Motor Protection Relay
REM 610

Operator's Manual - ANSI version
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1. Introduction

1.1. This manual

This manual provides basic information on the protection relay REM 610 and presents detailed instructions on how to use the human-machine interface (HMI) of the relay. In addition to the instructive part, a short chapter on commissioning and maintenance of the relay is included.

1.2. Use of symbols

This publication includes the following icons that point out safety-related conditions or other important information:

- The electrical warning icon indicates the presence of a hazard which could result in electrical shock.

- The warning icon indicates the presence of a hazard which could result in personal injury.

- The caution icon indicates important information or warning related to the concept discussed in the text. It might indicate the presence of a hazard which could result in corruption of software or damage to equipment or property.

- The information icon alerts the reader to relevant facts and conditions.

- The tip icon indicates advice on, for example, how to design your project or how to use a certain function.

Although warning hazards are related to personal injury, it should be understood that operation of damaged equipment could, under certain operational conditions, result in degraded process performance leading to personal injury or death. Therefore, comply fully with all warning and caution notices.

1.3. Intended audience

This manual is intended for operators, supervisors and administrators to support normal use of the product.
1.4. Product documentation

In addition to the relay and this manual, the delivery contains the following relay-specific documentation:

<table>
<thead>
<tr>
<th>Name</th>
<th>Document ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installation Manual</td>
<td>1MRS752265-MUM</td>
</tr>
<tr>
<td>Technical Reference Manual</td>
<td>1MRS752263-MUM</td>
</tr>
<tr>
<td>Operator's Manual</td>
<td>1MRS752264-MUM</td>
</tr>
</tbody>
</table>

1.5. Document conventions

The following conventions are used for the presentation of material:

- Push button navigation in the human-machine interface (HMI) menu structure is presented by using the push button icons, for example:
  
  To navigate between the options, use ▲ and ▼.

- HMI menu paths are presented as follows:
  
  Use the arrow buttons to select **CONFIGURATION\COMMUNICATION\SPA SETTINGS\PASSWORD SPA**.

- Parameter names, menu names, relay target messages and relay's HMI views are shown in a Courier font, for example:
  
  Use the arrow buttons to monitor other measured values in the menus **DEMAND VALUES** and **HISTORY DATA**.

- HMI messages are shown inside quotation marks when it is good to point out them for the user, for example:
  
  When you store a new password, the relay confirms the storage by flashing “——” once on the display.
# 1.6. Document revisions

<table>
<thead>
<tr>
<th>Version</th>
<th>IED Revision</th>
<th>Date</th>
<th>History</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>B</td>
<td>25.11.2003</td>
<td>Document created. Modified for ANSI compliance from the IEC version B.</td>
</tr>
<tr>
<td>B</td>
<td>C</td>
<td>31.01.2007</td>
<td>Content updated</td>
</tr>
</tbody>
</table>
2. Safety information

Dangerous voltages can occur on the connectors, even though the auxiliary voltage has been disconnected.

Non-observance can result in death, personal injury or substantial property damage.

Only a competent electrician is allowed to carry out the electrical installation.

National and local electrical safety regulations must always be followed.

The frame of the device has to be carefully grounded.

When the plug-in unit has been detached from the case, do not touch the inside of the case. The relay case internals may contain high voltage potential and touching these may cause personal injury.

The device contains components which are sensitive to electrostatic discharge. Unnecessary touching of electronic components must therefore be avoided.

Breaking the sealing tape on the upper handle of the device will result in loss of guarantee and proper operation will no longer be insured.
3. Product overview

3.1. Use of the relay

The motor protection relay REM 610 is a versatile multifunction protection relay mainly designed to protect motors in a wide range of motor applications.

The relay is based on a microprocessor environment. A self-supervision system continuously monitors the operation of the relay.

The HMI includes a liquid crystal display (LCD) which makes the local use of the relay safe and easy.

Local control of the relay via serial communication can be carried out with a computer connected to the front communication port. Remote control can be carried out via the rear connector connected to the control and monitoring system through the serial communication bus.

3.2. Features

- Three-phase motor start-up supervision based on thermal stress calculation with speed switch blocking ability
- Three-phase overcurrent protection with definite-time characteristic and speed switch blocking ability
- Three-phase short-circuit protection with instantaneous or definite-time characteristic
- Three-phase undercurrent (loss of load) protection with definite-time characteristic
- Non-directional ground-fault protection with definite-time characteristic.
- Three-phase thermal overload protection
- Three-phase unbalance protection based on the negative-phase-sequence current with inverse definite minimum time characteristic
- Phase reversal protection based on the negative-phase-sequence current
- Cumulative start-up time counter with restart disable function
- Circuit-breaker failure protection
- Temperature protection elements with definite-time characteristic
- Emergency start function
- Optional RTD module
  - with six measuring inputs
  - supports PTC thermistors and various RTD sensors
  - three additional galvanically isolated digital inputs
- Four accurate current inputs
- Time synchronization via a digital input
- Trip-circuit supervision
- User-selectable rated frequency 50/60 Hz
- Three normally open trip contacts
- Two change-over (form c) non-trip contacts
- Output contact functions freely configurable for wanted operation
- Two galvanically isolated digital inputs and three additional galvanically isolated digital inputs on the optional RTD module
- Disturbance recorder:
  - Recording time up to 80 seconds
  - Triggering by one or several internal or digital input signals
  - Records four analog channels and up to eight user-selectable digital channels
  - Adjustable sampling rate
- Non-volatile memory for:
  - Up to 100 event codes with time stamp
  - Setting values
  - Disturbance recorder data
  - Recorded data of the five last events with time stamp
  - Number of AR shots and pickups/trips for protection elements
  - Operation target messages and LEDs showing the status at the moment of power failure
- Multi-language support
- User-selectable password protection for the HMI
- Display of primary current values
- Demand values
- All settings can be modified with a PC
- Optical front communication connection: wirelessly or via cable
- Optional rear communication module with plastic fibre-optic, combined fibre-optic (plastic and glass) or RS-485 connection for system communication using the SPA-bus, IEC 60870-5-103 or Modbus (RTU and ASCII) communication protocol
- Battery back-up for real-time clock
- Battery charge supervision
- Continuous self-supervision of electronics and software
- Detachable plug-in unit
4. Operation

4.1. HMI features

4.1.1. Front panel

The front panel of the relay contains:

- Alphanumeric 2 × 16 characters’ LCD with backlight and automatic contrast control
- Threetarget LEDs (green, yellow, red) with fixed functionality
- Eight programmable target LEDs (red)
- HMI push-button section with four arrow buttons and buttons for clear/cancel and enter, used in navigating in the menu structure and in adjusting setting values
- Optically isolated serial communication port with a target LED.

![Front view of the relay](image)

**Fig. 4.1.1.-1 Front view of the relay**

1) LCD
2) HMI push-button section
3) Programmable target LEDs (red)
4) Target LEDs:
   - Left: Ready (green)
   - Center: Pickup/Alarm (yellow)
   - Right: Trip (red)
5) Target LED for front communication
6) Front communication port (infrared)

4.1.2. How to use the push buttons

The HMI contains push buttons for navigating in the menu.
Fig. 4.1.2.-1 Navigation push buttons

Use the navigation buttons to view, select and edit the wanted menu items.

- Activate the main menu by pressing an arrow button.
- Move between the menu levels and menu items by using the arrow buttons.
- Select the item to be edited or store a new value by pressing [Enter].
- Increase or decrease the activated digit, shift the activated decimal point, or navigate between options by using [↑] and [↓].
- Cancel and return the display to the previous mode (view mode or idle mode), by pressing [Clear/Cancel].

Table 4.1.2.-1 Button navigation and editing

<table>
<thead>
<tr>
<th>Wanted step or operation</th>
<th>Push button</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step downward in the main menu or a submenu</td>
<td>[↓]</td>
</tr>
<tr>
<td>Step upward in the main menu or a submenu</td>
<td>[↑]</td>
</tr>
<tr>
<td>Entering a submenu from the main menu or a higher submenu</td>
<td>[Enter]</td>
</tr>
<tr>
<td>Leaving a submenu for the main menu or a higher submenu</td>
<td>[Esc]</td>
</tr>
<tr>
<td>Increasing a value in the setting mode</td>
<td>[ Right]</td>
</tr>
<tr>
<td>Decreasing a value in the setting mode</td>
<td>[ Left]</td>
</tr>
<tr>
<td>Moving the cursor in the setting mode</td>
<td>[ ] or [ ]</td>
</tr>
<tr>
<td>Selecting the front connection at power up</td>
<td>[Enter]</td>
</tr>
<tr>
<td>Entering or leaving the setting mode, storing a new value</td>
<td>[Esc]</td>
</tr>
<tr>
<td>Entering the monitoring state</td>
<td>[Esc]</td>
</tr>
<tr>
<td>Adjusting the display contrast</td>
<td>[ Esc] and [Enter] or [Esc]</td>
</tr>
<tr>
<td>Resetting or canceling, leaving the setting mode without storing a new value</td>
<td>[Esc]</td>
</tr>
<tr>
<td>Resetting latched output contacts in the idle mode</td>
<td>[Esc] for 5 s</td>
</tr>
<tr>
<td>Acknowledging and resetting targets, latched output contacts and memorized values</td>
<td>[Esc] and [Esc]</td>
</tr>
<tr>
<td>Resetting thermal level to 0 at power up</td>
<td>[Esc]</td>
</tr>
</tbody>
</table>

4.1.3. Display

4.1.3.1. Display test at power up

When connecting the auxiliary voltage to the relay:
1. The backlight is turned on after the relay has performed the internal power-up tests and entered into the protection mode.

2. The display is tested by inverting it for approximately three seconds, see Fig. 4.1.3.1.-1. In case a restart disable target is displayed, the display test will not be run at power up.

3. The display is returned to the idle mode and the backlight is turned off if no operation target message is displayed. However, if the non-volatile function is active, a message shown on the display before the auxiliary voltage was disconnected reappears on the display.

![Fig. 4.1.3.1.-1 Display test at power up, display inverted](A04i216)

### 4.1.3.2. Display modes

When the display is in the idle mode, the name of the motor drive is displayed, which by default is **- ABB -**. To change the name of the motor drive, use SPA parameter **M20**.

![Fig. 4.1.3.2.-1 Display in the idle mode](A04i217)

When the display is in the view mode, you can only view the settings.

![Fig. 4.1.3.2.-2 Display in the view mode](A04i218)

When the display is in the setting mode, you can also edit the settings.

![Fig. 4.1.3.2.-3 Display in the setting mode](A04i219)
4.1.3.3. **Display backlight**

Normally the backlight of the display is off.

- Turn the backlight on by pressing an arrow button on the HMI. If the HMI panel is not used for approximately five minutes, the backlight is turned off automatically.
- Activating the power-saving built-in feature by pressing \( \text{\textchar'\x0048} \) turns the backlight off within 20 seconds.

4.1.3.4. **How to adjust the display contrast**

The display contrast is dependent on the temperature. The relay automatically adjusts the contrast for optimum readability. When the display is in the idle mode, you can also adjust the contrast manually.

- To increase the contrast, hold down \( \text{\textchar'\x0021} \) and adjust the contrast using \( \text{\textchar'\x0027} \).
- To decrease the contrast, hold down \( \text{\textchar'\x002d} \) and adjust the contrast using \( \text{\textchar'\x0029} \).

After power start up of the relay, the factory default value of the display contrast is automatically restored.

4.1.4. **Main menu**

The main menu contains six main groups:

- OPERATION
- MEASUREMENTS
- RECORDED DATA
- SETTINGS
- CONFIGURATION
- INFO

**MEASUREMENTS**

*Fig. 4.1.4.-1 Display showing the first main menu group*

- Navigate between the main menu groups by using \( \text{\textchar'\x0027} \) and \( \text{\textchar'\x0029} \).
- Return the display to the idle mode by pressing \( \text{\textchar'\x007b} \).

The display is returned to the idle mode on expiration of the time out.
4.1.5. Submenu

The menu structure contains several subgroups. The name of the main menu group is always shown on the first line. The second line displays either the name of the group menu, the name of the parameter and the parameter value, or just the parameter value, in which case it is also the name of the parameter.

![MEASUREMENTS](image1)

*Fig. 4.1.5.-1 Display showing the first submenu*

- Enter a submenu by pressing ▶; exit by pressing ◄.
- Navigate between the main levels in the submenus by using ▲ or ▼.
- Press ◄ to return the display to the idle mode.

4.1.6. HMI passwords

The HMI passwords are used to protect user-changeable values on technical level from being changed by an unauthorized person. There are two different HMI passwords; an HMI setting password for changing all user-changeable values and an HMI communication password for changing communication settings only. The password function remains inactive until the default password is replaced. The default HMI password is 999. You can also change the HMI passwords via SPA parameters V162 and V163, but you can only read the password via the HMI.

As soon as you have replaced the default HMI password, the new password is required for altering parameter values. Once you have given the valid password, the display remains in the setting mode until returned to the idle mode.

The following rules and exceptions apply, if the HMI passwords are in use:

- Navigating and reading parameter values do not require a password.
- All user-changeable values can be changed with the HMI setting password.
- User-changeable values under CONFIGURATION\COMMUNICATION can be changed either with the HMI communication password or the HMI setting password.
- Changing of the SPA password requires the HMI setting password.
- Changing of the HMI language does not require a password.
- Setting of time and date does not require a password.
- Performing trip lockout reset does not require a password.

![SETTING PASSWORD](image2)

*Fig. 4.1.6.-1 HMI setting password request for editing setting parameters*
Change the HMI setting password as follows:

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select CONFIGURATION\HMI PASSWORDS \SETTING PASSWORD and press .
3. Press to enter the setting mode and give the current HMI password if required. If the default password 999 is still valid, no password is required.
4. The first digit of the password to be edited starts to flash. Set the digit using and .
5. Activate the next digit to be set by pressing or .
6. To store the new password and return the display to the view mode, press . The display confirms the storage by flashing “−−−” once on the display.
   Alternatively, to exit the setting mode without storing the password change, press once before confirming and the display returns to the view mode.
7. Press to return the display to the idle mode.

The same procedure applies also when changing the HMI communication password.
4.1.7. **SPA password**

The password for SPA bus communication is required for altering parameter values via the SPA bus. The default password is 001. You can change the SPA password either via the HMI or the SPA bus by first entering the currently valid password into parameter V160 and then entering the new password into parameter V161.

Change the SPA password as follows:

1. Press an arrow button to access the main menu
2. Use the arrow buttons to select `CONFIGURATION\ COMMUNICATION\ SPA SETTINGS\ PASSWORD SPA` and press ↵.
3. Press ↵ to enter the setting mode and give the current HMI password if required. If the default password 999 is still valid, no password is required.
4. The first digit of the password to be edited starts to flash. Set the digit using ▲ and ▼.
5. Activate the next digit to be set by pressing ▲ or ▼.
6. To store the new SPA password and return the display to the view mode, press ↵. The display confirms the storage by flashing "---" once on the display.

Alternatively, to exit the setting mode without storing the SPA password change, press ▼ once before confirming and the display returns to the view mode.

7. Press ▼ to return the display to the idle mode.

---

**Fig. 4.1.7.-1 Changing SPA password**

4.1.8. **How to select language**

The relay allows you to choose among several different languages. The default language is English.

Change the display language as follows:
1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select CONFIGURATION\LANGUAGE and press → to enter the currently valid language.
3. Press → to enter the setting mode and give the password if required. The second line starts to flash indicating that you are allowed to set the language.
4. Use ▲ or ▼ to move the cursor to the wanted language.
5. Press → to confirm the selection. The selected language is shown on the display.
6. Press ← to return the display to the idle mode.

By pressing ← before confirming the selection, the former language remains active and the display is returned to the view mode. Pressing ← again returns the display to the idle mode.

The list of languages in the language selection menu differs depending on the HMI language set number in the order number.

4.1.9. How to set the real-time clock

The real-time clock used for time-stamped events is set via two different settings, one for Year-Month-Day and another for Hours-Minutes-Seconds.

To change one setting or both settings:
1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select CONFIGURATION\TIME and press →.
3. Use ▲ or ▼ to select the parameter to be edited.
4. Press ➤ to enter the setting mode and give the password, if required. If the default password 999 is still valid, no password is required.

5. The first digit of the setting value of the parameter to be edited starts to flash. Use ← and → to move the cursor and ▲ and ▼ to increase or decrease the value. The setting range (for example Year or Minutes) is shown on the right-hand side of the second line of the display.

6. To store a new value and return the display to the view mode, press ➤. 

7. To exit the setting mode without storing the changes, press ← once before confirming and the display is returned to the view mode.

8. Press ➤ to return the display to the idle mode.

Fig. 4.1.9.-1 Setting the real-time clock

### 4.1.10. How to switch between front and rear connection

There are two means of serial communication available for the relay: the front connection for SPA bus communication and optional rear communication modules for communication via the SPA bus, IEC 60870-5-103, MODBUS (RTU or ASCII) protocol.

If the relay is not provided with an optional rear communication module, or if the module has been disabled, the front connection is always active and switching between front and rear connection is not allowed.

If the optional rear communication module is installed and enabled, the default setting is the rear connection. Switch between front and rear connection as follows:
1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select CONFIGURATION\COMMUNICATION and press \. The cursor is at the setting currently in use (REAR CONNECTION or FRONT CONNECTION).
3. Press \ to enter the setting mode. The second line starts to flash.
4. Use \ or \ to select the wanted setting.
5. Press \ to confirm the selection.
6. Press \ to return the display to the idle mode.

When the front connection has been selected and there is no communication for approximately five minutes, the rear connection is automatically activated. To keep the front connection continuously active, press \ and \ simultaneously when connecting the auxiliary voltage to the relay.

When the rear connection is selected, the selected rear protocol is automatically activated.

---

**4.1.10.1. Target LED for front communication**

- Target off: the rear communication is currently selected.
- Lit target: the front communication port is currently selected.
- Flashing target: the front communication port is currently selected and the relay is communicating.

---

**4.1.11. How to select the protocol for rear communication**

REM 610 allows you to choose the communication protocol for rear connection.
The selected protocol is stored in the non-volatile memory and is therefore activated automatically after an interruption in the auxiliary voltage.

Select the rear communication protocol as follows:

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select CONFIGURATION\COMMUNICATION\REAR PROTOCOL and press . The cursor is at the setting currently in use (for example SPA).
3. Press to enter the setting mode. The second line starts to flash.
4. Use or to select the wanted setting.
5. Press to confirm the selection.
6. Press to return the display to the idle mode.

The HMI menu consists of a user level and a technical level. The user level is used for measuring and monitoring. The technical level is used for advanced protection relay setting and can be configured to require a password. The password is required after the default value 999 is replaced.

4.2. **HMI operation levels**

The HMI menu consists of a user level and a technical level. The user level is used for measuring and monitoring. The technical level is used for advanced protection relay setting and can be configured to require a password. The password is required after the default value 999 is replaced.

4.2.1. **User level**

4.2.1.1. **Menu groups of the user level**

The user level contains the following menu groups. You can monitor the data without a password.
4.2.1.2. How to monitor measured values

You can monitor all measured values via MEASUREMENTS in the HMI menu. In addition, the measured current values on phases Ia, Ib, and Ic and the measured value of In can also be monitored by activating the monitoring state.

To access the measured values on phases Ia, Ib, and Ic and the measured value of In, TH LEVEL via the HMI menu:

1. Press an arrow button to access the main menu.
2. The cursor is at the first menu item, MEASUREMENTS. Press \[ \text{ MEASUREMENTS } \] to see the measured value on phase Ia.
3. Use \[ \text{ \uparrow \downarrow } \] to monitor the measured values on phases Ia, Ib, and Ic and the measured value of In, I2 and TH LEVEL. The phase currents and the value of I2 are shown as multiples of the rated current, which correspond to the full load current (FLC) of the motor. In is shown as a percentage of the rated current of the current transformer (CT) while TH LEVEL is shown as a percentage of the thermal trip level. Press \[ \text{ MEASUREMENTS } \] once more to see the corresponding primary current value for Ia, Ib, Ic and In. If the conversion factors are set to zero, dashes "---" are displayed instead.
4. Use the arrow buttons to monitor other measured values in the menu DEMAND VALUES; see Fig. 4.2.1.2.-1.
5. Press \[ \text{ \rightarrow \leftarrow } \] to return the display to the idle mode.
To access the primary current values by activating the monitoring state:

1. Press ➔ and ➔ simultaneously to view the primary line currents on phases Iₐ, I₏ and Iᵣ and the ground-fault current, Iₐn.

2. Press ◄ to return the display to the idle mode.

The display has to be in the idle mode to be able to activate the monitoring state. The display is not returned to the idle mode automatically as the monitoring state does not have a time out. In case a fault is detected, however, the fault target displaces the monitoring state.
4.2.3. How to monitor recorded data

The contents of the event register and the information on motor start ups are found under the main menu group **RECORDED DATA**.

1. Press an arrow button to access the main menu.
2. Use ↑ or ↓ to select **RECORDED DATA** in the main menu and press → to enter the first event.
3. To navigate between the events, use ↑ and ↓.
4. To enter a submenu, use → and to exit, use ←.
5. To return the display to the idle mode, press ←.

Fig. 4.2.1.2.-2 Activating the monitoring state

Before you can monitor the correct primary current values, the parameters M80 and M83 must be correctly set via serial communication.
4.2.1.4. INFO menu group

The main menu group INFO contains information which you may need when ordering repair service.

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select INFO and press ↗ to enter the first submenu. The first submenu shows the device type, relay serial number, test date, the CPU module as well as the optional RTD module.
3. For specific information on the CPU module, use ⬇ to select CPU MODULE and press ↗ to view the CPU software number and revision. While in the CPU software number and revision view, press ↗ to view the CPU build number or ⬇ to view the CPU serial number.
4. Use the arrow buttons to monitor the corresponding information on the optional RTD module.
5. To return the display to the idle mode, press ⇓.
Fig. 4.2.1.4.-1 INFO menu group

1) Relay serial number
2) CPU module software number and revision
3) CPU module serial number
4) CPU module software build number
5) Communication module software number and revision
6) Communication module serial number
7) Communication module software build number

4.2.2. Technical level

4.2.2.1. Menu system of parameters

Press an arrow button to activate the main menu. If the default password is in use, no password is required to change the parameters. If the password protection is in use, "***" is shown on the display until you give the valid HMI password.

The views are used for reading and setting parameters, which are divided into two main groups:
- SETTINGS
- CONFIGURATION

4.2.2.2. How to change settings

The actual settings consist of the settings of group 1 or group 2, depending on which group has been selected to be active (indicated by an asterisk "*"). The actual settings can be seen in the first parameter menu, for example:
Setting parameters in setting group 1 and setting group 2

By switching between setting groups 1 and 2, you can activate a whole group of settings at the same time. Switch between the setting groups as follows:

- With the parameter GROUP 1/GROUP 2 under the main menu group SETTINGS.
- With a digital input signal, provided that SGB1...5/4 has been set to 1 in both setting groups (GRP1 and GRP2).
- With parameter V150 via the SPA bus.

When a large number of settings is to be altered, for example during the commissioning of the relay systems, use a PC equipped with the necessary software.

If no PC is available, or when only a few settings are to be altered:

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select the main menu group SETTINGS and the wanted group menu (for example PROTEC. ELEMENTS), and press .
3. Use or to select the parameter to be changed and press .
4. Use or to select setting group 1 or 2 (GRP1 or GRP2). The active setting group is indicated by an asterisk "*".
5. Enter the setting mode by pressing and give the password if required. If the default password 999 is still valid, no password is required.
6. The first digit of the setting value of the parameter to be edited starts to flash. Use and to move the cursor and and to increase or decrease the number.
7. To store a new value and return the display to the view mode, press . If the parameter is of a numerical kind, the display confirms the storage by flashing "--" once on the display.
8. To exit the setting mode without storing the changes, press once before confirming and the display returns to the view mode.
9. Press to return the display to the idle mode.
Switchgroups

The relay contains the following switchgroups:

SGF1   Output contacts
SGF2   Display settings
SGF3, SGF4 Protection functions
SGF5   Latching feature for programmable LEDs
SGB1...SGB5 Digital inputs (DI1...DI5)
SGR1...SGR5 Output contacts (PO1, PO2, PO3, SO1, SO2)
SGL1...SGL8 Programmable LEDs

To set functions via switchgroups:

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select the main menu group SETTINGS and the wanted switchgroup menu (for example SGF), and press ►.
3. Use ▲ or ▼ to select the wanted switchgroup (for example SGF2 for display settings) and press ►.
4. Use ▲ or ▼ to select setting group 1 or 2 (GRP1 or GRP2). The active setting group is indicated by an asterisk “*”.
5. Press ► to enter the setting mode and give the password if required.
6. Use ◀ or ▶ to select the bit to be set, and ▲ or ▼ to select the wanted bit state, see Fig. 4.2.2.2.-4.
7. Press ► to confirm the selection. After confirmation, the display returns to the view mode and shows the checksum of the switchgroup.
8. Press ◀ to return the display to the idle mode.
4.2.2.3. Configuration

In general, the parameters found under CONFIGURATION are set only once by the customer, that is, prior to commissioning of the relay.
To change a parameter:

1. Press an arrow button to access the main menu.
2. Use the arrow buttons to select the main menu group `CONFIGURATION` and the wanted group menu, and press →.
3. Use ▲ or ▼ to select the wanted parameter (for example `UNIT ADDRESS : xxx`) or a set of parameters (for example `SPA SETTINGS`). In case of a set of parameters, use arrow buttons until you reach the wanted parameter.
4. Press → to enter the setting mode and give the password if required.
5. The parameter text (enumerator) or the first digit of the parameter setting value starts to flash. Set the enumerator or the digit/character by using ▲ and ▼. Activate the next digit/character to be set by pressing ▼ or ▲. When setting an enumerator, however, the left and right arrows have no function.
6. To store a new value and return the display to the view mode, press →. If the parameter is of numerical kind, the display confirms the storage by flashing "--" once on the display.
7. To exit the setting mode without storing the changes, press ← once before confirming and the display returns to the view mode.
8. Press ← once more to return the display to the idle mode.

If a setting value outside the allowed limits is confirmed in the setting mode, the former value is restored.
Fig. 4.2.2.3.-1  CONFIGURATION menu, part 1
4.2.2.4. How to acknowledge and reset targets, output contacts and memorized values

- To clear the LEDs and the display, press \[ \text{button} \]. The LEDs and the display are cleared only if the fault has disappeared.
- To unlatch the output contacts, press \[ \text{button} \] for at least five seconds. Note that the LEDs and the display have to be cleared before this.
- Press \[ \text{button} \] and \[ \text{button} \] simultaneously for at least half a second to perform a master reset, that is, to clear targets and memorized values and to unlatch the output contacts. The display being inverted confirms this action. Memorized values include recorded data, disturbance recorder data and average values (demand values and history data values, except for the running time).

4.3. Protection relay targets

The operation of the relay can be monitored by means of three different HMI targets:

- Three target LEDs with fixed functionality:
  - Ready
  - Pickup/Alarm
  - Trip
- Eight programmable target LEDs
- Text message on the display

The protection functions are not affected by fault targets.

4.3.1. Target LEDs

When a protection element picks up or generates an alarm, the yellow target LED is lit.

When a protection element trips, the yellow target LED remains lit and the red target LED is lit.

When a picked up protection element is blocked, the yellow target LED starts to flash. The yellow target LED is also lit to indicate an alarm from a protection element.

4.3.1.1. Green target LED

Two different functions are embedded in the green target LED: power on and internal relay fault (IRF).
- **Target off:**
  The auxiliary voltage is not connected.

- **Lit target:**
  The relay is in operation. However, a less severe fault (warning) may have occurred. Refer to Section 4.3.2.3. Self-supervision.

- **Flashing target:**
  An internal relay fault requiring repair by an authorized service supplier has occurred. Refer to Section 4.3.2.3. Self-supervision.

### 4.3.1.2. Yellow target LED

*Fig. 4.3.1.2.-1 Yellow target LED*

- **Target off:**
  No protection element has picked up and there are no thermal alarms.

- **Lit target:**
  A protection element has picked up or generated an alarm. The pickup and alarm target can be selected to be either latching or non-latching with the SGF switches. A non-latching target is automatically cleared when the fault has disappeared and the protection element has been reset, whereas a latching target remains lit until manually cleared.

- **Flashing target:**
  Pickup protection elements have been blocked by an external digital input signal. The blocking target is non-latching, that is, it disappears with the digital input signal.

The yellow target LED continues flashing for as long as a protection element remains blocked. The blocking target disappears with the digital input signal or when the protection element is no longer picked up.

If a protection element is blocked when other protection elements are picked up, the target continues flashing. This is because a blocking target has a higher priority than a pickup target.

### 4.3.1.3. Red target LED

*Fig. 4.3.1.3.-1 Red target LED*
4.3.1.4. Programmable target LEDs

In addition to the three fixed LEDs, the relay contains eight LEDs which you can program to target the status of different type of relay signals. The programmable LEDs can target the following information:

- Trip signals from protection elements
- Alarm signals from protection elements
- Motor status and restart disable status
- Status of the digital input signals

Route the signals to the LEDs via switchgroups SGL1...SGL8; to LED1 with the switches of switchgroup SGL1, to LED2 with those of SGL2, and so forth.

For detailed information on the signals, refer to the Technical Reference Manual.

The LEDs are non-latching by default but you can also set them to operate as latching via switchgroup SGF5.

For instructions on setting the switchgroups, refer to Section 4.2.2.2. How to change settings.

4.3.2. Target messages

The messages give an overview of protection operations and internal relay faults.

4.3.2.1. Operation target messages

When a protection element picks up, the text PICKUP appears on the display along with the name of the function. Additionally, in case of a latching pick up target, the name of the energizing input(s) which caused the fault are displayed (except for the motor start-up supervision based on thermal stress calculation and the unbalance protection). The yellow target LED is lit.
Fig. 4.3.2.1.-1  Latching pickup target

When a protection element trips, the text TRIP appears on the display along with the name of the function. Additionally, the name of the energizing input(s) which caused the fault are displayed (except for the motor start-up supervision, phase unbalance, phase reversal, thermal overload and temperature protection). The red target is lit.

Fig. 4.3.2.1.-2  Trip target

In case of an alarm from the thermal overload or temperature protection, the text ALARM appears on the display along with the function symbol and the yellow target LED is lit.

Fig. 4.3.2.1.-3  Alarm target

In case of a restart disable state, the text RESTART DISABLE will appear on the display. The state will not affect the disable/alarm and trip LEDs, but instead you can use a programmable LED to indicate the state; refer to section Programmable target LEDs. The text message for the restart disable state is non-latching, whereas the status target via a programmable LED can be either latching or non-latching.

The restart of a motor can be disabled by the thermal protection, the cumulative start-up time counter or an external digital input signal. For the priority of targets for the restart disable state; refer to section Priority of operation target messages.
Latching and non-latching targets

A latching operation target message remains on the display until manually cleared or until replaced by a message of higher priority. However, if the fault is stable and has not disappeared, the operation target message and the LED(s) are not cleared. An operation target generated by a non-latching pickup is automatically cleared when the element is reset.

Priority of operation target messages

The messages on the display have a certain priority order. If different types of targets are activated simultaneously, the message with the highest priority appears on the display.

The priority order of the messages:
1. CBFAIL
2. Trip
3. Pickup/Alarm
4. Restart disable
   4.1. Thermal protection
   4.2. Cumulative start-up time counter
   4.3. External restart disable

When several protection elements generate pickups or alarms, the last pickup/alarm target message is displayed. When several protection elements trip, the first trip target message is displayed until the time, as specified by the NEW TRIP IND. setting value, has expired. After this, a new trip target message can replace the old one. A hidden trip target message can be brought forward by pressing .

4.3.2.2. Disturbance recorder target

When the display is in the idle mode, an asterisk "*" indicating that the disturbance recorder has been triggered and is ready to be unloaded, is shown in the lower right-hand corner of the display. Disturbance recorder status target can also be routed to the programmable LEDs.
4.3.2.3. Self-supervision

There are two types of fault targets; internal relay fault (IRF) targets and warnings. Internal relay faults prevent relay operation. Warnings are less severe faults and continued relay operation with full or reduced functionality is allowed.

Internal relay fault (IRF)

At permanent internal relay faults, the relay is no longer protecting and has to be sent for repair at an authorized service supplier. When the self-supervision system detects a permanent internal relay fault, the green target LED starts to flash. The text INTERNAL FAULT and a fault code appear on the display.

State the fault code when sending the relay for service.

As long as the green target LED (ready) is flashing, the fault target cannot be cleared. In case an internal fault disappears, the green target LED stops flashing and the relay is returned to the normal service state, but the fault target message remains on the display until manually cleared, or until a motor start up begins.

![INTERNAL FAULT FAULT CODE :30](image)

*Fig. 4.3.2.3.-1 Permanent IRF*

The fault code is a number which identifies the fault type. The fault codes are listed in the table below:

<table>
<thead>
<tr>
<th>Fault code</th>
<th>Type of fault</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>Error in output relay PO1</td>
</tr>
<tr>
<td>5</td>
<td>Error in output relay PO2</td>
</tr>
<tr>
<td>6</td>
<td>Error in output relay PO3</td>
</tr>
<tr>
<td>7</td>
<td>Error in output relay SO1</td>
</tr>
<tr>
<td>8</td>
<td>Error in output relay SO2</td>
</tr>
<tr>
<td>9</td>
<td>Error in the enable signal for output relays PO1,PO2,SO1,SO2</td>
</tr>
<tr>
<td>10, 11, 12</td>
<td>Error in the feedback, enable signal or output relays PO1,PO2,SO1,SO2</td>
</tr>
<tr>
<td>20, 21</td>
<td>Auxiliary voltage dip</td>
</tr>
<tr>
<td>30</td>
<td>Faulty program memory</td>
</tr>
<tr>
<td>50, 59</td>
<td>Faulty work memory</td>
</tr>
</tbody>
</table>
Table 4.3.2.3.-1 IRF codes (Continued)

<table>
<thead>
<tr>
<th>Fault code</th>
<th>Type of fault</th>
</tr>
</thead>
<tbody>
<tr>
<td>51, 52, 53(^a), 54, 56</td>
<td>Faulty parameter memory(^b)</td>
</tr>
<tr>
<td>55</td>
<td>Faulty parameter memory, calibration parameters</td>
</tr>
<tr>
<td>75</td>
<td>RTD module faulty</td>
</tr>
<tr>
<td>80</td>
<td>RTD module missing</td>
</tr>
<tr>
<td>81</td>
<td>RTD module unknown</td>
</tr>
<tr>
<td>82</td>
<td>RTD module configuration error</td>
</tr>
<tr>
<td>85</td>
<td>Power supply module faulty</td>
</tr>
<tr>
<td>86</td>
<td>Power supply module unknown</td>
</tr>
<tr>
<td>90</td>
<td>Hardware configuration error</td>
</tr>
<tr>
<td>95</td>
<td>Communication module unknown</td>
</tr>
<tr>
<td>104</td>
<td>Faulty configuration set for IEC 60870-5-103</td>
</tr>
<tr>
<td>131, 139, 195, 203, 222, 223</td>
<td>Internal reference voltage error</td>
</tr>
<tr>
<td>253</td>
<td>Error in the measuring unit</td>
</tr>
</tbody>
</table>

\(^a\) All setting values will be zero during the fault  
\(^b\) May be corrected by formatting to the factory setting.

Warning

In case of a less severe fault (warning), the relay continues to operate except for those protection functions possibly affected by the fault. At this type of fault, the green target LED remains lit as during normal operation, but the text WARNING with a fault code or a text message indicating the fault type replaces the name of the feeder on the display in the idle mode. Some of these faults can be corrected by a relay operator at site. After the fault has disappeared or been corrected, the message is automatically cleared.

If more than one type of fault occur at the same time, one single numeric code which indicates all the faults is displayed. For instance, 2049 implies two faults: the battery is low and the temperature sensor RTD6 is faulty. The code is composed of the weighting factors assigned to each fault type as follows: 1 + 2048; see Table 4.3.2.3.-2.
### Table 4.3.2.3.-2 Warning codes

<table>
<thead>
<tr>
<th>Fault</th>
<th>Weighting factor</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Battery low</td>
<td>1</td>
<td>Description Battery voltage level low&lt;br&gt;• Battery should be replaced&lt;br&gt;• Warning will not be displayed if non-volatile memory settings have been set to 0&lt;br&gt;• In case only this warning is active, it will be displayed in text format (BATTERY LOW)</td>
</tr>
<tr>
<td>Trip-circuit supervision</td>
<td>2</td>
<td>Error in trip circuit&lt;br&gt;• Check the trip circuit for broken conductors and correct.&lt;br&gt;• Warning will not be displayed if trip-circuit supervision (TCS) has been disabled</td>
</tr>
<tr>
<td>Power supply module temperature high</td>
<td>4</td>
<td>Temperature inside relay is too high&lt;br&gt;• Check that ambient temperature is within service temperature range</td>
</tr>
<tr>
<td>Communication module faulty or missing</td>
<td>8</td>
<td>Communication module faulty or not installed&lt;br&gt;• Check that plug-in unit is properly attached to relay case&lt;br&gt;• Check that communication module is installed&lt;br&gt;• Warning will not be displayed if rear communication module has been disabled&lt;br&gt;• In case only this warning is active, it will be displayed in text format (Comm.card faulty)</td>
</tr>
<tr>
<td>RTD module faulty</td>
<td>16</td>
<td>Three possible causes:&lt;br&gt;1. Storing in non-volatile memory has not been successful, which means that old settings will be taken into use after power up&lt;br&gt;2. Self calibration has failed&lt;br&gt;3. Offset voltage out of range - If warning is not cleared after a power reset, the relay may require service</td>
</tr>
<tr>
<td>Temperature sensor range error</td>
<td>32</td>
<td>At least one sensor (RTD1…6) is outside measurement range&lt;br&gt;• Check that sensors are not broken</td>
</tr>
<tr>
<td>Sensor circuit open or shorted (RTD1)</td>
<td>64</td>
<td>Circuit is open or shorted&lt;br&gt;• Check wiring of sensor&lt;br&gt;• Check that sensor is not broken</td>
</tr>
<tr>
<td>Sensor circuit open or shorted (RTD2)</td>
<td>128</td>
<td>Circuit is open or shorted&lt;br&gt;• Check wiring of sensor&lt;br&gt;• Check that sensor is not broken</td>
</tr>
</tbody>
</table>
### Table 4.3.2.3.-2 Warning codes (Continued)

<table>
<thead>
<tr>
<th>Fault</th>
<th>Weighting factor</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sensor circuit open or shorted (RTD3)</td>
<td>256</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Sensor circuit open or shorted (RTD4)</td>
<td>512</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Sensor circuit open or shorted (RTD5)</td>
<td>1024</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Sensor circuit open or shorted (RTD6)</td>
<td>2048</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Thermistor circuit open or shorted (Thermistor1)</td>
<td>4096</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Thermistor circuit open or shorted (Thermistor2)</td>
<td>8192</td>
<td>Circuit is open or shorted(a)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check wiring of sensor</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Check that sensor is not broken</td>
</tr>
<tr>
<td>Σ: 16383</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

\(a\) Temperature protection elements are out of operation

### 4.4. Detachable plug-in unit

#### 4.4.1. Identifying the product

You can find the order number on a label under the lower handle of the relay.

> When checking the order number of the relay plug-in unit, be careful not to lift the handle more than 25° (approx. 40 mm). Lifting the handle any further detaches the plug-in unit from the case.
4.4.1. Checking the order number of the relay

\[
\begin{align*}
\alpha &= 25^\circ \\
y &= 40 \text{ mm}
\end{align*}
\]

Fig. 4.4.1-1 Checking the order number of the relay

4.4.2. Detaching and installing the plug-in unit

Before detaching the plug-in unit from the case, the auxiliary voltage must be disconnected.

To detach the plug-in unit:

1. Lift the lower handle until the spring-loaded locks on both sides of the handle are released and the unit is pushed about 6 mm out of the case. This separates the connectors.
2. Pull the unit out of the case.

The relay features an automatic short-circuit mechanism in the current transformer (CT) connector. Therefore, detaching the plug-in unit will not open the secondary circuit of the CT which otherwise could cause dangerously high voltages.

Signal connectors are left open when the plug-in unit is detached.
Before fitting a relay plug-in unit into a relay case, check that the unit and the case have the same order number.

The order number of the case is printed on the bottom plate inside the case. However, if a substitute plug-in unit has to be used instead of the original unit, ensure that at least the first 10 characters in the order numbers of the case and the plug-in unit are identical, as in the following example:

<table>
<thead>
<tr>
<th>Order number of the relay case</th>
<th>REM610C55HCMP XX</th>
</tr>
</thead>
<tbody>
<tr>
<td>Order number of the plug-in unit</td>
<td>REM610C55HCNR XX</td>
</tr>
</tbody>
</table>

However, it is highly recommended that all characters in the order number of the substitute plug-in unit, except for those indicating a spare part, should match the ones of the case. Otherwise, it may result in loss of significant functionality in the application.

The relay features a built-in mechanical coding system which helps to prevent dangerous situations from arising in case a non-suitable plug-in unit is fitted into a relay case.

Forcing a non-suitable plug-in unit into a case breaks the relay and may cause dangerous situations.

When installing a plug-in unit into a case:
1. Check that the handle is down in its initial position.
2. Push the unit into the case until the locks click; see Fig. 4.4.2.-2.
4.4.3. Inserting and changing the battery

The battery may only be inserted and changed by trained service personnel.

To insert or change the battery, first detach the plug-in unit; refer to Section 4.4.2. Detaching and installing the plug-in unit.

The battery compartment is accessible from underneath the plug-in unit as shown in Fig. 4.4.3.-1.

1. Gently remove the battery with, for example, a flat-ended screwdriver. Be careful not to drop the battery inside the plug-in unit.
2. Insert a new battery under the battery holder and ensure that you install the battery with the correct polarity to avoid damage to the equipment.
3. Dispose the removed battery according to local environmental regulations on the disposal of lithium batteries.

The battery is not being charged during normal operation.

When the relay is taken out of service, the battery should be removed to avoid discharge. Typical battery discharge time is 14 days.
Fig. 4.4.3.-1  Inserting and changing the battery

A) Battery holder
B) Note! Polarity
C) Battery
5. Commissioning and maintenance

The relay should be subject to regular tests and maintenance in accordance with national regulations and instructions.

Prior to commissioning, the functionality of the application-specific relay configuration and settings have to be tested.

During relay commissioning, the operation of short-circuit and ground-fault protection is to be tested by using secondary injection testing to secure personal safety. Additionally, correct operation of input and output signals to and from the relay should be verified.

The relay is a numerical protection relay with functionality implemented in the relay software configuration. Software functionality does not change over time and the relay performs extensive self-supervision during operation. Therefore, it is not necessary to perform extensive relay testing during periodic maintenance.

When the protection relay is operating under the specified conditions (refer to the Technical Reference Manual), the manufacturer recommends preventive maintenance to be performed every five years. This periodically performed preventive maintenance is to be carried out to secure correct and safe operation of the relay. When performing preventive maintenance, the correct functionality of the relay is to be verified as well as the wiring circuitry to and from the relay.

If the environmental conditions at the relay operating site differ from those specified, for instance temperature and humidity, or if the atmosphere around the relay contains chemically active gases or dust, the relay ought to be visually inspected.

At the visual inspection, the following should be observed:

- Signs of mechanical damage on the relay, contacts and relay case.
- Rust spots or signs of corrosion on the terminals or case.

Do not open the secondary circuit of a current transformer during any phase of the testing when the primary circuit is live. The high voltage generated by an open CT secondary circuit may be lethal and damage instruments and insulation.

5.1. Commissioning instructions

Relay commissioning is carried out to confirm correct operation of the relay when it is taken into use.
Polarity checking of phase current transformers (CTs) should be performed to confirm that the wiring circuitry between the CTs and the relay is correct, which is a prerequisite for the protection functions in the relay to operate correctly. The circuit breaker tripping circuit, interlocking and signaling wiring should also be tested.

When commissioning the relay, secondary injection testing is performed to secure personal safety in case of short circuits or ground faults in the system. If wanted, secondary injection testing can also be used for more elaborate testing of the relay’s functionality.

Relay commissioning contains:

1. Verifying that the correct application-specific settings have been entered into the relay. This is done by reading the relay settings either via the HMI or serial communication and comparing these to the calculated application-specific settings. If read via serial communication, the settings can be stored as a commissioning setting record file.

2. Verifying the current measurements – refer to Section 5.3. Measurements verification

3. Testing of signal routing to output contacts – refer to Section 5.4. Function test

4. Testing of digital input signals availability – refer to Section 5.5. Digital input test


6. Testing of ground-fault protection – refer to Section 5.6.2. Testing of the ground-fault protection

5.2. Maintenance instructions

Relay preventive maintenance includes verification of the relay operation and changing the possibly worn parts. The verification is carried out to ensure that the relay hardware operates correctly, that is, as it did when first commissioned.

When performing periodic preventive maintenance, the whole circuit breaker tripping circuit should also be tested, if possible. This can easily be done with the plug-in unit removed from the relay case, as the terminals for output contacts in the relay case are left open in such a situation.

When the plug-in unit is removed from the case, internals of the case must not be touched. Relay case internals may have high voltage potential and touching these may cause personal injury.
5.2.1. Relay verification

The relay maintenance verification contains:

1. Verifying measurements – can be performed according to the instructions in Section 5.3. Measurements verification.
2. Verifying output contacts operation – can be performed according to the instructions in Section 5.4. Function test.

! The circuit breaker tripping circuit should be disconnected from the relay during this verification, in order to avoid unwanted operation in the system. Interlocking signals should also be disconnected from the relay during the verification in order to avoid dangerous situations from occurring in the system.

3. Verifying digital inputs operation – can be performed according to the instructions in Section 5.5. Digital input test.

5.2.2. Preventive parts replacement

When being used for real-time clock and recorded data functions, the battery should be changed every five years. Refer to Section 4.4.3. Inserting and changing the battery.

5.3. Measurements verification

As most of the protection functions in the protection relay are based on the phase currents and ground-fault current measured by the relay, it is important to verify that the relay is measuring proper values.

This measurements verification can be performed by examining the current readings on the display while injecting a pure sinusoidal current into the current input. If the reading on the display corresponds to the calculated value, taking the relay accuracy and display resolution into account, the relay is measuring proper values.

Rated current for the energizing input that is being verified is shown on the relay label under the lower handle of the relay.

The protected unit scaling factor, used for motor full load current FLA compensation, has to be taken into account when verifying phase currents measured by the relay.

The value to be shown on the display is calculated as follows:

\[
\text{Value on LCD (FLA)} = \left( \frac{\text{Injected current}}{\text{energizing input rated current}} \right) \times \text{FLA secondary factor}
\] (2)
When verifying the ground-fault current measured by the relay, the value to be shown on the display is calculated as follows:

\[
\text{Value on LCD (CT\%)} = \left( \frac{\text{Injected current}}{\text{energizing input rated current}} \right) \times 100\% \tag{3}
\]

### 5.4. Function test

This section describes how the signal routing from protection functions to, and operation of, the output contacts in the relay can be tested.

The internal signals are routed to the output contacts according to the SGR switch groups.

The test mode is accessible via FUNCTION TEST/DI under CONFIGURATION in the HMI menu. In the test mode, all internal signals from the different protection elements can be activated one by one, the self-supervision included.

1. Press an arrow button to access the main menu.
2. Use ▲ or ▼ to select CONFIGURATION in the main menu and press ‹. The cursor is at the first menu item, FUNCTION TEST/DI. Press ‹ again to enter the test menu.
3. The cursor is at the first parameter, FUNC.TEST. Press ‹ to enter the test mode and give the password if required.
4. Select the wanted signal with ▲ or ▼ and press ‹ to activate the signal. The signal remains active for as long as you press ‹.
5. Repeat the previous step to test other signals.
6. To exit the test mode, press ‹.
7. Press ‹ again to return the display to the idle mode.

The table below shows the activation order and the corresponding flashing digit when a signal is being tested.

<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Alarm of element 49</td>
</tr>
<tr>
<td>2</td>
<td>Trip of element 49</td>
</tr>
<tr>
<td>3</td>
<td>Pickup of element 48/14</td>
</tr>
<tr>
<td>4</td>
<td>Trip of element 48/14</td>
</tr>
<tr>
<td>5</td>
<td>Pickup of element 50P</td>
</tr>
<tr>
<td>6</td>
<td>Trip of element 50P</td>
</tr>
<tr>
<td>7</td>
<td>Pickup of element 37</td>
</tr>
<tr>
<td>8</td>
<td>Trip of element 37</td>
</tr>
<tr>
<td>9</td>
<td>Pickup of element 51N</td>
</tr>
<tr>
<td>10</td>
<td>Trip of element 51N</td>
</tr>
<tr>
<td>11</td>
<td>Pickup of element 46</td>
</tr>
</tbody>
</table>
### Table 5.4.1 Function test (Continued)

<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>12</td>
<td>Trip of element 46</td>
</tr>
<tr>
<td>13</td>
<td>Trip of element 46R</td>
</tr>
<tr>
<td>14</td>
<td>Motor start up</td>
</tr>
<tr>
<td>15</td>
<td>External trip</td>
</tr>
<tr>
<td>16</td>
<td>Alarm of element 49/38-1</td>
</tr>
<tr>
<td>17</td>
<td>Trip of element 49/38-1</td>
</tr>
<tr>
<td>18</td>
<td>Alarm of element 49/38-2</td>
</tr>
<tr>
<td>19</td>
<td>Trip of element 49/38-2</td>
</tr>
<tr>
<td>0</td>
<td>IRF</td>
</tr>
</tbody>
</table>

It is also possible to test the output contacts via serial communication by using the \( \circ \) parameters.

### 5.5. Digital input test

This section describes how the availability of signals connected to the digital inputs can be tested.

To monitor the status of the digital inputs, navigate in the HMI menu as follows:

1. Press an arrow button to access the main menu.
2. Use \( \uparrow \) or \( \downarrow \) to select CONFIGURATION in the main menu and press \( \rightarrow \). The cursor is at the first menu item, FUNCTION TEST/DI. Press \( \rightarrow \) again to enter the test menu.
3. Use \( \uparrow \) or \( \downarrow \) to select DI STATUS and press \( \rightarrow \) to see the status of DI1.
4. Use \( \uparrow \) and \( \downarrow \) to monitor the state of the other four digital inputs.
5. Press \( \leftarrow \) to return the display to the idle mode.

It is also possible to read the state of the digital inputs via serial communication.

### 5.6. Testing protection functions

The short-circuit and ground-fault protection functions in the relay can be tested with the setting values used during normal operation. If other settings are used during testing, make sure that the original settings are re-entered after the test is completed.

The test is performed as a secondary test, by injecting current to the current energizing inputs. To enable secondary testing without accidentally blocking other relays or tripping circuit breakers in the system, the relay has to be disconnected.
5.6.1. Testing of the short-circuit protection

If proper 3-phase secondary testing equipment is not available for current generation, the phase unbalance and phase reversal protection functions have to be out of operation during the test.

When calculating the current to be injected into the phase current energizing inputs, the calculation should be done on the basis of the following:

- The rated current, 1 A or 5 A, of the relay energizing input to be tested
- The protected unit scaling factor (used for motor full load current compensation)

This gives the current to be injected during the test as follows:

\[ \text{Injected current (A)} = 2.5 \times 50P \times \text{Rated current of the energizing input} \times \text{Protected unit scaling factor} \]

To perform the test, inject the current in all three phase current energizing inputs. The output contacts, to which the trip signal is routed from the short-circuit protection function, should be activated on the expiration of the set operate time of element 50P.

5.6.2. Testing of the ground-fault protection

When calculating the current to be injected into the ground-fault current energizing input, the calculation should be done on the basis of the following:

- The rated current, 1 A or 5 A, of the relay energizing input to be tested

This gives the current to be injected during the test as follows:

\[ \text{Injected current (A)} = 2.5 \times 51N \times \text{Rated current of energizing input} \]

To perform the test, inject the current in the ground-fault current energizing input. The output contacts, to which the trip signal has been routed from the ground-fault protection element, should be activated on the expiration of the set operate time of element 51N.
6. Spare parts

6.1. Plug-in unit

The relay’s construction allows a spare part in form of a plug-in unit. The outage time can therefore be reduced to a minimum in case the relay should fail.

In case of malfunction, please consult your relay supplier.

The spare plug-in unit to be used for a certain relay is suitable if at least the first 10 characters in the order number are identical with those in the order number of the case.

To obtain identical functionality to those of the original product, all characters in the order number, except for those indicating a spare part, should match the ones in the order number of the case.

The relay features a built-in mechanical coding system. This helps to prevent dangerous situations from arising in case a non-suitable plug-in unit is fitted into a relay case.

Forcing a non-suitable plug-in unit into a case breaks the relay and may cause dangerous situations.

The plug-in unit is calibrated as a whole to achieve the best possible operation accuracy and individual pieces of it should not be removed.

If the faulty plug-in unit is subject to guarantee and the fault is caused under circumstances covered by the warranty conditions, it should be returned for repair.

Ordering of spare parts is done by using the same ordering system as for ordering a new relay.

6.2. Battery

The battery for real-time clock and non-volatile memory can be purchased in stores specialized in electronic components.

Recommended battery manufacturers and types are:

- Panasonic of type BR2032\(^1\)
- Rayovac of type BR2032\(^1\)

\(^1\) Batteries of the recommended lithium BR-types cannot be recharged.
7. **Repair**

If the relay fails in operation or if the operating values differ remarkably from the specified values, the relay is to be given a proper service.

![Warning]

All major measures involving overhaul of electronics are to be taken by the manufacturer.

Contact the manufacturer or the nearest representative for further information on checking, service and re-calibration of the relay.

![Information]

When contacting ABB for ordering repair services, give a description of the fault and state the fault code, if applicable.
8. **Ordering information**

# Abbreviations

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ANSI</td>
<td>American National Standards Institute</td>
</tr>
<tr>
<td>AR</td>
<td>Auto reclosure</td>
</tr>
<tr>
<td>ASCII</td>
<td>American Standard Code for Information Interchange</td>
</tr>
<tr>
<td>CBFAIL</td>
<td>Circuit-breaker failure protection</td>
</tr>
<tr>
<td>CPU</td>
<td>Central processing unit</td>
</tr>
<tr>
<td>CT</td>
<td>Current transformer</td>
</tr>
<tr>
<td>DI</td>
<td>Digital input</td>
</tr>
<tr>
<td>HMI</td>
<td>Human-machine interface</td>
</tr>
<tr>
<td>IEC</td>
<td>International Electrotechnical Commission</td>
</tr>
<tr>
<td>IED</td>
<td>Intelligent electronic device</td>
</tr>
<tr>
<td>IRF</td>
<td>Internal relay fault</td>
</tr>
<tr>
<td>LCD</td>
<td>Liquid crystal display</td>
</tr>
<tr>
<td>LED</td>
<td>Light-emitting diode</td>
</tr>
<tr>
<td>PC</td>
<td>Personal computer</td>
</tr>
<tr>
<td>PO</td>
<td>Power output, process object</td>
</tr>
<tr>
<td>PTC</td>
<td>Positive temperature coefficient</td>
</tr>
<tr>
<td>RTD</td>
<td>Resistance temperature device</td>
</tr>
<tr>
<td>RTU</td>
<td>Remote terminal unit</td>
</tr>
<tr>
<td>SGB</td>
<td>Switchgroup for digital inputs</td>
</tr>
<tr>
<td>SGF</td>
<td>Switchgroup for functions</td>
</tr>
<tr>
<td>SGL</td>
<td>Switchgroup for LEDs</td>
</tr>
<tr>
<td>SGR</td>
<td>Switchgroup for output contacts</td>
</tr>
<tr>
<td>SO</td>
<td>Signal output</td>
</tr>
<tr>
<td>SPA</td>
<td>Data communication protocol developed by ABB</td>
</tr>
<tr>
<td>TCS</td>
<td>Trip-circuit supervision</td>
</tr>
</tbody>
</table>