

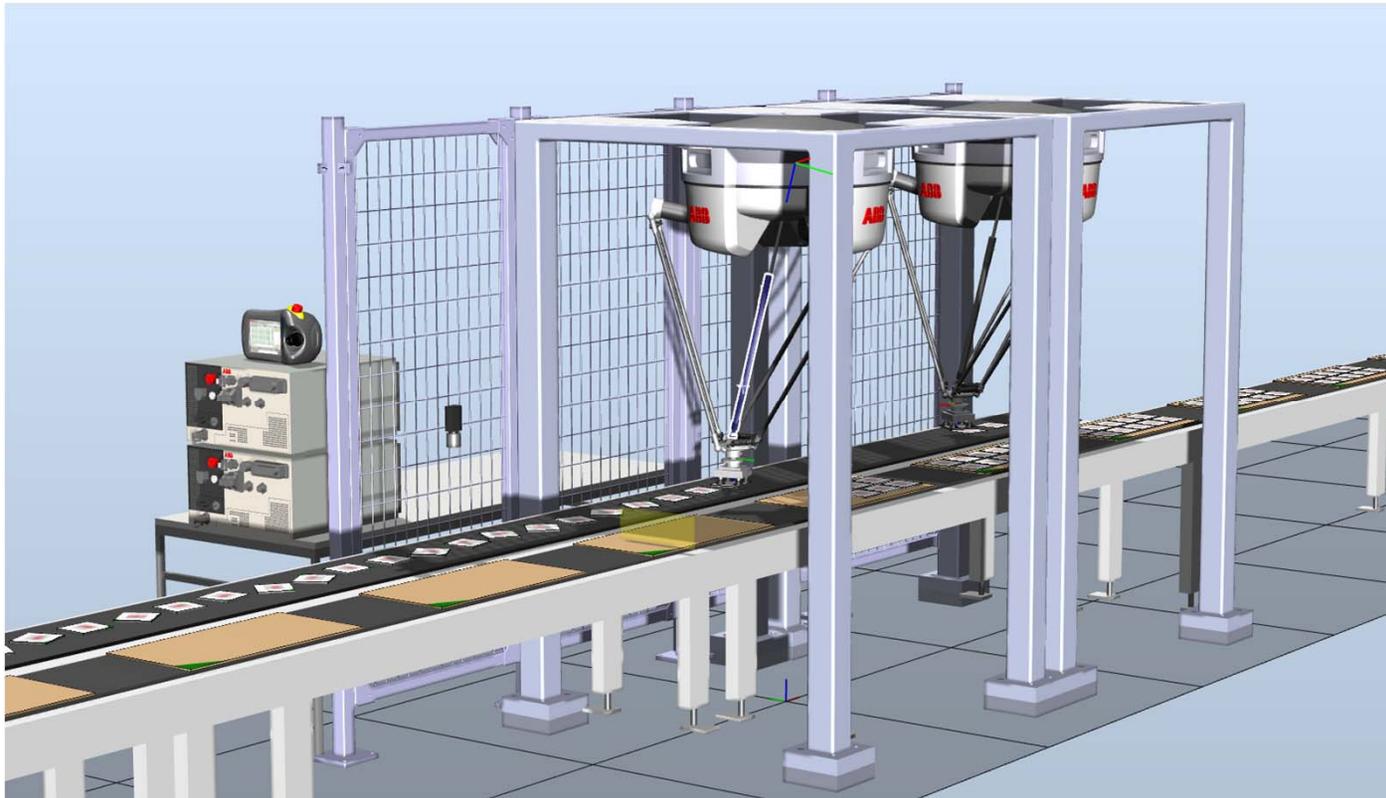
Klas Bengtsson, March 2014

# RobotStudio Picking PowerPac PickMaster 3

# The challenge of creating a picking line

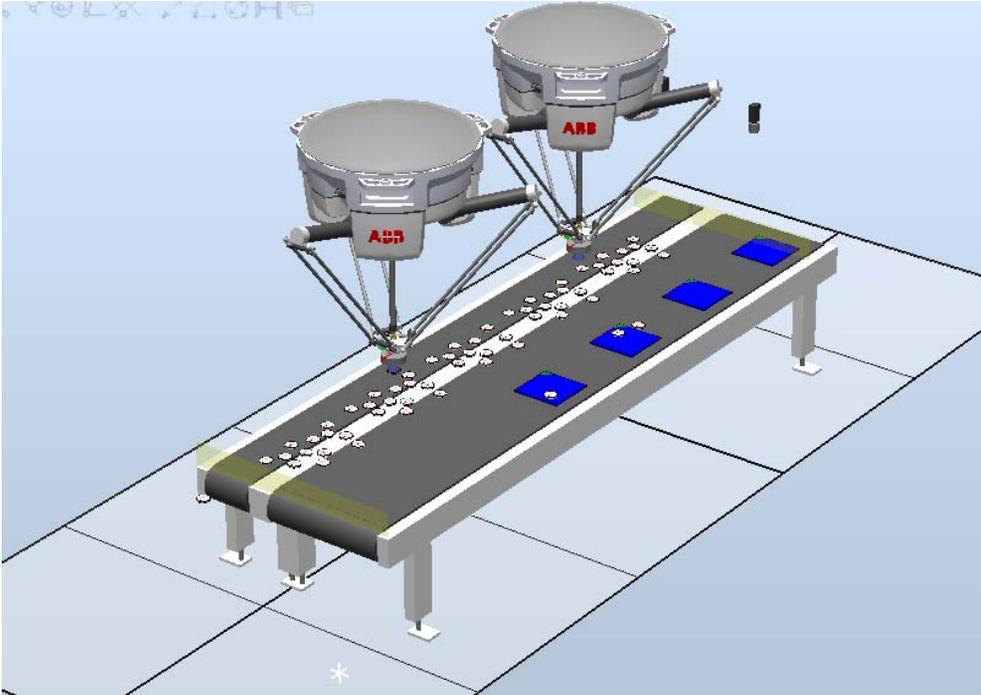
- Without advanced experience, it is difficult to understand how the final result in a multi robot picking line will variate with changes of the inflow of products
- It can be difficult to convince a customers that a multi robot picking line will deliver the desired result
- With an increasing number of different products and pack styles, the validation and programing time grows rapidly
- The calculated profit must be very good to balance the risk

# The solution

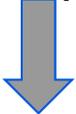


***RS PowerPac to simulate a picking  
line controlled by PickMaster3***

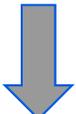
# Workflow



Configure the physical line



Add products and formats



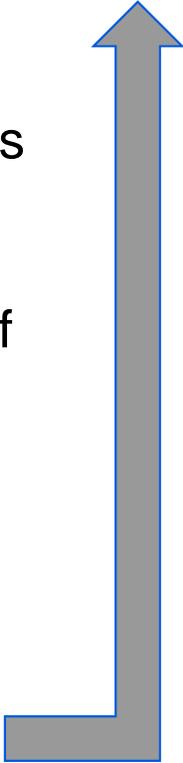
Define the in feed flow of products



Simulate



Transfer result to  
PickMaster3™

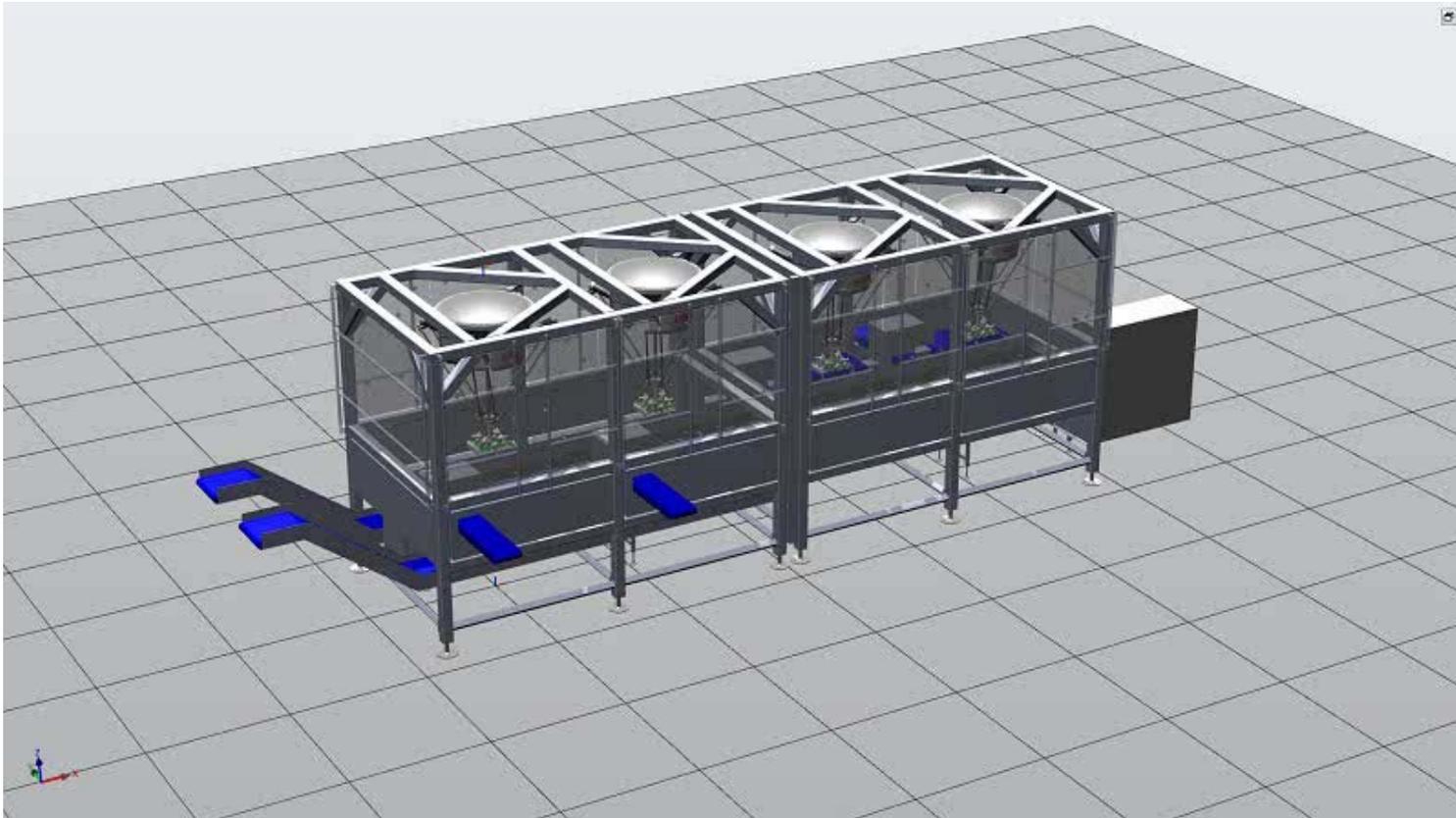


# Key facts

- Simple and intuitive
- Same functions as in PickMaster 3
- The flow of products can be defined as:
  - Average distribution
  - Own distribution of targets in one frame
  - Recording from a PM3 line can be used as input
- Gripping time given as input
- Virtual tuning
- Pickrate per robots displayed

# Key values

## Hit rate



**A simulation movie is an efficient sales tool**

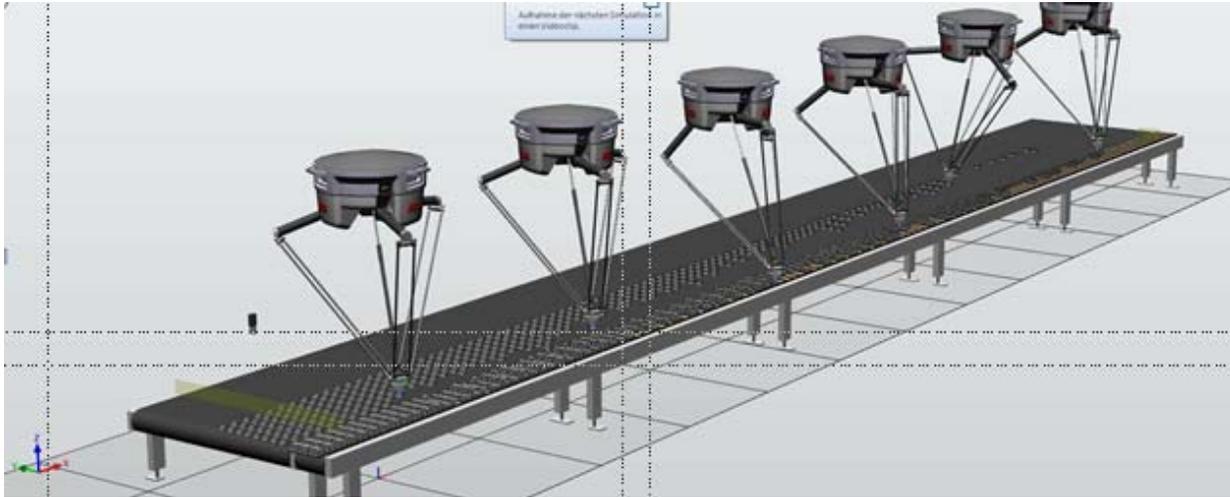
# Key values

## Improved margins



**Optimized efficiency that requires less "safety" margin" and substantially less validation time**

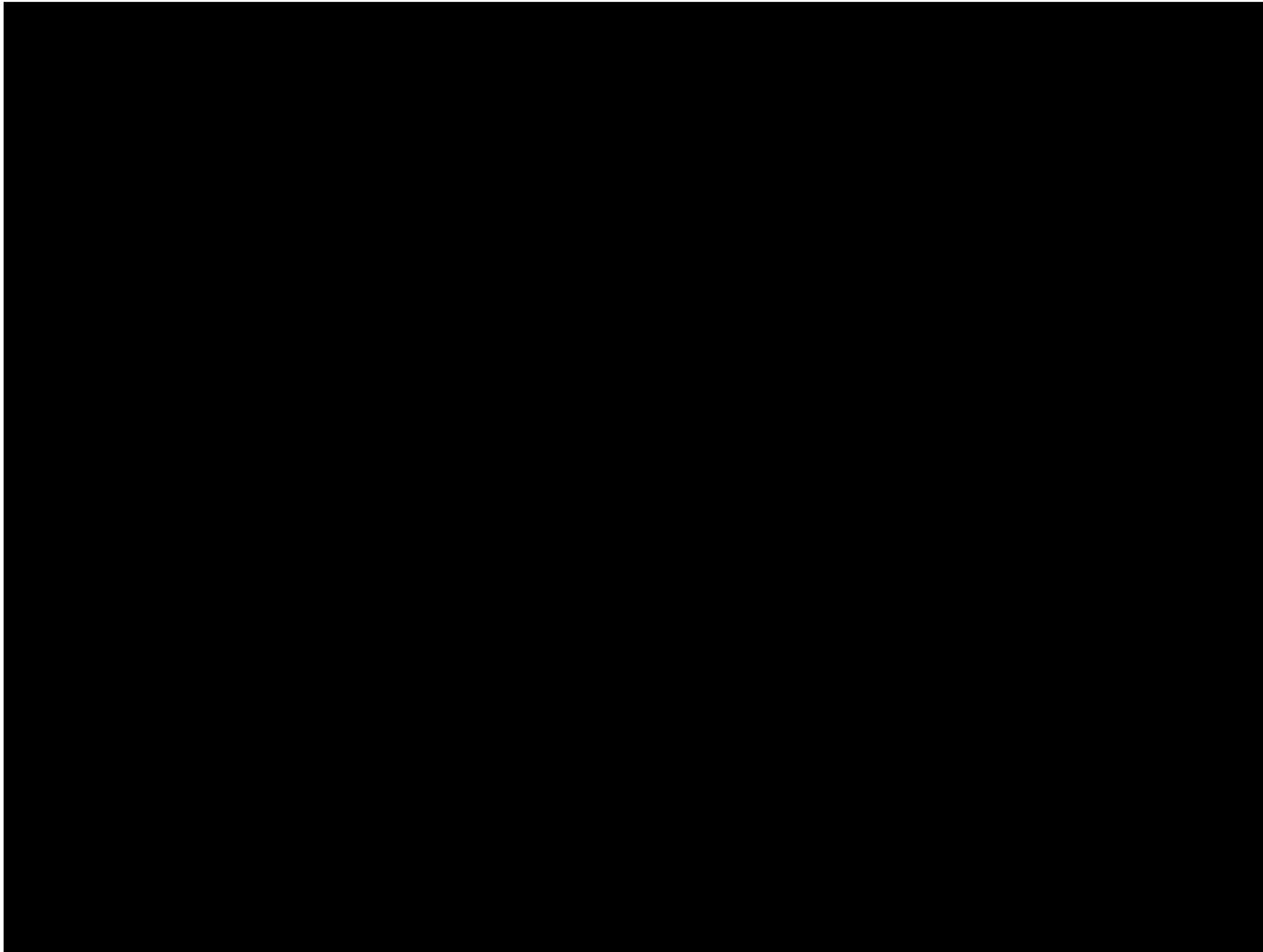
# Why more picking lines?



***”RS Picking PowerPac is a simulation and sales tool that improves the line efficiency while reducing the risks”***

# How to work with Picking PowerPac

## Movie link



Power and productivity  
for a better world™

