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Supersedes I.L. 41-503M dated May 1975
(|) Denotes Change Since Previous Issue

Type KF Underfrequency Relay



Before putting relays into service, remove all blocking which may have been inserted for the purpose of securing the parts during shipment, make sure that all moving parts operate freely, inspect the contacts to see that they are clean and close properly and operate the relay to check the settings and electrical connections.

1.0 APPLICATION

- | The type KF relay is a high-speed under-frequency relay which provides rapid sensing of system overload so that excessive load can be shed. It is particularly suitable for relatively isolated areas where a severe overload (i.e., more than 50%) could occur due to a tie-line trip.

2.0 CONSTRUCTION AND OPERATION

The relay consists of an induction cylinder unit, frequency sensitive components, indicating contactor switch, and auxiliary time delay unit (T). The principal parts of the relay can be seen in Figure 1 (page 7).

A. Induction Cylinder Unit

The induction cylinder unit is a product type unit operating on the interaction between the fluxes that are produced on the four poles. Mechanically, the induction unit is composed of four basic components; a die cast aluminum frame, an electromagnet, moving element assembly and a molded bridge. The frame serves as a mounting

structure for the magnetic core. The magnetic core which houses the lower pin bearing is secured to the frame by a locking nut. The bearing can be replaced, if necessary, without having to remove the magnetic core from the frame. The electromagnet has four coils mounted on the four poles. The coils mounted diametrically opposite each other are connected in series. The locating pins of the electromagnet are used to accurately position the lower pin bearing, which is mounted on the frame, with respect to the upper pin bearing which is threaded into the bridge. The electromagnet is secured to the frame by four mounting screws.

The moving element assembly consists of a spiral spring, contact carrying member, and an aluminum cylinder assembled to a molded hub which holds the shaft. The shaft has removable top and bottom jewel bearings. The shaft rides between the bottom pin bearing and the upper pin bearing with the cylinder rotating in an air gap formed by the electromagnet and the magnetic core. The stops for the moving element contact arm are in integral part of the bridge.

The bridge is secured to the electromagnet and frame by two mounting screws. In addition to holding the upper pin bearing, the bridge is used for mounting the adjustable stationary contact housing. The stationary contact housing is held in position by a spring type clamp. The spring adjuster is located on the underside of the bridge and is attached to the moving contact arm by a spiral spring. The spring adjuster is also held in place by a spring type clamp. With the contacts closed, the electrical connection is made through the stationary contact housing clamp, to the mov-

All possible contingencies which may arise during installation, operation or maintenance, and all details and variations of this equipment do not purport to be covered by these instructions. If further information is desired by purchaser regarding this particular installation, operation or maintenance of this equipment, the local ABB representative should be contacted.

ing contact, through the spiral spring out to the spring adjuster clamp.

B. Indicating Contactor Switch Unit (ICS)

The indicating contactor switch is a small dc operated clapper type device. A magnetic armature, to which leaf-spring mounted contacts are attached, is attracted to the magnetic core upon energization of the switch. When the switch closes, the moving contacts bridge two stationary contacts, completing the trip circuit. Also during this operation two fingers on the armature deflect a spring located on the front of the switch which allows the operation indicator target to drop. The target is reset from the outside of the case by a push rod located at the bottom of the cover.

The front spring, in addition to holding the target, provides restraint for the armature and thus controls the pickup value of the switch.

C. Frequency Sensitive Components:

The frequency sensitive components consist of capacitors and a variable reactor which is used for setting the relay to trip at the desired frequency.

D. Auxiliary Time Delay Unit

1. AC Operation - Non-Adjustable

This slugged telephone type relay in conjunction with a resistor, capacitor and full wave bridge provides time delay on pick-up when the KF relay contacts close. The contacts of the auxiliary time delay unit are connected in the trip circuit.

2. AC Operation - Adjustable

This telephone relay in conjunction with a static timing circuit and full wave bridge provides adjustable time delays (i.e. 6 cycles to 30 cycles) or pickup when the KF relay contacts close. The contacts of the auxiliary time delay unit are connected in the trip circuit.

3. DC Operation

This telephone relay in conjunction with a static timing circuit provides adjustable time delays (i.e. 6 cycles to 30 cycles) on pickup when the KF relay contacts close. The contacts of the auxiliary time delay unit are connected in the trip circuit.

3.0 CHARACTERISTICS

The KF relay operates to close its contacts when the applied source frequency is below a preset value. The operating characteristic curves for the various auxiliary time delay settings for changing frequency conditions is shown in Figure 5 (page 9).

3.1 RATING

The type KF underfrequency relay is rated 120 volts at 60 hertz, or 120 volts at 50 hertz. The adjustable range of frequency is 55 to 59.5 hertz for the 60 hertz relay and 44 to 49.5 for the 50 hertz.

3.2 TRIP CIRCUIT

The main contacts will close 30 amperes at 250 volts dc and the seal-in contacts of the indicating contactor switch will safely carry this current long enough to trip a circuit breaker. The indicating contactor switch has two taps that provide a pickup setting of 0.2 or 2 amperes. To change taps requires connecting of lead located in front of the tap block to the desired setting by means of screw connection.

3.3 TIME DELAY

KF with DC Timer - 6 to 30 cycles (adjustable)

KF with AC Timer - 6 to 30 cycles (adjustable)

KF with AC Timer - 6 cycles (non-adjustable)

3.4 TRIP CIRCUIT CONSTANTS

Indicating Contactor Switch -

0.2 amp tap 6.5 ohms dc resistance

2.0 amp tap 0.15 ohms dc resistance

3.5 ENERGY REQUIREMENTS

Relay Type	Voltage AC 60 Hz	Timer Condition	Burden
KF with DC Timer	120	N/A	14.7VA
KF with Adjustable AC Timer	120	Energized De-Energized	29.4VA 14.7VA
KF with Non-Adjustable AC Timer	120	Energized De-Energized	20.4VA 14.7VA

4.0 SETTINGS

4.1 FREQUENCY

The relay is set for trip frequency by means of the reactor adjusting screws. The relays are calibrated to trip at 1/2 hertz below rated frequency unless otherwise specified. Turning either of the adjusting screws in a clockwise direction decreases the frequency at which the relay trips. The rate of change of frequency at which the relay trips. The rate of change of frequency per second versus hertz below trip frequency at contact closure is shown in Figure 5 (page 9) for various time delays.

4.2 INDICATING CONTACTOR SWITCH (ICS)

The only setting of the ICS unit required is the selection of the 0.2 ampere pick-up tap. This is accomplished by connecting the lead located in the front of the tap block to the desired terminal by means of a connecting screw. When the relay energizes a 125 or 250 volt type WL relay switch, or equivalent, use the 0.2 ampere tap; for a 48 volt dc applications set the unit in a tap 2 and use a type WL relay with a S#304C209G01 coil, or equivalent. The relay is shipped set for 2.0 tap.

4.3 DC TAP

In the KF relay with dc operated auxiliary time delay unit, selection of the 125 or 48 volt tap must be made on resistor R2 depending on the battery voltage.

5.0 INSTALLATION

The relays should be mounted on switchboard panels or there equivalent in a location free from dirt, moisture, excessive vibration and heat. Mount the relay vertically by means of the mounting stud for the type FT projection case or by means of the four mounting holes on the flange for the semi-flush type FT case. Either the stud or the mounting screws may be utilized for grounding the relay. The electrical connections may be made directly to the terminals by means of screws for steel panel mounting or to the terminal stud furnished with the relay for thick panel mounting. The terminal stud may be easily removed or inserted by locking two nuts on the stud and then turning the proper nut with a wrench.

For detailed information on the FT case, refer to I.L. 41-076.

6.0 ADJUSTMENTS AND MAINTENANCE

The proper adjustments to insure correct operation of this relay have been made at the factory. Upon receipt of the relay no customer adjustments, other than those covered under "Settings" should be required.

6.1 ACCEPTANCE CHECK

The following check is recommended to insure that the relay is in proper working order.

A. Induction Cylinder Unit

Contact Gap - The gap between the stationary contact and the moving contact with the relay in the deenergized position should be approximately 1/16 inch.

B. Frequency Adjusting Reactor

1. Minimum Trip - Using a variable frequency source apply 120V at rated frequency for 1 hour to allow the relay to reach normal operating temperature. Apply 120V at the specified trip frequency to the relay. The contacts should just close. If no other trip frequency has been specified the relays are calibrated to trip at 59.5 hertz, for the 60 hertz relay and 49.5 hertz for the 50 hertz relay.
2. Reduce voltage to 40 volts. Check calibration. The cylinder unit contacts should close 0.06 to 0.08 hertz above the trip frequency.

C. Indicating Contactor Switch

Close the auxiliary time delay unit contacts and pass sufficient dc current through the trip circuit to close the contacts of the ICS. This value of current should not be greater than the particular ICS tap setting being used. The indicator target should drop freely.

The contact gap should be approximately 0.047" between the bridging moving contact and the adjustable stationary contacts. The bridging moving contact should touch both stationary contacts simultaneously.

D. Auxiliary Time Delay Unit (T)

1. AC operation - Non-adjustable
Block cylinder unit contacts closed. Apply 50 volts ac to terminals 8 and 9 of the KF relay. The T unit should operate. Reduce voltage to approximately 20 volts ac. The T unit should drop out. At rated voltage the time delay obtained from the telephone relay should be 6 cycles. Time vs voltage curve is shown in Figure 9 (page 10).
2. AC Operation - Adjustable
Block cylinder unit contacts closed. Apply 50 volts ac to terminals 8 and 9 of the KF relay. The T unit should operate. Reduce voltage to approximately 15 volts ac and the T unit should drop out. At rated voltage the time delay obtained should be 6 cycles. The timer can be set to provide up to 30 cycles delay by adjusting the rheostat located on the rear sub base. (See Figure 1, page 7). Time vs voltage curves are shown in Figure 9 (page 10).
3. DC Operation
Energize terminals 10 and 4 with rated dc voltage. Place switch across KF relay contacts. Closing the switch will now energize the timing circuit. The time delay obtained from the telephone relay should be 6 cycles. The timer can be set to provide up to 30 cycles delay by adjusting the rheostat located on the relay sub base. See Figure 1 (page 7).

6.2 ROUTINE MAINTENANCE

All relays should be inspected and checked periodically to assure proper operation. Generally a visual inspection should call attention to any noticeable changes. A minimum suggested check on the relay system is to close the contacts manually to assure that the breaker trips and the target drops. Then release the contacts and observe that the reset is smooth and positive.

All contacts should be periodically cleaned. A contact burnisher S#182A836H01 is recommended for this purpose. The use of abrasive material for cleaning contacts is not recommended, because of the danger of embedding small particles in the face of the soft silver and thus impairing the contact.

6.3 CALIBRATION

Use the following procedure for calibrating the relay if the relay has been taken apart for repairs or the adjustments have been disturbed. This procedure should not be used unless it is apparent that the relay is not in proper working order. (See "Acceptance Check").

A. Induction Cylinder Unit

1. The upper pin bearing should be screwed down until there is approximately 0.025" clearance between it and the top of shaft bearing. The upper pin bearing should then be securely locked in position with the lock nut. The lower bearing position is fixed and cannot be adjusted.
2. The contact gap adjustment for the cylinder unit is made as follows:

With the moving contact in the normally opened position, that is, against the right stop on the bridge, screw in the right hand stationary contacts until it just makes with the moving contact. Then advance the stationary contact an additional 1/4 turn. Screw the top hand stationary contact until it just touches the moving contact then back off the stationary contact two turns for a gap of 1/16 of an inch. The clamp holding the stationary contact need not be loosened for this adjustment, since the clamp utilizes a spring-type action in holding the stationary contact in position.

The set screw in the stationary contacts has been shop adjusted for optimum follow and this adjustment should not be disturbed.

The moving contact assembly has been factory adjusted for low contact bounce performance and should not be changed.

3. The sensitivity adjustment is made by varying the tension of the spiral spring attachment to the moving element assembly. The spring is adjusted by placing a screwdriver or similar tool into one of the notches located on the periphery of the spring adjuster and rotating it. The spring adjuster is located on the underside of the bridge and is held in place by a spring type clamp that does not have to be loosened prior to making the necessary adjustments.

The spring is to be adjusted such that when the relay is deenergized the moving contact just resets. Then move the spring adjuster 3/16 of a turn in the same direction.

B. Frequency Adjusting Reactor

The relay should be preheated for 1 hour with 120 volts and rated frequency before calibration is attempted. A source of variable frequency is required and should be connected to terminals 8 and 9 of the relay.

Set the source frequency to 59.5 hertz and adjust the frequency adjusting screws (See Figure 1) until the cylinder unit contact closes to the left. Reduce voltage to 40 volts and raise frequency to 59.57 hertz. Adjust control spring so that cylinder unit contact just closes to the left. Raise voltage to 120 volts and recheck 59.5 settings. Adjust frequency adjusting screws if necessary. Recheck 40 volt setting, it should be between 59.56 and 59.58 hertz. Repeat above procedure if necessary until relay contacts are made between the frequency limits.

C. Indicating Contactor Switch (ICS)

Close the auxiliary time delay unit (T) contact and pass sufficient dc current through the trip circuit to close the contacts of the ICS. This value of current should not be greater than the particular ICS tap setting being used. The indicator target should drop freely.

D. Auxiliary Time Delay Unit

1. AC Operation - Non-Adjustable

Block the KF relay contacts closed. Energize terminals 8 and 9 of the relay with rated voltage and frequency. Time the closing of the telephone relay contacts. This time should be 6 cycles.

2. AC Operation - Adjustable

Block the KF relay contacts closed. Energize terminals 8 and 9 of the relay with rated voltage and frequency. Time the closing of the telephone relay contacts. This time can be set over the range of 6 to 30 cycles utilizing the rheostat located on the rear sub-base (See Figure 1).

3. DC Operation - Adjustable

Energize terminals 10 and 4 with rated dc voltage. Place switch across KF relay contacts. Close switch and time the closing of the telephone relay contacts. Adjust rheostat on rear sub base for desired time delay. This time can be set over the range of 6 to 30 cycles utilizing the rheostat located on the rear sub-base (See Figure 1).

7.0 RENEWAL PARTS

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. When ordering parts, always give the complete nameplate data and styles from the electrical parts list

ELECTRICAL PARTS LIST

CIRCUIT SYMBOL		REFERENCE	STYLE
FREQUENCY SENSING CIRCUIT - FIGURES 2, 3, 4			
RESISTOR – R1		750 ohm, 25 W, $\pm 5\%$	1267285
CAPACITORS – Reactor Leg		.225 MFD, 750 VAC, $\pm 3\%$	606B340H07
Resistor Leg		2.0 MFD, 330 VAC, $\pm 3\%$	606B34H04
Reactor			290B179G04
AC FIXED 6 CYCLE TIMER - FIGURE 2			
RESISTOR (R2)		1600 ohm, 25W $\pm 5\%$	1267294
CAPACITORS – (3 In Parallel)		68 MFD, 35V, $\pm 20\%$	187A508H02
DIODES – (Bridge)		1N4821	188A342H16
TELEPHONE RELAY (T)			541D231H14
AC ADJUSTABLE 6 TO 30 CYCLE TIMER - FIGURE 3			
RESISTOR – (R2)		750 ohm, 25W, $\pm 5\%$	1267285
POTENTIOMETER		25 K ohm, 2 W, $\pm 10\%$	541D514H10
TELEPHONE RELAY (T)			541D514H10
CIRCUIT BOARD ASSEMBLY – STYLE 691B2G01			
CAPACITORS – C1		47 MFD, 35V, $\pm 20\%$	184A661H03
C2, C3, C5		6.8 MFD, 35 V, $\pm 5\%$	184A661H21
C4		0.1 MFD, 50 V, $\pm 20\%$	184A663H04
DIODES – D1, D2, D3, D4		1N5053	188A342H12
D5, D6, D7, D8, D9		1N645A	837A692H03
RESISTORS – R1, R11		3.3 K 1/2 W, $\pm 5\%$	184A763H39
R2		100 ohm, 1/2 W, $\pm 5\%$	184A763H03
R3		33 ohm, 1/2 W, $\pm 5\%$	187A290H13
R4		15 K ohm, 1/2 W, $\pm 5\%$	184A763H55
R5, R6		10 K ohm, 1/2 W, $\pm 5\%$	184A763H51
R7		470 ohm, 1/2 W, $\pm 5\%$	184A763H19
TRANSFORMERS – T1		H62, UTC	629A453H01
TRANSISTORS – Q1		2N2647, UJT	629A435H01
Q2		2N34127, NPN	848A851H02
Q3		2N3645, PNP	848A851H01
ZENER DIODES – Z1		1N2986B, 24 V, $\pm 5\%$	629A798H03
DC ADJUSTABLE 6 TO 30 CYCLE TIMER – FIGURE 4			
RESISTOR (R2)		420-2000 ohm, 25W, $\pm 5\%$	11D9511H08 ○
			11D9511H06 □
POTENTIOMETER		10 K ohm, 2W, $\pm 10\%$	185A067H02
TELEPHONE RELAY (T)			541D514H10 ○
			541D514H32 □
CIRCUIT BOARD ASSEMBLY – STYLE 878A418G01			
CAPACITORS – C1		47 MFD, 35 V, $\pm 20\%$	184A661H03
C2		47 MFD, 35 V, $\pm 5\%$	862A177H06
DIODES – D1, D2, D3, D4		1N645A	837A692H03
RESISTORS – R1		10 K ohm, 1/2 W, $\pm 5\%$	184A763H51
R2		1.2 ohm, 1/2 W, $\pm 5\%$	184A763H29
R3		680 K ohm, 1/2 W, $\pm 5\%$	184A763H23
R4		1.5 K ohm, 1/2 W, $\pm 5\%$	184A763H31 ○
		700 K ohm, 1/2 W, $\pm 5\%$	763A127H28 □
TRANSISTORS – Q1		2N4249, PNP	849A441H03
Q2		2N2647, UJT	629A435H01
ZENER DIODES – Z1		1N2989B, 30 V, $\pm 5\%$	629A798H01

○ = Old □ = New

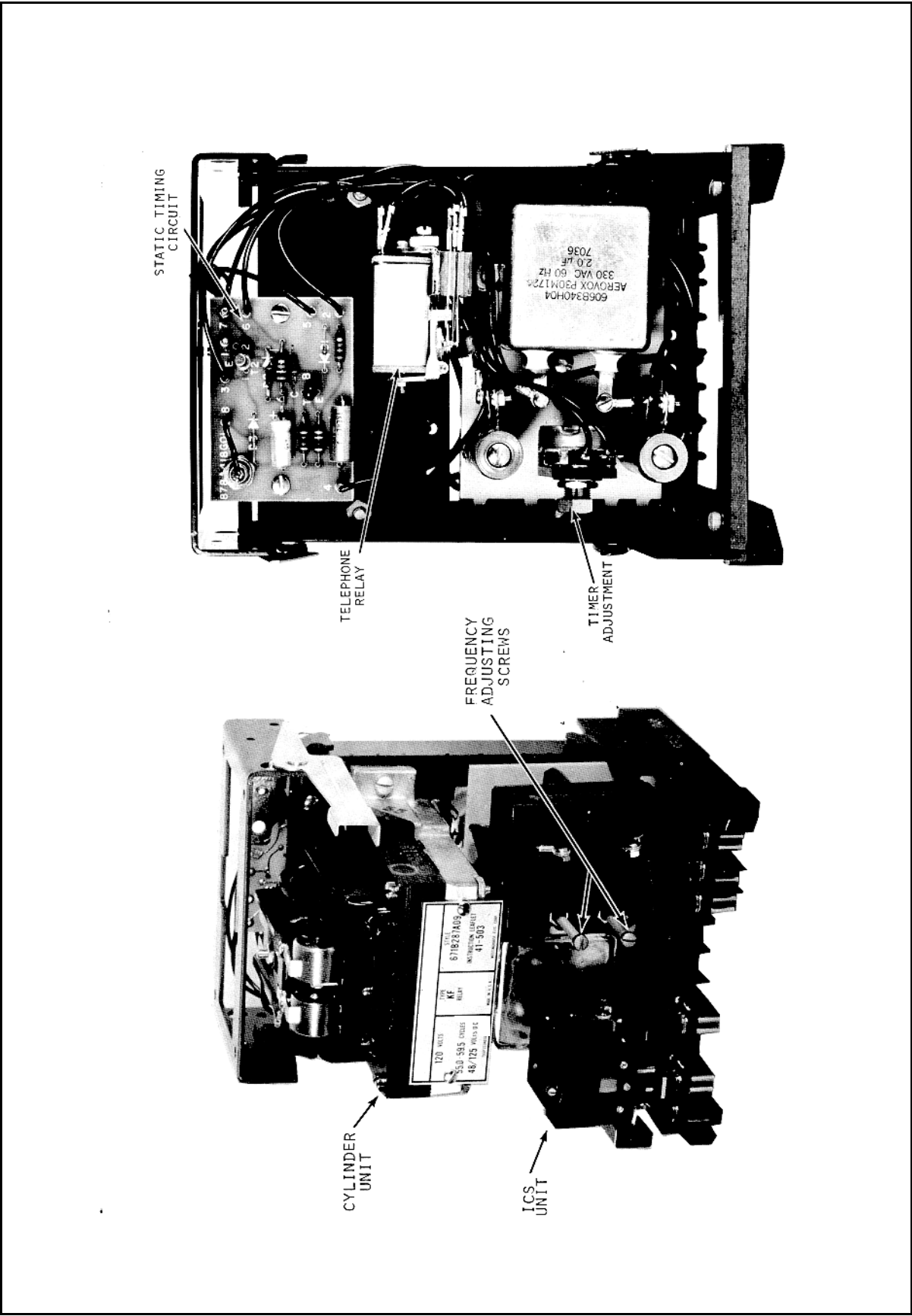


Figure 1: Type KF Relay for 60 Hertz without Case. (Front and Rear View)

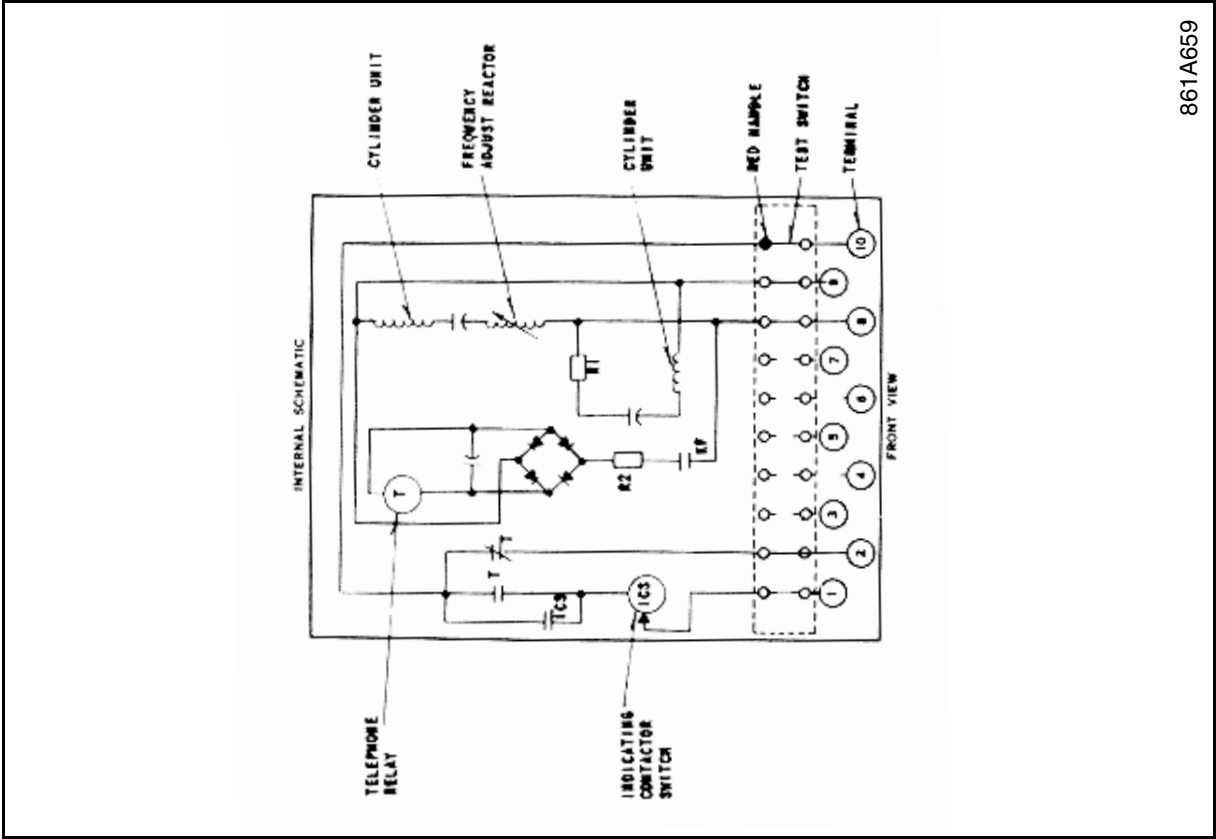


Figure 2: Internal Schematic of Type KF Relay with ac Operated Auxiliary Time Delay Unit

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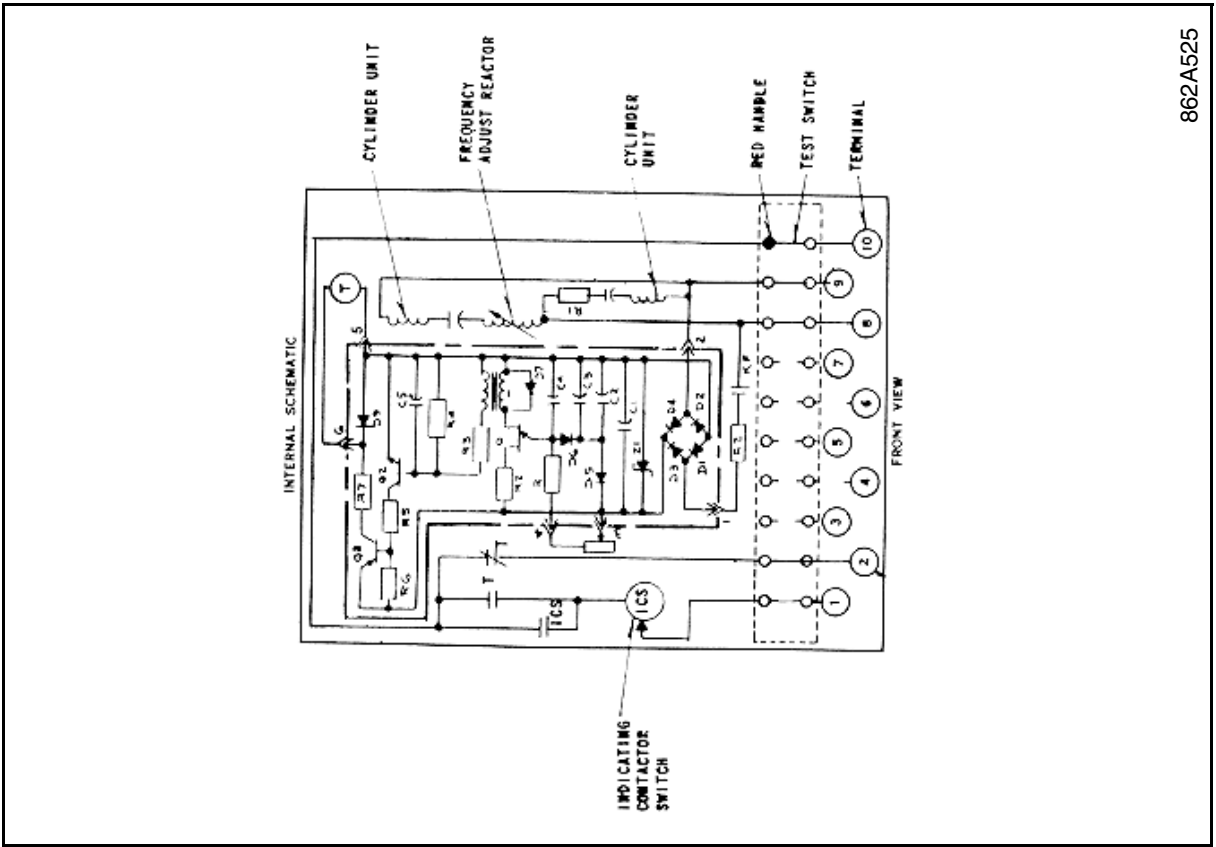


Figure 3: Internal Schematic of Type KF Relay with ac Operated Adjustable Auxiliary Time Delay Unit

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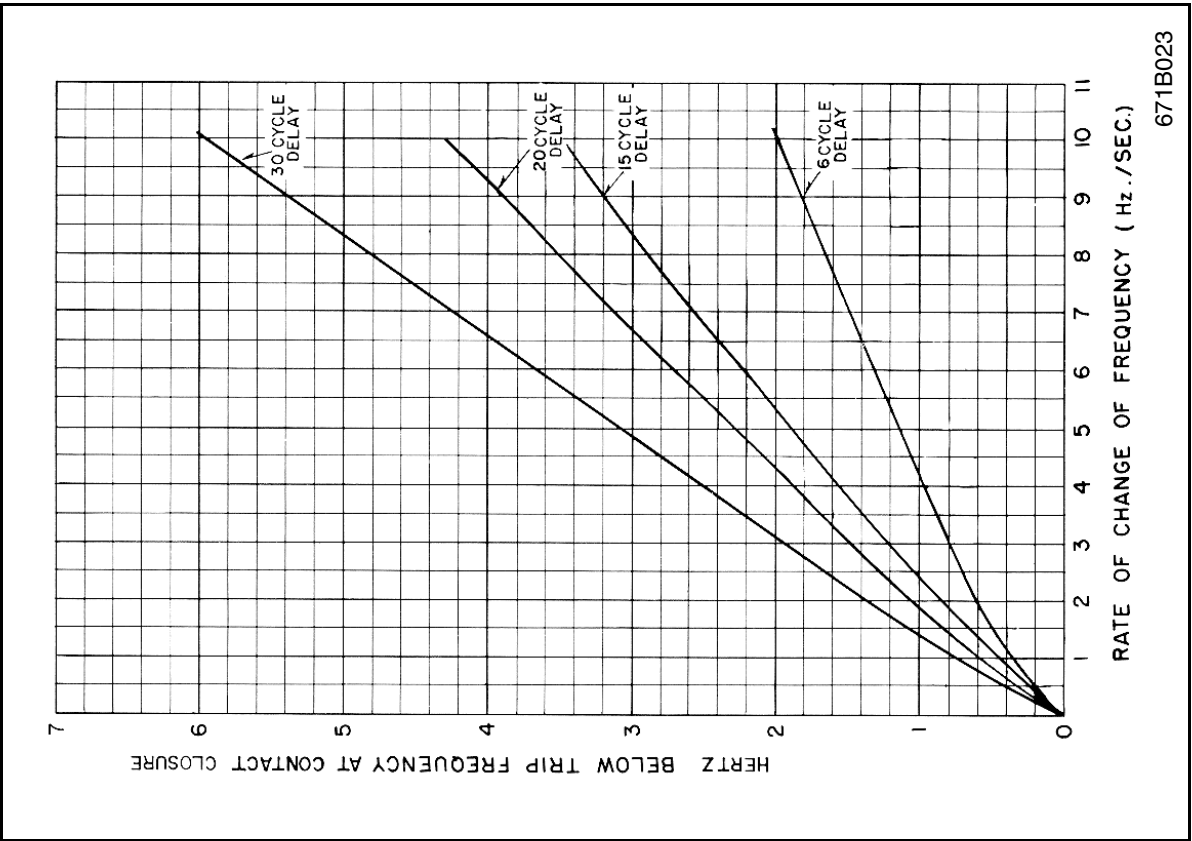


Figure 5: Operating Characteristics of Type KF Underfrequency Relay for Changing Frequency Conditions

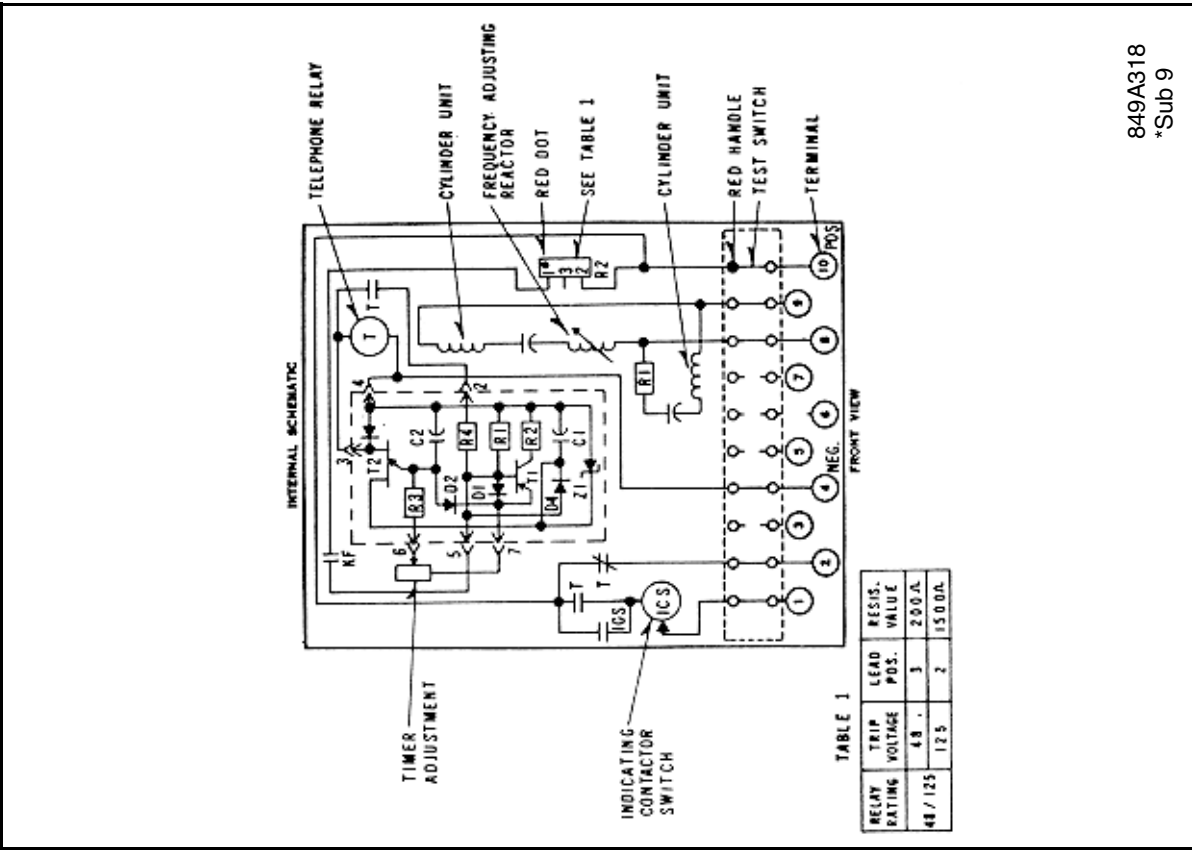


Figure 4: Internal Schematic of Type KF Relay with dc Operated Adjustable Auxiliary Time Delay Unit

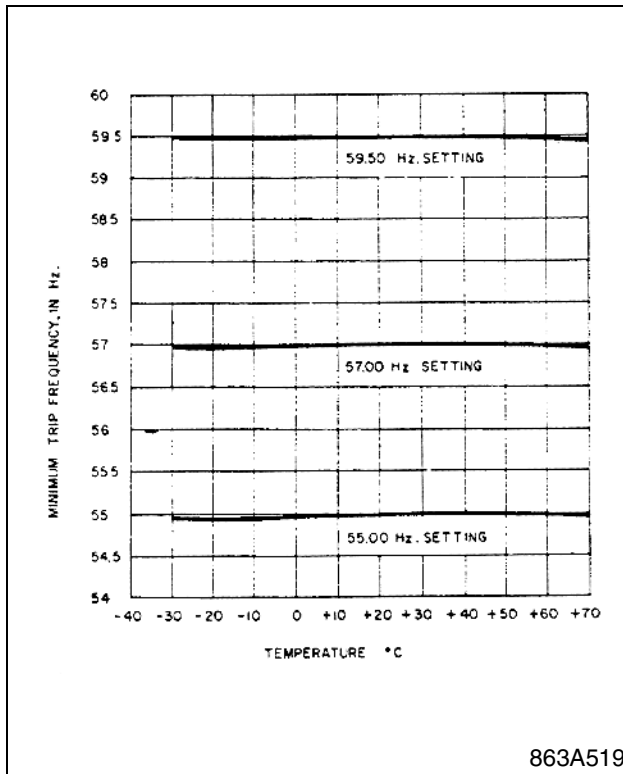


Figure 6: Typical Temperature vs. Minimum Frequency Curves 60 Hertz KF Underfrequency Relay

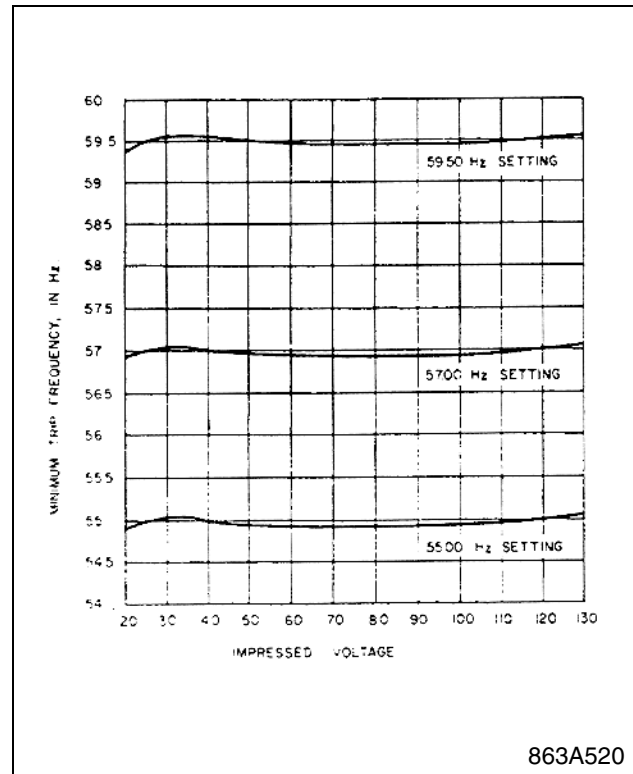


Figure 7: Typical Voltages vs. Minimum Frequency Curves 60 Hertz KF Underfrequency Relay

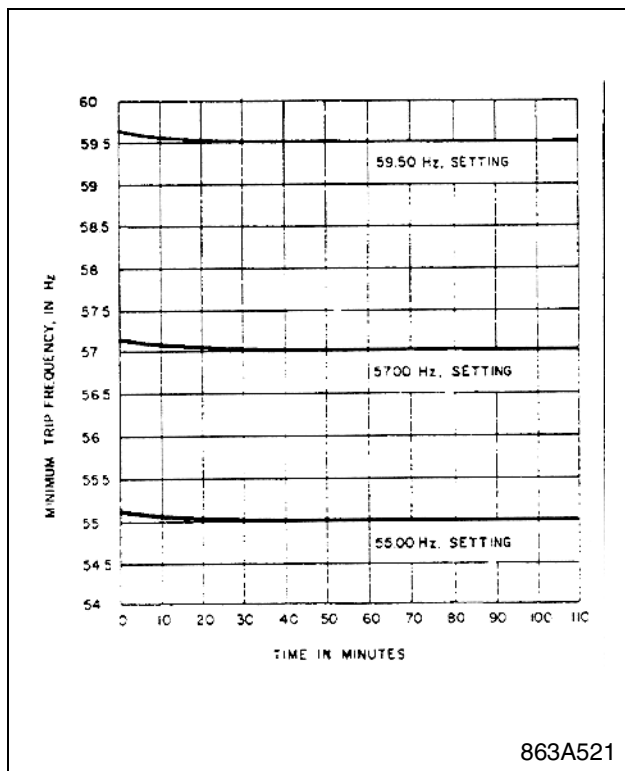


Figure 8: Warm-up Curve 60 Hertz KF Underfrequency Relay

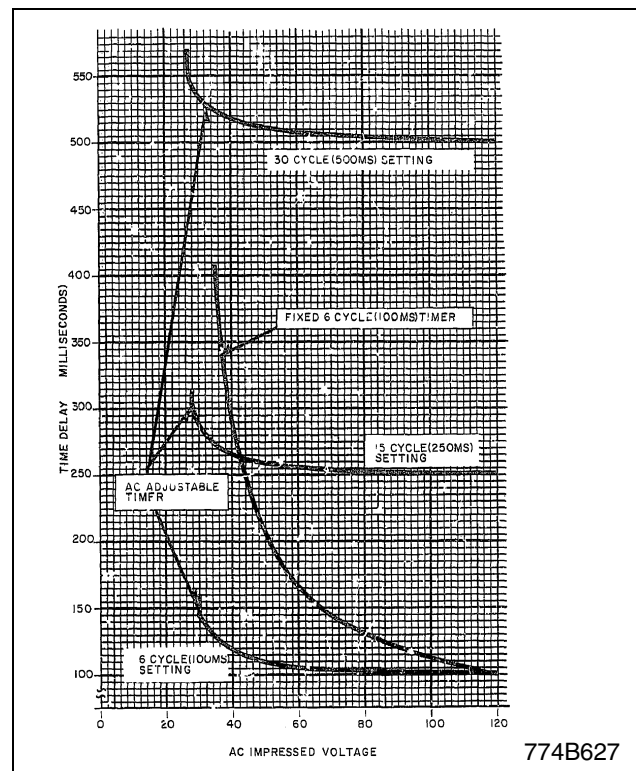


Figure 9: Typical Time Delay vs. Impressed AC Voltage

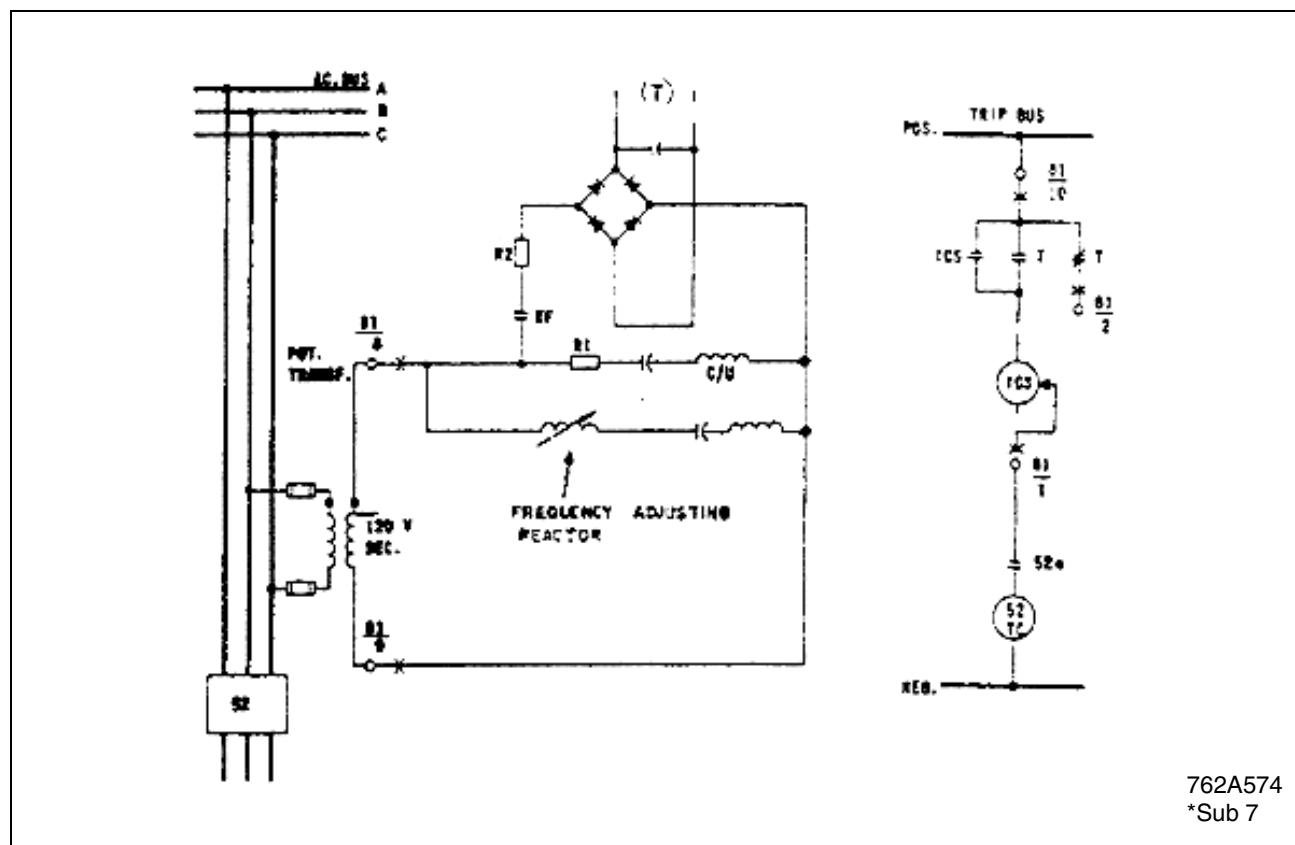


Figure 10: External Connections for the Type KF Underfrequency Relay with ac Operated Auxiliary Time Delay Unit

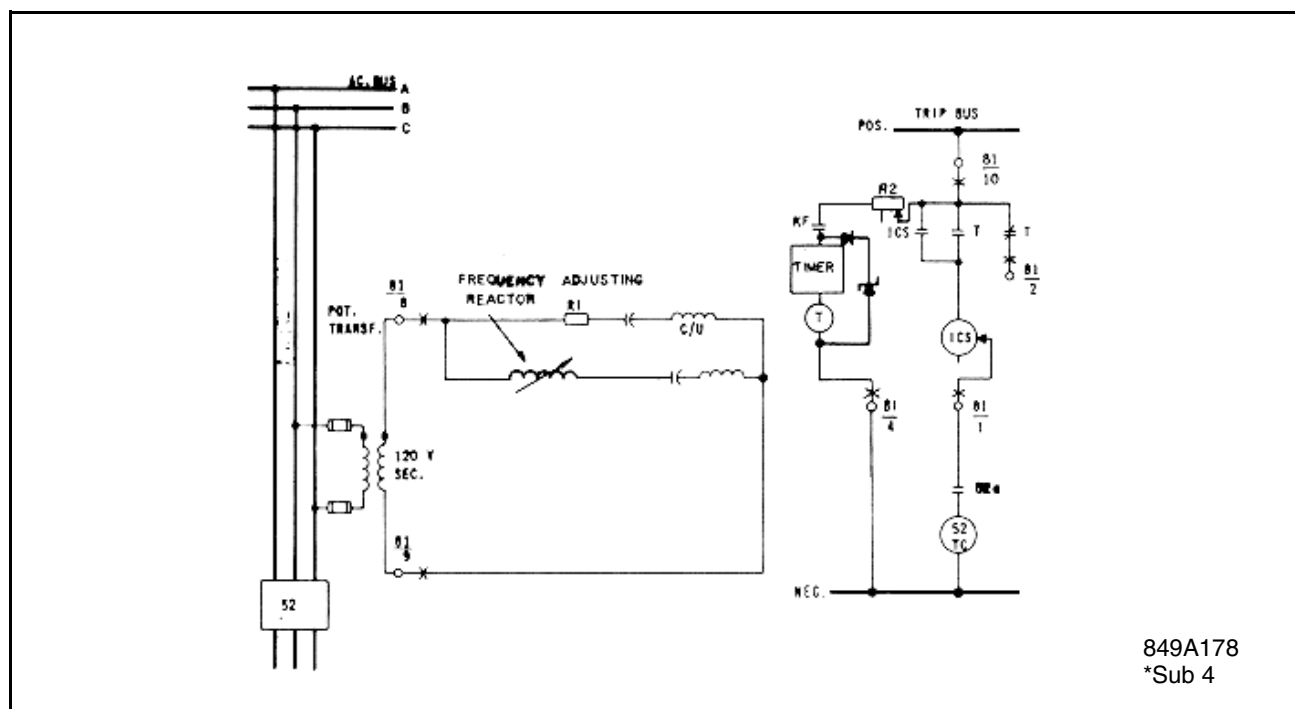


Figure 11: External Connections for the Type KF Underfrequency Relay with dc Operated Auxiliary Time Delay Unit

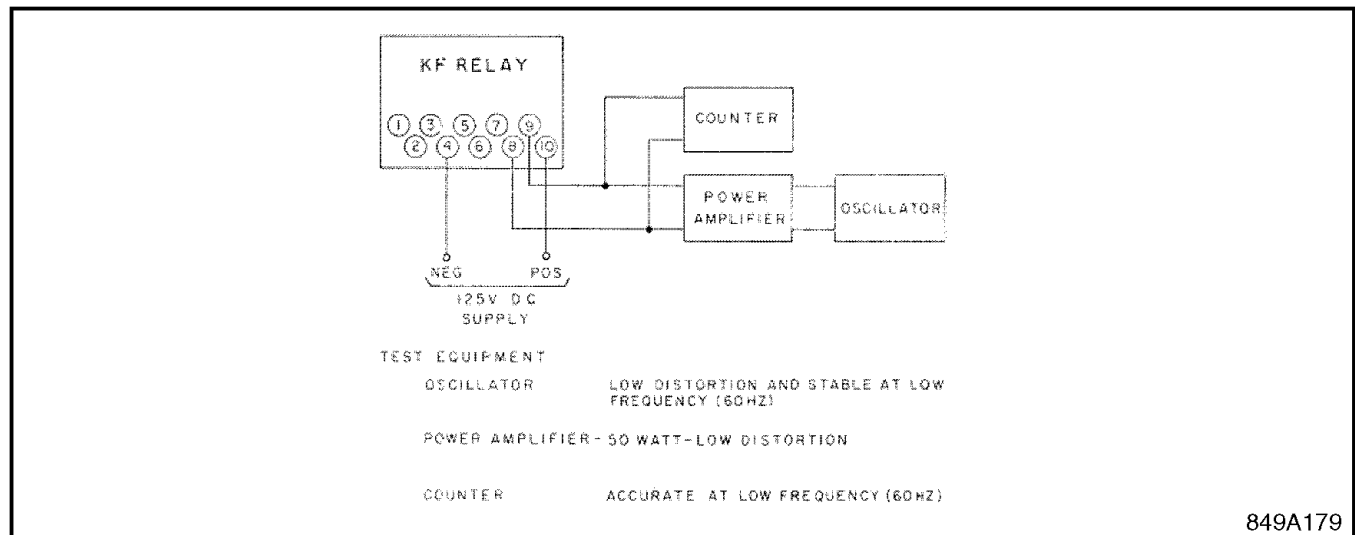


Figure 12: Diagram of Test Connections for KF Relay with dc Operated Auxiliary Time Delay Unit

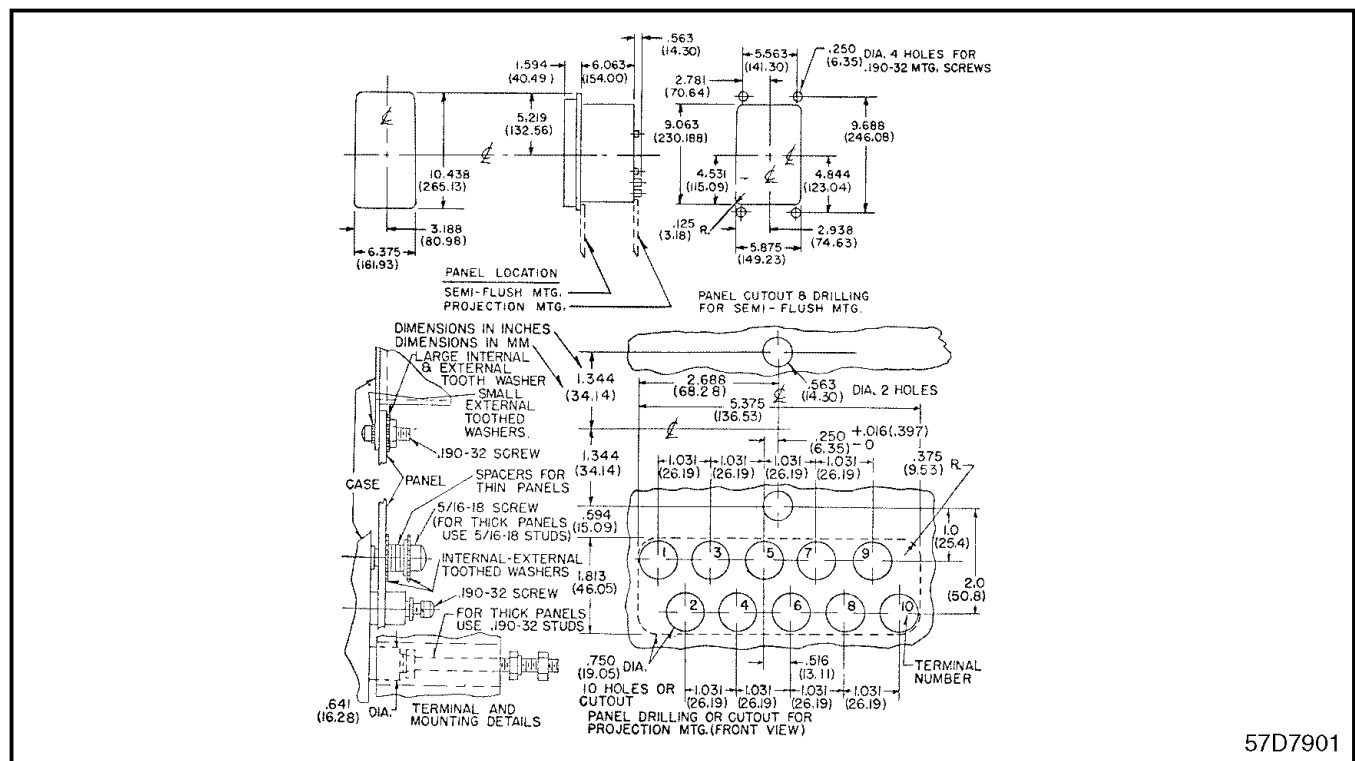


Figure 13: Outline & Drilling Plan for the Type KF Relay in Type FT-21 Case

AIRD AIRD

ABB Inc.

4300 Coral Ridge Drive
Coral Springs, Florida 33065

Telephone: +1 954-752-6700

Fax: +1 954-345-5329

www.abb.com/substationautomation