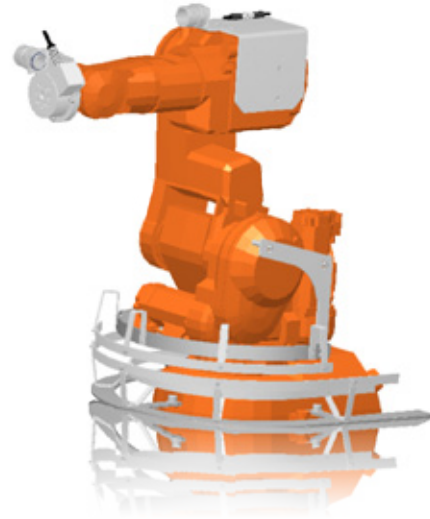


Function Package IRB 140 Force Control for Machining

The Force Control Function Package IRB 140 for machining applications enables customers and system integrators to exploit a new dimension of robot intelligence for finishing processes such as deburring, grinding and polishing (e.g. for work pieces made of steel, stainless steel, aluminum, magnesium, wood, plastics, glass, etc.).



New functionality

To activate the new functionality of force control for machining more easily and much faster for users this special Function Package was developed and can be provided for various manipulator types.

Integrated solution

The basic Function Package includes the software FC Base including a dedicated GUI (Graphical User Interface) for machining for the FlexPendant, a special axis computer plus, a DAQ board, the Force-/Torque-Sensor and the sensor cable which is integrated in a hose package.

Ready to use package

With this Function Package main advantages can be obtained, which enables customers to concentrate on the present application and process. By reason that the Function Package is delivered fully assembled, tested and verified – meaning that the basic set-up of the system is already done before delivery – valuable savings of resources like manpower, time and costs are given.

Higher productivity

The revolutionary technology of force control for machining in combination with the Function Package IRB 140 enables a faster integration (because of minimized programming and optimizing efforts) and a quality improvement (because of reduced risks for damaging tools, workpieces or even the robot) in the production. This leads to fewer costs, higher productivity and better process results due to the fact that not the position but the process itself gets controlled

Function Package IRB 140

Technical Data

Function Package Elements

Hose Package:	lower + upper hose package The integration of additional media is enabled.
Hose Cage:	lower + upper hose cage (Axis 1)
Hose Guide:	hose guide axis 1 + hose guide axis 2
Valve Plate:	The force sensor cable is spread across the valve plate. The assembly of additional components is possible.
Base Cable (Sensor):	3m, 7m, 15m, 22m, 30m (= corresponding to manipulator cable length)
Controller Hardware:	738-1 Prepared for Force Control
Controller Software:	661-2 Force Control base 877-1 Machining FC GUI 617-1 FlexPendant Interface
Mechanical assembly of hose package, force sensor, DAQ board and cabling is included if ordered together with a robot system. Equipment is fully tested and verified delivered.	

Application area

Available for manipulator:	IRB 140-6/0.81, IRB 140T-6/0.81
Available for controller:	IRC5 (RW 5.09 and higher)
Available for:	Single Robots MultiMove Robots (independent)
Not available for:	MultiMove Robots (coordinated)

Force Sensor Specification (Metric)

Delta IP60	
Sensor Diameter:	130 mm
Sensor Height:	47 mm
Sensor Weight:	1.8 kg
Degree of protection:	IP60
Max. Force (Fx, Fy):	±330 N
Max. Force (Fz):	±990 N
Max. Torque (Tx, Ty, Tz):	±30 Nm
Single Axis Overload (Fx, Fy):	±2600 N
Single Axis Overload (Fz):	±8600 N
Single Axis Overload (Tx, Ty):	±290 Nm
Single Axis Overload (Tz):	±400 Nm
Resolution (Fx, Fy):	1/16 N
Resolution (Fz):	1/8 N
Resolution (Tx, Ty, Tz):	5/1333 Nm

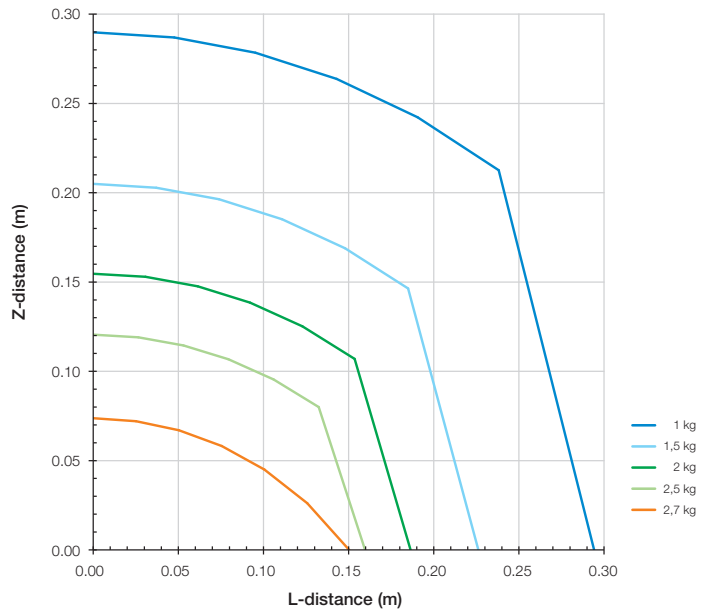
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Load diagrams IRB 140 (including the force sensor)

IRB 140-5

Sensor: 2,49kg, Length 51,13mm; Armload: Upperarm 1 kg, Wrist 0,5 kg



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IRB 140-6/0.81 and IRB 140T-6/0.81

Sensor: 2,49 kg, Length 51,13 mm; Armload: Upperarm 1 kg, Wrist 0,5 kg

