

# IRB 140

## **Industrial Robot**

## MAIN APPLICATIONS

Arc welding Assembly Cleaning/Spraying Machine tending Material handling Packing Deburring



#### Small, Powerful and Fast

Compact, powerful the IRB 140 industrial robot. Six axis multipurpose robot comprising the IRB 140 manipulator and IRC 5 industrial robot controller. Handles payload of 5kg, (11 lbs.) with long reach (810 mm/31.8 in.) of axis 5, optional floor, wall and suspended mounting. Available as Standard, Foundry, Clean Room and Wash versions, all mechanical arms completely IP67 protected, making IRB 140 easy to integrate in and suitable for a variety of applications. Uniquely extended radius of working area due to bend-back mechanism of upper arm, axis 1 rotation of 360 degrees and flexible mounting capabilities.

The compact, robust design with integrated cabling adds to overall flexibility. The Collision Detection option with full path retraction makes the robot reliable and safe.

Using the IRB 140T, cycle-times are considerably reduced where axis 1 and 2 predominantly are used.

Reductions between 15-20 % are possible using pure axis 1 and 2 movements.

This faster versions is well suited for packing applications and guided operations together with PickMaster.

IRB Foundry Plus and Wash versions are suitable for operating in extreme foundry environments and other harsh environments with demanding requirements on corrosion resistance and tightness. In addition to the IP67 protection, excellent surface treatment makes the robot high pressure steam washable. The whitefinish Clean Room version meets Clean Room class 10 regulations, making it especially suited for environments with stringent cleanliness standards.

The IRC 5 controller has the electronics for controlling the robot manipulator, external axes and peripheral equipment. The IRC 5 also contains system software with all basic functions for operating and programming, including two built-in Ethernet channels with 100 Mbit/s capacity. This ensures a significant increase in computing power as well as improved controller monitoring and supervision.



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### **TECHNICAL DATA, IRB 140 INDUSTRIAL ROBOT**

#### SPECIFICATION

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CYCLE TIME

5 kg Picking side cycle 25 x 300 x 25 mm

WORKING RANGE AND LOAD DIAGRAM

Robot versions	Handling capacity	Reach of	Remarks	Standard colour
IRB 140/IRB 140T	5 kg	810 mm		Orange
IRB 140F/IRB 140TF	5 kg	810 mm	Foundry Plus Protection	Orange
IRB 140CR/IRB 140TCR	5 kg	810 mm	Clean Room,	White
IRB 140W/IRB 140TW	5 kg	810 mm	Wash Protectic	n White
Supplementary load (on u	upper arm	alt. wrist)		
on upper arm		1 kg		
on wrist		0.5 kg		
Number of axes				
Robot manipulator		6		
External devices		6		
Integrated signal supply	12 signals on upper arm			
Integrated air supply	Max. 8 bar on upper arm			
PERFORMANCE				
Position repeatability	0.03 mm (average result			
		from ISO test)		
Axis movement				
Axis		Workir	ng range	
1, C Rotation		360°		
2, B Arm		200°		
3, A Arm		280°		
4, D Wrist		Unlimi	ted (400° defau	lt)
5, E Bend		240°		
6, P Turn		Unlimi	ted (800° defau	lt)
Max. TCP velocity		2.5 m/	's	
Max. TCP acceleration		20 m/s	S <sup>2</sup>	
Acceleration time 0-1 m/s	S	0.15 s	ec	
VELOCITY				
Axis no.		IRB 14	10 IRB	140T

Supply voltage	200–600 V, 50/60 Hz		
Rated power			
Transformer rating	4.5 kVA		
PHYSICAL			
Robot mounting	Any angle		
Dimensions			
Robot base	400 x 450 mm		
Robot controller H x W x D	950 x 800 x 620 mm		
Weight			
Robot manipulator	98 kg		
Robot controller	250 kg		
ENVIRONMENT	°		
Ambient temperature			
Robot manipulator	5–45°C (41-113°F)		
Robot controller	5–52°C (41-125°F)		
Relative humidity	Max. 95%		
Degree of protection,			
Manipulator	IP67		
Foundry/Wash	High pressure steam washable		
Clean Room	Class 10 (Federal Standard)/		
	class 4 (ISO)		
Noise level	Max. 70 dB (A)		
Safety	Double circuits with supervision		
	emergency stops and safety		
	functions,		
	3-position enable device		
Emission	EMC/EMI-shielded		



#### 380 670 1092 670 380 810 65 151 70 486 486 670 810

200°/s

200°/s 260°/s

360°/s

360°/s

450°/s

IRB 140

0,85s



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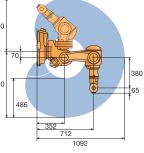


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250°/s

250°/s 260°/s

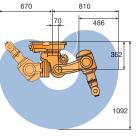
360°/s

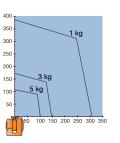
360°/s

450°/s

IRB 140T

0,77s





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