

June 2012

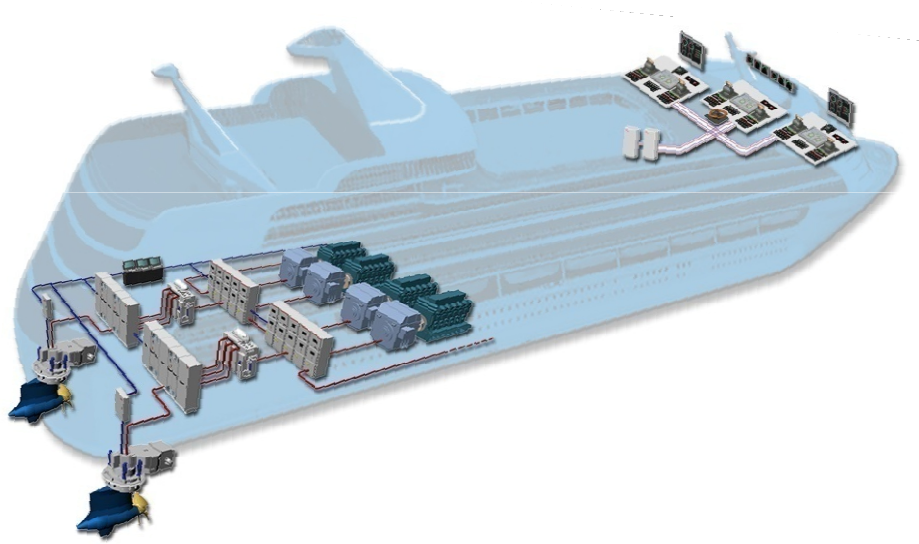
Azipod[®] XO

Azipod Propulsion System Features



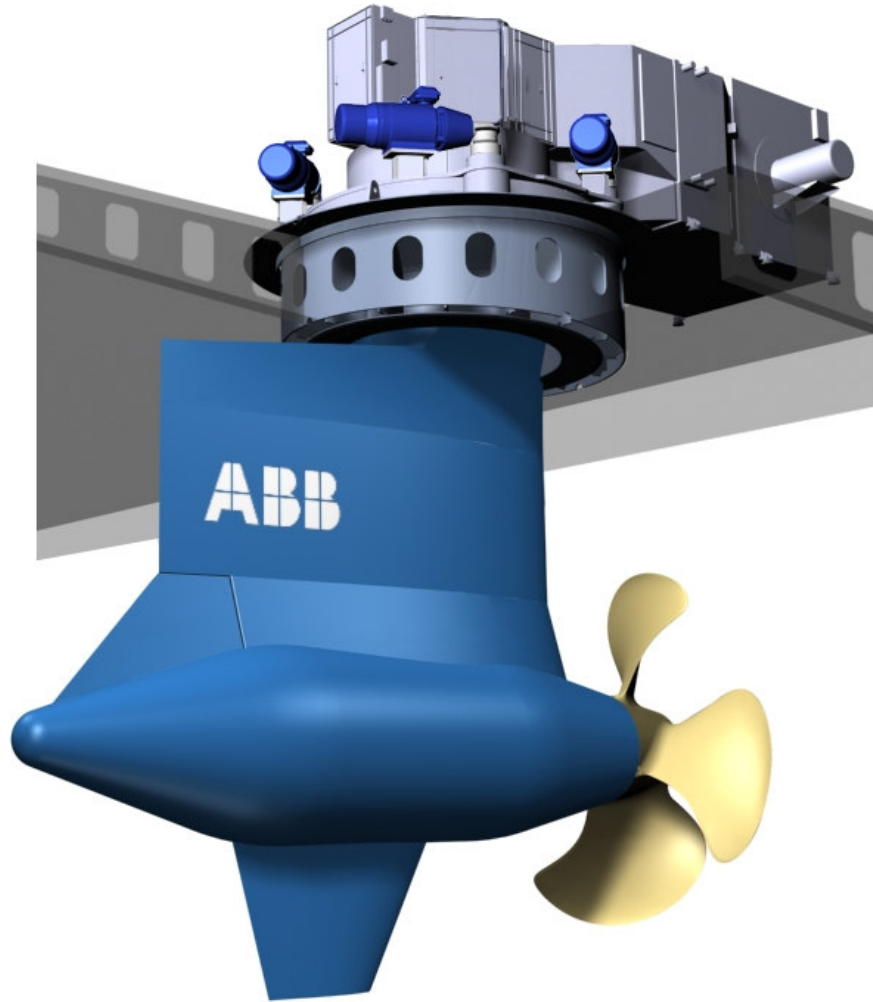
- Electric Propulsion System
- High Efficiency
- Excellent Manoeuvrability
- Increased Transportation Capacity
- About 7 million operating hours (Nov.2011)

Azipod[®] XO System is designed to provide



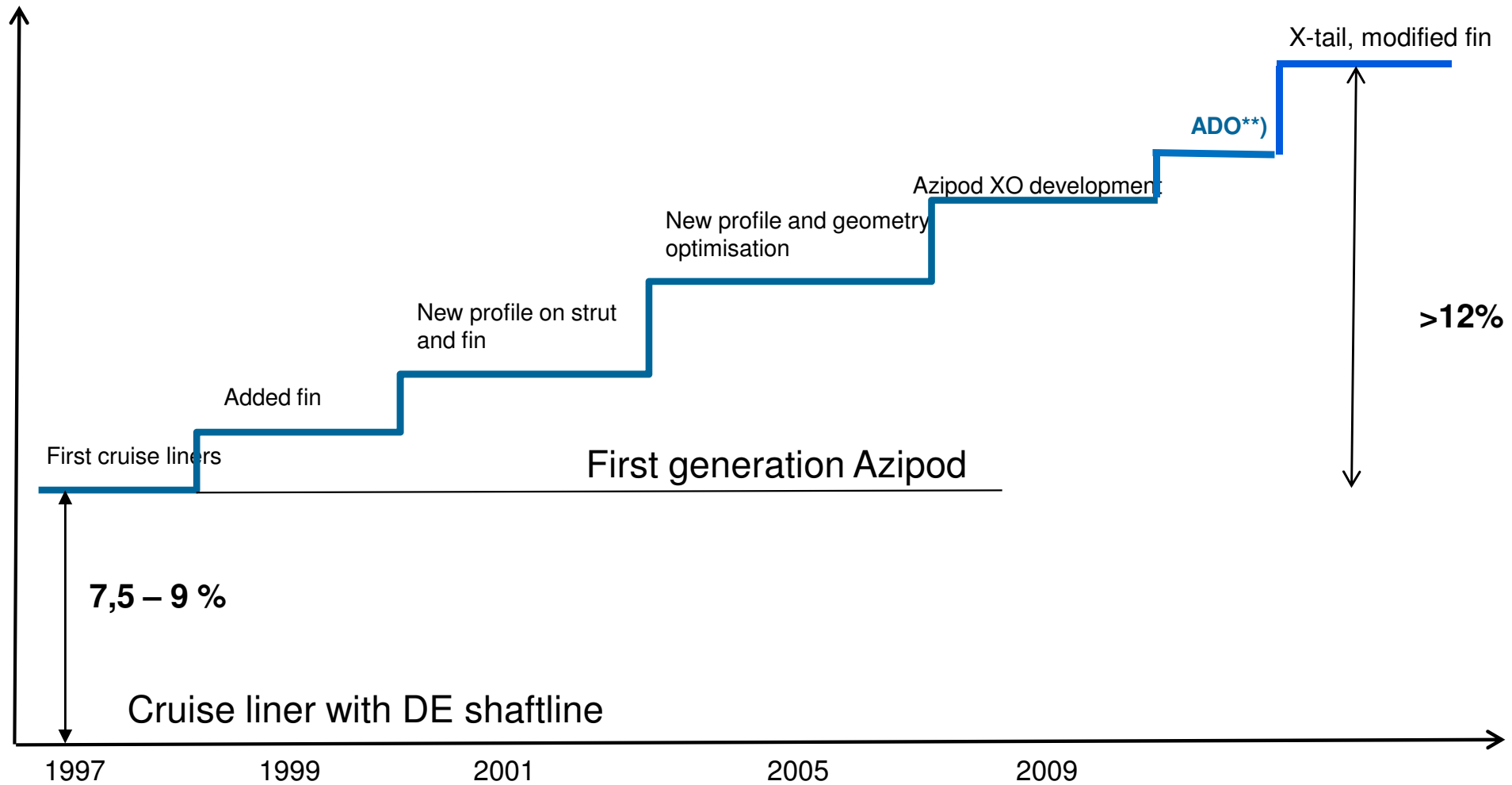
- Reduced life cycle costs
- Minimized emissions
- Enhanced maintainability
- Flexible integration to ship hull
- Improved reliability

Azipod® XO System Features



- Freely 360 degree rotating Azipod unit
- Fixed pitch pulling propeller
- Undisturbed water flow to propeller
- Extremely low vibrations

Efficiency development history (Azipod[®] V and X)

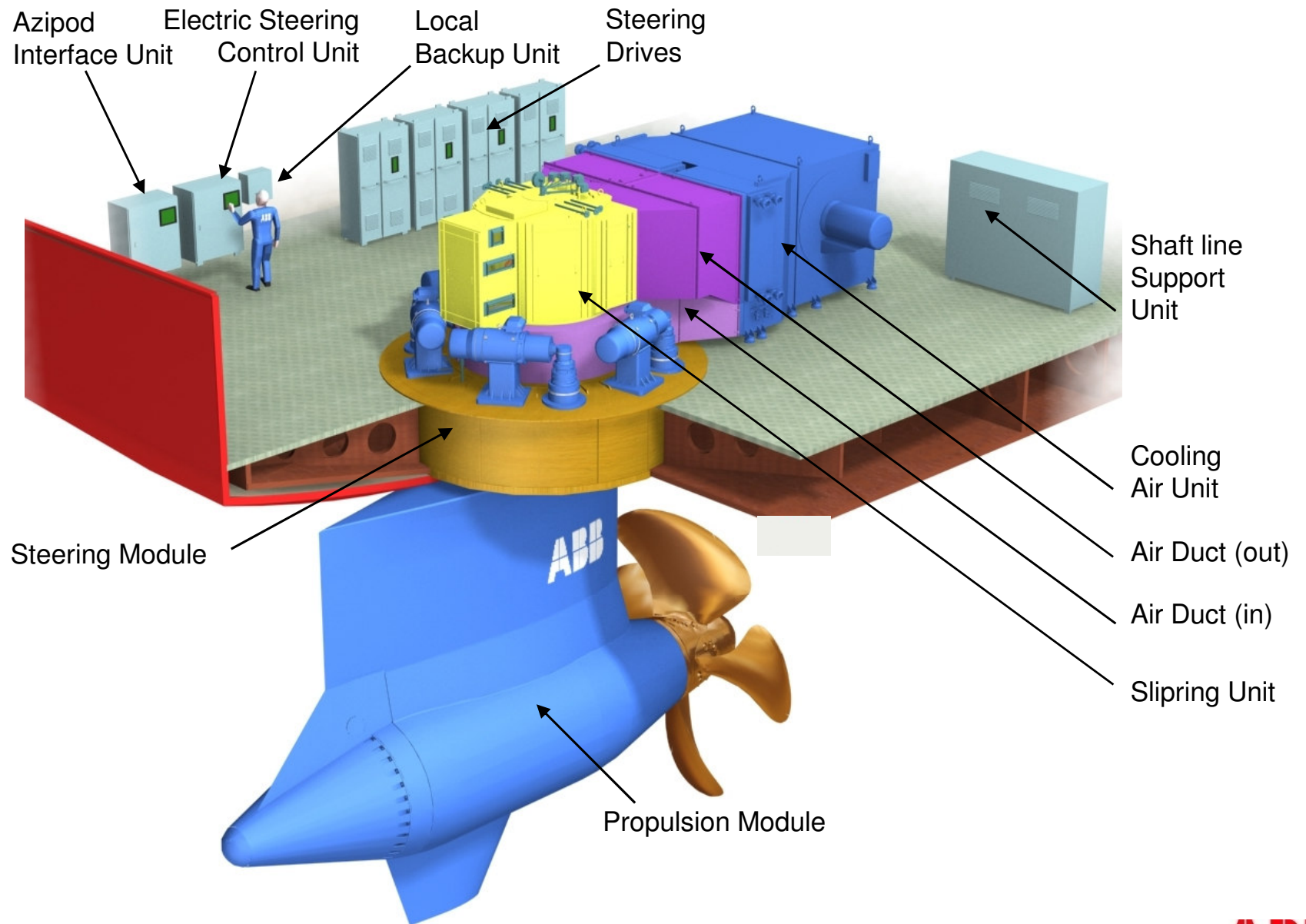


Designed for fuel saving up to 20%! *)

*) Compared to reference diesel – electric shaft line cruise liner

***) Azipod Dynamic Optimizer

Azipod[®] XO

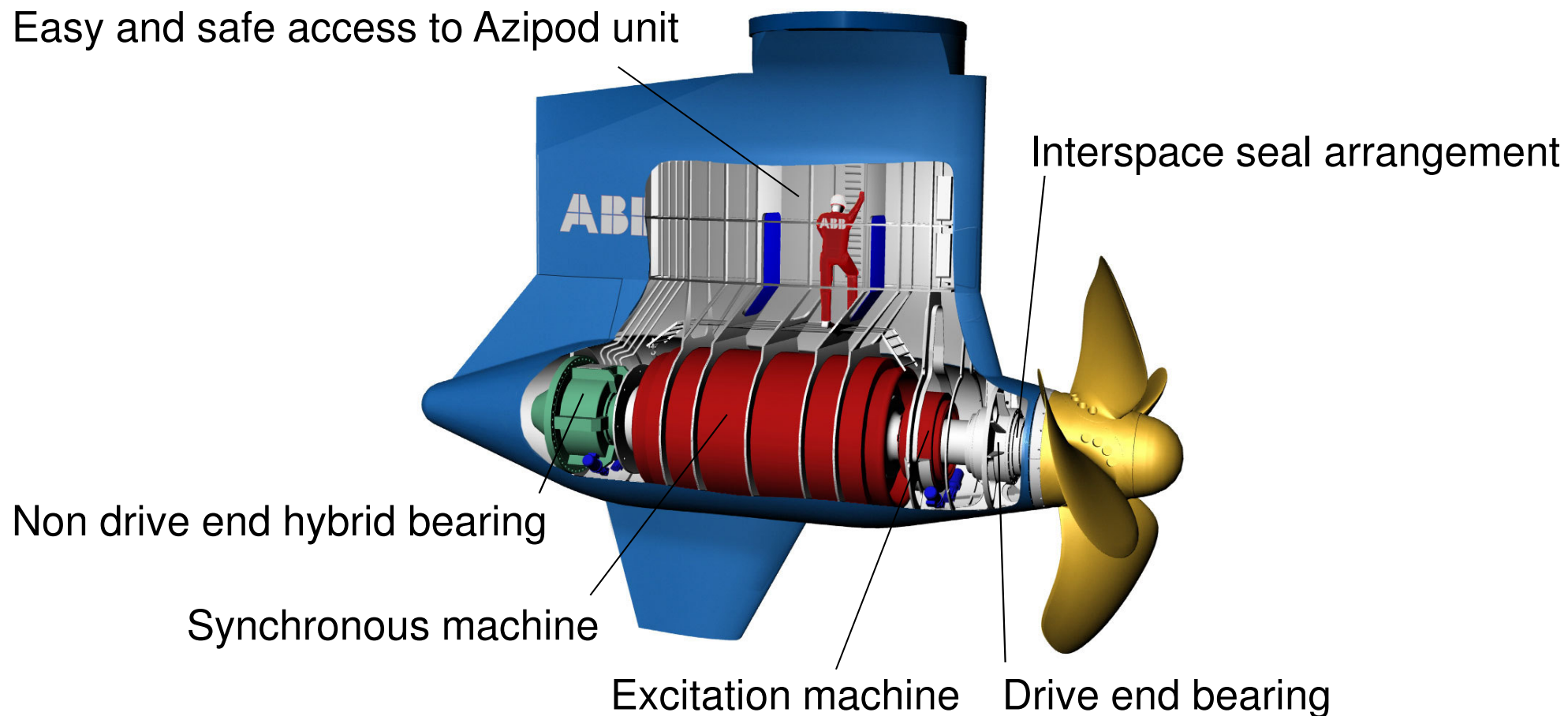


Main Components and new features

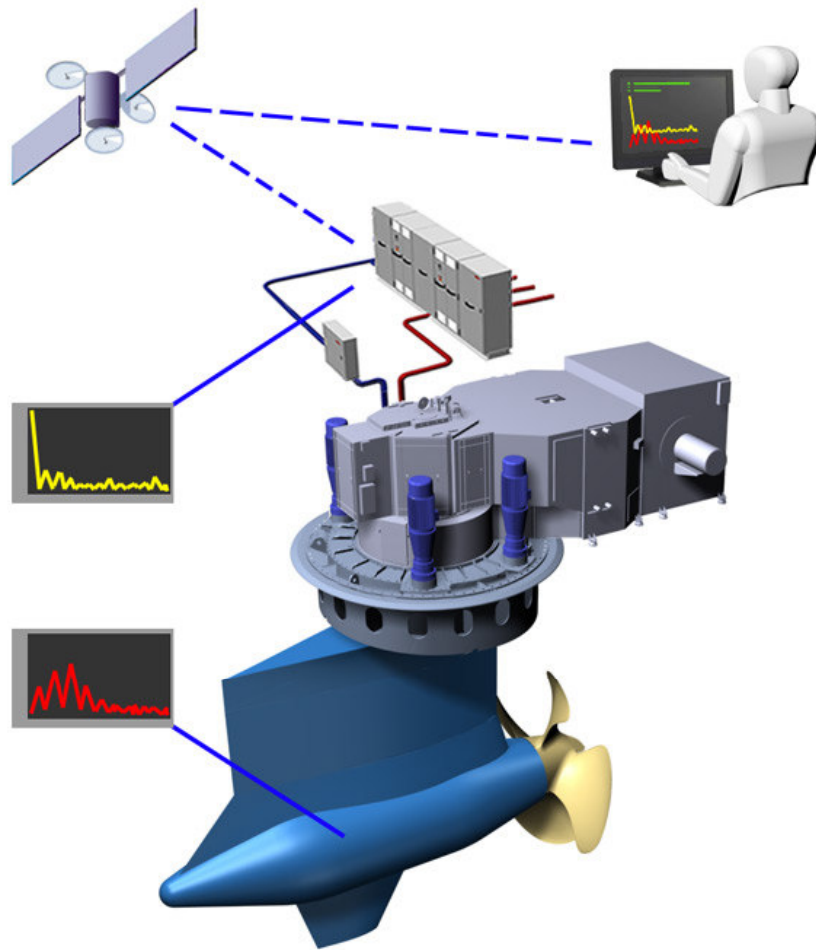
Advanced condition monitoring

Steering torque reduced over 20 %

Easy and safe access to Azipod unit



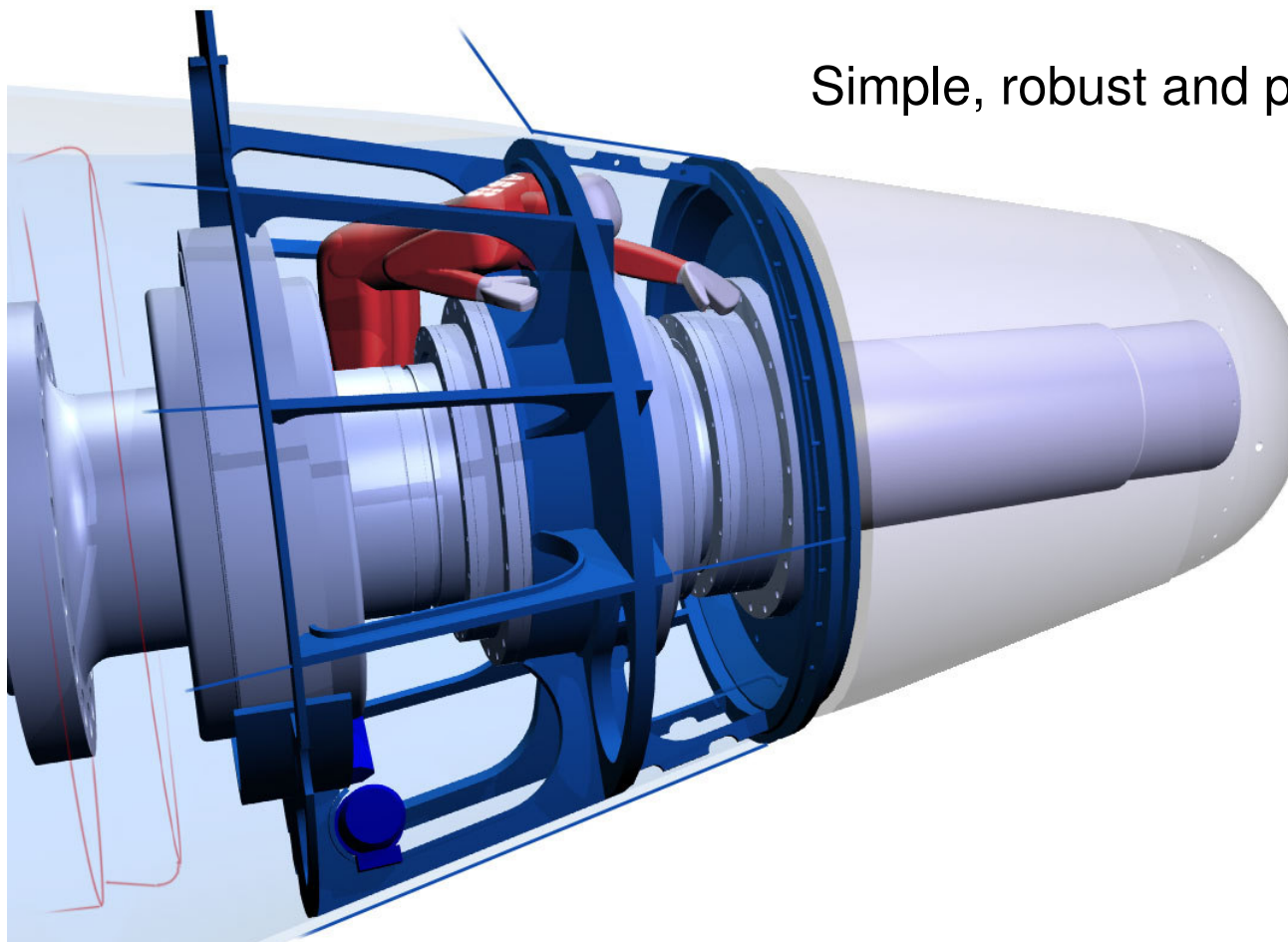
Advanced Condition Monitoring



- Remote Diagnostics
 - Preventive maintenance
 - Troubleshooting
- Monitored Systems
 - Propulsion and steering systems
 - Bearings
 - Seals
 - Lubrication

Interspace - Revolutionary Shaft Seal Arrangement

Seal change possible inside the Azipod unit *)



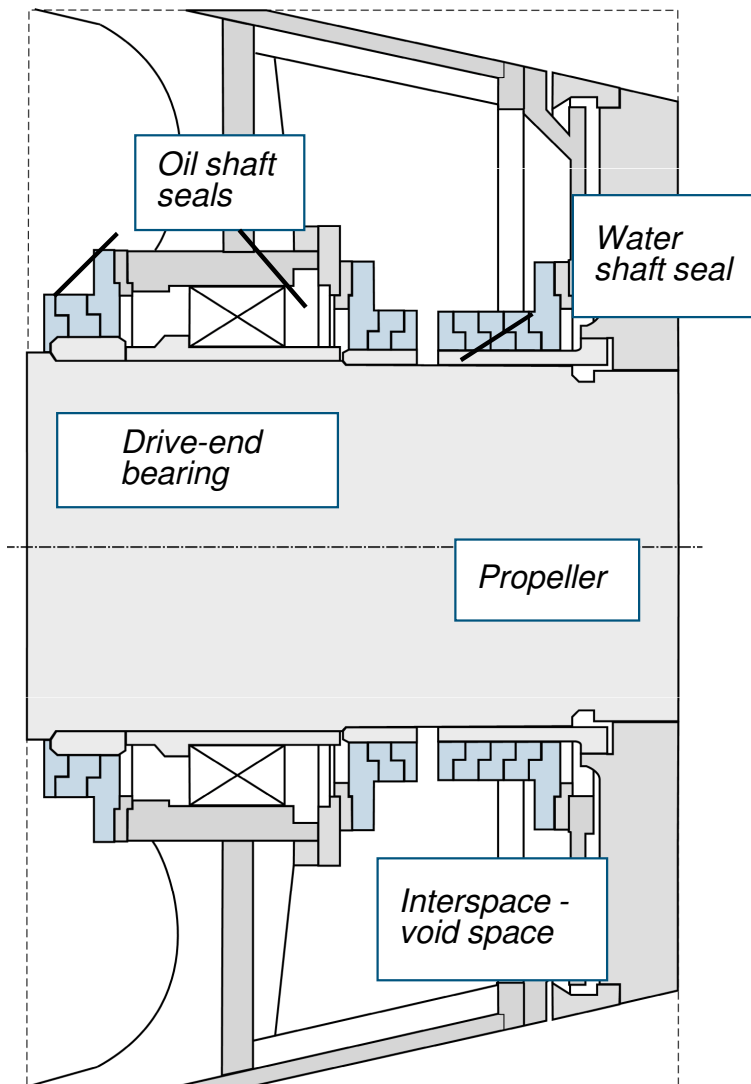
Simple, robust and proven technology

Patent pending

(*) depending on frame size



Interspace - Revolutionary Shaft Seal Arrangement



- Bearing oil seal separated from water seal
- Lubrications optimized for bearing and sealing – long lifetime
- Capacious void space with drainage for occasional leakages
- Designed for maximum reliability
- Designed to operate without harmful external leakages
- Protect the sea – **biodegradable** lubrication

Patent pending

No water to bearing oil – no bearing oil to the sea!

Hybrid Bearing, innovation which combines the advantages of two different types of bearings

Well known and proven technologies

Thrust pad change inside Azipod unit

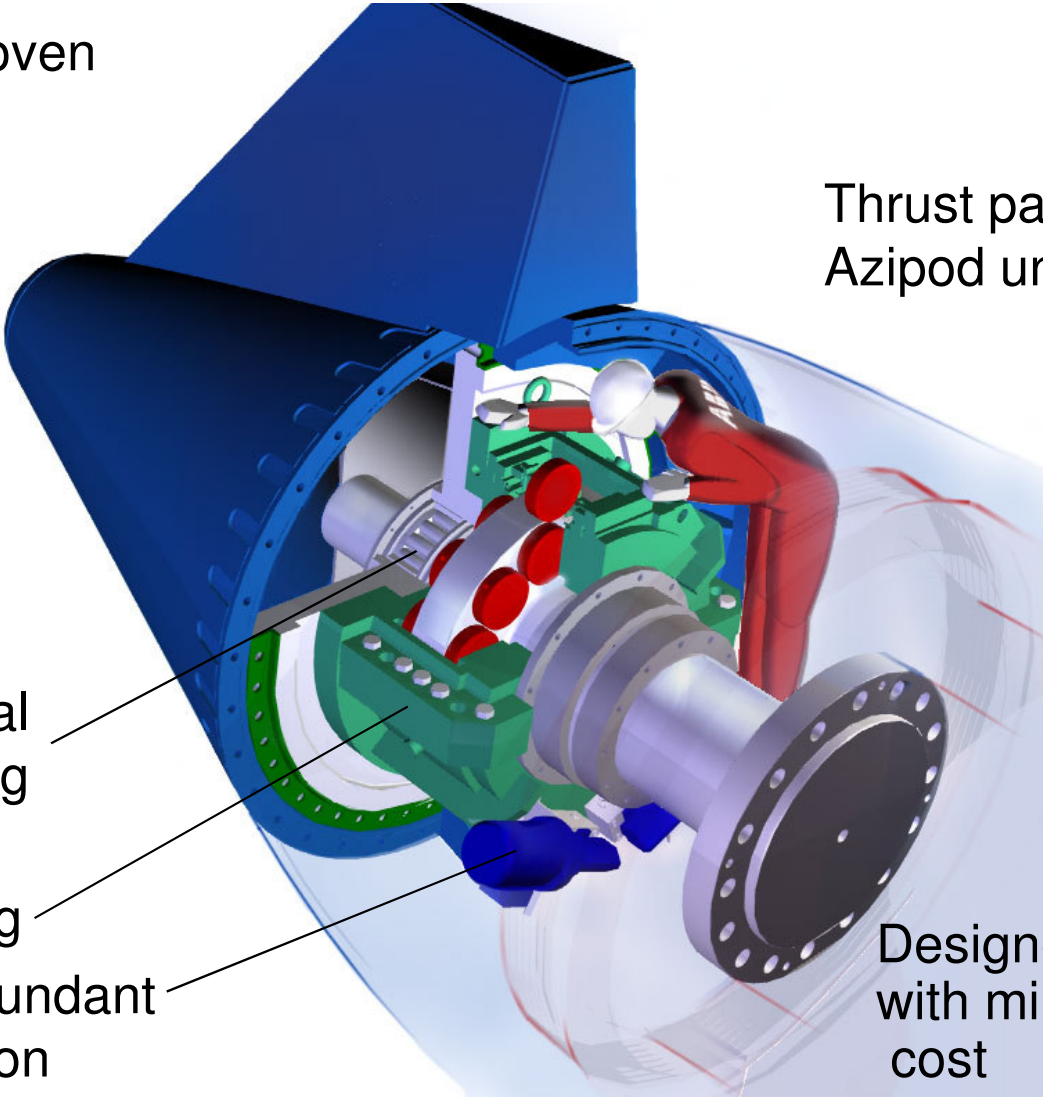
Non-drive-end radial **roller** bearing

Slide thrust bearing

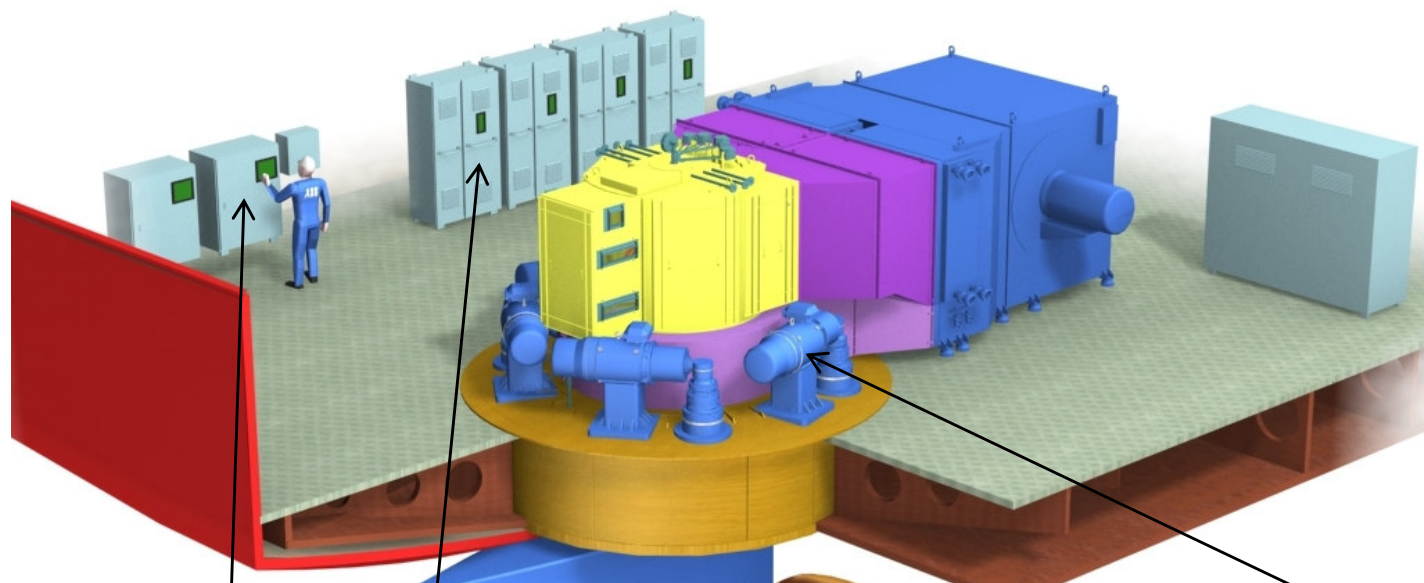
Redundundant lubrication

Designed to be robust with minimum maintenance cost

Patent pending



Electric Steering



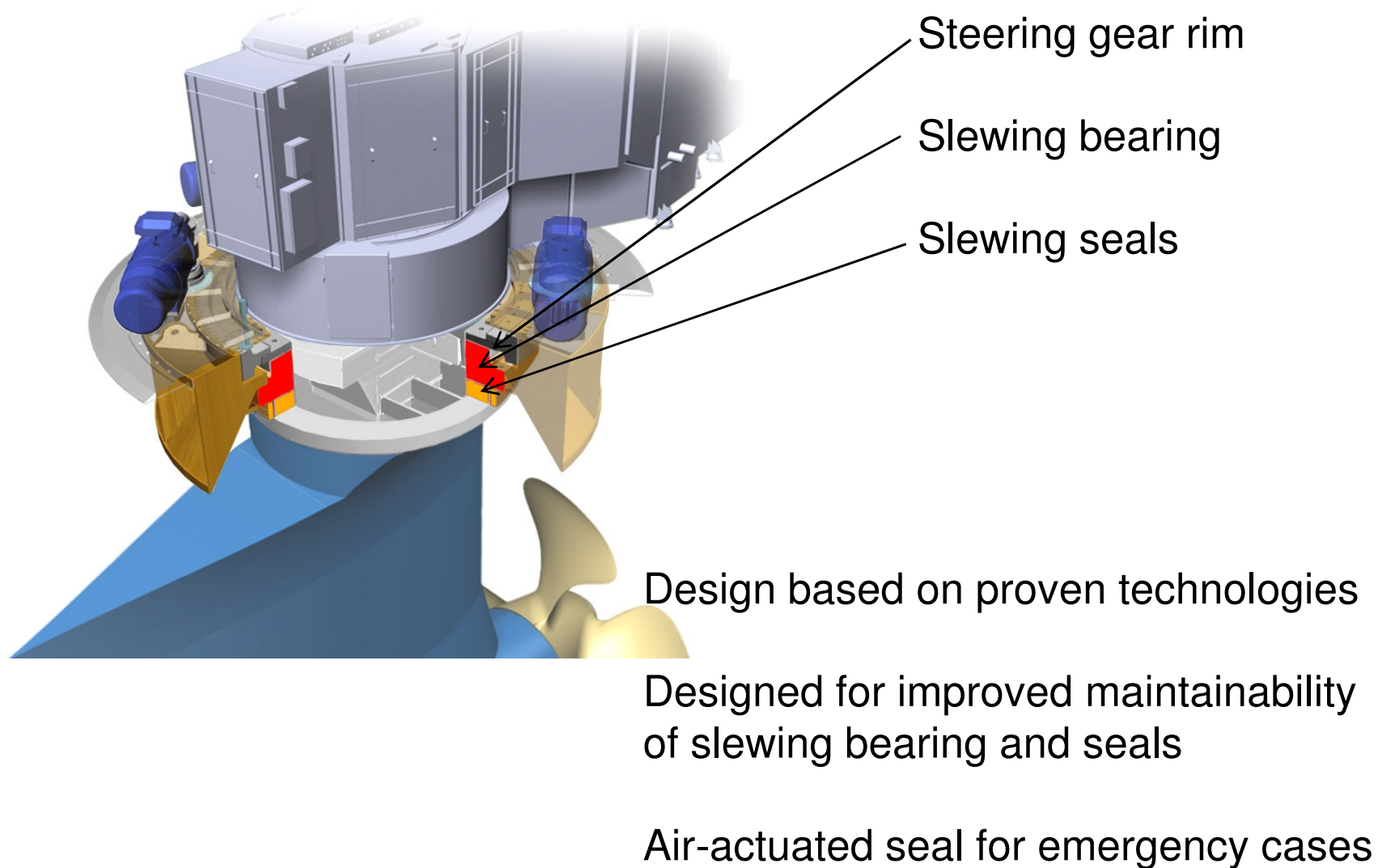
Steering motors

Steering Drives

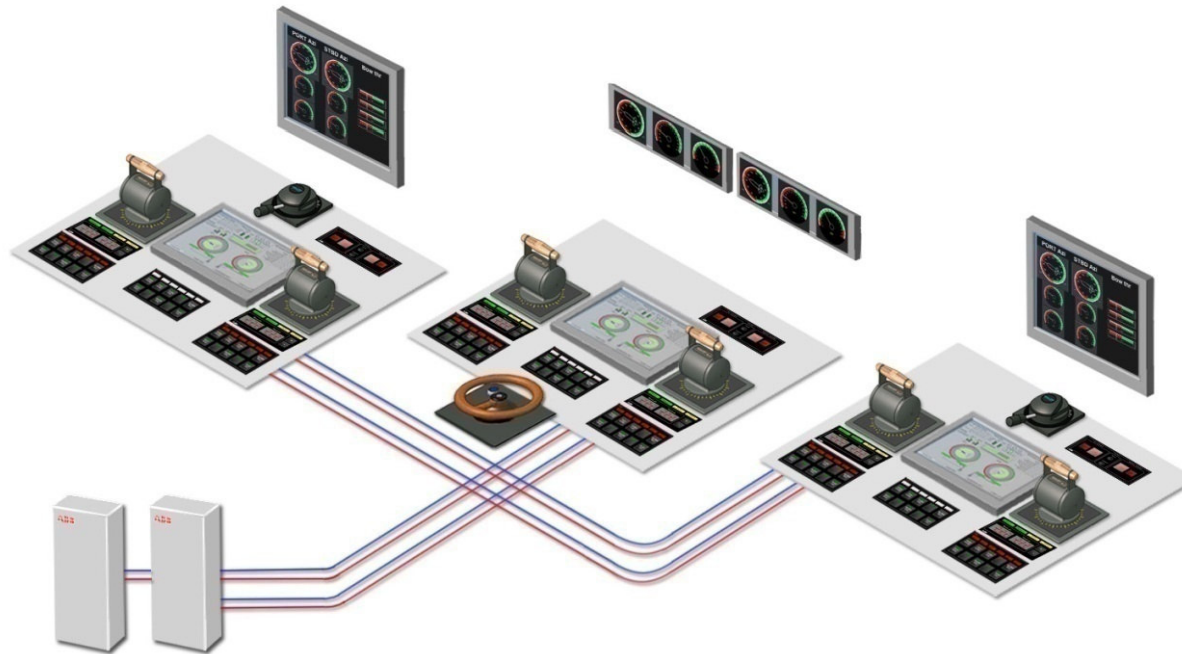
Electric steering control unit

Low noise
Low vibration
Easy Installation
Proven Solution from Azipod® C
Redundant steering drive system
Environmentally friendly

Steering Module



Intelligent Bridge Control Interface, Enhanced usability of Azipod[®] user interface on bridge



- Real time information for optimized operating practices
- Improved presentation of system state for deck officer
- Fieldbus-based modular system architecture

Intelligent Bridge Control Interface

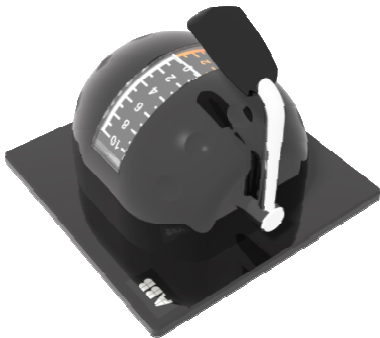
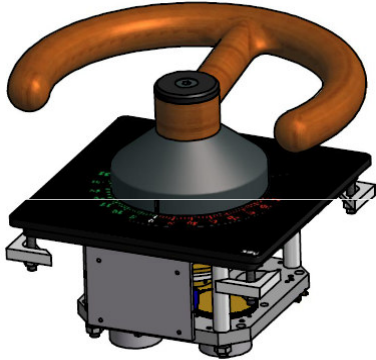
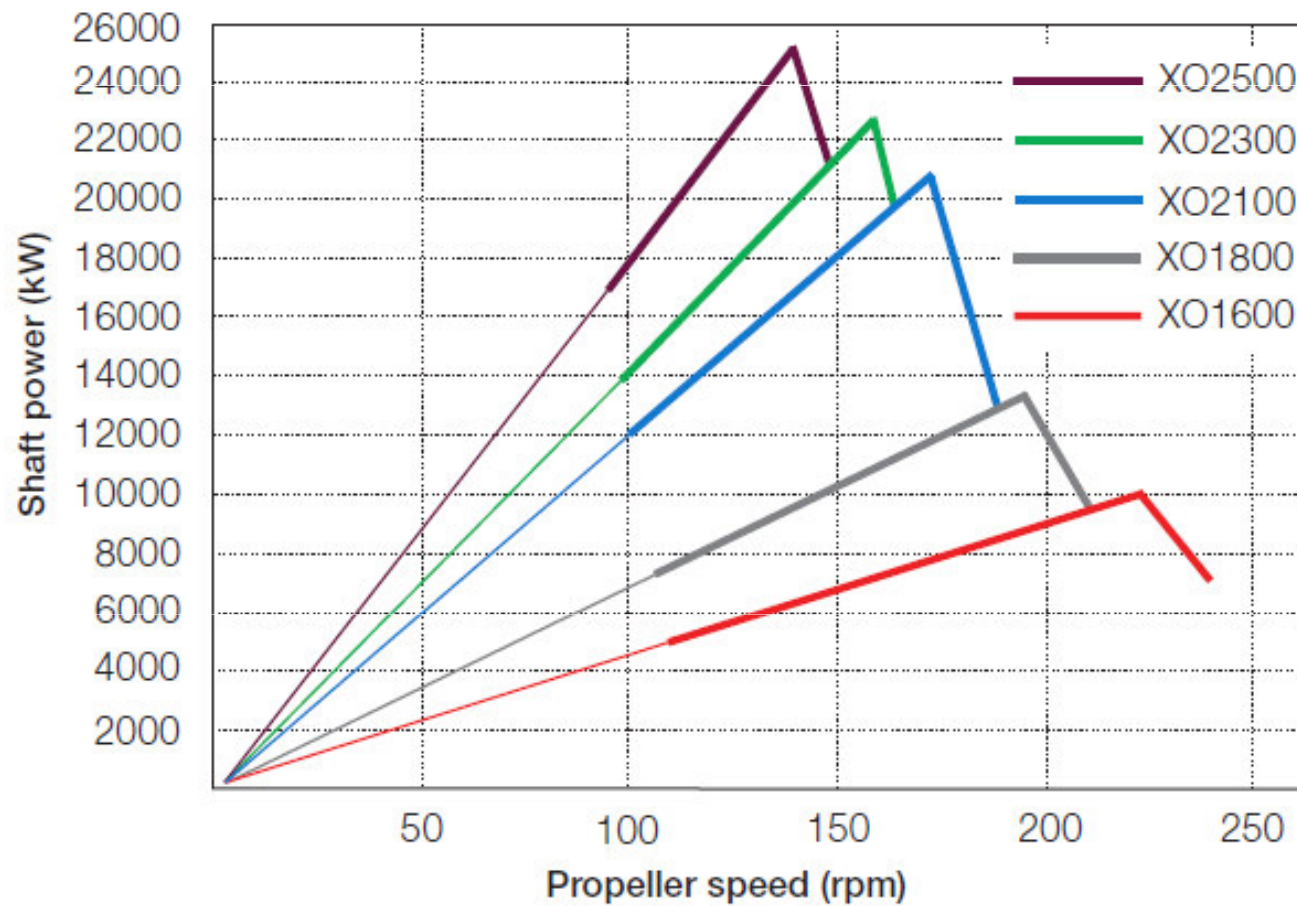


ABB OVERVIEW

Port Control place and mode Thrust: <input type="button" value="Center"/> Place: <input type="button" value="Center"/> Azimuth: <input type="button" value="Azimuth"/> Mode: <input type="button" value="Azimuth"/>		Actual Power 10 MW	Actual Power 11 MW	Starboard Control place and mode Thrust: <input type="button" value="Center"/> Place: <input type="button" value="Center"/> Azimuth: <input type="button" value="Azimuth"/> Mode: <input type="button" value="Azimuth"/>	
Steering Gear <input type="button" value="Running"/> <input type="button" value="Reduced Turning Power"/> <input type="button" value="Steering Brake"/> <input type="button" value="Alarm"/> <input type="button" value="Fault"/> <input type="button" value="Local Backup"/> <input type="button" value="Fast Mode"/>		Power Plant 		Steering Gear <input type="button" value="Running"/> <input type="button" value="Reduced Turning Power"/> <input type="button" value="Steering Brake"/> <input type="button" value="Alarm"/> <input type="button" value="Fault"/> <input type="button" value="Local Backup"/> <input type="button" value="Fast Mode"/>	
Port 				Starboard 	
Propulsion Status: <input type="button" value="Power Limit Active"/> Steering Status: <input type="button" value="Running"/>		PORT STBD RPM Order: <input type="text" value="115"/> <input type="text" value="120"/> RPM Actual: <input type="text" value="114"/> <input type="text" value="120"/>		Propulsion Status: <input type="button" value="Running"/> Steering Status: <input type="button" value="Running"/>	
<input type="button" value="OVERVIEW"/>			<input type="button" value="ADVANCED"/>		

Azipod® XO Product Series



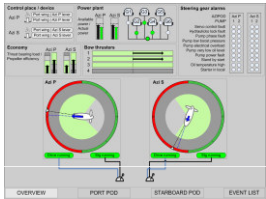
Azipod® X References

Owner	Ship type	Power/ship	Azipod Type
Celebrity Cruises	1 pc Cruise vessel	2 x 17,5 MW	XO 2100
Shin Nihonkai Ferry Co	2 pcs Fast ferries	1 x 12,9 MW	XC 2100
NCL	2 pcs Cruise vessels	2 x 17,5 MW	XO 2100
RCI	2 pc Cruise vessels	2 x 20,5 MW	XO 2300
Aida Cruises	2 pcs Cruise vessels	2 x 14 MW	XO 2100



NCL cruise vessel, picture
by Meyer Werft

Summary for Azipod® XO



- Power up to 20+ MW per unit
- Energy efficient
- Designed for extended docking intervals of future needs
- Electric steering and intelligent control systems
- Optimised maintainability
- Advanced condition monitoring

...Steering to Success!

Power and productivity
for a better world™

