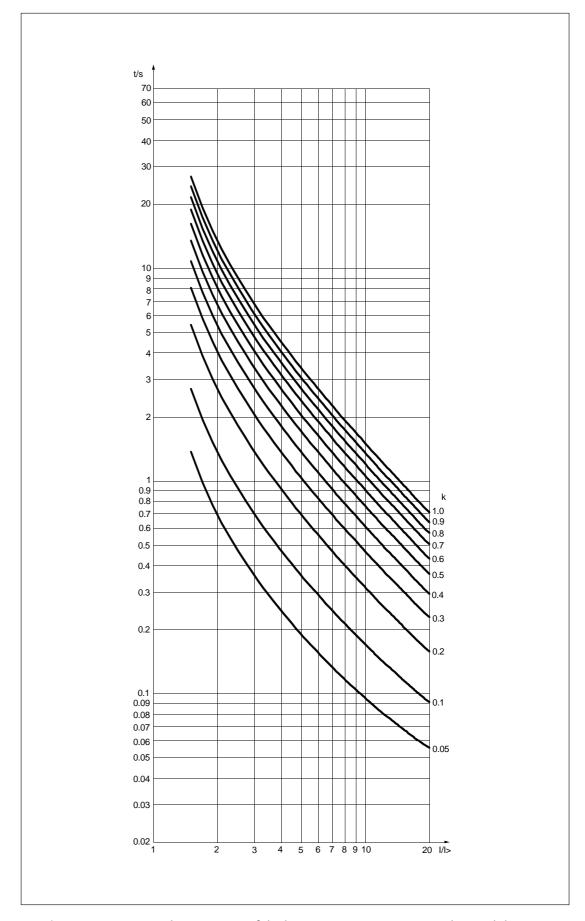


Fig. 4. Very inverse-time characteristics of the low-set overcurrent unit in relay module SPCJ  $4\mathrm{D}24$ 

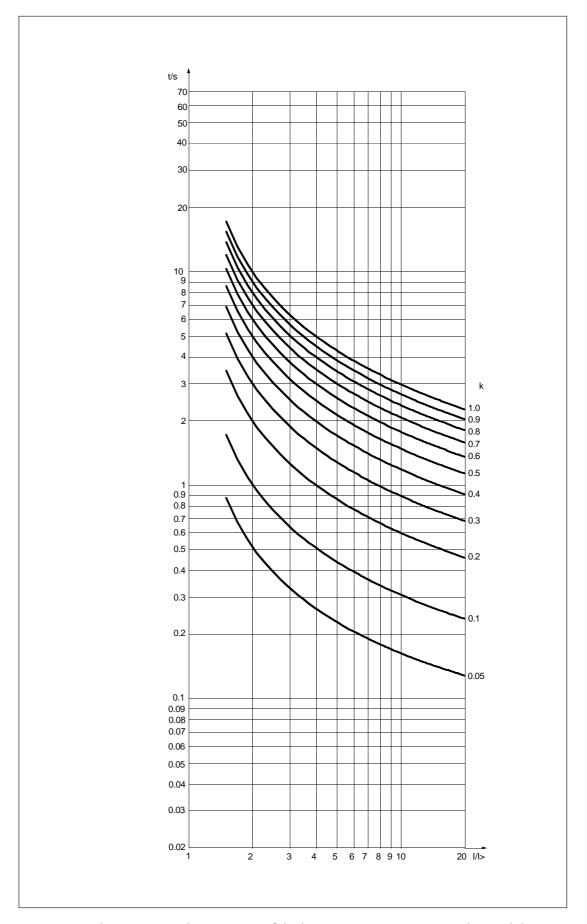


Fig. 5. Normal inverse-time characteristics of the low-set overcurrent unit in relay module SPCJ 4D24

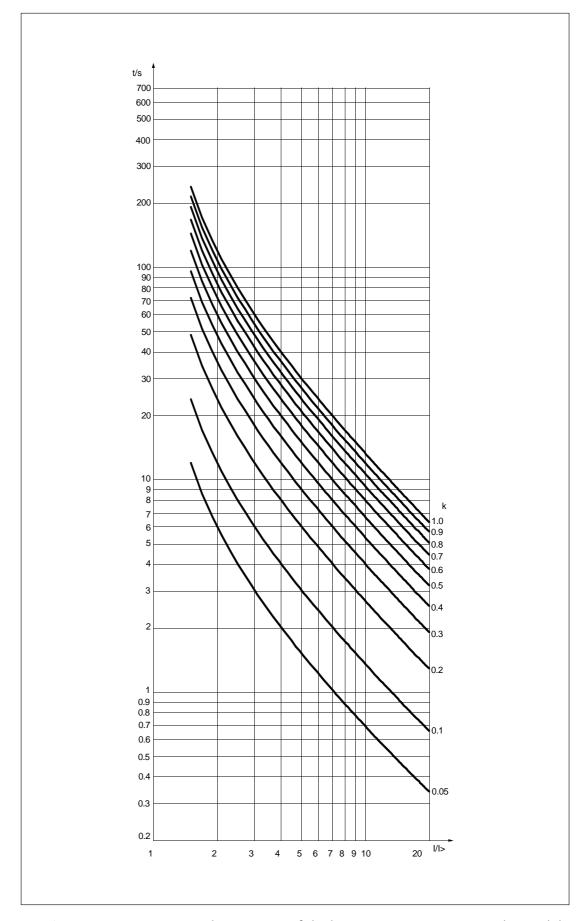


Fig. 6. Long-time inverse-time characteristics of the low-set overcurrent unit in relay module SPCJ  $4\mathrm{D}24$ 

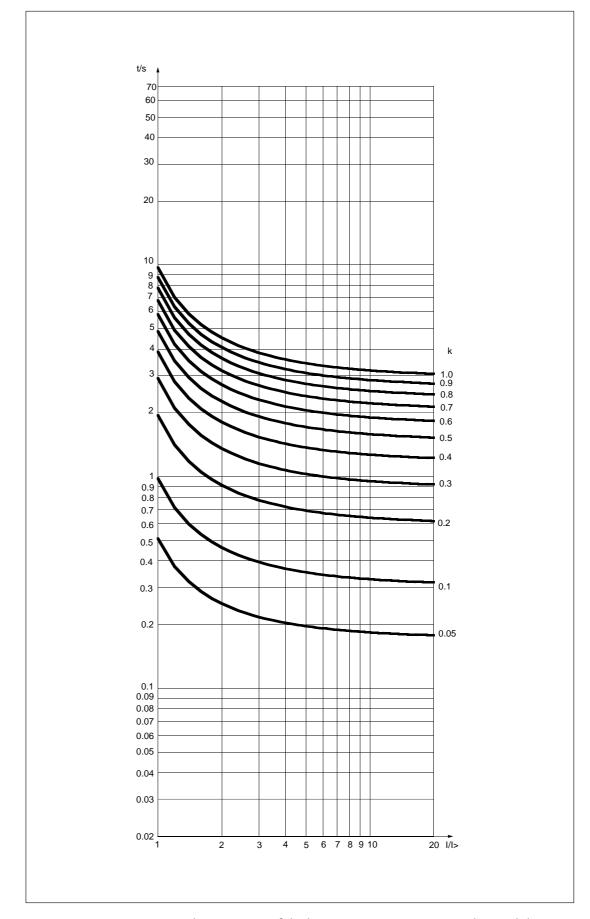


Fig. 7. RI-type inverse-time characteristics of the low-set overcurrent unit in relay module SPCJ  $4\mathrm{D}24$ 

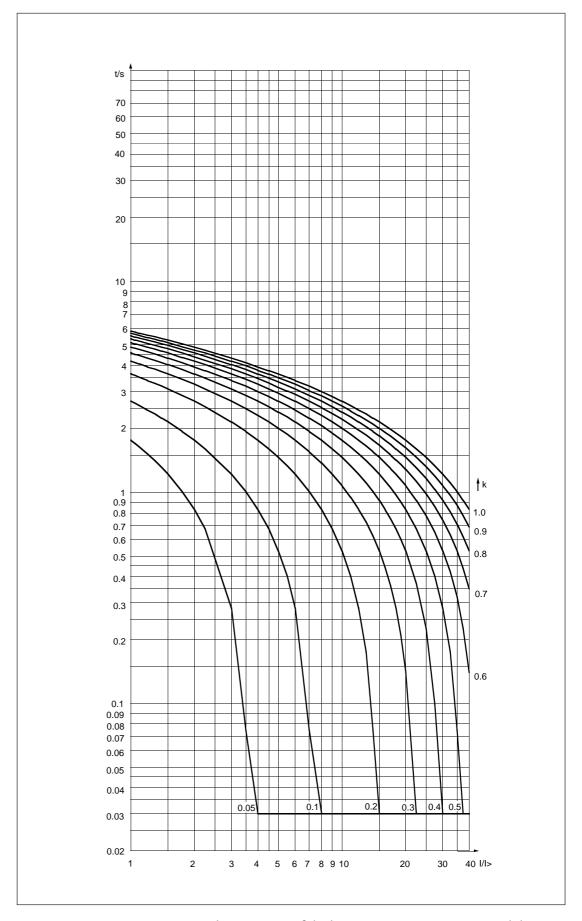


Fig. 8. RXIDG-type inverse-time characteristics of the low-set overcurrent unit in module SPCJ 4D24

### Technical data

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# Low-set overcurrent stage I>

Setting range	
- at definite time	0.55.0 x I <sub>n</sub>
- at inverse time	0.52.5 x I <sub>n</sub>
Starting time	< 70 ms
Operating time at definite time mode of operation	0.05300 s
Operating characteristics at IDMT mode of operation	Extremely inverse Very inverse

Normal inverse Long-time inverse RI-type inverse RXIDG-type inverse

Time multiplier k	0.051.00
Resetting time	< 80 ms
Retardation time	30 ms
Drop-off/pick-up ratio, typically	0.96
Operation time accuracy at definite time	
mode of operation	$\pm 2$ % of set value or $\pm 25$ ms
Operation time accuracy class E at inverse	
time mode of operation	5
Operation accuracy	$\pm$ 3 % of set value

### High-set overcurrent stage I>>

Setting range Starting time, typically Operating time Resetting time Retardation time Drop-off/pick-up ratio, typically Operation time accuracy Operation accuracy

### Low-set neutral overcurrent stage I<sub>0</sub>>

Setting range Starting time Operation time Resetting time Drop-off/pick-up ratio, typically Operation time accuracy Operation accuracy

### High-set neutral overcurrent stage I<sub>0</sub>>>

Setting range Starting time, typically Operation time Resetting time Drop-off/pick-up ratio, typically Operation time accuracy Operation accuracy

0.5...40.0 x I<sub>n</sub> or  $\infty$ , infinite 40 ms 0.04...300 s < 80 ms 30 ms 0.96  $\pm 2$  % of set value or  $\pm 25$  ms  $\pm$  3 % of set value

1.0...25.0 % In < 70 ms 0.05...300 s < 80 ms 0.96  $\pm 2$  % of set value or  $\pm 25$  ms  $\pm 4$  % of set value

2.0...200 %  $I_n$  or  $\infty$ , infinite 50 ms 0.05...300 s < 80 ms 0.96  $\pm 2$  % of set value or  $\pm 25$  ms  $\pm 4$  % of set value

# Serial communication parameters

Event codes

When the overcurrent and earth-fault relay module SPCJ 4D24 is linked to the control data communicator SACO 148 D4 over a SPA bus, the module will provide spontaneous event markings e.g. to a printer. The events are printed out in the format: time, text which the user may have programmed into SACO 148 D4 and event code.

The codes E1...E16 and the events represented by these can be included in or excluded from the event reporting by writing an event mask V155 for the overcurrent events and V156 for earth-fault events to the module over the SPA bus. The event masks are binary numbers coded to decimal numbers. The event codes E1...E8 are represented by the numbers 1, 2, 4...128. An event mask is formed by multiplying the above numbers either by 0, event not included in reporting, or 1, event included in reporting and adding up the numbers received, compare the procedure used in calculation of a checksum.

The event masks V155 and V156 may have a value within range 0...255. The default value of the overcurrent and earth-fault relay module SPCJ 4D24 is 85 both for overcurrent and earth-fault events, which means that all startings and trippings are included in the reporting, but not the resetting.

The output signals are monitored by codes E17...E26 and the events represented by these can be included in or excluded from the event reporting by writing an event mask V157 to the

module. The event mask is a binary number coded to a decimal number. The event codes E17...E26 are represented by the numbers 1, 2, 4...512. An event mask is formed by multiplying the above numbers either by 0, event not included in reporting or 1, event included in reporting and adding up the numbers received, compare the procedure used in calculation of a checksum.

The event mask V157 may have a value within the range 0...1024. The default value of the overcurrent and earth-fault relay module SPCJ 4D24 is 768 which means that only the operations of the trip relay are included in the reporting.

The codes E50...E54 and the events represented by these cannot be excluded from the reporting.

An event buffer is capable of memorizing up to eight events. If more than eight events occure before the content of the buffer is sent to the communicator an overflow event "E51" is generated. This event has to be reset by writing a command "0" to parameter C over the SPAbus.

More information about the serial communication over the SPA-bus can be found in the manual "SPA-BUS COMMUNICATION PROTOCOL", 34 SPACOM 2 EN1.

Event codes of the combined overcurrent and earth-fault relay module SPCJ 4D24:

Code	Event	Weight factor	Default value of the factor
E1	Starting of stage I>	1	1
E2	Starting of stage I> reset	2	0
E3	Tripping of stage I>	4	1
E4	Tripping of stage I> reset	8	0
E5	Starting of I>> stage	16	1
E6	Starting of I>> stage reset	32	0
E7	Tripping of stage I>>	64	1
E8	Tripping of stage I>> reset	128	0
	Default checksum for mask V155		85

Code	Event	Weight factor	Default value of the factor
E9	Starting of stage I <sub>0</sub> >	1	1
E10	Starting of stage $I_0$ > reset	2	0
E11	Tripping of stage I <sub>0</sub> >	4	1
E12	Tripping of stage $I_0$ > reset	8	0
E13	Starting of I <sub>0</sub> >> stage	16	1
E14	Starting of I <sub>0</sub> >>stage reset	32	0
E15	Tripping of stage I <sub>0</sub> >>	64	1
E16	Tripping of stage $I_0 >>$ reset	128	0
	Default checksum for mask V156		85

E17	Output signal TS1 activated	1	0
E18	Output signal TS1 reset	2	0
E19	Output signal SS1 activated	4	0
E20	Output signal SS1 reset	8	0
E21	Output signal SS2 activated	16	0
E22	Output signal SS2 reset	32	0
E23	Output signal SS3 activated	64	0
E24	Output signal SS3 reset	128	0
E25	Output signal TS2 activated	256	1
E26	Output signal TS2 reset	512	1
	Default checksum for mask V157		768

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-
-
-
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not included in the event reporting included in the event reporting 0

1

\* no code number

cannot be programmed -

Note !

The event codes E52...E54 are only generated by the data communicator unit (SACO 100M, SRIO 1000M, etc.)

#### Data to be transferred over the serial bus

In addition to the spontaneous data transfer the SPA bus allows reading of all input data (I-data) of the module, setting values (S-values), information recorded in the memory (V-data), and some other data. Further, part of the data can be altered by commands given over the SPA bus. All the data are available in channel 0.

R = data to be read from the unit

W = data to be written to the unit

(P) = writing enabled by a password

Data	Code	Data direction	Values
INPUTS			
Measured current on phase L1 Measured current on phase L2 Measured current on phase L3 Measured neutral current Blocking or control signal	I1 I2 I3 I4 I5	R R R R	$\begin{array}{l} 063 \ge I_n \\ 063 \ge I_n \\ 063 \ge I_n \\ 0210 \ \% \ I_n \\ 0 = no \ blocking \\ 1 = external \ blocking \ o \\ control \ signal \ active \end{array}$
OUTPUTS			
Starting of stage I>	O1	R	0 = I > stage not started
Tripping of stage I>	O2	R	1 = I> stage started 0 = I> stage not tripped
Starting of stage I>>	O3	R	1 = I> stage tripped 0 = I>> stage not started
Tripping of stage I>>	O4	R	1 = I>> stage started 0 = I>> stage not tripped
Starting of stage I <sub>0</sub> >	05	R	1 = I >> stage tripped $0 = I_0 > stage not started$
Tripping of stage I <sub>0</sub> >	O6	R	$1 = I_0$ > stage started $0 = I_0$ > stage not tripped
Starting of stage I <sub>0</sub> >> started	07	R	$1 = I_0$ stage tripped $0 = I_0$ stage no
Tripping of stage I <sub>0</sub> >> tripped	O8	R	$1 = I_0 >> stage started$ $0 = I_0 >> stage not$
Signal START1 TS1	O9	R, W (P)	$1 = I_0 >> $ stage tripped 0 = signal not active
Signal START2 SS1	O10	R, W (P)	1 = signal active 0 = signal not active
Signal ALARM1 SS2	O11	R, W (P)	1 = signal active 0 = signal not active
Signal ALARM2 SS3	O12	R, W (P)	1 = signal active 0 = signal not active
Signal TRIP TS2	O13	R, W (P)	1 = signal active 0 = signal not active 1 = signal active
Operate output relays	O41	R, W (P)	0 = not operated 1 = operated

Data	Code	Data direction	Values
Memorized I> start	O21	R	0 = signal not active
Memorized I> trip	O22	R	1 = signal active 0 = signal not active
Memorized I>> start	O23	R	1 = signal active 0 = signal not active
Memorized I>> trip	O24	R	1 = signal active 0 = signal not active
Memorized I <sub>0</sub> > start	O25	R	1 = signal active 0 = signal not active
Memorized I <sub>0</sub> > trip	O26	R	1 = signal active 0 = signal not active
Memorized I <sub>0</sub> >> start	O27	R	1 = signal active 0 = signal not active
Memorized I <sub>0</sub> >> trip	O28	R	1 = signal active 0 = signal not active
Memorized output signal TS1	O29	R	1 = signal active 0 = signal not active
Memorized output signal SS1	O30	R	1 = signal active 0 = signal not active
Memorized output signal SS2	O31	R	1 = signal active 0 = signal not active
Memorized output signal SS3	O32	R	1 = signal active 0 = signal not active
Memorized output signal TS2	O33	R	1 = signal active 0 = signal not active 1 = signal active
PRESENT SETTING VALUES			
Present starting value for stage I> Present operating time for stage I>	S1 S2	R R	0.55.0 x I <sub>n</sub> 0.05300 s
Present starting value for stage I>>	S3	R	$0.540 \ge I_n$ 999 = not in use (\infty)
Present operating time for stage I>>	S4	R	0.04300 s
Present starting value for stage I <sub>0</sub> >	S5	R	1.025.0 % I <sub>n</sub>
Present operating time for stage I <sub>0</sub> > Present starting value for stage I <sub>0</sub> >>	S6 S7	R R	0.05300 s 2200 % I <sub>n</sub>
Present operating time for stage I <sub>0</sub> >>	S8	R	999 = not in use (∞) 0.05300 s
Present checksum of switchgroup SGF1	S9	R	0255
Present checksum of switchgroup SGF2	S10	R	0255
Present checksum of switchgroup SGB	S11 S12	R R	0255
Precent checkeum of oursteheses VIII			
Present checksum of switchgroup SGR1 Present checksum of switchgroup SGR2	S12 S13	R	0255 0255

Data	Code	Data direction	Values
MAIN SETTING VALUES			
Starting value for I> stage,			
main setting	S21	R, W (P)	0.55.0 x I <sub>n</sub>
Operating time for I> stage,			II
main setting	S22	R, W (P)	0.05300 s
Starting value for I>> stage,			
main setting	S23	R, W (P)	0.540.0 x I <sub>n</sub>
Operating time for I>> stage,	-	<i>,</i> , , , ,	- 11
main setting	S24	R, W (P)	0.04300 s
Starting value for $I_0$ > stage,			
main setting	S25	R, W (P)	1.025.0 % I <sub>n</sub>
Operating time for $I_0$ > stage,			11
main setting	S26	R, W (P)	0.05300 s
Starting value for $I_0$ >> stage,			
main setting	S27	R, W (P)	2200 % I <sub>n</sub>
Operating time for $I_0 >>$ stage,			
main setting	S28	R, W (P)	0.05300 s
C C			
Checksum of group SGF1, main setting	S29	R, W (P)	0255
Checksum of group SGF2, main setting	S30	R, W (P)	0255
Checksum of group SGB, main setting	S31	R, W (P)	0255
Checksum of group SGR1, main setting	S32	R, W (P)	0255
Checksum of group SGR2, main setting	S33	R, W (P)	0255
Checksum of group SGR3, main setting	S34	R, W (P)	0255
SECOND SETTING VALUES Starting value for I> stage,			
second setting	S41	R, W (P)	0.55.0 x I <sub>n</sub>
Operating time for I> stage,	011	IC, W (I)	0. <i>jj</i> .0 x 1 <sub>n</sub>
second setting	S42	R, W (P)	0.05300 s
Starting value for I>> stage,	012	IC, W (I)	0.09900 3
second setting	S43	R, W (P)	0.540.0 x I <sub>n</sub>
Operating time for I>> stage,	0 10		
second setting	S44	R, W (P)	0.04300 s
Starting value for $I_0$ > stage,	011		
second setting	S45	R, W (P)	1.025.0 % I <sub>n</sub>
Operating time for $I_0$ > stage,	019		
second setting	S46	R, W (P)	0.05300 s
Starting value for $I_0 >>$ stage,			,
second setting	S47	R, W (P)	2200 % I <sub>n</sub>
	01/		
Operating time for Io>> stage.			
	S48	R. W (P)	0.05300 s
Operating time for I <sub>0</sub> >> stage, second setting	S48	R, W (P)	0.05300 s
second setting			
second setting Checksum of group SGF1, second setting	S49	R, W (P)	0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting	S49 S50	R, W (P) R, W (P)	0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting	S49 S50 S51	R, W (P) R, W (P) R, W (P)	0255 0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting Checksum of group SGR1, second setting	S49 S50 S51 S52	R, W (P) R, W (P) R, W (P) R, W (P)	0255 0255 0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting Checksum of group SGR1, second setting Checksum of group SGR2, second setting	S49 S50 S51 S52 S53	R, W (P) R, W (P) R, W (P) R, W (P) R, W (P)	0255 0255 0255 0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting Checksum of group SGR1, second setting	S49 S50 S51 S52	R, W (P) R, W (P) R, W (P) R, W (P)	0255 0255 0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting Checksum of group SGR1, second setting Checksum of group SGR2, second setting Checksum of group SGR3, second setting	S49 S50 S51 S52 S53	R, W (P) R, W (P) R, W (P) R, W (P) R, W (P)	0255 0255 0255 0255 0255
second setting Checksum of group SGF1, second setting Checksum of group SGF2, second setting Checksum of group SGB, second setting Checksum of group SGR1, second setting Checksum of group SGR2, second setting	S49 S50 S51 S52 S53	R, W (P) R, W (P) R, W (P) R, W (P) R, W (P)	0255 0255 0255 0255 0255

Data	Code	Data direction	Values
RECORDED AND MEMORIZED PARA	METERS		
Current in phase L1 at starting or tripping	V11V51	R	063 x I <sub>n</sub>
Current in phase L2 at starting or tripping	V12V52	R	$063 \times I_{n}$
Current in phase L2 at starting or tripping	V13V53	R	$063 \times I_n$
Netral current Io at starting or tripping	V14V54	R	0210 % I <sub>n</sub>
Duration of the latest starting		-	
situation of stage I>	V15V55	R	0100%
Duration of the latest starting			
situation of stage I>>	V16V56	R	0100%
Duration of the latest starting			
situation of stage $I_0$ >	V17V57	R	0100%
Duration of the latest starting			0
	V18V58	R	0100%
situation of stage $I_0 >>$	v 10 v Jo	K	0100%0
Maximum demand current for 15 min.	$\mathbf{V}^{1}$	D	0 25 <del></del> I
	V1 V2	R	$02.5 \times I_n$
Number of startings of stage I>	V2	R	0255
Number of startings of stage I>>	V3	R	0255
Number of startings of stage $I_0$ >	V4	R	0255
Number of startings of stage $I_0 >>$	V5	R	0255
Phase conditions during trip	V6	R	$1 = I_{L3}$ , $2 = I_{L2}$ ,
Thase conditions during trip	10	IX I	$4 = I_{L_{2}}, \qquad 2 = I_{L_{2}}, \qquad 4 = I_{1}, \qquad 8 = I_{0}$
			$16 = I_{L3} >>, 32 = I_{L2} >>$
			$64 = I_{L1} >>, 128 = I_0 >>$
Operation indicator	V7	R	09
Highest maximum demand current			
15 minute value	V8	R	02.55 x I <sub>n</sub>
CONTROL PARAMETERS			
Resetting of output relays	V101	W	1 = output relays and all
at self-holding			information from
0			the display are reset
Resetting of output relays	V102	W	1 = output relays and
and recorded data	V102	vv	
and recorded data			registers are reset
	1/150	D W/	
Remote control of settings	V150	R, W	0 = main settings
			activated
			1 = second settings
			activated, see
			section "Description
			of function"
Event mask word for overcurrent events	V155	R, W	0255, see section
	· • > > >		"Event codes"
Event mask word for earth-fault events	V156	R W/	
Event mask word for earth-fault events	V156	R, W	0255, see section
		D 1111	"Event codes"
Event mask word for output signal events	V157	R, W	01023, see section
			"Event codes"
Opening of password for remote settings	V160	W	1999
Changing or closing of password for			
remote settings	V161	W (P)	0999
ienote bettings	, 101	** (1)	····///

Data	Code	Data direction	Values
Activating of self-supervision output	V165	W	1 = self-supervision output is activated and IRF LED turned on 0 = normal mode
EEPROM formatting	V167	W (P)	2 = formatted with a power reset for a fault code [53]
Internal error code	V 169	R	0255
Data comm. address of the module Data transfer rate	V200 V201	R, W R, W	1254 4,8 or 9,6 kBd (W) 4800 or 9600 Bd (R)
Programme version symbol	V205	R	042 _
Event register reading	L	R	time, channel number
Re-reading of event register	В	R	and event code time, channel number and event code
Type designation of the module	F	R	SPCJ 4D24
Reading of module status data	С	R	<ul> <li>0 = normal state</li> <li>1 = module been subject to automatic reset</li> <li>2 = overflow of event regist.</li> <li>3 = events 1 and 2 together</li> </ul>
Resetting of module state data	С	W	0 = resetting
Time reading and setting	Т	R, W	00.00059.999 s

The event register can be read by L-command only once. Should a fault occur e.g. in the data transfer, the contents of the event register may be re-read using the B-command. When required, the B-command can be repeated. Generally, the control data communicator SACO 100M reads the event data and forwards them to the output device continuously. Under normal conditions the event register of the module is empty. In the same way the data communicator resets abnormal status data, so this data is normally a zero. The setting values S1...S14 are the setting values used by the protection functions. These values are set either as the main settings and switchgroup checksums S21...S34 or as the corresponding second settings S41...S54. All the settings can be read or written. A condition for writing is that remote set password has been opened.

When changing settings, the relay unit will check that the variable values are within the ranges specified in the technical data of the module. If a value beyond the limits is given to the unit, either manually or by remote setting, the unit will not perform the store operation but will keep the previous setting. Fault codes

A short time after the internal self-supervision system has detected a permanent relay fault the red IRF indicator is lit and the output relay of the self-supervision system operates. Further, in most fault situations, an auto-diagnostic fault code is shown on the display. This fault code consists of a red figure 1 and a green code number which indicates the fault type. When a fault code appears on the display, the code number should be recorded and given to the authorized repair shop when overhaul is ordered. In the table below some fault codes that might appear on the display of the SPCJ 4D24 module are listed:

Fault code	Type of error in module
4	Faulty trip relay path or missing output relay card
30	Faulty program memory (ROM)
50	Faulty work memory (RAM)
51	Parameter memory (EEPROM) block 1 faulty
52	Parameter memory (EEPROM) block 2 faulty
53	Parameter memory (EEPROM) block 1 and block 2 faulty
54	Parameter memory (EEPROM) block 1 and block 2 faulty with
	different checksums
56	Parameter memory (EEPROM) key faulty.
	Format by writing a "2" to variable V167
195	Too low value in reference channel with multiplier 1
131	Too low value in reference channel with multiplier 5
67	Too low value in reference channel with multiplier 25
203	Too high value in reference channel with multiplier 1
139	Too high value in reference channel with multiplier 5
75	Too high value in reference channel with multiplier 25
252	Faulty filter on Io channel
253	No interruptions from the A/D-converter



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