The Company

We are an established world force in the design and manufacture of instrumentation for industrial process control, flow measurement, gas and liquid analysis and environmental applications.

As a part of ABB, a world leader in process automation technology, we offer customers application expertise, service and support worldwide.

We are committed to teamwork, high quality manufacturing, advanced technology and unrivalled service and support.

The quality, accuracy and performance of the Company’s products result from over 100 years experience, combined with a continuous program of innovative design and development to incorporate the latest technology.

The UKAS Calibration Laboratory No. 0255 is just one of the ten flow calibration plants operated by the Company and is indicative of our dedication to quality and accuracy.

Electrical Safety

This equipment complies with the requirements of CEI/IEC 61010-1:2001-2 ‘Safety Requirements for Electrical Equipment for Measurement, Control and Laboratory Use’. If the equipment is used in a manner NOT specified by the Company, the protection provided by the equipment may be impaired.

Symbols

One or more of the following symbols may appear on the equipment labelling:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>!</td>
<td>Warning – Refer to the manual for instructions</td>
</tr>
<tr>
<td>!</td>
<td>Caution – Risk of electric shock</td>
</tr>
<tr>
<td>⬇</td>
<td>Protective earth (ground) terminal</td>
</tr>
<tr>
<td>⬇</td>
<td>Earth (ground) terminal</td>
</tr>
<tr>
<td>⬇</td>
<td>Direct current supply only</td>
</tr>
<tr>
<td>⬇</td>
<td>Alternating current supply only</td>
</tr>
<tr>
<td>⬇</td>
<td>Both direct and alternating current supply</td>
</tr>
<tr>
<td>⬇</td>
<td>The equipment is protected through double insulation</td>
</tr>
</tbody>
</table>

Information in this manual is intended only to assist our customers in the efficient operation of our equipment. Use of this manual for any other purpose is specifically prohibited and its contents are not to be reproduced in full or part without prior approval of the Technical Publications Department.

Health and Safety

To ensure that our products are safe and without risk to health, the following points must be noted:

1. The relevant sections of these instructions must be read carefully before proceeding.
2. Warning labels on containers and packages must be observed.
3. Installation, operation, maintenance and servicing must only be carried out by suitably trained personnel and in accordance with the information given.
4. Normal safety precautions must be taken to avoid the possibility of an accident occurring when operating in conditions of high pressure and/or temperature.
5. Chemicals must be stored away from heat, protected from temperature extremes and powders kept dry. Normal safe handling procedures must be used.
6. When disposing of chemicals ensure that no two chemicals are mixed.

Safety advice concerning the use of the equipment described in this manual or any relevant hazard data sheets (where applicable) may be obtained from the Company address on the back cover, together with servicing and spares information.
### 1 Introduction

1.1 System Schematic

### 2 Mechanical Installation

2.1 Location – Environmental Conditions

2.1.1 AquaProbe

2.1.2 Transmitter

2.2 Location – Flow Conditions

2.2.1 International Standard for Flow Measurement

2.2.2 Velocity Limitations

2.3 Location – Mechanical

2.3.1 AquaProbe

2.3.2 Transmitter

2.4 Safety

2.5 Installing the AquaProbe

2.6 Setting the Insertion Depth

2.6.1 Centre Line Method for Pipe Diameters ≤1 m (≤40 in)

2.6.2 Centre Line Method for Pipe Diameters >1 m ≤2 m (>40 in ≤80 in)

2.6.3 Mean Axial Velocity Method

2.7 AquaProbe Alignment

### 3 Electrical Installation

3.1 Connections

3.1.1 Sensor Terminal Box Connections (Remote Versions only)

3.1.2 Environmental Protection

3.1.3 Transmitter Connections

3.2 Input/Output Connections

3.2.1 Frequency Outputs

3.2.2 PLC Interface

3.2.3 MIL Connector Input/Output Connections (Option)

3.2.4 Local Computer Connection

3.2.5 Remote Computer Connection (Option)

3.2.6 Power Supply Connection Options

3.2.7 Pressure Transducer (Optional)

3.2.8 Environmental Protection (Option)
Insertion-Type Electromagnetic Probe Flowmeter
AquaProbe 2

4 Setting Up ........................................................................................................................................30
  4.1 Introduction .....................................................................................................................................30
  4.2 Centre Line Method ......................................................................................................................31
  4.3 Mean Axial Velocity Method (1/8 Diameter) ................................................................................32
  4.4 Partial Velocity Traverse ..............................................................................................................32
  4.5 AquaProbe Transmitter Setup ...................................................................................................32

5 Start Up And Operation ...................................................................................................................33
  5.1 Fitting the Battery .........................................................................................................................33
  5.2 Start-up .........................................................................................................................................34
  5.3 Display Activation .........................................................................................................................34
  5.4 Replacing the Battery ...................................................................................................................35

Appendix A ...............................................................................................................................................36
  A.1 Testing the Flow Profile for Symmetry ........................................................................................36
     A.1.1 Partial Velocity Traverse ......................................................................................................36
     A.1.2 Single Entry Point Method .................................................................................................36
     A.1.3 Dual Entry Point Method ..................................................................................................37

Appendix B AquaMaster Block Diagram .............................................................................................38

Notes ....................................................................................................................................................39
1 Introduction

The AquaProbe electromagnetic insertion flowmeter is designed for measurement of the velocity of water. The flowmeter, available in four standard lengths, can be installed in any pipeline of internal diameter from 200 mm (8 in) to 8000 mm (360 in), through a small tapping. The AquaProbe is designed for use in survey applications such as leakage monitoring and network analysis and in permanent locations where cost or space limitations preclude the use of conventional closed pipe meters.

### Note. Warranty

The AquaProbe sensor tip material is warranted for a period of 3 years as standard against material and manufacturing defects. This warranty can be extended for a further 2 years upon request. The AquaProbe shaft and mechanical components, along with the transmitter, have a standard 12 month warranty period.

### Note. Care of the Equipment

- The tip of the AquaProbe is a precision-built part of the equipment and must be handled with care.
- When the AquaProbe is not in use, fully retract the tip of the probe and replace the end-cap.
- When removing/inserting the probe into the pipeline, ensure that the valve is fully open.
- Damage to the probe affects the performance.
- Physical damage to the probe invalidates the warranty.

1.1 System Schematic

![System Schematic](image-url)
2 Mechanical Installation

2.1 Location – Environmental Conditions

2.1.1 AquaProbe

Fig. 2.1 Environmental Requirements – AquaProbe
2.1.2 Transmitter

A – Within Temperature Limits

-20 °C (−4 °F) Minimum

60 °C (140 °F) Maximum

B – Within Environmental Rating

IP68 (NEMA 6) ENCLOSURE 6P

Submerged – Up to 9 Months Accumulated Time

1.5 m (60 in)

C – Shade from Heat

Fig. 2.2 Environmental Requirements – AquaMaster & Explorer Transmitter
2.2 Location – Flow Conditions
The probe may be installed in one of two positions in the pipe; either on the centre line or at the mean axial velocity point (1/8 pipe diameter). It may also be traversed across the pipe to determine the velocity profile.

Note. Ensure that the sensor is installed in the pipe with the flow direction arrow on the probe case matching the pipe flow.

Fig. 2.3 Flow Conditions

2.2.1 International Standard for Flow Measurement

Section 2.2: 1982 ‘Method of measurement of velocity at one point of a conduit of circular cross section’ describes the inference of volumetric flow from measurement of velocity at a single point. Several conditions must be fulfilled to validate the method, which uses calculations based on empirical data.

Where the validating conditions can be met, the method described in Section 2.2 is the most practical. It is possible to measure the velocity either on the centre line, which reduces sensitivity to positional errors, or at the assumed point of mean flow velocity.

Table 2.1, page 7 is an extract from ISO 7145 (BS 1042): Section 2.2: 1982 and is reproduced with the permission of BSI. Complete copies of the standard can be obtained by post from BSI Publications, Linford Wood, Milton Keynes, MK14 6LE.

Note. Where the above ideal conditions cannot be achieved, the flow profile must be tested for symmetry in order to obtain reliable flow results.
2.2.2 Velocity Limitations

All insertion probe devices are susceptible to the vortex shedding effect which can cause severe vibration of the probe, resulting in damage and/or measurement instability. Electromagnetic devices with no moving parts, such as AquaProbe, are less susceptible to this effect than mechanical devices.

The graphs below show the maximum permissible velocities, depending on the probe’s location. This information is provided as a guide only. Some installations may experience unwanted vibration resonance which may further limit the maximum velocity at which the AquaProbe may be used.

---

* Expressed in multiples of the diameter of the conduit.

Downstream from the measurement cross-section, the straight length shall be at least equal to five duct diameters whatever the type of disturbance.

**Table 2.1 Straight Pipe Lengths**

<table>
<thead>
<tr>
<th>Type of disturbance upstream from the measuring cross-section</th>
<th>Minimum upstream straight length*</th>
</tr>
</thead>
<tbody>
<tr>
<td>90° elbow or a t-bend</td>
<td>For a measurement at the point of mean axial velocity</td>
</tr>
<tr>
<td>Several 90° coplanar bends</td>
<td>50</td>
</tr>
<tr>
<td>Several 90° non-coplanar bends</td>
<td>50</td>
</tr>
<tr>
<td>Total angle convergent 18 to 36°</td>
<td>80</td>
</tr>
<tr>
<td>Total angle divergent 14 to 28°</td>
<td>30</td>
</tr>
<tr>
<td>Fully opened butterfly valve</td>
<td>45</td>
</tr>
<tr>
<td>Fully opened plug valve</td>
<td>30</td>
</tr>
<tr>
<td>For a measurement on the axis of the conduit</td>
<td>25</td>
</tr>
<tr>
<td></td>
<td>25</td>
</tr>
<tr>
<td></td>
<td>50</td>
</tr>
<tr>
<td></td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>25</td>
</tr>
<tr>
<td></td>
<td>25</td>
</tr>
<tr>
<td></td>
<td>15</td>
</tr>
</tbody>
</table>

---

* Expressed in multiples of the diameter of the conduit.

Downstream from the measurement cross-section, the straight length shall be at least equal to five duct diameters whatever the type of disturbance.

**Table 2.1 Straight Pipe Lengths**

<table>
<thead>
<tr>
<th>Pipe Size in Inches</th>
<th>Maximum Velocity in m/s</th>
<th>Maximum Velocity in ft/s</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>6.0</td>
<td>19.7</td>
</tr>
<tr>
<td>16</td>
<td>5.0</td>
<td>16.4</td>
</tr>
<tr>
<td>24</td>
<td>4.0</td>
<td>12.8</td>
</tr>
<tr>
<td>32</td>
<td>3.0</td>
<td>9.8</td>
</tr>
<tr>
<td>48</td>
<td>2.0</td>
<td>6.5</td>
</tr>
<tr>
<td>56</td>
<td>1.0</td>
<td>3.3</td>
</tr>
<tr>
<td>64</td>
<td>0.0</td>
<td>0.0</td>
</tr>
</tbody>
</table>

**Fig. 2.4 Maximum Permissible Velocity for Different Pipe Sizes**
Fig. 2.5  Maximum Permissible Velocity for Different Pipe Sizes

Fig. 2.6  Maximum Permissible Velocity for Different Insertion Lengths
2.3 Location – Mechanical

2.3.1 AquaProbe

**Note.** Pipeline recommended to be metal for electrical screening.

Dimensions in mm (in)

![Diagram showing mechanical requirements for AquaProbe](image)

**Fig. 2.7 Mechanical Requirements – AquaProbe**
2.3.2 Transmitter

Dimensions in mm (in)

![Image of Transmitter Dimensions]

Installation and Wiring Access
300 (11.8) min.
450 (17.7) Preferred

Allowance for Cable Bend
130 (5.1) [Standard]
200 (7.9) [Armoured]

Fig. 2.8 Clearance Dimensions – Transmitter

Dimensions in mm (in)

![Image of Transmitter Mounting Plate Details]

Transmitter Mounting Plate Details

Allowance for Cable Bend
130 (5.1) [Standard]
200 (7.9) [Armoured]

Fig. 2.9 Clearance Dimensions – Transmitter
### 2.4 Safety

**Warning.** The Aquaprobe is provided with a safety mechanism (see Fig. 2.10A) that must be attached to its securing collar as shown in Fig. 2.10B. This prevents rapid outward movement by the probe if nut 1 is released.

**Note.** To ensure maximum safety, the positioning collar **MUST** be tightened in place using a 4 mm hexagon key.

---

![Fig. 2.10 Safety Mechanism](image)

---

See Warning
2.5 Installing the AquaProbe

Warning. When inserting or removing the AquaProbe suitable restraining equipment must be used to prevent the probe being forced out under pressure. Ensure that the valve is fully open.

Dimensions in mm (in)

Referring to Fig. 2.12:

1. Tighten the nut (hand tight only).
2. Remove the cap.
3. Apply PTFE tape.
4. Insert the probe into the valve.
5. Tighten firmly.

Fig. 2.11 Insertion Bore Clearance

Fig. 2.12 Installing the AquaProbe
2.6 Setting the Insertion Depth

2.6.1 Centre Line Method for Pipe Diameters ≤1 m (≤40 in)

**Warning.** When inserting or removing the AquaProbe suitable restraining equipment must be used to prevent the probe being forced out under pressure. Ensure that the valve is fully open.

**Note.** Safety restraint omitted for clarity.

Referring to Fig. 2.13:

1. Determine the internal diameter (D).
2. Open the valve fully.
3. Slacken the nut.
4. Insert the probe into the valve.
5. Slide the positioning collar down to the nut and lock in place.
6. Retract the probe fully.
7. Unlock, slide the positioning collar down and lock at the distance: \[ \frac{D}{2} + 30 \text{ mm (1.181 in)} \]
8. Insert the probe to position collar depth.
9. Tighten to 40 Nm (30 ft lbf).

Fig. 2.13 Setting the insertion Depth – Centre Line Method for Pipe Diameters 1 m (40 in)
2.6.2 Centre Line Method for Pipe Diameters >1 m ≤2 m (>40 in ≤80 in)

**Warning.** When inserting or removing the AquaProbe suitable restraining equipment must be used to prevent the probe being forced out under pressure. Ensure that the valve is fully open.

**Note.** Safety restraint omitted for clarity.

Referring to Fig. 2.14:
1. Determine the internal diameter (D).
2. Measure to the top of the valve plate (VP).
3. Slacken the nut.
4. Lower the probe to touch the valve plate.
5. Slide the positioning collar down to the nut and lock in place.
6. Retract the probe fully.
7. Unlock, slide the positioning collar down and lock at the distance:
   \[
   \frac{D}{2} + VP + 30\text{ mm (1.181 in)} + \text{pipe thickness.}
   \]
8. Open the valve fully.
9. Insert probe to position the collar depth.
10. Tighten to 40 Nm (30 ft lbf).

Fig. 2.14 Setting the Insertion Depth – Centre Line Method for Pipe Diameters >1 m 2 m (>40 in 80 in)
2.6.3 Mean Axial Velocity Method

**Warning.** When inserting or removing the AquaProbe suitable restraining equipment must be used to prevent the probe being forced out under pressure. Ensure that the valve is fully open.

**Note.** Safety restraint omitted for clarity.

Referring to Fig. 2.15:

1. Determine the internal diameter (D).
2. Measure to the top of the valve plate (VP).
3. Slacken the nut.
4. Lower the probe to touch the valve plate.
5. Slide the positioning collar down to the nut and lock in place.
6. Retract the probe fully.
7. Unlock, slide the positioning collar down and lock at the distance:
   \[
   \frac{D}{8} + VP + 30 \text{ mm (1.181 in)} + \text{pipe thickness.}
   \]
8. Open the valve fully.
9. Insert probe to position the collar depth.
10. Tighten to 40 Nm (30 ft lbf).

**Fig. 2.15 Setting the Insertion Depth – Mean Axial Velocity Method**
2.7 AquaProbe Alignment

**Warning.** When inserting or removing the AquaProbe suitable restraining equipment must be used to prevent the probe being forced out under pressure. Ensure that the valve is fully open.

**Note.** Safety restraint omitted for clarity.

Referring to Fig. 2.16:
1. Slacken the nut.
2. Align parallel to the pipe (within 2°) – measurement error due to misalignment (of <2) is <0.15%.
3. Tighten to 40 Nm (30 ft lbf).

*Fig. 2.16 Probe Alignment*
3 Electrical Installation

3.1 Connections

3.1.1 Sensor Terminal Box Connections (Remote Versions only)

Caution. (Remote versions)
- Make connections only as shown.
- Remove foil screens
- Twist the three screen wires together and sleeve them.
- Twist cable pairs together
- Maintain Environmental Protection at all times.
- Conduit connections must provide cable entry sealing.

---

![Sensor Terminal Box Connections (Remote Version) Diagram]

**CABLE**

<table>
<thead>
<tr>
<th>ABB</th>
<th>Belden 8777</th>
</tr>
</thead>
<tbody>
<tr>
<td>Violet</td>
<td>White</td>
</tr>
<tr>
<td>Blue</td>
<td>Black</td>
</tr>
<tr>
<td>Green</td>
<td>Sleeved Ground</td>
</tr>
<tr>
<td>Yellow</td>
<td>Red</td>
</tr>
<tr>
<td>Orange</td>
<td>Black</td>
</tr>
<tr>
<td>Red</td>
<td>Green</td>
</tr>
<tr>
<td>Brown</td>
<td>Black</td>
</tr>
</tbody>
</table>

**Maximum Cable Lengths**

- 250 m
- 80 m

---

Caution. With Belden Cable 8777, ensure that the black wires are not interchanged, and remain with the associated twisted pair.
3.1.2 Environmental Protection

![Potting the Terminal Box](image)

**Warning.**
- Potting materials are toxic – use suitable safety precautions.
- Read the manufacturers instructions carefully before preparing the potting material.
- The remote sensor terminal box connections must be potted immediately on completion to prevent the ingress of moisture.
- Check all connections before potting – see Section 3, Page 17.
- Do not overfill or allow the potting material to come into contact with 'O' rings or grooves.
- Do not let potting material enter conduit, if used.
3.1.3 Transmitter Connections

Caution.
- To ensure cable glands seal, use cable of diameter 7 to 11 mm (0.28 to 0.43 in) only.
- Ensure cable glands are tightened after wiring.
- Ensure that 'O' ring seals and mating surfaces are clean, to maintain environmental rating.

---

![Figure 3.3 Transmitter Connection Terminal Access](image)

**Fig. 3.3 Transmitter Connection Terminal Access**

---

![Figure 3.4 Transmitter Connection (Glands/Conduit Entry)](image)

**Fig. 3.4 Transmitter Connection (Glands/Conduit Entry)**
Caution. (Remote versions)
- Make connections only as shown.
- Remove foil screens
- Twist the three screen wires together and sleeve them.
- Twist cable pairs together
- Maintain Environmental Protection at all times.
- Conduit connections must provide cable entry sealing.

Note. This arrangement is an option.
3.2 Input/Output Connections

**Caution.**
- Refer to SPECIFICATION SHEET for Input/Output ratings.
- Inductive loads must be suppressed or clamped to limit voltage swings
- Capacitive loads must be inrush current limited.

3.2.1 Frequency Outputs

![Diagram of Frequency Output Connections]

**Note.** Outputs 1, 2 & 3 are not polarity sensitive. The common connection for these outputs is designated ‘COM’.
3.2.2 PLC Interface

Note. Outputs 1, 2 & 3 are not polarity sensitive. The common connection for these outputs is designated 'COM'. Output 3 is an option and may not function on some models.
### 3.2.3 MIL Connector Input/Output Connections (Option)

![Fig. 3.9 MIL Connector Connections](image_url)

#### Table 3.1 MIL Connector Connections

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Function</th>
<th>Color (Output cable)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>B</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>C</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>D</td>
<td>O/P 1</td>
<td>Forward Pulses</td>
<td>Orange</td>
</tr>
<tr>
<td>E</td>
<td>O/P 3</td>
<td>Output 3</td>
<td>White/Orange</td>
</tr>
<tr>
<td>F</td>
<td>O/P 2</td>
<td>Reverse Pulses or Direction</td>
<td>Blue</td>
</tr>
<tr>
<td>G</td>
<td>O/P Com</td>
<td>Common</td>
<td>Drain Wire</td>
</tr>
<tr>
<td>H</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>J</td>
<td>I/P Gnd</td>
<td>Input Common</td>
<td>White</td>
</tr>
<tr>
<td>K</td>
<td>I/P+</td>
<td>Contact Input</td>
<td>Violet</td>
</tr>
<tr>
<td>L</td>
<td>RXD</td>
<td>Receive data (serial input connection)</td>
<td>Turquoise</td>
</tr>
<tr>
<td>M</td>
<td>TXD</td>
<td>Transmit data (serial output connection)</td>
<td>Brown</td>
</tr>
<tr>
<td>N</td>
<td>RTS</td>
<td>Request to send</td>
<td>Red/Black</td>
</tr>
<tr>
<td>P</td>
<td>CTS</td>
<td>Clear to send</td>
<td>Yellow/Red</td>
</tr>
<tr>
<td>R</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>S</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>T</td>
<td>RI</td>
<td>Ring Indicator</td>
<td>Yellow</td>
</tr>
<tr>
<td>U</td>
<td>– Reserved</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>V</td>
<td>Serial GND</td>
<td>Comms Ground</td>
<td>Green</td>
</tr>
</tbody>
</table>

*Table 3.1 MIL Connector Connections*
3.2.4 Local Computer Connection

Fig. 3.10 Local Computer Connections – AquaMaster

Fig. 3.11 Local Computer Connections – Explorer
3.2.5 Remote Computer Connection (Option)

![Diagram of RS232 Connections]

Fig. 3.12 RS232 Connections

<table>
<thead>
<tr>
<th>AquaMaster Terminal</th>
<th>RS232</th>
<th>9-PIN PC Connector</th>
<th>25-PIN PC Connector</th>
</tr>
</thead>
<tbody>
<tr>
<td>TXD</td>
<td>TXD</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>RXD</td>
<td>RXD</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>RTS</td>
<td>RTS</td>
<td>7</td>
<td>4</td>
</tr>
<tr>
<td>CTS</td>
<td>CTS</td>
<td>8</td>
<td>5</td>
</tr>
<tr>
<td>RI</td>
<td>RI</td>
<td>9</td>
<td>22</td>
</tr>
<tr>
<td>GND</td>
<td>GND</td>
<td>5</td>
<td>7</td>
</tr>
</tbody>
</table>

Table 3.2 RS232 Connections
3.2.6 Power Supply Connection Options

Warning.
- DISCONNECT THE SUPPLY FROM ANY CABLES BEING TERMINATED ON THE TRANSMITTER.
- Electrical installation and earthing (grounding) must be in accordance with relevant national and local standards.

Note. Power Supply connections/earthing arrangements are identical for Cathodically Protected systems.

---

**Fig. 3.13 Power Supply Connections (AC Version Transmitter)**
Fig. 3.14 Power Supply Connections (DC Version Transmitter)
3.2.7 Pressure Transducer (Optional)
Optional pressure transducer cables are available for a range of pressures and cable lengths.

**Caution.** Ensure that only the pressure transducer supplied with the transmitter is used. Use of other pressure transducers requires alteration of the pressure span and zero factors in the transmitter – see Quick Reference Programming guide.

*Fig. 3.15 AquaMaster Transmitter fitted with Optional Pressure Transducer Connector*

*Fig. 3.16 Explorer Transmitter fitted with Optional Pressure Transducer Connector*
3.2.8 Environmental Protection (Option)

**Warning.**
- Potting materials are toxic – use suitable safety precautions.
- Read the manufacturers instructions carefully before preparing the potting material.

---

**Fig. 3.17 Potting the Transmitter**

**Caution.**
- For increased protection against accidental water ingress, for example by poor gland tightening, pot the termination area.
- Check all connections and operations before potting – see Section 3, Page 17.
- Do not overfill or allow the potting material to come into contact with 'O' rings or grooves.
- Do not let potting material enter conduit, if used.
4 Setting Up

4.1 Introduction

The basic equation for volume measurement using AquaProbe is:

\[ Q = A F_i F_p V \]

Where:
- \( Q \) = flow rate,
- \( F_i \) = insertion factor
- \( F_p \) = profile factor
- \( V \) = velocity
- \( A \) = area

The pipe diameter, profile factor and insertion factor must be determined as detailed in see Section 5.2, Page 34 to 5.3, as applicable.

**Note.** Due to software configuration, all calculations are in metric units. Therefore if using an imperial pipe, the diameter MUST be converted into millimeters (1 in = 25.4 mm) i.e. a 36 in pipe = 914 mm
4.2 Centre Line Method

1. Determine the internal diameter D of the pipe, in millimeters, by the most accurate method available.
2. Determine the profile factor \( F_p \) from Fig.4.1.
3. Calculate the insertion factor

\[
F_i = \frac{1}{1 - (38/(\pi D))}
\]

**Example** – for a pipe of internal diameter 593 mm (23.35 in):

\[
F_p = 0.861 \text{ (derived from Fig. 4.1)}
\]

\[
F_i = \frac{1}{1 - (38/(\pi 593))}
\]

\[
F_i = 1.021
\]

*Fig. 4.1 Profile Factor vs Velocity for Pipe Sizes 200 to 2000 mm (8 in to 80 in)*
4.3 Mean Axial Velocity Method (1/8 Diameter)

1. Determine the internal diameter $D$ of the pipe, in millimeters, by the most accurate method available.

2. A profile factor $F_P$ of 1 must be used.

3. Calculate the insertion factor

$$F_i = \left[ 1 + \frac{12.09}{D} + \frac{1.3042}{\sqrt{D}} \right]$$

**Example** – for a pipe of internal diameter 593 mm (23.35 in):

$$F_P = 1$$

$$F_i = \left[ 1 + \frac{12.09}{593} + \frac{1.3042}{\sqrt{593}} \right]$$

$$F_i = 1.074$$

4.4 Partial Velocity Traverse

Refer to Appendix A.1.1, page 36 for the procedure.

4.5 AquaProbe Transmitter Setup

The AquaProbe Transmitter can be set up to display point velocity, mean velocity or flow rate, as required. For full programming details refer to the AquaProbe Quick Reference Guide.
5 Start Up And Operation

Warning.

- The lithium battery used in this device may present a risk of fire or chemical burn if mistreated. Do not recharge, disassemble, heat above 100°C or incinerate.
- Replace battery with ABB Limited Part No. WABC2001 only. Use of another battery may present a risk of fire or explosion.
- Dispose of used battery promptly. Keep away from children.
- Dispose of used batteries in accordance with your local regulations.
- Where possible, recycle used batteries.
- Contact your local environmental authority for further information regarding disposal or recycling schemes for used batteries.

Note.

- If fitting a battery on an external powered (AC or DC) unit, ensure the unit is powered during this operation.
- Each battery must be connected to the cable from the same side of the termination area as the battery position in the lid.

5.1 Fitting the Battery

If the AquaMaster has been supplied with one or two batteries, but not connected, then proceed as follows:

1. Remove the top cover of the transmitter – see Section 3.1.3, Page 19.
2. Invert the cover.
3. Slide out the connector from behind the battery retaining clamp.
4. Connect the battery or batteries to the wire connector(s) inside the top of the transmitter unit; left hand battery to left hand connector and right hand battery to right hand connector.
5. Ensure that the end of the battery with the connection wires is pushed up against the inside end of the top cover.
6. Push the connection centrally behind the battery retaining clamp to secure the battery.
7. Fit the top cover to the transmitter and ensure the screws are tightened fully.
5.2 Start-up
If the AquaMaster is received with a protective plastic film over the display window, remove this film before commencing normal operation.

When the power is connected or the plastic film is removed, the AquaMaster performs a self test operation, and indicates a successful completion with 'EE Pass' displayed.

If the display shows 'EE Fail 1', remove all power, check the sensor wiring and apply power.

If the display shows 'EE Fail 2 or 3', contact ABB.

5.3 Display Activation
For normal operation, activate the light sensitive display by first covering the display area totally. On removing the covering, the display activates and cycles through the programmed set of display measurements.

With external power applied, the display is permanently activated.

To alter the displayed set of measurements, or instrument setup, see the Quick Reference Programming Guide.

**Note.** For the use of local or remote serial communication, and configuration, see the Quick Reference Programming Guide.
5.4 Replacing the Battery

**Caution.** If replacing the battery on an external powered (AC or DC) unit, ensure it is powered during this operation. For dual battery units, replace only the battery above the indicated battery legend.

**Note.** Each battery must be connected to the cable from the same side of the termination area as the battery position in the lid.

**Normal Operation**

If both batteries are good, no battery alarm is indicated.

![Normal Operation Display](image)

**Replace Battery**

When a battery alarm is shown, replace the cell on the side indicated. (In this example, the Right Battery).

![Replace Battery Display](image)

**Replace both batteries**

If both batteries require replacement, it is important to first change the cell indicated by the steady icon.

![Replace both batteries Display](image)

The flashing icon indicates the battery currently in use.

**Proceed as follows:**

1. Remove the top cover of the transmitter – see Section 3.1.3, Page 19.
2. Invert the cover.
3. Slide out the connector from behind the battery retaining clamp and pull the connector apart.
4. Remove the battery.
5. Fit a new battery (ABB Part No. WABC2001) ensuring that the end of the battery with the connection wires is pushed up against the inside end of the top cover.
6. Connect the battery connector to the connector previously removed.
7. Push the connection centrally behind the battery retaining clamp to secure the battery.
8. Fit the top cover to the transmitter and ensure the screws are tightened fully.
Appendix A

A.1 Testing the Flow Profile for Symmetry
If there is any doubt as to the symmetry of the flow profile (see Section 2.2, Page 6), a Partial Velocity Traverse should be carried out. This procedure involves comparing the value of velocity at two points at equal distances from the centre line.
It is normal to compare the flow velocities at insertion depths of 1/8 and 7/8 of the pipe diameter as these points are always on the ‘knee’ of the profile.

A.1.1 Partial Velocity Traverse
Determine the internal diameter D of the pipe, in millimeters, by the most accurate method available. If the AquaProbe insertion length is greater than the internal diameter of the pipe, proceed with the Single Entry Point Method detailed in Section A.1.2. If the AquaProbe insertion length is less than the internal diameter of the pipe, proceed with the Dual Entry Point Method detailed in Section A.1.3.

A.1.2 Single Entry Point Method
1. Insert the probe to a depth of 1/8 the pipe diameter – see Fig. 2.15.
2. Calculate the insertion factor
   \[ F_i = \left[ 1 + \frac{12.09}{D} + \frac{1.3042}{\sqrt{D}} \right] \]
3. Refer to the AquaProbe Transmitter Configuration Manual and enter a Blockage Factor (BL) of value equal to \( F_i \).
4. Record the flow velocity reading.
5. Insert the probe to a depth of 7/8 the pipe diameter.
6. Calculate the insertion factor.
   \[ F_i = \left[ 1 + \frac{12.09}{D} + \frac{1.3042}{\sqrt{D}} \right] \]
7. Refer to the AquaProbe Transmitter Configuration Manual and enter a Blockage Factor (BL) of value equal to \( F_i \).
8. Record the flow velocity reading.
9. Calculate the ratio of the two values recorded.

If the ratio is between 0.95 and 1.05 the flow profile is acceptable and the procedure detailed in Section 4.2, Page 31 can be used. If outside this ratio the AquaProbe should be resited for optimum accuracy.

Note. Due to software configuration, all calculations are in metric units. Therefore if using an imperial pipe, the diameter **MUST** be converted into millimeters (1 in = 25.4 mm) i.e. a 36 in pipe = 914 mm.
A.1.3 Dual Entry Point Method
Refer to Section 2.5 and fit a second mounting boss directly opposite the one already fitted.

**Note.** Due to software configuration, all calculations are in metric units. Therefore if using an imperial pipe, the diameter **MUST** be converted into millimeters (1 in = 25.4 mm) i.e. a 36 in pipe = 914 mm.

1. Insert the probe to a depth of $\frac{1}{8}$ the pipe diameter through the original mounting boss.
2. Calculate the insertion factor.
   
   $$F_i = \left[ 1 + \frac{12.09}{D} + \frac{1.3042}{\sqrt{D}} \right]$$

3. Refer to the AquaProbe Transmitter Configuration Manual and enter a Blockage Factor (BL) of value equal to $F_i$.
4. Record the flow velocity reading.
5. Insert the probe to a depth of $\frac{1}{8}$ the pipe diameter through the second mounting boss.
6. Record the flow velocity reading.
7. Calculate the ratio of the two values recorded

If the ratio is between 0.95 and 1.05 the flow profile is acceptable and the procedure detailed in Section 4.2, Page 31 can be used. If outside this ratio the AquaProbe should be resited for optimum accuracy.
Appendix B AquaMaster Block Diagram
Notes
PRODUCTS & CUSTOMER SUPPORT

Products

Automation Systems
- for the following industries:
  - Chemical & Pharmaceutical
  - Food & Beverage
  - Manufacturing
  - Metals and Minerals
  - Oil, Gas & Petrochemical
  - Pulp and Paper

Drives and Motors
- AC and DC Drives, AC and DC Machines, AC Motors to 1kV
- Drive Systems
- Force Measurement
- Servo Drives

Controllers & Recorders
- Single and Multi-loop Controllers
- Circular Chart and Strip Chart Recorders
- Paperless Recorders
- Process Indicators

Flexible Automation
- Industrial Robots and Robot Systems

Flow Measurement
- Electromagnetic Flowmeters
- Mass Flowmeters
- Turbine Flowmeters
- Wedge Flow Elements

Marine Systems & Turbochargers
- Electrical Systems
- Marine Equipment
- Offshore Retrofit and Refurbishment

Process Analytics
- Process Gas Analysis
- Systems Integration

Transmitters
- Pressure
- Temperature
- Level
- Interface Modules

Valves, Actuators and Positioners
- Control Valves
- Actuators
- Positioners

Water, Gas & Industrial Analytics

Instrumentation
- pH, Conductivity and Dissolved Oxygen Transmitters and Sensors
- Ammonia, Nitrate, Phosphate, Silica, Sodium, Chloride, Fluoride, Dissolved Oxygen and Hydrazine Analyzers
- Zirconia Oxygen Analyzers, Katharometers, Hydrogen Purity and Purge-gas Monitors, Thermal Conductivity

Customer Support

We provide a comprehensive after sales service via a Worldwide Service Organization. Contact one of the following offices for details on your nearest Service and Repair Centre.

United Kingdom
ABB Limited
Tel: +44 (0)1453 826661
Fax: +44 (0)1453 829671

United States of America
ABB Inc.
Tel: +1 215 674 6000
Fax: +1 215 674 7183

Client Warranty

Prior to installation, the equipment referred to in this manual must be stored in a clean, dry environment, in accordance with the Company’s published specification.

Periodic checks must be made on the equipment’s condition. In the event of a failure under warranty, the following documentation must be provided as substantiation:

1. A listing evidencing process operation and alarm logs at time of failure.
2. Copies of all storage, installation, operating and maintenance records relating to the alleged faulty unit.
ABB has Sales & Customer Support expertise in over 100 countries worldwide

www.abb.com

The Company's policy is one of continuous product improvement and the right is reserved to modify the information contained herein without notice.

Printed in UK (04.10)
© ABB 2010