Hardware manual
ACS580MV drives
(200 kW to 6300 kW, 6 kV to 11 kV)
## List of related manuals

### Drive hardware manuals and guides

<table>
<thead>
<tr>
<th>Manual Description</th>
<th>Code (English)</th>
</tr>
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<tr>
<td>ACS580MV hardware manual</td>
<td>2UBB004520</td>
</tr>
<tr>
<td>ACS-AP-X assistant control panels user’s manual</td>
<td>3UA0000085685</td>
</tr>
<tr>
<td>ACS580MV Engineering Guideline</td>
<td>2UBB013672</td>
</tr>
<tr>
<td>ACS580MV Gravity Center for Packing</td>
<td>2UBB022468</td>
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<tr>
<td>ACS580MV Wiring Diagram of system 0</td>
<td>2UBB005084</td>
</tr>
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<td>ACS580MV Wiring Diagram of system 1</td>
<td>2UBB005085</td>
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<tr>
<td>ACS580MV Wiring Diagram of system 2</td>
<td>2UBB005086</td>
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<tr>
<td>User’s manual Start-up and maintenance PC tool Drive composer</td>
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<tr>
<td>ACS580MV Preventive Maintenance Schedule</td>
<td>2UBB022658</td>
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<tr>
<td>ACS580MV Synchronized Bypass Unit Hardware Manual</td>
<td>2UBB005655</td>
</tr>
<tr>
<td>ACS580MV Wiring Diagram of Synchronized Bypass Unit</td>
<td>2UBB005212</td>
</tr>
<tr>
<td>ACS580MV Synchronized Bypass unit Engineering Guideline</td>
<td>2UBB005656</td>
</tr>
<tr>
<td>ACS580MV Manual Bypass unit Hardware Manual</td>
<td>2UBB005416</td>
</tr>
<tr>
<td>ACS580MV Manual Bypass unit Engineering Guideline</td>
<td>2UBB005683</td>
</tr>
<tr>
<td>ACS580MV Air duct interface Outline Drawing AC Fan Box</td>
<td>2UBB005072</td>
</tr>
<tr>
<td>ACS580MV Air duct interface Outline Drawing EC Fan Box</td>
<td>2UBB005074</td>
</tr>
<tr>
<td>ACS580MV Base frame &amp; TEU layout design</td>
<td>2UBB020589</td>
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### Drive firmware manuals and guides

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<th>Code (English)</th>
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</thead>
<tbody>
<tr>
<td>ACS580MV primary control program firmware manual</td>
<td>3BHS811381</td>
</tr>
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</table>

### Option manuals and guides

Manuals and quick guides for I/O extension modules, fieldbus adapters, etc.


For more information, please refer to ACS580 MV Hardware Manual which can be found by scanning the QR code below.

### APP version (IOS/Android)  Web page version

![QR code for APP version](image1)

![QR code for Web page version](image2)
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## Terms and trademarks

### Terms

The following table lists the terms and abbreviations you should be familiar with when using the manual. Some of the terms and abbreviations used in the manual are unique to ABB and might differ from the normal usage.

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<tr>
<th>Term / Abbreviation</th>
<th>Meaning</th>
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<tr>
<td>BCU</td>
<td>Control unit used for controlling drives, inverters and converters via fiber optic links.</td>
</tr>
<tr>
<td>Converter</td>
<td>Short form for ACS580MV frequency converter.</td>
</tr>
<tr>
<td>COU</td>
<td>Control unit Short form for control compartment of the drive.</td>
</tr>
<tr>
<td>DDCS</td>
<td>Distributed Drive Control System DDCS is an acronym for a serial communication protocol designed for data transfer via optical fibers.</td>
</tr>
<tr>
<td>Drive</td>
<td>Short form for ACS580MV frequency converter.</td>
</tr>
<tr>
<td>Drive system</td>
<td>The drive system includes all equipment used to convert electrical into mechanical power to give motion to the machine.</td>
</tr>
<tr>
<td>DriveStartup</td>
<td>DriveStartup guides step by step through the complete commissioning including reporting.</td>
</tr>
<tr>
<td>Equipment</td>
<td>Frequency converter and related equipment.</td>
</tr>
<tr>
<td>EMC</td>
<td>Electromagnetic compatibility All measures to suppress electromagnetic disturbances caused by different electrical equipment in the same electromagnetic environment, and to strengthen the immunity of the equipment to such disturbances.</td>
</tr>
<tr>
<td>ESD</td>
<td>Electrostatic discharge</td>
</tr>
<tr>
<td>Ground</td>
<td>Earth</td>
</tr>
<tr>
<td>To ground</td>
<td>The conducting path (e.g. conductor) between the electric equipment (e.g. frequency converter) and the earth. The electric equipment is connected to the earth, e.g. by a grounding set or a grounding switch.</td>
</tr>
<tr>
<td>INU</td>
<td>Inverter Unit The INU converts the DC voltage to the required AC motor voltage and frequency.</td>
</tr>
<tr>
<td>IGBT</td>
<td>Insulated Gate Bipolar Transistor</td>
</tr>
<tr>
<td>Line voltage</td>
<td>RMS voltage of the main power supply of the drive.</td>
</tr>
<tr>
<td>MCB</td>
<td>Main Circuit Breaker The MCB is a major protection device of the drive system and connects / disconnects the main power supply to the drive. The MCB is controlled entirely by the drive.</td>
</tr>
<tr>
<td>PCB</td>
<td>Printed Circuit Board</td>
</tr>
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</table>
Trademarks

Names that are believed to be trademarks of other companies and organizations are designated as such. The absence or presence of such a designation should however not be regarded as an offence of the legal status of any trademark. The following registrations and trademarks are used in this manual:

<table>
<thead>
<tr>
<th>Term / Abbreviation</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Windows®</td>
<td>Registered trademark of Microsoft Corporation</td>
</tr>
<tr>
<td>Ethernet®</td>
<td>Registered trademark of Xerox Corporation</td>
</tr>
<tr>
<td>Profibus®</td>
<td>Registered trademark of Profibus International (P.I.)</td>
</tr>
<tr>
<td>Modbus®</td>
<td>Registered trademark of the Modbus IDA organization</td>
</tr>
</tbody>
</table>
Safety instructions

Contents of this chapter

This chapter contains the safety instructions which you must obey when you install and operate the drive and do maintenance on the drive. If you ignore the safety instructions, injury, death or damage can occur.

Safety instructions are used to highlight a potential hazard when working on the equipment. Safety instructions must be strictly followed! Non-compliance can jeopardize the safety of personnel, the equipment and the environment.

<table>
<thead>
<tr>
<th><strong>DANGER</strong></th>
<th>indicates a hazardous situation which, if not avoided, will result in death or serious injury.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>WARNING</strong></td>
<td>indicates a hazardous situation which, if not avoided, could result in death or serious injury.</td>
</tr>
<tr>
<td><strong>CAUTION</strong></td>
<td>indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.</td>
</tr>
</tbody>
</table>

The safety instructions are derived from the following standards:

- ISO 3864-2:2004 (E)
  
  Graphical symbols – Safety colors and safety signs – Part 2: Design principles for product safety labels
User’s responsibilities

It is the responsibility of those in charge of the drive to ensure that each person involved in the installation, operation or maintenance of the drive has received the appropriate training and has thoroughly read and clearly understood the instructions in this manual and the relevant safety instructions.

General safety information

To maintain safety and minimize hazards observe the following:

• Before the drive is energized, make sure that:
  • all foreign objects are removed from the drive
  • all internal and external covers are securely fastened and all doors are closed, locked and / or bolted
  • the manual release of the door safety switches is in the locked position.

• Before starting to work on the drive, make sure that:
  • the main and auxiliary power supply to the drive is switched off, locked out, and tagged out
  • the drive is dead
  • safety ground connections are in place
  • appropriate personal protective equipment is provided and used when required
  • everyone involved is informed.

• When working near the running drive protective earmuffs should be worn.

• Before work is carried out simultaneously on the drive and on other drive system equipment, make sure that
  • the relevant safety codes and standards are observed
  • all energy sources of the equipment are turned off
  • lock-out and tag-out devices are in place
  • barriers and appropriate covers are used on equipment which is still live
  • everyone involved is informed.

• In case of fire in the drive room:
  • Observe the established rules and regulations for fire protection
  • Only firemen with appropriate protective equipment are allowed to enter the drive room.
Possible residual risks

The following risks can arise from a drive system and pose a hazard to people. These risks must therefore be taken into account by the system integrator and / or the plant owner when assessing the risks of the machinery.

• Electric power equipment generates electro-magnetic fields which can cause a hazard to people with metal implants and / or a pacemaker.

• Drive system components can move unintentionally when being commissioned, operated, or serviced due to, for example:
  • Operation of the equipment outside the scope of the specifications
  • Incorrectly assembled or installed equipment
  • Wrongly connected cables
  • External influence on, or damage of the equipment
  • Wrong parameter settings
  • Software errors
  • Faulty hardware.

• Hazardous touch voltages can be present on drive system components caused by, for example:
  • Operation of the equipment outside the scope of the specifications
  • External influence on, or damage of the equipment
  • Induced voltages by external equipment (e.g. induced voltage from a spinning rotor)
  • Condensation on equipment components, or pollution
  • Faulty hardware.

• High temperatures, noise, particles, or gases can be emitted from drive system components caused by, for example:
  • Operation of the equipment outside the scope of the specifications
  • External influence on, or damage of the equipment
  • Wrong parameter settings
  • Software errors
  • Faulty hardware.

• Hazardous substances can be emitted from drive system components due to, for example:
  • Incorrect disposal of components.
Safety labels

Safety labels are attached to the cabinet where necessary to alert personnel of potential hazards when working on the equipment. The instructions on the safety labels must always be followed, and the labels must be kept in a perfectly legible condition.

General safety in installation, start-up and maintenance

These instructions are for all personnel that install the drive and do maintenance work on it:

- If you select an external source for the start command and it is on, the drive will start immediately after fault reset unless you configure the drive for pulse start. See the firmware manual.
- When the control location is not set to Local, the stop key on the control panel will not stop the drive.
Electrical safety in installation, start-up and maintenance

■ Precautions before electrical work

These warnings are for all personnel who do work on the drive, motor cable or motor.

DANGER
High voltage!

Before starting to work on the drive, make sure:

- that the main and auxiliary power supply to the drive is switched off, locked out, and tagged out
- that the drive is dead
- that safety ground connections are in place
- that personal protective equipment is provided and used when required
- that everyone involved is informed.

Before energizing the drive, make sure:

- that all foreign objects are removed from the drive
- that all internal and external covers are securely fastened and all doors are closed, locked and / or bolted
- that the release dials of safety switches are in the locked position.

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrician, do not do installation or maintenance work. Go through these steps before you begin any installation or maintenance work.

1. Clearly identify the work location.
2. Disconnect all possible voltage sources.
   - Open the main circuit breaker of the drive.
   - Wait until internal circuits are discharged completely and doors are unlocked (15 minutes).
   - Open the upstream disconnector to disconnect the supply voltage from the input busbars.
   - Disconnect any external power sources from the control circuits before you do work on the control cables.
3. Protect any other energized parts in the work location against contact.
4. Take special precautions when close to bare conductors (e.g. when the protective plate between COU and TEU is removed).
5. Measure that the installation is de-energized.
   - Use only instrumentation (e.g., meters, oscilloscopes, etc.) intended for high voltage measurements.

6. Always discharge equipment and verify that it is neither electrically alive nor thermally hot.

7. Always install temporary grounding as required by the local regulations.

8. Ask for a permit to work from the person in control of the electrical installation work.

### Additional instructions and notes

- Do not connect the drive to a voltage higher than what is on the rating plate.
- The motor cable terminals of the drive are at a dangerous voltage when the input power is on, regardless of whether the motor is running or not.
- External wiring can supply dangerous voltages to the terminals of relay outputs.

### Grounding

- Always ground the drive, the motor and adjoining equipment according to the maintenance instructions in this manual. Assure that the drive is grounded on both sides, i.e. on supply and motor side. This is necessary for the personnel safety. Proper grounding also reduces electromagnetic emission and interference.
- Make sure that the cross-section of the grounding conductors is sufficient. See the *ACS580MV Engineering Guideline*. Obey the local regulations.
Introduction to the manual

Contents of this chapter
This manual documents the operation, maintenance and troubleshooting of the ACS580MV medium voltage drive.

This manual and parts thereof must not be reproduced or copied, or disclosed to third parties, nor used for any unauthorized purpose without written permission from ABB Beijing Drive Systems Company Ltd.

The hardware and software described in this manual is provided under a license and may be used, copied, or disclosed only in accordance with the terms of such license.

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Fax    +86 10 5821 7618
E-mail mvdrives.supportline@cn.abb.com
Web   http:// www.abb.com/motors&drives

Equipment covered by the manual
This manual covers a standard drive and provides generic information on the drive. The manual does not claim to cover all variations and details of the drive, nor to consider all
eventualities that may arise during installation, commissioning, operation and maintenance of the drive.

If the drive is adapted to specific customer needs or applications, and handling, installation, and operation of the drive are affected by these modifications, information on these modifications is provided in the appropriate documentation (e.g. outline drawings, wiring diagrams, technical data, engineering notes).

If information is required beyond the instructions in this manual, refer the matter to ABB.

**Target groups and required qualifications**

The drive presented in this manual is part of an industrial environment where voltages are present that contain a potential hazard of electric shock and/or burn. For this reason, only personnel who have a thorough knowledge of the drive and the industrial environment and have obtained the required qualification must handle, install, operate, or maintain the drive.

The manual addresses personnel who are responsible for unpacking, transportation, installation, operation and maintenance of the drive. The personnel must carry out the below listed tasks in a manner that does not cause physical harm or danger, and that ensures the safe and reliable functioning of the drive.

**Note:** Commissioning of the drive must only be performed by qualified and certified ABB personnel.

- **Handling**
  
The personnel must be skilled and experienced in unpacking and transporting heavy equipment.

- **Mechanical installation**
  
The personnel must be qualified to prepare the installation site according to the site and equipment requirements and to perform the installation accordingly.

- **Electrical installation**
  
The personnel must have a sound knowledge of the relevant electrical codes and specifications covering low and medium voltage equipment, be experienced with electrical wiring principles, and know the electrical symbols typically used in wiring diagrams.

- **Operation**
  
The personnel include all persons who operate the drive from the local operating panel of the drive. The personnel must know the functions of the operating panel, be adequately trained for the drive, and know the driven process. Special knowledge of frequency converter technology is not required.
Maintenance

The personnel include all persons who

- are qualified to carry out preventive and corrective maintenance on drive as described in this manual
- are thoroughly familiar with the drive
- have a sound knowledge of the relevant electrical codes and specifications covering low and medium voltage equipment
- are able to assess the hazards associated with the energy sources of the drive system and act correspondingly
- know the safe shutdown and grounding procedures for the drive system.

Contents of the manual

This manual contains the instructions and information for the basic drive configuration.

Relevant chapters of the manual

<table>
<thead>
<tr>
<th>Chapter</th>
<th>Handling</th>
<th>Installation</th>
<th>Operation</th>
<th>Maintenance</th>
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</table>

Related manuals

See List of related manuals on the inside of the front cover.

User’s responsibilities

It is the responsibility of those in charge of the drive to ensure that each person involved in the handling, installation, operation or maintenance of the drive has received the appropriate training and has thoroughly read and clearly understood the instructions in this manual and the relevant safety instructions.
Intended equipment use

Those in charge of the drive must ensure that the drive is only used as specified in the contractual documents, operated under the conditions stipulated in the technical specifications and on the rating plate of the drive, and serviced in the intervals as specified by ABB.

Use of the drive outside the scope of the specifications is not permitted.

Intended equipment use also implies that only spare parts recommended and approved by ABB must be used.

Unauthorized modifications and constructional changes of the drive are not permitted.

Cyber security disclaimer

This product is designed to be connected to and to communicate information and data via a network interface. It is Customer's sole responsibility to provide and continuously ensure a secure connection between the product and Customer network or any other network (as the case may be). Customer shall establish and maintain any appropriate measures (such as but not limited to the installation of firewalls, application of authentication measures, encryption of data, installation of anti-virus programs, etc) to protect the product, the network, its system and the interface against any kind of security breaches, unauthorized access, interference, intrusion, leakage and/or theft of data or information. ABB and its affiliates are not liable for damages and/or losses related to such security breaches, any unauthorized access, interference, intrusion, leakage and/or theft of data or information.

Categorization by frame size and option code

Some instructions, technical data and dimension drawings which concern only certain frame sizes are marked with the symbol of the frame size (e.g. 6R6, 10R6). The frame size is not marked on the rating plate. To identify the frame size of your drive, see the Technical Data.
Function and hardware description

Contents of this chapter
This chapter provides information on the power equipment and cabinet design and briefly describes the operation principle of the drive.

Product overview
The air-cooled ACS580MV is a general purpose frequency converter for the control of standard induction motors. It is used for a wide variety of applications in different industries with a voltage of 6 kV to 11 kV and a power range of 200kW to 6300 kW.

The drive is characterized by
- integrated multi-winding input transformer
- modular power electronics
- 30 / 36 / 48 / 54 pulse diode rectifier input
- no additional filter requirement
- multi-level output voltage
- motor cables up to 600 m as standard.

Note: The principle design and layout, and the arrangement of the major power electronics components is the same for all frame sizes of the drive. For this reason, the ACS580MV type 11R6 is used for illustrations.
For information on the power and voltage range of your drive, see the **Technical data** and the **Rating plate** of the drive. For further information on the general drive characteristics, refer to the ACS580MV catalog.

**Typical drive line-up (drive type 11R6)**

The dimensions and weight of the cabinet depend on the drive power.

### Rating plate

The rating plate includes an IEC rating, appropriate markings, a type designation and a serial number, which allow identification of each unit. The rating plate is located on the
back of the control compartment door (1 in figure below). An example label is shown below.

Label with MV full typecode for ABB internal use is pasted below the rating plate.

<table>
<thead>
<tr>
<th>No.</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Location of rating plate</td>
</tr>
<tr>
<td>2</td>
<td>Type designation, see ACS580MV catalog.</td>
</tr>
<tr>
<td>3</td>
<td>Ratings</td>
</tr>
<tr>
<td>4</td>
<td>Compliance information</td>
</tr>
<tr>
<td>5</td>
<td>Serial number.</td>
</tr>
</tbody>
</table>

Label with MV full typecode for ABB internal use is pasted below the rating plate.
System overview and single line diagram

The ACS580MV drive consists of the following parts:

- integrated input transformer with multiple secondary windings (TRU)
- power modules connected in cascaded h-bridge technology (INU)
- control system based on BCU-02 control unit.

Power supply configuration

The drive requires two independent power supplies:

- Main MV power supply for the power modules via the integrated input transformer
- Auxiliary power supply for the control and cooling equipment.

If the drive is equipped with the optional cabinet heaters, an additional AC supply is required.

Main power supply to input isolation transformer

The main power is fed to the drive by the input isolation transformer which adapts the line voltage to the required voltage for the power modules. The input isolation transformer is always part of the drive system.
The secondary side of the input transformer is a multi-winding configuration that matches the number of individual power modules (3 x 5 modules (6/6.3 kV) or 3 x 6 modules (6.6 kV) or 3 x 8 modules (10 kV) or 3 x 9 modules (10.5/11 kV).

**Auxiliary power supply**

The drive needs auxiliary power for:

- the cooling fans
  The power is always fed by a three-phase power supply.
- the control hardware
  The power is fed by a single-phase power supply.
- the optional cabinet heaters
  The power is fed by a single-phase power supply.

The power feed for the auxiliary supply must be protected with a suitable circuit protection rated for the inrush current. For information on the type dependent auxiliary power consumption figures, see ACS580MV power supply consumption of the drive in the *ACS580MV Engineering Guideline*.

Several auxiliary power supply schemes are available. As a standard, the customer has to provide the following supplies:

**Standard configuration**

- External 3 phase supply for fan supply (380 - 425 VAC)
- External single phase supply for control supply (100 - 240 VAC or 120 - 370 VDC)
- With optional cabinet heaters: additional external single phase supply (220 - 240 VAC)

Alternatively:

- External 3 phase supply with PE and neutral line (380 - 425 VAC)
  Control auxiliary power is taken from one phase and the neutral line.
- With optional cabinet heaters: additional external single phase supply (220 - 240 VAC)

**Alternative configurations**

For details on optional alternative supply configurations see *ACS580MV Engineering Guideline*.

**Cabinet layouts**

This section describes the main design features and introduces the major power electronics and control components of a typical ACS580MV.
Terminal unit

The terminal unit (TEU) is located behind the control unit (COU). A bolted protection plate separates the two compartments. The plate is integrated into the protection loop to prevent access when the drive is energized.

The compartment provides the terminals for the feeder and motor cables, and the ground bus for the termination of the ground cable and the cable screens.

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Voltage dividers</td>
</tr>
<tr>
<td>2</td>
<td>Motor side terminals</td>
</tr>
<tr>
<td>3</td>
<td>Input terminals</td>
</tr>
<tr>
<td>4</td>
<td>Cable entry plate</td>
</tr>
<tr>
<td>5</td>
<td>Cabinet grounding busbar</td>
</tr>
</tbody>
</table>

Terminal compartment with cover plate removed
For further information on the cable entry, see
- ACS580MV Base frame & TEU layout design
- Chapter Electrical installation, Cable entries for external connections.

**Transformer unit**

The integrated input transformer is placed on the right side of the drive. It is delivered as a separate unit (TRU) and joint with the converter unit at the final installation location.

1. Fan units
2. Terminal block for monitoring and fan supply
3. Transformer
4. Transformer secondary terminals leading to the power modules
5. Transformer primary side power terminals

**Transformer unit (drive type 11R6)**

The transformer is air-cooled by means of one or two fan units, depending on the drive size.

Optionally, the integrated input transformer is available as a step-up or step-down version.

**Inverter unit**

The inverter unit (INU) is part of the drive unit, i.e. it is located between the control unit and the transformer. The INU contains the series connected low voltage power modules (see section *Power module*) and the associated control equipment (control hub).
Inverter unit (drive type 11R6)

**Power module**

Three types of power modules are used:

- Power module 0 (frame sizes R1, R2, R3)
- Power module 1 (frame sizes R4, R5, R6)
- Power module 2 (frame sizes R7, R8, R9)

The power modules are mounted on guide rails and bolted to the frame for easy replacement.

For information on the dimensions and the weight, see *Technical data.*
1. Input cables (3 phases)
2. Power cable terminals
3. Input fuses
4. Fiber optic terminal
5. Output busbar (behind cable terminals)

Power module 0/1 (frame size R1 - R6)

Power module circuit diagram

<table>
<thead>
<tr>
<th>Component</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>F1, F2</td>
<td>Input fuses</td>
</tr>
<tr>
<td>D1 - D6</td>
<td>Diode rectifier bridge</td>
</tr>
<tr>
<td>C</td>
<td>DC circuit capacitor</td>
</tr>
<tr>
<td>S1 - S4</td>
<td>Inverter IGBTs</td>
</tr>
<tr>
<td>R1</td>
<td>Charging resistor</td>
</tr>
</tbody>
</table>
Each power module integrates in one single housing a
- 6 pulse diode rectifier bridge
- DC circuit
- inverter IGBTs
- gate driver electronics.

The active 3-phase unit is designed as a self-commutated, multi-level voltage source inverter. As a result of the multi-level topology, the drive produces an optimum number of switching levels - e.g. 21 level for 6 kV, 33 level for 10 kV, phase to phase.

The resulting waveforms permit the use of standard motors.

Output current and voltage waveforms for 10 kV, 50 Hz

Charging circuit
The DC link capacitor is charged via the charging resistor R1 when the MCB is closed and the drive is connected to the main power supply. Thus, excessive inrush currents are prevented.

The charging sequence is started by pressing the SUPPLY ON pushbutton on the control compartment door. After the charging sequence has finished, the charging resistor is bypassed and the DC link will reach its nominal level. The drive then is in status Stopped.

When the DC link has been charged, it is possible to keep the drive in this state to facilitate a more rapid start-up procedure.

Discharging the power modules
Discharging is initiated by pressing the SUPPLY OFF pushbutton on the control compartment door. The energy stored in the DC link is dissipated in the resistors of the power part of the drive. For safety reasons, the cabinet doors are locked for 15 minutes.
during the DC link capacitors discharge. After the DC link capacitors have discharged completely the cabinet doors of the power compartments unlock and the **SUPPLY OFF** pushbutton changes to a permanent light. The power modules can then be grounded with the supplied grounding hook (for details see *Shutting down the drive for maintenance*).

- **Control unit**

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Control supply, mini circuit breakers</td>
</tr>
<tr>
<td>2</td>
<td>MCB control relays</td>
</tr>
<tr>
<td>3</td>
<td>Customer terminal blocks and cable duct</td>
</tr>
<tr>
<td>4</td>
<td>Control unit (BCU)</td>
</tr>
<tr>
<td>5</td>
<td>Local control equipment (backside)</td>
</tr>
<tr>
<td>6</td>
<td>Fan supply, breakers</td>
</tr>
<tr>
<td>7</td>
<td>24 VDC power supply for control</td>
</tr>
<tr>
<td>8</td>
<td>-24 VDC converter for control</td>
</tr>
<tr>
<td>9</td>
<td>EMC cushions for cable bottom entry</td>
</tr>
<tr>
<td>10</td>
<td>PE busbar</td>
</tr>
<tr>
<td>11</td>
<td>I/O controller</td>
</tr>
<tr>
<td>12</td>
<td>Terminal blocks &amp; fuses</td>
</tr>
</tbody>
</table>

*Control compartment with open swing frame*
34 Function and hardware description

Control compartment with swing frame closed

1. CVMI2 board
2. Cabinet heater (optional)

Control compartment with front door closed

1. Local control panel and pushbuttons
2. Sealing grommets for cable top entry
Cabinet design

The cabinet has been designed using the MNS cabinet system of ABB. The design consists of a skeletal frame to which the outer panels are bolted to. Corrosion resistant materials are used to protect the cabinet from corrosion.

The basic elements of the frame are C-shaped steel profiles with screw holes at a regular distance of 25 mm. The profiles are anti-corrosion-coated. The outer panels are bolted to the C-shaped profiles with self-tapping screws. The panels are also protected by hot-dip zinc-coating.

The outside of the doors and the side panels are painted to enhance the appearance of the cabinet. The standard color is RAL 7035 and RAL 7032.

The cabinet's inside panels are not painted, because paint tends to reduce the effectiveness of metallic bonding which is important for successful EMC.

- Protection class

Standard protection class is IP21. IP42 is available as option.

Door locking system

All doors and removable cover plates of the drive and the transformer units are either lockable or bolted. Additionally, the door of the INU is secured with a safety switch. The safety switch is tied into an interlocking circuit that prevents the door from being opened as long as the DC link of the drive is charged.

The door of the control compartment (1) is not integrated into the interlocking circuit and can always be opened. However, the removable cover plates leading to the terminal compartment are equipped with safety contacts that are tied into the interlocking circuit. An Emergency off is initiated if one of these contacts is opened.
Door locks

1 Door of control compartment: lockable
2 Cover plates to TEU with safety contact: bolted. The main power cannot be switched on when the plate is removed.
3 Doors of INU compartment: electromechanically locked
4 Doors of transformer unit: bolted
**Cooling system**

The drive unit and the transformer unit are each equipped with one or several fan units, depending on the drive type. Optionally, the drive and the integrated transformer can each be equipped with a redundant fan configuration. This configuration ensures that the operation of the drive system is not interrupted if a fan fails.

---

*Fan units on top of transformer unit*

- **Function**

  **Fan groups**

  For control reasons, the fan unit(s) of the drive and the integrated transformer are combined to groups.

  - Fan unit 1 of the drive and fan unit 1 of the integrated transformer belong to group 1.
  - Fan unit 2 of the drive and fan unit 2 of the integrated transformer belong to group 2.

  The fan units of a group are always switched on and off together.

- **Starting, stopping**

  The standard fan unit or fan group 1 is switched on by the control system of the drive when the charging of the DC link is initiated. When the MCB has opened, the fan units continue to run for a preset time.

- **Air flow inside the drive**

  Drive unit: the fan unit feeds the cooling air to the main power electronic components and transfers the heat to the outside of the cabinet.

  Transformer unit: the fan unit feeds the cooling air to the transformer and transfers the heat to the outside of the cabinet.

  The air enters the drive cabinet through the louvered panels at the front, passes the power modules in the INU compartment, or the transformer in the TRU. The air then exits through the outlet of the fan unit on the cabinet top.
Air flow through the drive

When a fan of the drive or a fan of the integrated transformer fails, the control system of the drive switches on the stand-by fan automatically in case of redundant fans. The failure of a fan is indicated on the control panel of the drive.

Temperature monitoring

The power modules, the INU compartment and the transformer are monitored for overtemperature.
Control system and interfaces

Contents of this chapter

This chapter contains an overview of the control system, the default I/O connection diagram, descriptions of the terminals and contains references to related manuals and documentation.

Main components

The control compartment incorporates the hardware for the control, monitoring and protection functions of the drive, and the communication interfaces to the local control panel and to the remote control devices. Depending on the control concept of the drive system, the remote control devices include a higher-level control system and / or remote operator stations.
Control system block diagram

The BCU is the major component of the drive control system and performs general drive, motor control, and closed loop functions.

The main internal control devices and the peripheral input and output interfaces to the customer communicate with the BCU via optical fibers and hardwired I/Os.

The control hub provides the interfaces between the inverter unit and the control compartment. This includes the inverter control as well as the monitoring signals from the inverter cabinet.

DDCS communication channels are used for high speed data transfer via the control hub to the PEBB control boards inside the power modules.

Internal and external, analog and binary I/O signals are connected to the BCU via an AC500 I/O controller. The I/O controller and the BCU communicate via a fieldbus link.

Analog measurement signals (i.e. supply and motor voltages and currents) are transmitted to the BCU via the CVMI2 board.

For the physical locations of the control components see chapter Function and hardware description.
Control unit (BCU)

The BCU is a control unit used for controlling drives, inverters and converters via fiber optic links. The BCU contains integrated branching unit functionality for collecting and storing real-time data from the converter modules to help fault tracing and analysis. The data is stored in a SD card (data logger memory).

**BCU control unit**

The BCU has an integrated Ethernet port for PC tool communication and a removable memory unit. When, for example, a converter is replaced, the parameter settings can be retained by transferring the memory unit from the defective converter to the new one.

**I/O extension and fieldbus modules**

The BCU has three option slots for I/O extensions, encoders and fieldbus adapters. Two are available for customer use, allowing the use of following fieldbus protocols: Profibus, Modbus RTU, Modbus TCP, EtherNet/IP, Profinet, and/or analog and digital I/O extension adapters.

The actual configuration of the I/O extensions and fieldbus adapters can be derived from the option codes in the ordering code of the drive (for identification refer to the ACS580MV catalog). Typical configuration includes one I/O extension adapter plus one fieldbus module, OR, two I/O extension adapters.
For the related manuals refer to the project documentation, containing the relevant Manuals and quick guides for I/O extension modules, fieldbus adapters, etc.

**Control tasks**

The BCU has specific control and closed-loop tasks assigned to it. It processes drive and status information, performs the speed and torque control tasks, and monitors the operation of the drive.

All relevant drive variables (e.g. speed, torque, current, voltage) are continuously monitored by the control system. Pre-programmed protection functions ensure that these variables remain within certain limits in order to maintain safe operation of the drive. These internal functions are not programmable by the user.

Optionally, the drive can monitor signals from external equipment. These can be activated and adjusted with parameters.

Other general control, protection and monitoring tasks regarding the whole drive include control and monitoring of:

- Main circuit breaker
  
  The main circuit breaker (MCB) is an important switching and protection device of the drive system. Therefore it must only be controlled by the drive.

- Door locking system

- Cooling fans

**Parameters and application macros**

The control system is configured, customized, and tuned with a set of application parameters. The application parameters are organized in functional groups and have factory-set default values (application macros).

The following application macros are available:

- Factory (default application macro)
  
  The Factory macro is suited to relatively straightforward speed control applications such as fans, pumps and conveyors.

- Hand/Auto
  
  The Hand/Auto macro is suited to speed control applications where two external control devices are used.

- PID control
  
  The PID control macro is suitable for process control applications, for example closed-loop pressure, level or flow control systems.

- Sequential control
  
  The Sequential control macro is suited for speed control applications in which a speed reference, multiple constant speeds, and two acceleration and deceleration ramps can be used.

The default parameter values are adjusted during commissioning to the specific application of the drive in order to activate the specific control, monitoring and protection functions for the driven process, and to define the signals and data transferred between drive and external equipment.
For detailed information on the parameters for signal allocation, signal type selection, signal inversion, scaling, and filtering, see:

- *ACS580MV primary control program firmware manual*

**Control locations and operating modes**

The ACS580MV has two main control locations: external and local. The control location is selected with the **Loc/Rem** key on the control panel or in the PC tool.

Refer to *ACS580MV primary control program firmware manual*.

- **Application macros**

Refer to *ACS580MV primary control program firmware manual*.

**Local operating elements**

The local operating elements are located on the front door of the control compartment.

- **Local control panel**

The control panel serves as the basic user interface for operating and monitoring the drive when the local operating mode has been selected.

The control panel can be attached to or detached from the drive without having to switch off the auxiliary power supply first.

Using the control panel, it is possible

- to enter start-up data
- to control the drive with a reference value, and start, stop and direction commands
- to display actual values (3 values can be read simultaneously)
- to display and adjust parameters
- to display information on the most recent fault events
- to display history graphs
- to upload and download complete parameter sets.

The control panel has a status LED that indicates if there are any faults or warnings present. The table below shows the meaning of the LED indications.

<table>
<thead>
<tr>
<th>LED status</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Green, continuous</td>
<td>Normal operation</td>
</tr>
<tr>
<td>Green, flickering</td>
<td>Data is transferred between the PC tool and drive through the USB connection of the control panel.</td>
</tr>
<tr>
<td>Green, flashing</td>
<td>Alarm pending</td>
</tr>
<tr>
<td>Red</td>
<td>Drive in fault state.</td>
</tr>
</tbody>
</table>

For details on use and maintenance of the control panel refer to *ACS-AP-X assistant control panels user’s manual*. 
Local operating elements

- **Supply OFF/ON pushbuttons**

  The **SUPPLY OFF** pushbutton is used to disconnect the drive from the main power supply. It is illuminated when the MCB is open and the drive is discharged.

  The **SUPPLY ON** pushbutton is used to connect the drive to the main power supply. It is illuminated when the MCB is closed.

---

1. Control panel
2. Supply OFF/ON pushbuttons and indication lamps
3. Alarm (flashing) / Fault (on) indication light
4. Emergency Reset button (optional for SIL3)
5. Emergency off button
### Alarm and fault indications

When a failure occurs in the drive or in the equipment monitored by the drive, the control panel displays a corresponding alarm or fault message and the red Fault / Alarm button on the control compartment door lights up:

<table>
<thead>
<tr>
<th>Button / Light</th>
<th>Color</th>
<th>Status</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fault/Alarm</td>
<td>Red</td>
<td>Off</td>
<td>Normal operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Flashing</td>
<td>Alarm pending</td>
</tr>
<tr>
<td></td>
<td></td>
<td>On</td>
<td>Drive in fault state</td>
</tr>
</tbody>
</table>

### Emergency off

The Emergency off button initiates an immediate stop of the drive.

In the event of an Emergency off, the following happens immediately:

- the pulses of the inverter are blocked
- the MCB is tripped.
- the DC link is discharged.

All auxiliary circuits remain live.

### Monitoring

Basic system monitoring is done with the local control panel. For more detailed diagnosis and signal monitoring the Drive Composer – PC tool is available.

### I/O interfaces

#### Customer control and process I/Os

This chapter provides an overview of the hardwired I/Os. For details refer to ACS580MV Engineering Guideline and ACS580MV Catalog.

Please note that this I/O interface only available in standard option, if Synchronized Bypass or manual bypass selected, please see I/O interface in separated Synchronized Bypass hardware manual or Manual bypass hardware manual.
Control system and interfaces

XPOW
External power input
1 +24V  +24 VDC, 2 A (internally used)
2 GND  24 VDC, 2 A (internally used)

XAI
Reference voltage and analog inputs
1 +VREF  10 VDC, R<sub>L</sub> 1…10 kohm
2 -VREF  -10 VDC, R<sub>L</sub> 1…10 kohm
3 AGND  Ground
4 AI1+  Speed reference
5 AI1-  0(2)…10 V, R<sub>L</sub> >200 kohm
6 AI2+  By default not in use.
7 AI2-  0(4)…20 mA, R<sub>L</sub> >100 ohm

XAO
Analog outputs
1 AO1  Motor speed rpm
2 AGND  0…20 mA, R<sub>L</sub> <500 ohm
3 AO2  Motor current
4 AGND  0…20 mA, R<sub>L</sub> <500 ohm

XRO1, XRO2, XRO3
Relay outputs
11 NC  Ready
12 COM  250 VAC/30 VDC
13 NO  2 A
21 NC  Running
22 COM  250 VAC/30 VDC
23 NO  2 A
31 NC  Fault (-1)
32 COM  250 VAC/30 VDC
33 NO  2 A

XD24
Digital interlock
5 +24 VD  +24 VDC 200 mA
6 DICOM  Digital input ground
7 +24 VD  +24 VDC 200 mA
8 DIOGND  Digital input/output ground

XDO
Digital input/outputs
1 DIO1  MCB trip command (internally used)
2 DIO2  MCB status closed (internally used)

XDI
Digital inputs
1 DI1  Stop (0) / Start (1)
2 DI2  Forward (0) / Reverse (1)
3 DI3  Reset
4 DI4  Acc/Dec time set 1 (0) / set 2 (1)
5 DI5  Constant speed 1 (1 = On)
6 DI6  By default, not in use

X13
Control panel connection (internally used)
X205
Memory unit connection (internally used)
XETH
PC ethernet connection for Drive Composer

Default control connections for the factory macro
### Customer Interface Terminal Block

<table>
<thead>
<tr>
<th>X1</th>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>MCB close cmd</td>
<td>floating contacts to customer making capability: 40 A thermal current: $I_{th} = 6,A,\text{at} 40^\circ\text{C}$ breaking capability:</td>
</tr>
<tr>
<td>3</td>
<td>MCB open cmd</td>
<td>AC-15 50 Hz $I_{e}(240,V)=4,A$, le(500 V)=2 A DC-13 $I_{e}(24,V)=2.5,A$, le(110 V)=0.7 A, le(240 V)=0.4 A</td>
</tr>
<tr>
<td>5</td>
<td>MCB trip/unlock cmd 1</td>
<td>maximum load: 17 V, 5 mA</td>
</tr>
<tr>
<td>7</td>
<td>MCB closed status</td>
<td>Connect contact from customer internal supply 24 V dc, 5 mA</td>
</tr>
<tr>
<td>9</td>
<td>MCB open status</td>
<td>Connect contact from customer internal supply 24 V dc, 5 mA, max resistance 140 $\Omega$</td>
</tr>
<tr>
<td>11</td>
<td>MCB ready status</td>
<td>Connect contact from customer internal supply 24 V dc, 5 mA</td>
</tr>
<tr>
<td>13</td>
<td>Emergency off 1</td>
<td>Connect contacts from customer Max resistance 60 $\Omega$.</td>
</tr>
<tr>
<td>15</td>
<td>Emergency off 2</td>
<td>Internal supply, 24 V dc, 25 mA</td>
</tr>
<tr>
<td>17</td>
<td>Remote MCB close cmd</td>
<td>Connect contacts from customer internal supply 24 V dc, 5 mA</td>
</tr>
<tr>
<td>19</td>
<td>Remote MCB open cmd</td>
<td>Switchable</td>
</tr>
<tr>
<td>21</td>
<td>Alarm</td>
<td>RO, NC/NO can be selective, 250 V AC/24 V DC, 2 A</td>
</tr>
<tr>
<td>23</td>
<td>Emergency off reset</td>
<td>to be check</td>
</tr>
<tr>
<td>25</td>
<td>24Vdc</td>
<td>24Vdc for digit input</td>
</tr>
</tbody>
</table>

*Customer interface terminal block*
### Control system and interfaces

#### Hand/Auto macro (changes compared to factory macro)

<table>
<thead>
<tr>
<th>XAI</th>
<th>Reference voltage and analog inputs</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>AI1+</td>
</tr>
<tr>
<td>5</td>
<td>AI1-</td>
</tr>
<tr>
<td>6</td>
<td>AI2+</td>
</tr>
<tr>
<td>7</td>
<td>AI2-</td>
</tr>
</tbody>
</table>

**PID control macro (changes compared to factory macro)**

<table>
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<tr>
<th>XAI</th>
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</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>AI1+</td>
</tr>
<tr>
<td>5</td>
<td>AI1-</td>
</tr>
<tr>
<td>6</td>
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</tr>
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**Sequential control macro (changes compared to factory macro)**

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<td>7</td>
<td>AI2-</td>
</tr>
</tbody>
</table>

**Hand/Auto macro (changes compared to factory macro)**

<table>
<thead>
<tr>
<th>XAI</th>
<th>Reference voltage and analog inputs</th>
</tr>
</thead>
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</table>

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<td>AI2+</td>
</tr>
<tr>
<td>7</td>
<td>AI2-</td>
</tr>
</tbody>
</table>
Control system and interfaces   49

- I/O signal requirements
  See the Technical data.

- Communication interfaces
  See the ACS580MV primary control program firmware manual and the Technical data.
Guidelines for planning the electrical installation

References
For instructions for planning the electrical installation of the drive and for the technical requirements for the protection and control of the medium voltage supply see the ACS580MV Engineering Guideline.

For selecting a specific drive type and options refer to ACS580MV Engineering Guideline.

Limitation of liability
The installation must always be designed and made according to applicable local laws and regulations. ABB does not assume any liability whatsoever for any installation which breaches the local laws and/or other regulations. Furthermore, if the recommendations given by ABB are not followed, the drive may experience problems that the warranty does not cover.
Transportation, storage and disposal

Contents of this chapter

This chapter provides information and instructions for transportation, storage and disposal of the drive.

Safety

The drive must only be handled by personnel who are skilled and experienced in unpacking and transporting heavy equipment.

All work must be carried out by qualified personnel according to the site and equipment requirements and in compliance with the local regulations.

Transport conditions

The transport conditions for the drive are based on IEC 60721-3-2 'Classification of environmental conditions: Classification of groups of environmental parameters and their severities; Transportation'.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Limits</th>
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</thead>
<tbody>
<tr>
<td>2K4 (climatic conditions), 2C2 (chemical gases), 2S2 (solid particles), 2M2 (vibration and shock)</td>
<td></td>
</tr>
<tr>
<td>Low air temperature</td>
<td>-40 °C</td>
</tr>
<tr>
<td>High air temperature</td>
<td>70 °C</td>
</tr>
<tr>
<td>Relative humidity</td>
<td>5 to 95 %, no condensation</td>
</tr>
</tbody>
</table>
Unpacking and inspection
1. Remove all packaging material carefully.
2. Check the drive and accompanying equipment for damages.
3. Compare the complete delivery with the purchase order and the packing list.
4. If parts are missing or damaged, immediately inform the shipping company and ABB.
   It is recommended to photograph the damages and send the photographs to ABB.

Lifting and transportation

It is recommended to have the following information at hand before transporting the cabinet:

- Chapter *Technical data* provides details on dimensions, weight, and of center of gravity of the cabinet.
- Chapter *Maintenance* provides instructions if the door of the INU compartment cannot be opened.

**General notes on transportation**
- Drive components can be damaged during transportation. Therefore, transport the cabinet in an upright position.
- Transport separated units only!
- Keep the doors closed to prevent dirt from entering. Metallic dust in particular can cause damage and failure when the drive is energized.

**Dimensions and weights**
- Choose the load capacity according to the following table. For center of gravity see the *ACS580MV Gravity Center for Packing*.

<table>
<thead>
<tr>
<th>Type</th>
<th>Drive unit</th>
<th>Transformer unit</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Height (mm)</td>
<td>Depth (mm)</td>
</tr>
<tr>
<td>6/6.3R1</td>
<td>2571</td>
<td>1176</td>
</tr>
<tr>
<td>6/6.3R2</td>
<td>2571</td>
<td>1176</td>
</tr>
<tr>
<td>6/6.3R3</td>
<td>2571</td>
<td>1176</td>
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<tr>
<td>6/6.3R4</td>
<td>2571</td>
<td>1176</td>
</tr>
<tr>
<td>6/6.3R5</td>
<td>2571</td>
<td>1176</td>
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<tr>
<td>6/6.3R6</td>
<td>2571</td>
<td>1176</td>
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<tr>
<td>6/6.3R7</td>
<td>2571</td>
<td>1376</td>
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<tr>
<td>6/6.3R8</td>
<td>2571</td>
<td>1376</td>
</tr>
<tr>
<td>6/6.3R9</td>
<td>2571</td>
<td>1376</td>
</tr>
<tr>
<td>6.6R1</td>
<td>2571</td>
<td>1176</td>
</tr>
<tr>
<td>6.6R2</td>
<td>2571</td>
<td>1176</td>
</tr>
</tbody>
</table>
Using a crane

- Use lifting equipment (e.g., web slings, chain slings, round slings, safety hooks, shackles) that corresponds to the weight of the cabinet.
- Use a metal beam through the holes in the base frame.
- Use appropriate safety hooks or shackles to attach a sling.
- Do not pass a sling through the fastening hole.
- Verify that the slope angle (1 in figure below) corresponds to the weight of the cabinet.

<table>
<thead>
<tr>
<th>Type</th>
<th>Drive unit</th>
<th>Transformer unit</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Height (mm)</td>
<td>Depth (mm)</td>
</tr>
<tr>
<td>6.6R3</td>
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<tr>
<td>6.6R4</td>
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<td>6.6R5</td>
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<td>6.6R6</td>
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<td>6.6R7</td>
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<td>6.6R8</td>
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<tr>
<td>10R1</td>
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<tr>
<td>10.5/11 R1</td>
<td>2571</td>
<td>1176</td>
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<tr>
<td>10.5/11 R2</td>
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</tr>
</tbody>
</table>
• Observe the center of gravity (see the ACS580MV Gravity Center for Packing).
• Lift the cabinet slowly and steadily to the required clearance height maintaining the cabinet in upright position.
• Check the horizontal position of the cabinet. Reposition the slings, if necessary.

**Using a forklift**

• Only transport the cabinet with the long side facing the driving direction.

• Use forks with sufficient length to ensure stable transportation and to prevent tipping.
The forks must be at least as long as the cabinet.

- Insert the fork fully into the cabinet's forklift pockets.

## Storage

### Storage conditions

The minimum requirements for storage are based on IEC 60721-3-1 'Classification of environmental conditions: Classification of groups of environmental parameters and their severities; Storage'.

<table>
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<td>70 °C</td>
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<tr>
<td>Relative humidity</td>
<td>5 to 85 %, no condensation</td>
</tr>
</tbody>
</table>

Cabinets can be stored for up to one year in the original packaging as long as they are not damaged or opened. For information on longer storage periods, contact the ABB service organization.

### Preparing cabinets for storage

If the drive is taken out of service for a longer time proceed as follows:

1. Cover all cable inlets and ventilation slots with an impermeable plastic or aluminum foil and a wooden panel.
2. Add a desiccant of the appropriate quality:
   - 1 unit desiccant (30 g) absorbs 6 g water vapor.
     - The following quantity is needed when using a polyethylene foil:
       - 10 units/m² foil
3. Close and lock the doors of the cabinet.
4. Use polyethylene or equivalent for packaging:
   - 0.3 g/m²/24 h water vapor diffusion
5. Attach humidity indicators to the packaging.

Check the storage conditions and the packaging regularly. Immediately repair any damages that occur during the storage period.

### Storage and handling instructions for spare parts

Electronic devices (e.g., circuit boards, power modules) are sensitive to electrostatic discharge (ESD). ESD can damage these devices.

Apply ESD handling precautions before handling these devices.

Check the spare parts immediately after receipt for damages. Report any damage to the shipping company and the ABB service organization.
Observe the following to maintain spare parts in good condition and to keep the warranty valid during the warranty period:

- Keep spare parts in their original packaging.
- Store printed circuit boards in anti-static bags or boxes.
- Storage temperature range: -5 °C to + 55 °C (23 °F to 131 °F)
- Storage place requirements:
  - Free of vibration and shock
  - Protected against dust, sand, vermin and insects
  - Free of corrosive gases, salt or other impurities that could damage electronic equipment
  - Dry; no condensation
  - Relative air humidity: 5 to 85%
    If in doubt whether the maximum allowed humidity is exceeded, protect the spare parts by an external heater.
- Ground yourself with a wrist strap before touching a component.
- Put the component on a grounded working surface protected against electrostatic discharges.
- Hold the component only at the edge.

Reforming capacitors of the power modules

- Power modules that are used as spare parts must be installed and operated in a drive every 2 years in order to reform the capacitors and thus reduce the risk of a potential hazard. For detailed information, go to ACS580MV PM capacitor reforming instructions. (2UBB017371)

Disposal of packaging materials and components

Dispose of the packaging materials and the drive components at the end of the life time of the drive according to the international and local regulations.

The main parts of the drive can be recycled to preserve natural resources and energy. Product components and materials should be dismantled and separated.

Generally all metals, such as steel, aluminum, copper and its alloys, and precious metals can be recycled. Plastics, rubber, cardboard and other packaging material can be used in energy recovery. Printed circuit boards and capacitors need selective treatment according to IEC 62635 guidelines. To aid recycling, plastic parts are marked with an appropriate identification code.

Contact your local ABB distributor for further information on environmental aspects and recycling instructions for professional recyclers.
Mechanical installation

Contents of this chapter
This chapter describes the mechanical installation procedure of the drive.

Safety
All installation work must be carried out by qualified personnel according to the site and equipment requirements and in compliance with the local regulations.

Examining the installation site
Examine the installation site (see the ACS580MV Engineering Guideline):

- The installation site is sufficiently ventilated or cooled to transfer away the drive losses. ¹)

- The ambient conditions of the drive meet the specifications. ¹)

- The wall behind the unit is of non-flammable material.

- There is enough free space above the drive to enable cooling air flow, service and maintenance. See the ACS580MV Base frame & TEU layout design.

- The floor that the unit is installed on is of non-flammable material, as smooth as possible, and strong enough to support the weight of the unit. Check the floor flatness with a spirit level. The maximum allowed deviation from the surface level is 5 mm in every 5 meters. Level the installation site, if necessary, as the cabinet is not equipped with adjustable feet.

¹) The heat losses and ambient conditions are specified in the ACS580MV Engineering Guideline.
Necessary tools

The tools required for moving the unit to its final position, fastening it to the floor and wall and tightening the connections are listed below:

- crane, fork-lift (check load capacity!), iron bar, jack and rollers
- Pozidrive and Torx (2.5…6 mm) screwdrivers
- torque wrench
- set of wrenches or sockets

Overview on installation work

The installation includes the following work:

- Preparing the foundation
- Moving the converter and transformer units to their final location
- Aligning and bolting together the units
- Fixing base frames to the floor

General notes on installation

Foreign matter and particularly metallic dust can cause failure and damage when the drive is energized.

Ensure that foreign matter cannot enter the cabinet:

- Close the doors and cover openings completely when work is discontinued.
- Retrieve any foreign matter which accidentally dropped into the cabinet.

Dimensions, clearances

See Outline drawing for information on:

- Cabinet dimensions
- Clearances to be observed
- Mounting hole sizes

Preparing the foundation

The floor must be of non-flammable material, with a smooth and non-abrasive surface, protected against humidity diffusion, leveled and able to support the weight of the cabinet.

The maximum recommended allowable overall unevenness is ≤ 5 mm per 5 m.

Cable ducts

Cable ducts should be of non-flammable material with a non-abrasive surface.

All cable entries and exits should be protected to prevent dust, humidity and animals entering the drive.

Fire protection

Suitable fire protection measures should be applied to prevent fire spreading into the drive.
Cabinet roof

The cabinet roof is not designed as a mounting base for foreign devices, cable ducts and so on. Therefore, it is not permitted to install any foreign device on the roof.

Installing fan units

AC fans are already mounted when delivered from works.
EC fans need to be installed with fan box in the field.

For information on the number of fan units to be installed, see ACS580MV Base frame & TEU layout design.

Installation

1. Lift the fan unit onto the cabinet roof by means of a forklift or a crane (if using a crane, empty the lifting eyes in the fan roof).

- ~70 kg for EC500 fan units
- ~90 kg for EC560 fan units

NOTICE

The mounting position can be identified by the cutouts in the drive roof.

2. Use the supplied screws to fasten the fan units to the cabinet roof.

For information on the electrical installation, see Control and power supply cables for fan units.
Bolting together the units

Required bolts are attached to the drive unit side wall adjoining the transformer unit. Align the units. Then bolt the units together using the 12 hexagonal bolts with 5N·M (see figure below).

Fixing units to the floor

Floor fixings are not supplied. 16 anchor bolts as illustrated (B in figure below), or screws, nuts and washers of size M16 are recommended (diameter of holes in base frame: 18 mm).
Fixing the base to the floor

Location of tool kit and accessories

1. **COU Key**
   Key for control unit fix on the door of COU.

2. **Combination screws**
   Screws for combining converter and transformer are fixed on the door of control unit.

3. **Tool Kit**
   You can find the tool kit by open the door of control unit. It is on the bottom of the cabinet.

Open the box, you can find all the tools and accessories for future use. A description of all the items in the kit is delivered alongside. Please pay attention to the screw
driver which is used for open the transformer cabinet is in this box, it should be kept by authorized person, actions without authorization are dangerous.

4. **Absorbing material in cabinet - Desiccant**

   Place Desiccant in the cabinet, one bag for per door, position them on the bottom plate uniformly distributed.

   **Notice:** Take out from the cabinet in time after unpacking. To prevent other violations.
Electrical installation

Contents of this chapter
This chapter gives instructions on the installation of the power cables and wiring of control and auxiliary power.

Safety

WARNING Hazardous voltage!
Improper work could lead to life-threatening injury or death.

The electrical installation must be carried out by qualified personnel according to the site and equipment requirements, and the relevant electrical codes.

When the electrical installation is completed, the main and auxiliary power supply to the drive must not be switched on without the consent of the ABB commissioning personnel.

Take appropriate measures to prevent main and auxiliary power supply from being switched on during installation.

Overview of installation work
The electrical installation includes the following wire and cable connections:

• Cables between integrated transformer and drive
• Power cables, ground cables
• Auxiliary power, control and serial communication cables
• Power supply and signal cables for fans in transformer unit
Cable requirements

For information on the requirements for power cables and the ground cable see the ACS580MV Engineering Guideline.

For information on the requirements for the auxiliary power cable and the control cables, see Auxiliary power and control cables guideline.

Parallel routing of power cables

Cables between drive and motor can be laid in parallel. The number of cables laid in parallel is limited by the number of entry holes of the entry plate.

For information on the supply voltages, see Rating label of the drive.

Terminal sizes for auxiliary and control connections

<table>
<thead>
<tr>
<th>Terminal</th>
<th>Wire cross-section (mm²)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Solid wire</td>
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</table>

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<td>Solid wire</td>
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</tbody>
</table>
Ground cable and cable shield connections

The cabinet is equipped with ground buses (marked PE, Protective Earth) for grounding the armor and shields of the cables, and for the connection of the ground cable.

To identify the ground buses, see ACS580MV Wiring Diagram.

- **Grounding of the drive system**

Grounding of the drive system must be in line with the ACS580MV Engineering Guideline.

<table>
<thead>
<tr>
<th>Terminal</th>
<th>Wire cross section (mm²)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Solid wire</td>
</tr>
<tr>
<td>-S4: 1,3,5</td>
<td>1.5...35 mm²</td>
</tr>
<tr>
<td>-F11: 1,3,5</td>
<td>1.5...25 mm²</td>
</tr>
<tr>
<td>-F31: 1</td>
<td>1.5...25 mm²</td>
</tr>
<tr>
<td>-F4: 1</td>
<td>1.5...25 mm²</td>
</tr>
</tbody>
</table>

<table>
<thead>
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<tbody>
<tr>
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<tr>
<td>Digital inputs</td>
<td>0.5...2.5 mm²</td>
</tr>
<tr>
<td>Digital outputs</td>
<td>0.5...2.5 mm²</td>
</tr>
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<td>Analog inputs</td>
<td>0.5...2.5 mm²</td>
</tr>
<tr>
<td>Analog outputs</td>
<td>0.5...2.5 mm²</td>
</tr>
</tbody>
</table>
Grounding drive system and integrated transformer

1. Input transformer (TRU)
2. Drive
3. Motor
4. Earth electrode
5. Ground cable
6. Cable screen
7. Cable shield
8. Equipotential bonding conductor
Cables and PE busbar between integrated transformer and drive

Cables and PE busbar between drive and integrated transformer includes the following connections:

- Transformer primary and secondary cables
- Temperature sensor cables
- Three-phase power supply cable to each of the transformer fan units
- PE Busbar to connect INU and TRU.
  or
  Auxiliary supply from internal main transformer (option)
- Heating cable (option)

The cables are identified by their specific number and are labeled with the designation of the terminal where they are connected to.

The terminals for the primary and the secondary cables are located on the side wall of the drive cabinet. The transformer terminals are accessible through the left side door of the transformer unit. The cables must be mounted to the transformer terminals as shown in the figure below.
The supply cables for the fan units of the transformer and the control cables are routed through the cable lead-through in the side wall.

**Transformer terminal connections**

The required tightening torque for the internal transformer terminal connections is 15 Nm. Use a torque wrench.

The PE busbar is connected with INU and TRU PE busbars through the side wall.

**PE busbar connection**
For further information on locating the temperature sensor cables, auxiliary power supply cables and the optional heating cable, see ACS580MV Wiring Diagram.

**Cable entries for external connections**

Power cable terminals are located in the terminal compartment behind the control compartment. They can be accessed after removing the metal cover (tripping loop terminals -XS1 on the cover must be opened first).

The drive is prepared for top or bottom cable entry with one or a combination of the following cable entries:

- Metal plate hole cable entry for power cables, ground cables
- Cable entry with EMC plates, EMC cushions and sealing grommets for auxiliary and control cables

For detailed information e.g. location and dimensions, see ACS580MV Base frame & TEU layout design.

- **Power cable entry via holes in cable entry plate**

Power cable entry can be from bottom or top.

![Diagram of cable entry plate with labels](image)

1. Power cable entry plate (in TEU)
2. Auxiliary and control cable entry (in COU)
3. Sealing compound

*Galvanized plate for cable entry.*

*Plate mounted on top. See Sealing holes in entry plates for more information.*

- **Control and auxiliary cable entry with EMC plates**

Cable entry can be from bottom or top.
Galvanized plate (1 in figure below) with EMC cushions (2, 3, 4) and sealing grommets (5). See *ACS580MV Base frame & TEU layout design* for details and for the possible mounting variants.

**Material for cable entry with EMC plate (bottom mounted)**

The EMC cushions (1 in figure below) are mounted on the underside of the EMC plate when entering cables from top. They are mounted on top of the EMC plate when entering cables from underneath.

*EMC cushion. See *Preparing the cables* for more information.*
Installing power and ground cables

Further information

See *ACS580MV Base frame & TEU layout design* for information on:

- Project-specific cable entry
- Distance between the point of cable entry and the termination bars
- Busbar and fastening hole dimensions
- Busbar designations

See *ACS580MV Wiring Diagram* for information on:

- Conventions for cross-references and device identification

Preparing the cable entry and the cables

**NOTICE**

Risk of damage or malfunction!

Waste inside the cabinet can cause damage or malfunction.
If possible, do not cut cables inside the terminal compartment. Retrieve any waste which accidentally dropped into the cabinet.

Determining the cable length

1. Determine the required length of a cable between the point of entry and the connection point inside the cabinet.
2. Cut the cable to the required length before connection.

Preparing cables for entry plates

- Prepare the cable termination as illustrated in the figure below.
Power cable termination

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Outer cable sheath</td>
</tr>
<tr>
<td>2</td>
<td>Entry plate</td>
</tr>
<tr>
<td>3</td>
<td>Conductor screen extension to be connected to PE</td>
</tr>
<tr>
<td></td>
<td>ground busbar</td>
</tr>
<tr>
<td>4</td>
<td>Heat-shrinkable termination</td>
</tr>
<tr>
<td>5</td>
<td>Sealing compound</td>
</tr>
</tbody>
</table>
Connecting the cables

**NOTICE** Risk of flashover

High voltages will be present in the terminal compartment. High voltages can cause flashover between the electric potential of different conductors, and the electric potential of a conductor and earth.

Therefore, a minimum clearance of **59.5 mm** must be maintained between a conductor and earth, and **90 mm** between a conductor and the terminals of any other conductor.
Terminal compartment with cover plate removed, view from front

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Voltage dividers</td>
</tr>
<tr>
<td>2</td>
<td>Motor side terminals</td>
</tr>
<tr>
<td>3</td>
<td>Input terminals</td>
</tr>
<tr>
<td>4</td>
<td>Cable entry plate (bottom plate)</td>
</tr>
</tbody>
</table>
Power cable entry from top ((1) screen extensions to ground)
Checking the cable insulation

- Check the insulation of each cable before connection and verify that the results are within the specification of the cable manufacturer.
- Leave the cables unconnected at both ends until the commissioning personnel has given permission to connect them.

Connections

Connect the cables to their corresponding busbars:

- Feeder cables to busbars U1, V1, W1
- Motor cables to busbars U2, V2, W2
- Screen ends of all conductors and the shields of all cables to the PE ground busbar
- Ground cable to the PE ground busbar

Bolted connections

Material requirements

- Use stainless steel bolts and nuts with the appropriate steel grade and property class for the connection (recommended: A2-70 [designation according to ISO 3506]).
Nuts with bonded coating can be used as an alternative to uncoated stainless steel nuts.

Connection type

The following connection type is recommended when connecting a cable lug (4) to a busbar:

- Spring washer (1) and flat washer (2) on each side of the busbar (3).

Other washers can be used, provided they maintain the required contact pressure.

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Spring washer (2 pcs. per terminal)</td>
</tr>
<tr>
<td>2</td>
<td>Flat washers (2 pcs. per terminal)</td>
</tr>
<tr>
<td>3</td>
<td>Busbar</td>
</tr>
<tr>
<td>4</td>
<td>Cable lug</td>
</tr>
<tr>
<td>5</td>
<td>M12 bolt</td>
</tr>
<tr>
<td>6</td>
<td>M12 nut</td>
</tr>
</tbody>
</table>

- Use cable lugs suitable for M12 bolts. The required tightening torque is 40 Nm.

Lubrication

- If stainless steel bolts and nuts are used, lubricate the thread and head contact surface of the bolt using recommended pastes, e.g. Molykote D paste.

  **Note:** If a coated nut (e.g. with bonded molybdenum-disulfide \([\text{MoS}_2]\) coating) is used, the connection does not have to be lubricated.

Tightening torque

- Tighten bolted connections with bolts of sizes M10 and greater with the recommended nominal torque for the bolt size used.

### Installing auxiliary, control and serial communication cables

#### Further information

See *ACS580MV Base frame & TEU layout design* for information on:

- Project-specific cable entry
• Dimensions between point of cable entry and terminals

See ACS580MV Wiring Diagram for information on:
• Conventions for cross-references and device identification
• Terminal designations

Preparing the cable entry and the cables

Determining the cable length

1. Determine the required length of a cable between the point of entry and the connection point inside the cabinet.
2. Cut the cable to the required length before connection.

Routing the cables

• Route the cables as illustrated through the provided cable duct to the customer terminals or fieldbus modules in the control compartment.
Preparing the cables

1. Remove the grommets.
2. To ensure proper sealing, cut along the marking that corresponds to the cable diameter. Slide the grommet onto the cable. The grommet must fit tightly to prevent water from entering the cabinet.

3. If necessary, remove the entry plate and pull the cables through the entry holes.
4. Loosen the screws of the EMC cushion brackets and push the cushions apart (arrow).

5. Remove the cable insulation at the point of entry (1).
   If the outer cable screen is non-conductive, cut open the cable screen in the middle of the stripped area (1). To turn the conductive side inside out, pull the cable screen ends over the cable insulation (2). Connect the screens ends with a continuous conducting foil (3).
6. Pull the cables through the EMC cushions.
7. Push the cushions together so they fit tightly around the bare screen and tighten the screws.

Connecting the cables
- Connect the cables for digital and analog input and output signals to the corresponding terminals / modules.
- If a twisted pair cable is used, leave the unshielded cable ends twisted until they reach the terminals.
- Leave unshielded conductor ends as short as possible (not longer than 50 mm).
- Connect the shield of serial communications cables to the PE busbar located near the fieldbus adapter.
Control and power supply cables for fan units

1. Route the control and power supply cables through one of the cable entries located in the floor of the fan unit. Choose either the front or the rear cable entry, according to the position of the fan cable connector.

2. Connect each cable to the appropriate connector.

NOTICE
The control and power supply cables are already prepared in the factory for connection.

Sealing holes in entry plates

- Seal the gap between cable and entry plate with the supplied two component sealant. For mixing and applying the sealing compound, follow the instructions on the packaging.
Final checks

- Check that the entry plates are properly fastened and cable entries are correctly sealed.
Installation checklist

Contents of this chapter
This chapter contains an installation checklist which you must complete before commissioning can take place.

Safety

DANGER
High voltage!

Obey the instructions in chapter Safety instructions. If you ignore them, injury or death, or damage to the equipment can occur.

Before starting to work on the drive, make sure:

- that the main and auxiliary power supply to the drive is switched off, locked out, and tagged out
- that the drive is dead
- that safety ground connections are in place
- that personal protective equipment is provided and used when required
- that everyone involved is informed.

Before energizing the drive, make sure:

- that all foreign objects are removed from the drive
- that all internal and external covers are securely fastened and all doors are closed, locked and / or bolted
- that the release dials of safety switches are in the locked position.
WARNING! Obey the instructions in chapter Safety instructions. If you ignore them, injury or death, or damage to the equipment can occur.

NOTICE! The field engineer should confirm that the power cables are connected to the correct bus bars before switching on the main power. Once the main power direct reach the output bus bars by wrong connections, the power modules would be irreversible damaged.

Checklist
Do the steps in section Precautions before electrical work on page 17 before you start the work. Go through the checklist together with another person.

**Mechanical installation**

1. The infrastructure of the electric room is finished and the installation site is sufficiently ventilated or cooled and dehumidification to ensure the converter can running at the appropriate temperature and humidity.

2. The wall behind the unit is of non-flammable material. Please take the photo and send back.

3. There is enough free space above the drive to enable cooling air flow, service and maintenance. See layout drawing. Please take the photo and send back.

4. Ambient operating conditions meet the specifications given in chapter Technical data

5. Drive installed according to the instructions in this manual (Chapters Mechanical installation and Electrical installation)

6. Drive securely fastened to the floor

7. INU cabinet and transformer cabinet have finished combination.

8. The floor that the unit is installed on is of non-flammable material, as smooth as possible, and strong enough to support the weight of the unit. Check the floor flatness with a spirit level. The maximum allowed deviation from the surface level is 5 mm in every 3 meters. Level the installation site, if necessary, as the cabinet is not equipped with adjustable feet.

9. Fan units installed
10. Visual inspection:
   no badly affixed or damaged components
   no foreign objects inside cabinet
   no dirt, dust and humidity inside cabinet

**Electrical installation**

1. Types and cross-sections of control cables suitable for the signal type and signal level

2. Types and cross-sections of power cables selected according to the ACS580MV Engineering Guideline

3. Pulse encoder cable screens connected to **screen grounding point** and not connected directly to the pulse encoder interface (only applicable for drives with pulse encoder interface)

4. Internal cabling to integrated transformer (power, auxiliary, control and heater cables) made according to the instructions in this manual (Chapter Electrical installation)

5. Cable entry made according to the instructions in this manual (Chapter Electrical installation)

6. All control cable screens and conductors are connected according to the instructions in this manual (Chapter Electrical installation), appropriately labeled, and the customer-side connections are completed

7. Heating cable (if supplied) installed according to the instructions in this manual (Chapter Electrical installation)

8. Ground cable of drive securely connected at both ends

9. Input and motor cables not connected at both ends (cables must be meggered before connection, drive optional - recommended in case of long storage time, humid environment or visible transportation damages)

**Door interlocking**

1. Door locks tested and in operation

2. The manual release of the door safety switch(es) is in the **locked** position.

**Main circuit breaker (MCB)**

1. Type of MCB selected as per ACS580MV Engineering Guideline
Installation checklist

2. High voltage connections completed

3. MCB ready to be tested with drive

4. MCB interposing relay settings tested

5. Local close order is disabled, and the connection to switch or button is canceled.

6. The wiring of the control & signal cables connecting with the converter is finished.

7. Safety devices checked and in operation

8. The user manual and technical specification is available.

9. Withstand voltage test of the MCB have been done according to Manufacture’s specifications. The official test report must be available.

Motor

1. Motor installed, aligned and alignment protocol available

2. Motor decoupled from driven load

3. Ground connection completed

4. Customer side motor protection set and ready (e.g. winding temperature, vibration)

5. Motor auxiliaries (e.g. bearing lubrication, heater cooling) ready

6. The user manual and technical specification is available.

Power cables

1. All cable screens are connected. Please take the photo and send back.
2. Grounding cables of transformer, converter and motor are connected and tighten.  

3. Types and cross sections of power cables are selected according to the “ABB power cable specification”. Type of cable _____.

4. Transformer and motor cables are not fastened at both ends (cables and converter must be meggered before connection).

**Insulation tests**

1. All power cables to drive, and from drive to motor are meggered, and measured values are within the required limits.

2. Test report of the megger test available  

**Note:** If the test is carried out by the commissioning engineer of the drive, an additional day per drive motor combination needs to be reserved. After the test, the feeder cables can be connected, except at the drive end. The test must comply with the specification.

3. Optional insulation tests of the drive are completed and documented. Insulation tests of the drive recommended in case: long storage time (>4 months), humid environment or visible damages due to transportation/installation.

**Power supply**

1. Medium voltage available for start-up of drive

2. Low voltage auxiliary power available for start-up of drive

**Miscellaneous**

1. Sufficient number and correct type of spare parts available

2. Cooling of drive room ready for load run of drive

3. Optional equipment ready

4. Drive room properly dust filtered (dust filters at air inlet), see ACS580MV Engineering Guideline
Operation

Contents of this chapter

This chapter contains the start-up procedure of the drive. The default device designations (if any) are given in brackets after the name, for example “main switch-disconnector (Q1)”. The same device designations are also used in the ACS580MV Wiring Diagram, typically.

Operating conditions

The operating conditions for the drive are according to IEC 60721-3-3 'Stationary use at weather-protected locations' (unless indicated otherwise). For details see Technical data.

Safety

The drive must only be operated by qualified and authorized personnel, i.e. personnel who are familiar with the operation of the drive and the hazards involved.

Overview

The chapter outlines the local operation of the drive. For additional details on using the local control panel see User’s Manual “ACS-AP-X assistant control panels user’s manual”.

Control of the drive via a PLC or a higher-level control system is not described in this chapter. If the drive is controlled from remote, see the appropriate manuals for information.

The panel messages and parameter settings used in this chapter are typical examples to illustrate the related instructions and display functions and may therefore differ from the actual messages and parameter settings in the drive.
Overview on drive status and sequences

The following section lists the main operating states of the drive and the related indications on the local control panel when the drive is put into operation (see Start sequence of the drive), when it is stopped (see Stop sequence of the drive), or when a fault condition has occurred.

For information on other status messages, such as fault status messages in particular, see the ACS580MV primary control program firmware manual.

Status indications

The drive status is indicated with a status icon on the control panel.

<table>
<thead>
<tr>
<th>Status icon</th>
<th>Animation</th>
<th>Drive status</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>-</td>
<td>Stopped</td>
</tr>
<tr>
<td></td>
<td>-</td>
<td>Stopped, start inhibited</td>
</tr>
<tr>
<td>Blinking</td>
<td>Stopped, start command given but start inhibited</td>
<td></td>
</tr>
<tr>
<td>Blinking</td>
<td>Faulted</td>
<td></td>
</tr>
<tr>
<td>Flashing</td>
<td>Running, at reference, but the reference value is 0</td>
<td></td>
</tr>
<tr>
<td>Rotating</td>
<td>Running, not at reference</td>
<td></td>
</tr>
<tr>
<td>Rotating</td>
<td>Running, at reference</td>
<td></td>
</tr>
</tbody>
</table>
Operation

Start sequence of the drive

- **Drive not ready**
- **Drive OFF**

**Conditions for start:**
- Auxiliary supply on
- TEU protective plate mounted
- TRU / INU door closed and locked
- Drive not grounded
- No emergency off active
- No fault active

**SUPPLY ON command**

- MCB closes
- DC link charges
- Fans switch on

**Drive stopped**

- **Enter setpoint**
- **Start command**

**INU starts modulation**

**Drive running**

**Operation**
Operation

Stop sequence of the drive

- Drive running
- Stop command
- Speed ramps down
  INU stops modulation
- Drive stopped
- SUPPLY OFF command
  MCB opens
  DC link discharges (15 Min)
  Fan switches off after a delay
- Drive OFF
  Actions:
  TRU / INU door released for opening
  Switch off auxiliary supply
- Drive not ready

- Drive not ready
Emergency stop sequence

Energizing and starting the drive

It is recommended to have the following documents at hand when starting the drive locally for the first time after commissioning:

- *ACS580MV Wiring Diagram* to identify the circuit breakers
- User’s Manual “**ACS-AP-X assistant control panels user’s manual**”

Checks before starting the drive

---

DANGER

Hazardous voltages!

All covers must be screwed in place to prevent unintentional contact with energized components.

The manual release of the door safety switches must be in the locked position. The locked position prevents doors of medium voltage compartments being opened unintentionally during operation.
When the drive is put into service after it has been commissioned, or after it has been taken out of service for maintenance or troubleshooting, check the drive according to the following list:

- Check that no tools and foreign objects are left inside the cabinets.
- Check that all auxiliary power supplies from external sources are switched on.
- Check that all internal circuit breakers of the drive are closed.
- Check that all grounding devices are removed.
- Check that all covers are mounted and the doors are closed, locked and / or bolted.
- Check that the MCB is in **operating** position.
- Check that there is no run interlock active.

### Starting the drive from remote

When the drive is operated from remote through a higher-level control system or an operator control desk, follow the instructions in the appropriate manuals.

### Starting the drive locally

5. Press the **SUPPLY ON** pushbutton to connect the drive to the main power supply. The following takes place:

   - The MCB closes.
   - The DC link charges.

While the DC link charges, the **SUPPLY ON** pushbutton flashes. As soon as the DC link is charged, the **SUPPLY ON** pushbutton changes to a permanent light.
1. Enable the local control mode of the control panel by pressing the **Loc/Rem** key (1). The drive is in state **Stopped** and the display shows .

2. Enter the setpoint. See “**ACS-AP-X assistant control panels user’s manual**”.

3. Press the **Start** key (2) to start the motor.

   After the motor has been magnetized, the motor speed ramps up to the setpoint.

   While the motor is accelerating, the run status indication on the display blinks. When the motor speed has reached the setpoint, the run status indication lights up permanently.

### Stopping the drive

This section describes how to stop the drive using the local operator panel of the drive. If the drive is remotely-controlled, follow the established shutdown procedures.

For details on using the local control panel see “**ACS-AP-X assistant control panels user’s manual**”.

---

---
1. Enable the local control mode of the control panel by pressing the **Loc/Rem** key (1).

2. Press the **Stop** key (2).

   The motor stops according to the preset stop function and the drive stops modulating. When the motor has reached zero speed, the drive is in state **Stopped** and the display shows ![stopped icon].

---

**DANGER**

**Hazardous voltages!**

The ACS580MV is not de-energized in the state **Stopped**. Before doors are opened / removed or work is begun on the drive, the system must first be de-energized (see Chapter *Maintenance, Shutting down the drive for maintenance*).
Fault tracing

Contents of this chapter
This chapter describes the fault tracing possibilities of the drive.

Alarm and fault indications
When a failure occurs in the drive or in the equipment monitored by the drive, the control panel displays a corresponding alarm or fault message and the red Fault / Alarm button on the control compartment door lights up:

- Alarm: flashing light
- Fault: permanent light
Warning and fault messages

In case of an alarm or fault refer to the ACS580MV primary control program firmware manual for the descriptions, causes and remedies of the drive control program warning and fault messages.

- Diagnosis data and parameter backup

See User’s manual “Start-up and maintenance PC tool Drive composer”
Maintenance

Contents of this chapter
This chapter contains instructions for preventive maintenance and component replacements and the Maintenance schedule with recommended maintenance intervals.

Safety

DANGER
High voltage!
Obey the instructions in chapter Safety instructions. If you ignore them, injury or death, or damage to the equipment can occur.

Before starting to work on the drive, make sure:

• that the main and auxiliary power supply to the drive is switched off, locked out, and tagged out
• that the drive is dead
• that safety ground connections are in place
• that personal protective equipment is provided and used when required
• that everyone involved is informed.

Before energizing the drive, make sure:

• that all foreign objects are removed from the drive
• that all internal and external covers are securely fastened and all doors are closed, locked and / or bolted
• that the release dials of safety switches are in the locked position.
Preparation for maintenance work

**Documentation and reporting of maintenance work**

It is recommended to record all troubleshooting and maintenance work in a logbook including:
- Date and time
- Detailed description

**Required tools and equipment**

Standard set of tools. If special tools are needed for a maintenance task, a specific list is provided.

Use only instrumentation (e.g. meters, oscilloscopes, etc.) intended for high voltage measurements (that is, isolation is provided inside the instrument, not provided by isolating the chassis ground of the instrument). Never defeat the instrument's grounding.

**Storage and handling of spare parts**

To ensure safe and reliable operation, it is important to use only spare parts recommended and approved by ABB.

For information on types and identification codes, see the spare part kits or contact ABB service organization.

**Shutting down the drive for maintenance**

See Chapter *Operation, Stopping the drive* for instructions on de-energizing the drive using the local operator panel of the drive. If the drive is remotely-controlled, follow the established shutdown procedures.

**NOTICE**

Foreign matter and particularly metallic dust can cause failure and damage when the drive is energized.

Ensure that foreign matter cannot enter the cabinet:
- Close the doors and cover openings completely when the work is discontinued.
- Retrieve any foreign matter accidentally dropped into the cabinet.

**NOTICE**

All maintenance tasks that are listed in the maintenance schedule, but are not described in detail in this manual, may only be carried out by ABB.

Call ABB service if such a task is due.
For details on using the local control panel, see User’s Manual “ACS-AP-X assistant control panels user’s manual”.

**DANGER**

Hazardous voltages!

For work in the medium voltage circuit of the drive the connection of grounding equipment at the appropriate locations is a must. The grounding equipment ensures that hazardous voltages cannot be fed into the drive neither from the main power supply nor the motor.

### De-energizing the drive

1. Stop the drive following the instructions in Chapter *Operation, Stopping the drive*.
2. Set the local control panel to local control mode by pressing the Loc/Rem key (1)

3. Press the **SUPPLY OFF** pushbutton to disconnect the drive from the main power supply. The following takes place:
   - The MCB opens.
   - The DC link discharges.

   While the DC link discharges, the **SUPPLY OFF** pushbutton flashes.

   - Wait 15 minutes until the DC link capacitors have discharged completely (the delay time is triggered when the main power feeder is disconnected).
After the DC link capacitors have discharged completely, the cabinet doors of the power compartments unlock, the **SUPPLY OFF** pushbutton changes to a permanent light and the status line displays.

4. Rack-out, lock-out, ground and tag-out the main power feeder.
5. Switch off and lock-out all auxiliary voltages from external sources.
6. Verify that the drive system is de-energized.
7. To connect a grounding set, continue with **Connecting a grounding set** on page 104.
8. To open the door of the medium voltage compartment, continue with **Unlocking and locking the doors** on page 104.

**Tip:** To open the power compartment doors, auxiliary voltage is required.

9. Before start working in the power compartment, the power modules must be individually grounded by touching them with the grounding stick. See **Grounding power module with grounding hook** on page 107.

### Unlocking and locking the doors

The door is secured by a safety switch and the control compartment door has pivoted door handles and locks with triangular inserts. Open the door with the supplied key.

1. To release the door handle, insert and turn the key to the right. The door handle will pop out.
2. To open the door, turn the door handle
   - to the right, if the door is hinged on the right,
   - to the left, if the door is hinged on the left.
3. To lock the door, bring the door handle in line with the door plate and press the handle down until it clicks in.

### Connecting a grounding set

Before starting to work on the drive, you must ground the three input and three output terminals in the terminal unit (TEU). Always ground the drive on both sides, i.e. on supply and motor side. Grounding on motor side is needed to avoid induced voltage from a spinning rotor.
For this purpose, two grounding harnesses are needed. They can be ordered separately as an optional grounding harness set (consisting of two grounding harnesses plus a telescopic insulating pole) for the 3-phase power input.

**Notice:** To adapt grounding harness ordered from ABB, ball type grounding studs are provided as option.

**Example for grounding harness**

1. Open the COU door.
2. Connect the enclosure grounding clamp (item 2 in the figure above) to the cabinet’s PE busbar.
3. Remove the protective plate between COU and TEU.
4. Use the telescopic insulating pole to connect the busbar grounding clamps to the busbars in the Terminal Unit, and to tighten each connection.
Grounding power module with grounding hook

Since the power modules are on a floating potential, one must check at the module terminals for residual voltages before starting work at the modules.

Required tools

- Voltmeter or multimeter with impedance of >=10 Mohm (not part of supply)
- Voltage divider probe (not part of supply)
- Grounding hook (part of supply)

The grounding hook is attached to the left side wall inside the COU cabinet. The other end of the PE cable is fixed to the PE busbar (see the figure below). The length of the PE cable is 4.5 m or 6 m, depending on the drive type.

Grounding hook in stowed position
Procedure:

1. Open the INU door.
2. Connect the voltage divider probe to the volt-/multimeter and select the appropriate metering range (see the instruction manuals of the devices).
3. Connect the grounding clip of the voltage divider probe to the cabinet (PE busbar, see the instruction manual of the probe).
4. Touch the power terminals in front of each power module with the contact electrode of the probe and check that the voltage is below 50 V.
5. Touch again the power terminals of each power module with the contact tip of the grounding hook to fully discharge the circuit.
6. Hang the grounding hook to the terminal of the power module to be serviced and leave it there until work on the module is finished.
7. Make sure again that all power module terminal voltages are below 50 V. Use a multimeter and measure the voltage between the grounded power terminal and all other power module terminals before working on the power module.

Starting the drive after maintenance

See Chapter Operation, Energizing and starting the drive for instructions on energizing the drive using the local operator panel of the drive. If the drive is remotely-controlled, follow the established start-up procedures.

Emergency release of the door safety switch

**DANGER**

Hazardous voltages!

Touching energized components can be fatal.

Before you unlock the safety switch, verify that the drive is de-energized.

Do not unlock the safety switch permanently.

The door of the INU compartment is secured by a safety switch (item 1 in figure below).
Location of door safety switch

The safety switch is tied into the door interlocking circuit of the drive and the interlocks from the main circuit breaker of the drive. The interlocking system ensures that:

- the main power can only be connected to the drive if the door is securely closed and the safety switch is in the locked position.
- the door can only be opened if the main circuit breaker is open and the DC link is discharged.

Also, the door of the INU compartment can not be opened

- if the drive is disconnected from the auxiliary power
- if the safety switch of the door is in the locked position.

If the auxiliary voltage is switched off and the door is locked but cannot be opened, check the position of the release dial of the safety switch. If the release dial is in the locked position, unlock the safety switch as described in Safety-switch settings on page 109. ABB can also provide thicker air cassette as optional for high level protection.

Safety-switch settings

There’re two kinds of safety switches as follows,

Safety-switch setting 1
Unlocking

1. To access the release dial of the safety switch, remove the cap in the top right corner of the INU compartment door.

2. Turn the release dial from the locked to the unlocked position.

3. When the door is open, turn the release dial to the locked position.

4. Insert the cap again.

Safety-switch setting 2

<table>
<thead>
<tr>
<th>1</th>
<th>Release dial</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>Unlocked position</td>
</tr>
<tr>
<td></td>
<td>The unlocked position enables opening the door of a medium voltage unit whether the auxiliary voltage is switched on or off.</td>
</tr>
<tr>
<td>3</td>
<td>Locked position</td>
</tr>
<tr>
<td></td>
<td>Locked is the normal operating setting. To open the door of a medium voltage unit, the DC link must be discharged and the auxiliary voltage must be switched on.</td>
</tr>
</tbody>
</table>
3. Turn the release dial from the locked to the unlocked position.

4. When the door is open, turn the release dial to the locked position and screw in the locking screw.

5. Insert the cap again.

**Cleaning the interior of the cabinet**

![Warning symbol]

**WARNING!** Use a vacuum cleaner with an antistatic hose and nozzle. Using a normal vacuum cleaner creates static discharges which can damage circuit boards.

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* on page 102 before you start the work.

2. When necessary, clean the interior of the cabinet with a soft brush and a vacuum cleaner.

3. Check the air inlet filters of the cabinet. Clean when necessary. For cleaning, see section *Cleaning the door air inlet meshes* below.

4. When the work is completed the drive can be started up again. See Chapter *Operation, Energizing and starting the drive*.

**Replacing the door air filters**

Inspect filter mat condition, replace if necessary. Replace filter mat regularly according to PM schedule. see *ACS580MV Preventive Maintenance Schedule*. ABB also provide air filter cassette as option for higher level protection.
1. Lift the grating and pull it away from the door.
2. Remove the air filter.
3. Place the new filter into the grating.
4. Reinstall the filter and grating in reverse order.

**Cleaning heat sinks of power modules**

The heat sink fins of the power modules pick up dust from the cooling air. The drive runs into overtemperature warnings and trips if the heat sink is not clean. When necessary, clean the heat sink as follows.

**WARNING!** Obey the instructions in chapter *Safety instructions*. If you ignore them, injury or death, or damage to the equipment can occur.

**WARNING!** Use a vacuum cleaner with antistatic hose and nozzle. Using a normal vacuum cleaner creates static discharges which can damage circuit boards.

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.
2. Ground the power modules according to *Grounding power module with grounding hook* on page 107.
3. Remove the power module from the cabinet. See *Replacing the power modules* on page 118.
4. Blow dry clean compressed air (not humid) from front to back and simultaneously use a vacuum cleaner at the air outlet to trap the dust. Note: If there is a risk of dust entering adjoining equipment, perform the cleaning in another room.
5. Reinstall the power module into the drive.
6. Repeat the above steps for all power modules.
7. When the work is completed the drive can be started up again. See Chapter *Operation, Energizing and starting the drive*. 
Replacing roof AC fans*

1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.

2. Switch off the motor starter of the fan unit to isolate the fan unit from the auxiliary power supply. To identify the motor starter, see the ACS580MV Wiring Diagram.

3. Remove the hex-head combination screws (M6x16) that attach the top cover to the fan box. Lift the top cover and pull it away from the fan box.

4. Disconnect the connector and make sure that the supply connector is detached from the support beam.

5. Remove the four hex-head combination screws (M6x16) that attach the support beam to the side plate of fan box frame.

**NOTICE**
For some types of fan boxes two additional hex-head combination screws must be removed.

6. Fix the lifting eyes to the support beam. Attach lifting gear, appropriate for the weight of the impeller, to the lifting eyes. Lift off the support beam and the impeller attached to it.
7. Remove the hex-head screws which attach the support beam to the impeller.

**NOTICE**

Type and quantity of the hex-head screws depend on the impeller model.

8. Disconnect the power cable from the connector on the support beam.

9. Mount the new impeller to the support beam.

10. Connect the wires of the fan motor cable to the terminal block according to the electrical drawings.

11. Proceed in reverse order as previously described to reinstall the impeller with the support beam.

12. Check by hand for proper fan rotation before energizing the drive.

13. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

14. Check visually the direction of fan rotation when starting the drive. The correct rotation direction please refer to arrow direction posted on fan box.

* Depends on site situation, ACS580MV fan box can be mounted backward, the screw positions are compatible between fan box and cabinet top plate. The procedure can refer to instruction above. For details of the AC fan box outline information, see [ACS580MV Air duct interface Outline Drawing of AC Fan Box](#).
Required tools and equipment

- Screwdriver for M6 and M10 screw
- Lifting eye: M8, 2 pieces

The fans can be lifted by crane or by hand.
Replacing roof EC fans*

**Procedure**

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.

2. Switch off the motor starter of the fan unit to isolate the fan unit from the auxiliary power supply. To identify the motor starter, see the *ACS580MV Wiring Diagram*.

3. Remove the hex-head combination screws that attach the top cover to the fan box. Lift the top cover and pull it away from the fan box.

4. Disconnect the control and power supply cables of the fan.

5. Remove the fastening screws from the support plate and the duct ring.

6. Using the lifting eyes in the fan housing cover and a lifting gear, lift off the support plate with the fan attached to it.
7. Unscrew the support plate from the fan.

**NOTICE**
Type and quantity of the hex-head screws depend on the impeller model.

8. Replace the fan and re-assemble in reverse order of removal.

* depends on site situation, ACS580MV fan box can be mounted backward, the screw positions are compatible between fan box and cabinet top plate. The procedure can refer to instruction above. For details of the EC fan box outline see ACS580MV Air duct interface Outline Drawing of EC Fan Box.
Replacing the power modules

WARNING! Obey the instructions in chapter Safety instructions. If you ignore them, injury or death, or damage to the equipment can occur.

- Required manpower and tools
  Two persons are required for replacing a power module.
  The following tools are needed:
  - Screwdrivers: M6, M8, M10, M12
  - Torque wrench with extension bar

- Replacement of a power module frame size R1 - R3
  The replacement procedure is basically the same for power modules of R1-R3. The main difference is the weight of the module types. Replacement power modules must always be of the same type.
Dismounting

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Ground the power modules according to *Grounding power module with grounding hook* on page 107.

4. Disconnect the fiber optic links from the power module.

5. Loosen and detach the three power cables and the two busbars behind the cables.

6. Loosen and detach the one fixation screws in the front of power module.

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<table>
<thead>
<tr>
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<tbody>
<tr>
<td>1</td>
<td>Busbar connections</td>
</tr>
<tr>
<td>2</td>
<td>Power cable terminals</td>
</tr>
<tr>
<td>3</td>
<td>Fixation screws</td>
</tr>
<tr>
<td>4</td>
<td>Terminals for fiber optic cables</td>
</tr>
</tbody>
</table>
7. Slide out the power module by hand

Mounting
1. Install the new module in reverse order of removal.
2. Switch on all miniature circuit breakers in the control compartment.
3. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

Converter module testing and repair
Testing and repair of a defective power module is done at ABB works. Send the module in for repair.

Replacing the power module fuse R1 - R3
1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Ground the power modules according to Grounding power module with grounding hook on page 107.
4. Loosen the 2 mounting screws of the fuse to be replaced.
5. Pull out the fuse.
6. Install the replacement fuse in reverse order of removal.
7. Reinstall the power module in reverse order of removal.
8. Switch on all miniature circuit breakers in the control compartment.
9. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.
Replacing power module fuse on a module of frame size R1 - R3

■ Replacement of a power module frame size R4 - R6

The replacement procedure is basically the same for power modules of frame size R1-R3. The main difference is the weight of the module types. Replacement power modules must always be of the same type.

Dismounting

1. Stop, de-energize and ground the drive following the steps in section Shuting down the drive for maintenance before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Ground the power modules according to Grounding power module with grounding hook on page 107.
4. Disconnect the fiber optic links from the power module.
5. Loosen and detach the three power cables and the two busbars behind the cables.
6. Loosen and detach the two fixation screws in the front of power module.

7. Slide out the power module by hand

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<tr>
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<tbody>
<tr>
<td>1</td>
<td>Busbar connections</td>
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<tr>
<td>2</td>
<td>Power cable terminals</td>
</tr>
<tr>
<td>3</td>
<td>Fixation screws</td>
</tr>
<tr>
<td>4</td>
<td>Terminals for fiber optic cables</td>
</tr>
</tbody>
</table>

- Weight of power module: max. 21 kg.

Obey local regulations when lifting the power modules.
Mounting
1. Install the new module in reverse order of removal.
2. Switch on all miniature circuit breakers in the control compartment.
3. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

Converter module testing and repair
Testing and repair of a defective power module is done at ABB works. Send the module in for repair.

Replacing the power module fuse R4 - R6
1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Ground the power modules according to Grounding power module with grounding hook on page 107.
4. Loosen the 2 mounting screws of the fuse to be replaced.
5. Pull out the fuse.
6. Install the replacement fuse in reverse order of removal.
7. Reinstall the power module in reverse order of removal.
8. Switch on all miniature circuit breakers in the control compartment.
9. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

Replacing power module fuse on a module of frame size R4 - R6
Replacement of a power module frame size R7 - R9

The replacement procedure is basically as for power module of frame size R4-R6. The main difference is the weight of the module types. Replacement power modules must always be of the same type.

Tools and accessories

<p>| | |</p>
<table>
<thead>
<tr>
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<tbody>
<tr>
<td>1</td>
<td>Hoisting gear</td>
</tr>
<tr>
<td>2</td>
<td>Hoist</td>
</tr>
<tr>
<td>3</td>
<td>Lifting belt</td>
</tr>
</tbody>
</table>

Dismounting

1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Ground the power modules according to Grounding power module with grounding hook on page 107.
4. Attach the hoist to the front base beam of the cabinet.
5. Disconnect the fiber optic links from the power module.
6. Loosen and detach the three power cables and the two busbars in front of the power module.

7. Loosen and detach the three fixation screws (M6X16) that attach the power module to the front lock.

8. Slide out the power module by hand until stopped by the front lock.

9. Lift the blocking bar of the front lock and pull out the power module until the front lock
stops it again.

10. Connect the second lifting belts to the lifting eyes provided on the power module.
11. Lift again the blocking bar of the front lock, pull the power module completely out of the support module beam and lower it.
**WARNING!** Weight of power module: max. 65 kg. Obey local regulations when lifting the power modules.

**Mounting**

1. Loosen and detach the two combination screws (M6X16) from the front lifting bar that attach the power module to be replaced.
2. fix the adapt plate to the new power module with two combination screws (M6X16), but don’t fix tightly.

3. Install the new module in reverse order of removal.

4. Adjust the metal plate to alien the middle three holes with lock holes, fix the connection with five combination screws (M6X16).

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<table>
<thead>
<tr>
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<tbody>
<tr>
<td>1</td>
<td>Adapt plate</td>
</tr>
<tr>
<td>2</td>
<td>screw M6X16</td>
</tr>
</tbody>
</table>
5. Switch on all miniature circuit breakers in the control compartment.
6. When the work is completed the drive can be started up again. See Chapter
   *Operation, Energizing and starting the drive*

**Replacing the power module fuse R7 - R9**

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Ground the power modules according to *Grounding power module with grounding hook* on page 107.
4. Loosen the 2 mounting screws of the fuse to be replaced.
5. Pull out the fuse.
6. Install the replacement fuse in reverse order of removal.
7. Reinstall the power module in reverse order of removal.
8. Switch on all miniature circuit breakers in the control compartment.
9. When the work is completed the drive can be started up again. See Chapter *Operation, Energizing and starting the drive*.

*Replacing power module fuse on a module of frame size R7 – R9*

**Capacitors**

The power module intermediate circuits contain electrolytic capacitors. Their lifespan depends on the operating time of the drive, loading and ambient temperature. You can prolong capacitor life by lowering the ambient temperature.
In order to ensure reliable drive operation, replace the power modules according to the maintenance interval table.

- **Reforming capacitors of the power modules**
  Power modules that are used as spare parts must be installed and operated in a drive every 2 years in order to reform the capacitors and thus reduce the risk of a potential hazard.

**Testing main power supply circuit**

The main power supply circuit must be tested regularly according to the preventive maintenance interval table. The tests consist of the actuation and checking of proper reaction of

- Emergency stop
- MCB door button (Main power supply OFF and ON)
- Panel stop
- customer specific devices

**Replacing the control panel battery**

The battery is housed on the rear of the control panel. Replace with a new battery. Dispose the old battery according to local disposal rules or applicable laws.

For details refer to the *ACS-AP-X assistant control panels user’s manual*.

**Circuit board replacements**

**NOTICE**

Electrostatic discharge (ESD) can damage electronic boards and components.

Do not touch printed circuit boards or other sensitive components without applying static-sensitive handling precautions!

Do not touch the components without wearing ESD protection device.

Put the board or component on a grounded working surface protected against electrostatic discharges.

Hold a board only at the edge.

Handle a faulty board as carefully as a new one.

**NOTICE**

Any electrical board replacement must be done after power is off. Only qualified electricians are allowed to carry out electrical parts replacement.

- **Control unit (BCU) and memory unit (ZMU)**
  To locate the BCU see figure *Control compartment with open swing frame* on page 33.
Procedure:

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.
2. Switch off all miniature circuit breakers in the control compartment.
3. Unplug all connectors on the BCU.
4. Loosen the end brackets of BCU.

5. Keep the top of the BCU (looking to the back in cabinet) in place and twist the bottom (looking towards you) to pull it out of the mounting rail.

When a BCU is replaced, the parameter settings can be retained by transferring the memory unit (ZMU) from the defective BCU to the new BCU. The ZMU is located on the control unit, see B in figure *Replacement of BCU components* below.
NOTICE
In case of a defective ZMU, the drive needs to be re-parametrized. Please contact ABB service.

6. Remove the ZMU: undo the fastening screw B and pull out the memory unit.
7. Insert the new ZMU and fasten the screw.

8. Install the new BCU in reverse order of removal.

9. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive. After power-up, the BCU scans the memory unit. If a different control program or different parameter settings are detected, they are copied to the BCU. This can take several minutes.

10. Contact ABB service as soon as possible to obtain a new license before the trial mode expires.

**NOTICE**

After a BCU or memory replacement, the license might not match the new hardware. The drive can be operated with full functionality in trial mode for 30 days. If the drive is not relicensed within this period, it will stop working after the trial period is over.

**Replacing the SD memory card**

The SD card is used to record fault information for analysis. It can be removed while the drive is running.

SD/SDHC flash memory type: maximum supported size 4 GB, CLASS 4, 6, 10.

To replace the SD memory card:

1. Check that the yellow LED is off (see D in the Replacement of BCU components figure above).
   - Do not remove the SD card while the yellow LED is lit, which indicates that writing to the SD card is in progress.

2. Undo the fastening screw of the clip covering the memory card and press the card to remove it. For the card location, see C in the figure Replacement of BCU components above.

3. Insert the new card in reverse order.

**Replacing the real-time clock battery**

The real-time clock battery must be replaced if the “BATT” LED is not illuminated when the control unit is powered (see D in the Replacement of BCU components figure Replacement of BCU components above).

Real-time clock battery type: BR2032:

- Temperature range -30 ... +80 °C (-22 ... 176 °F)
- Voltage 3 V
- Nominal capacity approx. 200 mAh
- To be replaced every 5 years

Procedure:

1. Stop, de-energize and ground the drive following the steps in section Shutting down
the drive for maintenance before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Undo the fastening screw and remove the battery (see A in figure Replacement of BCU components above).

4. Insert the new battery according to the figure Replacement of BCU components.

5. Set the real-time clock.

6. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

7. Dispose the old battery according to local disposal rules and applicable laws.

### High voltage divider board

To locate the high voltage divider board see figure Control compartment with open swing frame on page 33.

Procedure:

1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Loosen the cable connection at the board to be removed.

4. Hold the divider board and remove the two fixation screws.

5. Install the replacement divider board in reverse order of removal.

6. When the work is completed, the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

### CVMI2 board

To locate the CVMI2 board, see figure Terminal compartment with cover plate removed on page 28.

Procedure:

1. Stop, de-energize and ground the drive following the steps in section Shutting down the drive for maintenance before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Unplug the fiber optic link (A1, A8), the power supply connector (X201) and the signal connectors (X203, X204, X205, X206, X207,).

4. Loosen the 4 fixation screws and remove the board.

5. Install new CVMI2 board reconnect in reverse order of removal.

6. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.

### Control hub

To locate the control hub see figure Inverter unit (drive type 11R6) on page 30.

Procedure:
1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Unplug all fiber optic links on the daughter boards and fiber optic links Y1,Y2,Y3,Y4, power supply connector (X1), signal connectors (X2) and the pressure tube.

4. Hold the control hub, loosen the 8 fixing screws on the mounting plate and remove the module.

5. Install the new control hub in reverse order.

6. When the work is completed the drive can be started up again. See Chapter *Operation, Energizing and starting the drive*.

---

**Control hub daughter board**

The control hub daughter boards are mounted in slots on the control hub board.

1. Stop, de-energize and ground the drive following the steps in section *Shutting down the drive for maintenance* before you start the work.

2. Switch off all miniature circuit breakers in the control compartment.

3. Unplug all fiber optic links on daughter boards.

4. Loosen the screws of the retainer and remove it.
5. Pick the daughter board to be replaced and withdraw.
6. Install the new daughter board in reverse order.
7. When the work is completed the drive can be started up again. See Chapter Operation, Energizing and starting the drive.
Maintenance schedule

The recommended intervals for maintenance and component replacement are based on the normal operating conditions of the drive. The drive should be checked at least every two years by qualified personnel whose recommendations should be followed. Depending on the actual condition of the drive, the maintenance work can be carried out before or after the recommended interval.

For detailed inspect and replacement time interval. See ACS580MV Preventive Maintenance Schedule
Drive seasonal operation

This chapter contains instruction for drive special preventive maintenance when drives standy more than 2 months. The objective is to avoid malfunction or damage components when the drives restart up after a long time storage, further to improve operating efficiency and extending the life of the drives. The example practice is heating application which drives only operate in winter days.

**Shutting down the drive for maintenance**

See chapter Maintenance, shutting down for maintenance for instructions. Follow the established shutdown procedure by using local operator panel of the drive.

**Maintain the drive for preservation**

During standby, it is important to make the drive protected from harsh ambient conditons of dust, temperature and humidity. Keep the temperature in E-house be relative stable in the range of 0°C to 50°C, and relative humidity be lower than 70%. Recommended maintenance solutions.

- **Preferred solution:** put silica gel bags (type of desiccant) inside the cabinets. Silica gel bags should not be in direct contact with metal parts because they can cause corrosion after saturation. The required bag quantity can be calculated based on protection capacity and cabinet dimension. Close all the doors and cover the drive with plastic film and seal it by tape as tight as possible. That will provide protection against dust, salty air or pest during storage.

  ABB offered desiccant is 3ABD00005991 (500g/bag). Refer to the minimum desiccant quantity based on door width.

<table>
<thead>
<tr>
<th>Distribution</th>
<th>Minimum desiccant quantity</th>
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<tbody>
<tr>
<td>1xDoor width 600mm</td>
<td>1x500g</td>
</tr>
<tr>
<td>2xDoor width: 800mm</td>
<td>3x500g</td>
</tr>
</tbody>
</table>

- **Alternative solution:** cover and seal cabinet inlet/outlet and fan box with plastic or waterproof clothes. That will alleviate the impact from dust, salty air or pest during storage.

**Maintain the drive before restarting up**

The maintenance actions can be done by end users to to avoid potential malfuction or damage components when drive restarting up. Following the chapter of Maintenance schedule (Years from start-up) to do the recommended maintenance and component replacement. It is mandatory to complete the checklist before restarting up can take place.

<table>
<thead>
<tr>
<th>Visual inspection and take maintenance actions if need</th>
<th></th>
</tr>
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<tbody>
<tr>
<td>1 No dust in E-house</td>
<td></td>
</tr>
<tr>
<td>2 Cleaning heatsinks with an ESD vacuum cleaner. It is prohibited to replace PEBBs or open PEBBs. If really needed, contact ABB.</td>
<td></td>
</tr>
<tr>
<td>3 Air inlet and outlet are clean</td>
<td></td>
</tr>
<tr>
<td>4 All air filter mats are clean. Otherwise, replace with new ones from ABB. It is prohibited to wash the filter mats because the tissue structure will be destroyed</td>
<td></td>
</tr>
<tr>
<td>5 No dust and corrosion in cabinet</td>
<td></td>
</tr>
<tr>
<td>6 No tools and foreign objects are left inside the cabinets. Don’t forget move out the desiccants in the cabinets.</td>
<td></td>
</tr>
<tr>
<td>7 No condensing in cabinet</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Cable and connector</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1 Fully inspect tighteness of terminals, connectors connection and visual damage of cables.</td>
<td></td>
</tr>
</tbody>
</table>
- **Start the drive following chapter of “Operation”**

**Attention:**

- It is not allowed to start the drive if there is any condensing in drives. Make sure to heat and remove the condense and moisture in drives before drives are ready to SUPPLY ON.

- Reform DC-link capacitors in Power modules and spare power modules if the stock age more than 1 year following 2UBB017371_ACS580MV capacitor reforming instruction.

ABB provide standard drive startup service package. 400-810-8885
Technical data

For the technical specifications of the drive, e.g. ratings sizes and technical requirements see the following documents:

For technical data, drive types and options refer to ACS580MV Catalog.

For mechanical layout, dimensions and required free space see ACS580MV Base frame & TEU layout design.

For motor and cable selection and for the technical requirements for the protection and control of the medium voltage supply refer to ACS580MV Engineering Guideline.

The list of available general documents is provided in List of related manuals on the inside of the front cover of this manual.
Further information

Product and service inquiries
Address any inquiries about the product to your local ABB representative, quoting the type designation and serial number of the unit in question. A listing of ABB sales, support and service contacts can be found by navigating to www.abb.com/searchchannels.

Product training
For information on ABB product training, navigate to www.abb.com/drives and select Training courses.

Document library on the Internet
You can find manuals and other product documents in PDF format on the Internet. Go to www.abb.com/drives and select Document Library. You can browse the library or enter selection criteria, for example a document code, in the search field.
Contact us

www.abb.com/drives
www.abb.com/drivespartners

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