IRBP B
Industrial robot positioner

The ABB positioners are optimized to be used for manipulating of work pieces in arc welding, thermal cutting and other applications. All axes can be fully coordinated with the robot when programming as well as during operation.

IRBP B
This positioner features a twin station solution where the robot works on one side and the operator loads and unloads on the other side. A screen is fitted between the two stations, which protects the operator from the arc.

The IRBP B is ideal for workpieces that have to be rotated around two axes to reach the optimal process position.

The positioner IRBP B, which comes in three variants, is designed to handle workpieces including fixture of a weight up to 750 kg.

The modular design, few and heavy-duty moving parts as well as minimal maintenance demands make the positioner service friendly.

Dynamically adaptive software plus high-speed drives result in fast changeovers and high productivity.

General positioner features
All ABB positioners offer users a complete and efficient solution. They are of a robust design to ensure excellent stability and are well protected for operation in harsh production environments. All positioners can be combined with any ABB six axes robots except the small IRB 120.

The positioners are easy to use with clear, simple instructions for programming. The control equipment is located in the robot controller and uses the same drive system and software as the robots.

ABB’s positioners are designed to be highly functional yet compact to make maximum use of available floor space. Standardized dimensions for all rotating plates greatly simplify the exchange of fixtures.

Dynamic modelling allows rapid acceleration, fast movements and re-orientation so that cycle times are kept to a minimum. The dynamic model automatically compensates for the effects of gravity, inertia and friction to provide fast and accurate movements (QuickMove™) following of the programmed path (TrueMove™).

The Load ID-function is used to calculate the center of gravity and the inertia of the workpiece and of the fixture.

To meet requirements from our users the positioners can be supplied, or retrofitted, with a comprehensive range of pneumatic swivels (1 and 2 channels) and slip-rings (10 power signals and ProfiBus).

ABB positioner systems can be supplied with all necessary safety equipment.
## Specification

<table>
<thead>
<tr>
<th>Variants</th>
<th>Handling capacity (kg)</th>
<th>Max load diff. sides 1 and 2 (kg)</th>
<th>Index time (s)</th>
<th>Weld to weld time (s)</th>
<th>Repetitive accuracy (r=500)</th>
<th>Max rotation speed (°/s) Axis 1</th>
<th>Max rotation speed (°/s) Axis 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>IRBP B-250</td>
<td>250 (each side)</td>
<td>175</td>
<td>3.4 - 3.8</td>
<td>5.2 - 5.6</td>
<td>+/-0.05</td>
<td>150</td>
<td>180</td>
</tr>
<tr>
<td>IRBP B-500</td>
<td>500 (each side)</td>
<td>250</td>
<td>3.5 - 3.7</td>
<td>5.8 - 6.0</td>
<td>+/-0.05</td>
<td>90</td>
<td>150</td>
</tr>
<tr>
<td>IRBP B-750</td>
<td>750 (each side)</td>
<td>250</td>
<td>3.5 - 3.7</td>
<td>5.8 - 6.0</td>
<td>+/-0.05</td>
<td>90</td>
<td>150</td>
</tr>
</tbody>
</table>

## Measurements

<table>
<thead>
<tr>
<th>Variants</th>
<th>A</th>
<th>øB</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
<th>øI</th>
<th>øG</th>
<th>H</th>
<th>J</th>
</tr>
</thead>
<tbody>
<tr>
<td>IRBP B-250</td>
<td>900</td>
<td>683</td>
<td>900</td>
<td>1786</td>
<td>2000</td>
<td>3040</td>
<td>1180</td>
<td>1000</td>
<td>238.5</td>
<td>173</td>
</tr>
<tr>
<td>IRBP B-500</td>
<td>1000</td>
<td>1450</td>
<td>950</td>
<td>2620</td>
<td>2000</td>
<td>4132</td>
<td>1450</td>
<td>1450</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>IRBP B-750</td>
<td>1000</td>
<td>1450</td>
<td>950</td>
<td>2620</td>
<td>2000</td>
<td>4132</td>
<td>1450</td>
<td>1450</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

For complementary information, please see the product specification. ABB reserves the right to change data without notice.

We reserve the right to make technical changes or modify the contents of this document without prior notice. With regard to purchase orders, the agreed particulars shall prevail. ABB does not accept any responsibility whatsoever for potential errors or possible lack of information in this document.

We reserve all rights in this document and in the subject matter and illustrations contained therein. Any reproduction, disclosure to third parties or utilization of its contents – in whole or in parts – is forbidden without prior written consent of ABB.

Copyright © 2019 ABB
All rights reserved