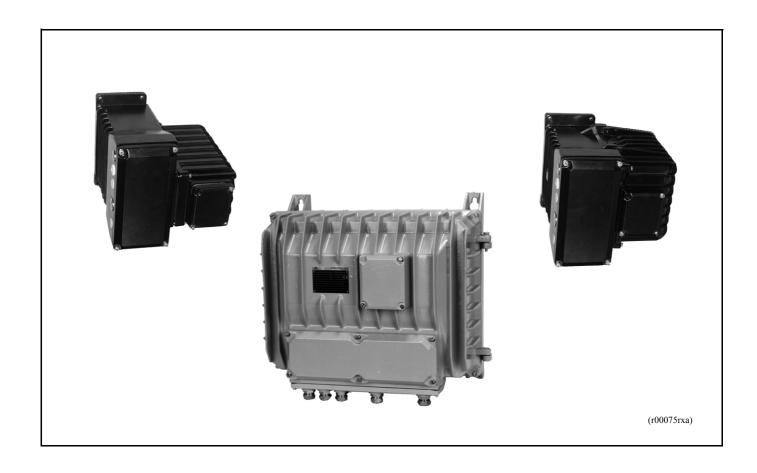
Electronics for Electrical, Power Electronics **Continuous Actuators**For Field Mountine EAN 823, EBN 853, EBN 861

For Field Mounting

Operating Instructions

42-68-822EN Rev. 2





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ELECTRICAL WARNING



.An instruction with reference to electrical components or equipment. It draws attention to the risk of injury or death to persons or damage to the product, process or surroundings

WARNIG



General instruction that draws attention to the risk of injury or death to persons or damage to the product, process or surroundings

INFORMATION



Further reference for more detailed information or technical details.

1. Device Identification

1.1 General

The ID labels of the power electronics are located both on the base (power supply) and on the cover (electronics and software memory) of the unit. As the base and cover are considered as separate assemblies, they may have different serial numbers (BA numbers).

1.2 ID Label on the Base

1	Elektronik / Electronics Type:		- N	
2	B-Nr./No	NL		Germany
3	U = 230 V	Jahr/Year		Зег
4	f = 50/60 Hz ± 5%	Pmax. = W		.⊑
5	t =°C	IP 66	CF	Made
6	Ext. Sicherung / Fuse		Ma	
	Automation D-32425 Minden		\B	B

- 1. Electronics type
- 2. Device no./ No. of non-standard version
- 3. Permissible supply voltage range / Year of manufacture
- 4. Permissible frequency range / Max. power dissipation
- 5. Permissible ambient temperature / Protection class
- 6. Information on external fuse

1.3 ID Labels on the Cover

1.3.1 ID Label for Software Description

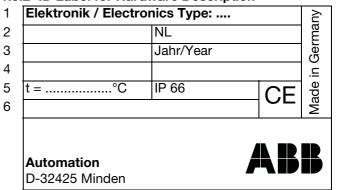
1	Für / For Antrieb / Actuator
2	Mit / NL. Nr./No
3	Eingestellt / adjusted auf/for M=°/s
4	F-Nr. / No. Software Version
5	

- Associated actuator
- 2 Number of non-standard version (if required)
- 3 Adjusted torque / Adjusted speed
- 4 Device number of cover

Downloaded software version

5 Available for customer-specific information

1.3.2 ID Label for Hardware Description



- 1. Electronics type
- 2. Device number / No. of non-standard version
- Year of manufacture
- 4. /
- 5. Permissible ambient temperature / Protection class
- 6.

2. General

2.1 Proper Use

Power electronics models EAN 823, EBN 853 and EBN 861 are to be used exlusively for triggering elektrical actuators of the PME 120, LME 620, RSD... or RHD ... series. Do not use them for any other purpose. Otherwise, a hazard of personal injury or of damage to or impairment of the operational reliability of the device may arise.

2.2 Safety and Precautions

When mounting the electronics in areas which may be accessed by unauthorized persons, take the required protective measures.

- Only qualified specialists who have been trained for these tasks are authorized to mount and adjust the electronics, and to make the electrical connection.
- When working on the electronics always observe the locally valid accident prevention regulations and the regulations concerning the construction of technical installations.



3. Storage

The devices may be stored under moist and aggressive condition for a short time. The equipment is protected against external corrosive influences. However, direct exposure to rain, snow, etc. must be avoided

Condensation may occur in the terminal box. Therefore, it is protected by a desiccant, which ensures sufficient protection for approximately 150 days. The desiccant can be regenerated at a temperature of 90° C within 4 h.

The desiccant must be removed prior to commissioning the electronics.

3.1 Long-time Storage

If you intend to store or transport the device for a longer time, we recommend to wrap it in plastic foil and add desiccant. Regularly check if the desiccant is still active.

4. Delivery settings

Behavior in 0/100% position: Shut-off with rated torque

Setpoint function: Linear; setpoint = positioning value

Input (setpoint): 4 ... 20 mA ¹⁾

Function: Positioner, parameter: setpoint

Output (actual value): 4 ... 20 mA 1)

Digital inputs: 1) DI 1 switch-over manual/automatic and v.v.

DI 2 / DI 3 manual control +/-

Digital outputs: 1) DO 1 ready to operate, DO 2/3 end position signal-

ling

Range: Not adjusted

The configuration of your actuator may differ from the standard configuration specified above. It can be called up for display using the configuration program.

1) not with fieldbus communication.

5. Assemblies

Power electronics EAN 823, EBN 853 and EBN 861 consist of 2 parts each, one containing the connecting units (EAN 823 and EBN 853) and the transformer, the other containing the electronics and the commissioning and service panel (CSP) for local operation and adjustment of the actuator.

5.1 EAN 823 / EBN 853

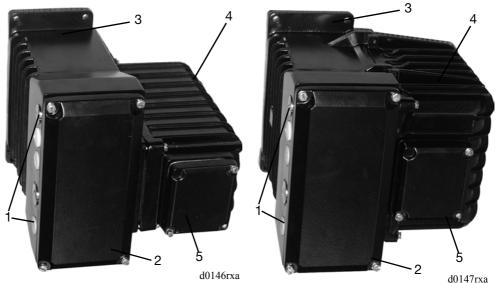


Figure 1: Electronic unit EAN 823

Figure 2: Electronic unit EBN 853

- 1 taphole for cable glands
- 2 cover for connection chamber
- 3 connection housing
- 4 electronic hod
- 5 cover for comissiooning and service panel

5.1.1 Connection chamber

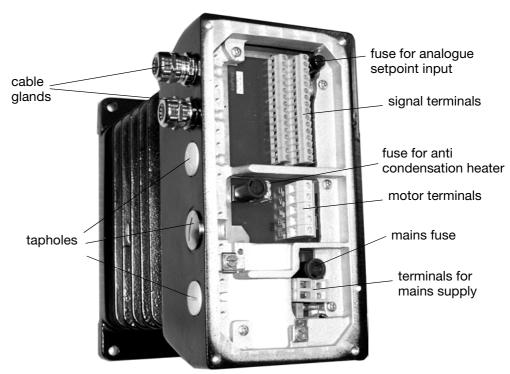


Figure 3: connection chamber EAN 823 / EBN 853.

The standard scope of delivery considers tapholes covered with srew-in plugs. Adapters for PG or NPT cable glands are available on request.

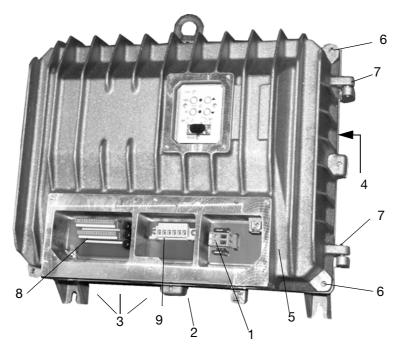


Figure 4: EBN 861

- 1 Mains cable
- 2 Power cable (motor) to the actuator
- 3 Link cable (signals)
- 4 Transformer and power part
- 5 Part for electronics and for commissioning and service field
- 6 Cover screws
- 7 Hinge screws
- 8 Terminal strip (signals)9 terminal strip (motor / brake)

6. Technical Data

6.1 General

	EAN 823	EBN 853	EBN 861	
Supply voltage	,		230 V AC (190 V 60 V); 47.5 63 Hz; 1Ph	
External fuses	16 A; slow-blow 35 A fuse 16 A thermal safety of			
Analog input ¹⁾	0 / 4 20 mA	0 / 4 20 mA		
Analog output ¹⁾	0 / 4 20 mA, ele	ctrically isolated		
Digital inputs, DI ¹⁾	Logical 0:-3V + 5 V or open, electrically isolated Logical 1:+12 V+ 35 V, electrically isolated			
Digital outputs, DO 1)	Potential-free relai	y contact, max. 6	60 V, 150 mA	
Digital communication	RS 232 for commis or Profibus DP	ssioning and serv	ice, optional FSK / HART®	
Default settings	Behavior in 0/1009 Setpoint function:		Shut-off with rated torque Linear; setpoint = positioning value	
	Input (setpoint):		20 mA ¹⁾	
	Function:		Positioner, parameter: set- point	
	Output (actual valu	ue):	4 20 mA ¹⁾	
	Digital inputs: Digital outputs:	automatic and v.v 3 manual control -		
Individual settings	See d	ata sheet 68-2.40	or on request	
Protection class		IP 66		
Humidity		• ,	densation permitted)	
Ambient temperature	-25° C +55° C			
Mounting orientation	Mounting on vertical mounting plate, cable glands to the left glands at the bottom		mounting plate, cable	
Varnish	2-component epoxy resin (RAL 9005, black)			
Link cable between actuator and electronics	optionally 5m, 10m or 20m			
Weight Table 1:	approx. 10 kg approx. 11 kg approx. 42 kg		approx. 42 kg	

¹⁾ Not available for communication via Profibus DP

6.2 Current Consumption of EAN 823

	I _{max} 115 V	I _{max} 230 V	I pos.
PME 120 AN	1.0 A	0.55 A	each around
LME 620 AN	1.0 A	0.55 A	40 50% of I _{max}

Table 2:

6.3 Current Consumption of EBN 853

	I _{max} 115 V	I _{max} 230 V	I pos.
RHD 250-10	1.8 A	0.9 A	
RHD 500-10	2.2 A	1.1 A	
RHD 800-10	3.4 A	1.7 A	
RHD 1250-12	6.0 A	3.0 A	
RHD 2500-25	4.8 A	2.4 A	
RHD 4000-40	4.0 A	2.0 A	
RHD 8000-80	4.0 A	2.0 A	each around
RSD 10-5,0	3.4 A	1.7 A	40 50% of I _{max}
RSD 10-10,0	3.8 A	1.9 A	
RSD 20-5,0	4.8 A	2.4 A	
RSD 20-7,5	3.8 A	1.9 A	
RSD 50-3,0	4.0 A	2.0 A	
RSD 100-1,5	4.4 A	2.2 A	
RSD 200-0,7	5.0 A	2.5 A	

Table 3:

6.4 Current consumption of EBN 861

	I _{max} 230 V	I pos.
RHD 2500-10	5.3	
RHD 4000-10	10.0	
RHD 8000-15	8.0	around 40 50%
RHD 16000-30	12.5	of I _{max}
RSD 50-10,0	6.4	
RSD 100-10,0	12.5	
RSD 200-5,5	13.0	

Table 4:

6.5 Fuses

Electronics	Fuse type	Mounting site	U = 115 V	$U = 230 V^{1)}$
	Series fuse	external	16 A, slow	
EAN 823	Mains fuse	in connection chamber	6.3 A, slow	3.15 A, slow
LAIT OLO	Relay fuse for DO 1, DO 2, DO 3	on processor board, contact manufacturer for replacement	3 x 0.5 A; medium time-lag	
	Series fuse	external	16 A, slow	
	Mains fuse	in connection chamber	12.5 A, slow	10 A, slow
EBN 853	Relay fuse for DO 1, DO 2, DO 3	on processor board, contact manufacturer for replacement	3 x 0.5 A; medium time-lag	
	Brake fuse	power board	0.315 A, medium time-lag	
	Intermediate circuit fuse	power board	10 A, super-quick	
	Series fuses ¹⁾	external	35 A fuse 16 A thermal safety cutout	
EBN 861	Relay fuse for DO 1, DO 2, DO 3	on processor board, contact manufacturer for replacement	3 x 0.5 A; medium time-lag	
	Brake fuse	on board (power section)	0.315 A, medium time-lag	
	Intermediate circuit fuse	power board	15 A, medium time-lag	

Table 5:

1) The 35 A fuse and the thermal safety cutout (16 A) are included in the scope of delivery. They ensure safe operation for the special swiching conditions of power electronics EBN 861. Note that the cable cross-sectional area between the fuse and the electronics must be at least 2.5 mm².

7. Mounting

Install the electronics close to the actuator. The connection is made via a 32-pin connector on the actuator side and screw terminals on the electronics side. The electronics are provided with the appropriate PG cable glands (see Figures 1 to 3 for the assignment).

7.1 Preparing the electronics

- Make sure that disconnection on site is possible.
- Shield all signal cables and the motor cable between the actuator and the electronics
- The shield of the connection cable between the electronics and the actuator must be applied to both housings.

7.2 Mounting of EAN 823 / EBN 853

Disconnect the electronics and the actuator prior to all installation and service works.

- Fasten the unit to the vertical mounting plate, using screws of property class 8.8 (tensile strength 800 N|mm²; yield strength 640 N/mm²)
- Make sure that there is enough spacing for mounting, and that the unit can be easily accessed
- Make sure that the cable glands are oriented to the left
- Remove the cover of the connection chamber (2)
- Insert the cables through the cable glands and connect them according to the wiring diagram.
- Check if the cable is connected properly; then close the connection chamber cover. Adjust as described in section 9.

7.2.1 Mounting electronics EBN 861

Electronics unit EBN 861 has a total weight of around 42 kg. For safety reasons it may be necessary to mount each of the two parts separately.

- Undo and remove the cover screws (4).
- Undo the hinge screw (5)
- Fold down the front part, then lift it off from the hinge bolts towards the top.
- Undo the internal connection between the two housing parts.
- First mount the rear part of the housing
- Attach the front housing part to the hinge bolts, insert a screw into the top bolt and fasten
- Make the internal connections between the two housing parts.
- Close the cover and fasten the cover screws (4)
- Connect the cables

The item numbers refer to Figure 1 to 4.





8. Electrical Connection

The electrical connection is done with a combined plug on the actuator and with screw terminals on the electronics.



8.1 Wiring diagram EAN 823 (Conventional)

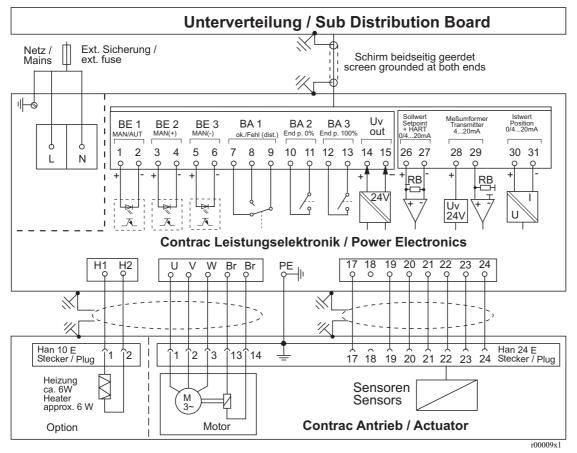


Figure 5:

8.2 Wiring diagram EAN 823 (Profibus DP)

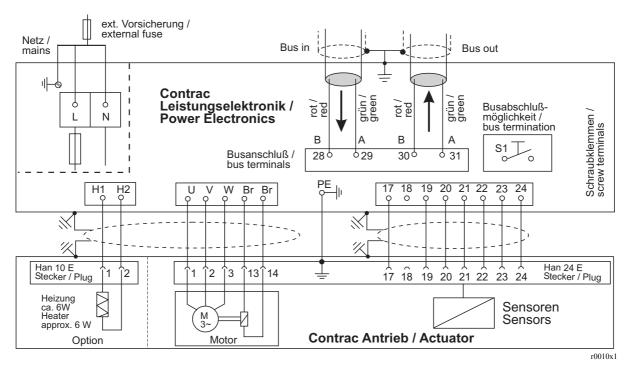


Figure 6:

8.3 Wiring diagram EBN 853 (Conventional)

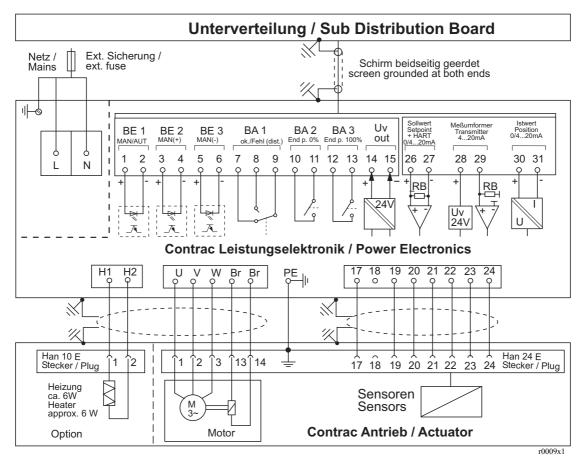


Figure 7:

8.4 Wiring diagram EBN 853 (Profibus DP)

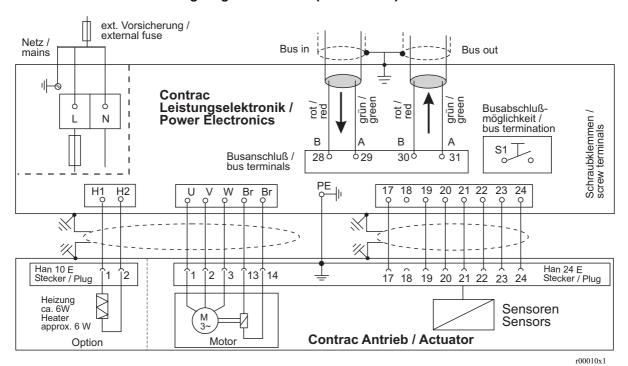


Figure 8:

8.5 Wiring diagram EBN 861 (Conventional)

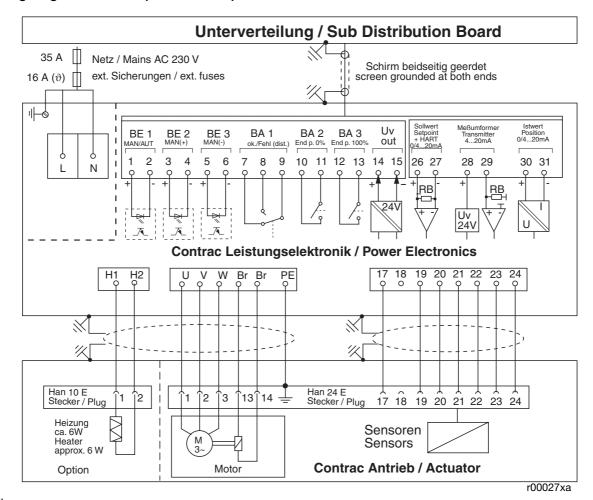


Figure 9:

8.6 Wiring diagram EBN 861 (Profibus DP)

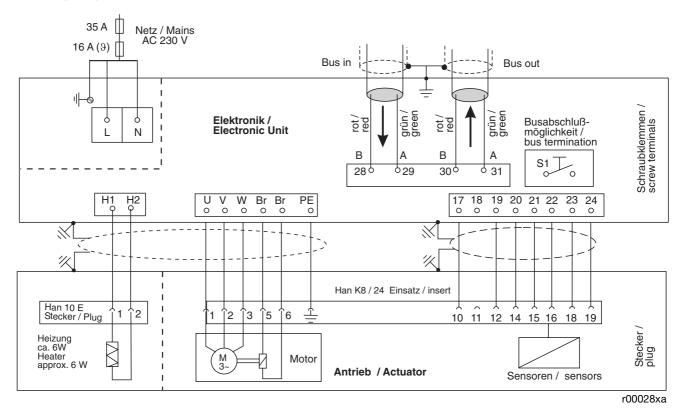
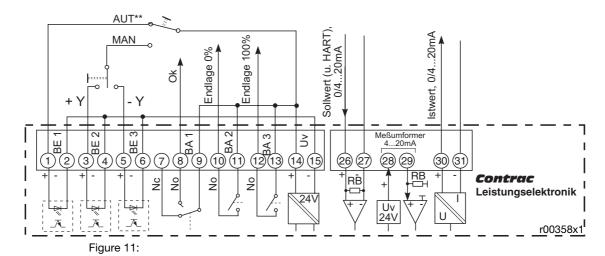


Figure 10:

8.7 Signal Inputs and Outputs

8.7.1 Standard



8.7.2 Operation after a Step Controller

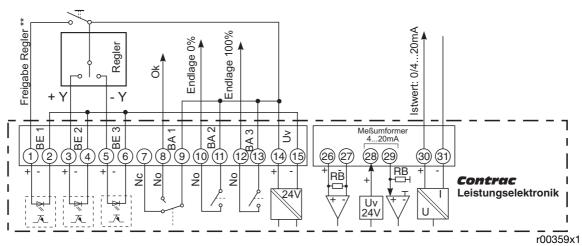


Figure 12:

8.8 Connecting the Cable Shield

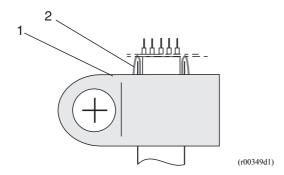
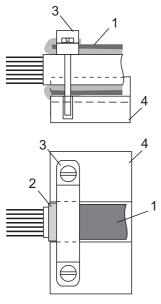


Figure 13: Connecting the cable shield of EAN 823 and EBN 853



- Remove approximately 2 cm of the cable sheathing (1) at the cable entry of the housing (4).
- Open the cable shield in this area and fold it back over the cable sheathing (1).
- Insert the cable end in the cable entry and fasten it with the clamp; make sure that the shield is folded back and in contact with the clamp and the electronics housing.

Figure 14: Connecting the cable shield of EBN 861

9. Setup

The basic settings (definition of end positions) can be made via the **L**ocal **C**ontrol **P**anel (LCP). It is used for adapting the actuator to the operating range and the effective direction without a PC. The actuator can be set up and configured completely using the appropriate configuration program.

The commissioning and service field is located on the electronics!

9.1 Setup via LCP

9.1.1 Operating elements

1. Write-protect switch (Default setting: OFF)

2. LED for 100% position Indication if adjustment procedure, saved position, or

fault by different flash frequencies.

3. Drive buttons Press to cause drive motion

4. Reset button Press to restart processor and clear any 0% and 100%

values.

5. Power LED Indicates available mains supply

6. RS 232 socket Connection socket to PC

7. Potential toggle switch Connection of reference potential to the system or pro-

tective earth (by default set to system)

8. LED for 0% position Indication if adjustment procedure, saved position, or

fault by different flash frequencies...

9. Accept button (0%) Press to define current position as 0%; simultaneously

press push button 11 to complete the adjustment proce-

dure.

10. Accept button (100%) Press to define current position as 100%; simultaneously

press push button 10 to complete the adjustment proce-

dure

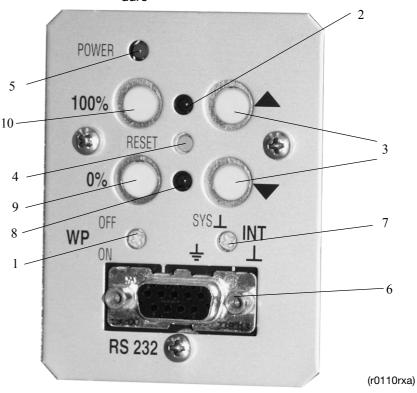


Figure 15: Local Control Panel (LCP)

The actuator range is not preset in factory!

9.1.2 Initial situation

- Electronics connected to power supply and actuator
- Write-protect switch (1) set to "OFF" position
- Electronics in operating mode "MAN" (no signal on DI 1)
- No fault (if a fault occurs, both LEDs flash alternately at 4 Hz)

9.1.3 Setup procedure

- Undo the screws of the LCP cover
- Swing the cover to the side



9.1.3.1 "Setting" mode

 Set electronics to "setting" mode by pressing both push buttons (3) simultaneously for approx. 5 seconds, until both LEDs (2 + 8) are flashing synchronously at approx.
 4Hz

9.1.3.2 Defining first position (0% or 100%)

- Move to desired position by pressing one push button (3).
- To accept the position, press push button (10) or (9); the associated LED flashes at approx. 1Hz when value is correctly accepted, the other continues to flash at approx. 4Hz

(Higher precision in 2nd position)

9.1.3.3 Defining second position (0% or 100%)

- Move to second position by pressing one push button (3).
- To accept the position, press push button (10) or (9); both LEDs (2) and (8) are flashing at approx. 1Hz when value is accepted correctly.

9.1.3.4 Saving the settings

- The settings are accepted by simultaneously pressing the push buttons (10 + 9); the LEDs (2 + 8) extinguish after a short time, and the adjustment procedure is completed.
- If the selected range is too small for the actuator, both LEDs will flash again at 4Hz.
 Repeat the adjustment procedure a larger value (min. positioning travel).
 (See positioning travel specification on actuator ID label)

9.1.3.5 Correction after setup

- If the setting is to be corrected after accepting the first value, first press the Reset button (4) and then repeat the setting.
- If the correction is to be done after saving the settings, the entire adjustment procedure must be repeated.

9.2 Adjustment using the configuration program

Context-sensitive help information is available in the configuration program at all times. For basic handling and installation instructions refer to the associated manual, number 41/68-001.

A conductive ground connection is established between the PC and the CONTRAC electronics with the RS 232 communication cable. If the PC is grounded, this may cause a ground loop in the installation.



9.3 Indication at LCP

Function	Indication			
Adjustment				
Change-over to adjustment mode: Both LEDs flash synchronously a				
Press and hold both drive switches for	approx 4Hz after time has expired.			
approx. 5 seconds				
Moving to an end position	Both LEDs continue to flash at 4Hz while			
Use respective drive button on CSF	driving.			
Saving the first end position	The associated LED flashes at approx.			
Press button 0% or 100%	1 Hz, the other continues at 4 Hz.			
Saving the second end position	The associated LED flashes at approx.			
Press button 0% or 100%	1 Hz synchronously to the first one.			
Terminate adjustment	Both LEDs are briefly lit together and			
Press 0% and 100% buttons simulta-	then extinguish.			
neously				
Opera	ition			
Normal operation: MAN / AUT	LED off			
Driving with button on CSF	LED off			
Priority over control system				
Fault (both LEDs flash	alternately at 4Hz)			
Reset:	If no other fault conditions exist, both			
Resets fault indications	LEDs extinguish.			
Reset if operating range is exceeded;	After approx. 5 seconds the flash rhythm			
press and hold both drive button for 5 sec-				
onds, then press Reset button	electronics switch to adjustment mode.			

Table 6:

ubject to technical changes.
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Subject to technical changes Printed in the Fed. Rep. of Germany 42/68-822 EN 03. 02